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Introduction to AI - SS 2019 Practical 4 20.06.2019

Problem 8: Progression Planning for the Blocks' World Domain

The files blocksworld.pddl and pb3.pddl define the following PDDL description of the Blocks' World domain.

```
blocksworld.pddl:
                                                                                (clear ?underob)
                                                            :precondition (and
                                                                                (holding ?ob))
(define (domain blocksworld)
                                                           :effect (and (arm-empty) (clear ?ob)
(:requirements :strips :equality)
                                                                         (on ?ob ?underob)
(:predicates (clear ?x)
                                                                         (not (clear ?underob))
             (on-table ?x)
                                                                         (not (holding ?ob))))
             (arm-emptv)
             (holding ?x)
                                                          (:action unstack
             (on ?x ?y))
                                                            :parameters (?ob ?underob)
                                                            :precondition (and (on ?ob ?underob)
(:action pickup
                                                                         (clear ?ob) (arm-empty))
  :parameters (?ob)
                                                            :effect (and (holding ?ob) (clear ?underob)
  :precondition (and (clear ?ob)
                                                                         (not (on ?ob ?underob))
                (on-table ?ob) (arm-empty))
                                                                         (not (clear ?ob)) (not
  :effect (and (holding ?ob) (not (clear ?ob))
                                                                         (arm-empty)))))
               (not (on-table ?ob))
               (not (arm-empty))))
                                                          pb3.pddl
(:action putdown
                                                          (define (problem pb3)
  :parameters (?ob)
  :precondition (and (holding ?ob))
                                                             (:domain blocksworld)
  :effect (and (clear ?ob) (arm-empty)
                                                             (:objects a b c)
               (on-table ?ob)
                                                            (:init (on-table a) (on-table b)
               (not (holding ?ob))))
                                                                    (on-table c) (clear a)
                                                                    (clear b) (clear c)
(:action stack
                                                                    (arm-empty))
  :parameters (?ob ?underob)
                                                             (:goal (and (on a b) (on b c))))
```

Implement progession planning and validate your implementation in the Blocks' world domain. For reading the domain and problem description, use the uploaded PDDL scanner (pddlscanner.lua). The function run() reads and scans respective PDDL files.

The functions PDDLScanner:get_domain(ddecl) and PDDLScanner:get_problem(pdecl) yield tables with scanned descriptions. It has the following fields: name, reqs, const, preds, acts and pname, dname, objs, init, goal, respectively.

The functions pretty_print_domain and pretty_print_problem print the read PDDL to the screen and show how the data structures are used.