

Let

①

New Coverage - Eigenvalues, and Eigenvectors.

Consider, matrices as square, now
we looking for special numbers;
Eigenvalues, - vectors

Here we will cover, what are
these numbers
→ some lectures as how
do we use it.
— and why do we want it.

What's Eigen Vectors?

Matrix:

$A = \dots$ what does matrix do;

It acts on vectors, it
multiplies vectors X .

∴ In goes vector X and
out comes vector Ax

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- like a reflection.
- vectors we specifically interested in?
— are all that come out in same direction, as he went in
- , But that won't be typical:
 - Most vectors, Ax points in same different direction, but there are certain vectors where Ax, come out parallel to x.
 - those are Eigen vectors

Eigenvectors

Ax parallel to x same multiple (lambda) of x.

$$Ax = \lambda x$$

Big equation.

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- we look for special vectors, But remember most vectors won't be eigenvectors

- when saying same direction, allow it to be very opposite direction
- if allow λ to be negative or 0.

$$\begin{array}{l} \lambda x \text{ (Eigenvector x)} \\ \lambda \text{ (Eigenvalue)} \end{array}$$

Eigenvalue 0 \Rightarrow not special deal \Rightarrow

$$Ax = 0x$$

then what's Eigenvectors, if $\lambda v = 0$.

\therefore they all group in null space

$$Ax = 0$$

\therefore if A is singular [*i.e. it takes some vector x into 0*]

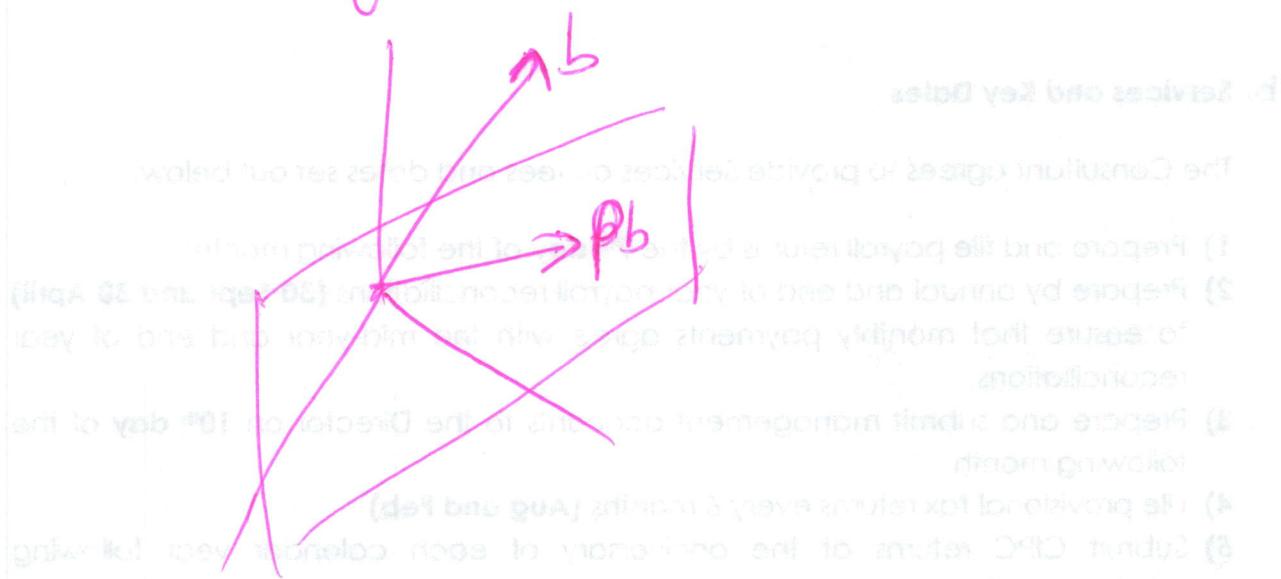
$$\lambda = 0 \rightarrow \text{eigenvalue}$$

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• How do we find the x^s and x^t

- we don't have equation $Ax=b$
- ~~As we can't use elimination any more.~~
- λ , and x , are both unknown
- we need a good idea on how to find them.

First let's take a few matrices:



Suppose we have a plane, what are the eigenvectors of a projection matrix?

- What are the x^s and x^t 's for a projection matrix.

• \Rightarrow we take a vector b , what matrix does it map to Pb

- Is b an eigenvector? In this picture No

1. b is not an Evector, because Pb , its projection, is in a different direction. (5)

2. What vectors are E'vectors of P ?

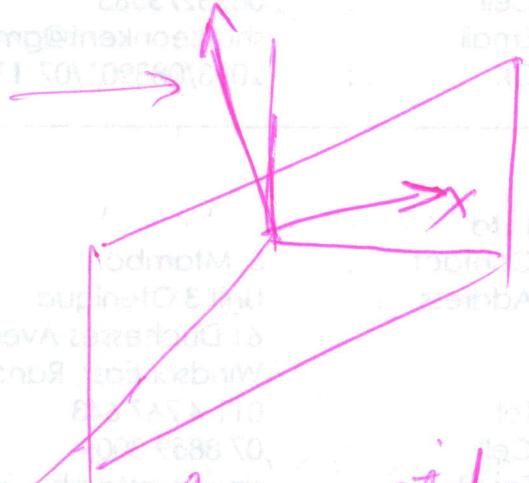
3. Mat vectors do get projected in same direction
Or they start?

4. If vector is already in plane.

5. Any x in plane : Px

Not in plane, but

1.



∴ vector had
already mapped to plane

2. And now if projected, what now do I get back?

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∴ it does not move.

Any $x \in$ Plane is unchanged by P

$$Px = x$$

that tells me that x is ϵ 'vector

and that also tells me that λ tells

the ϵ 'value λ with a multiplier.

$$\epsilon\text{'value} = 1$$

$$\lambda = 1.$$

we have a whole plane of ϵ 'vectors.

- Are there any other ϵ 'vectors? Yes

3Dim, \Rightarrow so hopefully

3 independent ϵ 'vectors.

2 in plane, $\therefore 1$ not in plane

∴ any $x \perp$ to plane; $Px = Ox$

$$\therefore \lambda = 0$$

What are the ~~values~~ for a projection matrix? \textcircled{P}

$$\begin{matrix} 1 & = & 1 \\ 1 & = & 0 \end{matrix}$$

What about a Permutation Matrix:

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \text{ what can be vector } X?$$

what vector can I multiply by
and end up in same direction?

If I ~~if~~ I permute it, it will change:
which vector will have value 1

$$X = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \textcircled{A} (\underline{x \text{ vector}})$$

$$\textcircled{B} \quad Ax = \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \lambda = 1 \quad \textcircled{A} \text{ and } \textcircled{B} \quad Ax = x$$

$$\therefore X = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \textcircled{B}$$

$$\textcircled{B} \quad Ax = \begin{bmatrix} -1 \\ -1 \end{bmatrix} \textcircled{B} = \lambda = -1 \quad \begin{bmatrix} Ax = -x \end{bmatrix}$$

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- Special about λ 's:

.. $n \times n$ matrices will have n λ 's.

But not so easy to find them.

But here is nice fact!



\therefore sum of λ 's = sum down the diagonal

: Called trace \rightarrow

- Sum of λ 's = $a_{11} + a_{22} + \dots + a_{nn}$

\rightarrow the trace tells you what λ value is, then
next one is easy to find.

- How to solve $Ax = \lambda x$ [\therefore two unknowns both in equation]

Reunite:

$$(A - \lambda I)x = 0$$

Don't know λ or x , but do know:

this matrix: $(A - \lambda I)$ must be singular

, and what do we know about SINGULAR
matrices: ... the determinant is 0.

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$$\therefore \det(A - \lambda I) = 0$$

\therefore got an equation for λ

\therefore Called the characteristic equation.
or eigenvalue equation.

\therefore Find λ First [or n different λ 's] or repeated

\therefore after we find λ , then finding X is just by Elimination.

take another Example:

$$A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$$

- made it 2×2
- made it Symmetric
- made it constant down diagonal

$$\therefore \det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix}$$

\therefore Its matrix with λ removed from the diagonal

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diagonal is diagonal and I am taking its determinant.

Want this to be zero

$$\begin{bmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{bmatrix} = (3-\lambda)^2 - 1$$

$$= \lambda^2 - 6\lambda + 8$$

set to 0 and solve.
quadratic equation,
and use factorization.
= $(\lambda-4)(\lambda-2)$ A

What's the number here

: of a trace

What's the number here

: of the det

A

i. $\lambda_1 = 4, \lambda_2 = 2$ (Eigenvalues)

Now to get the eigenvectors?

Lets find the eigenvector for 4 first.

Linear Algebra
100%

Calculus 2
100%

COS 42.7V

According to numerical results
no solution found
for linear algebra

20%
100%
100%
100%
100%



(11)



$$A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$$

(Subtract 4)

$$\xrightarrow{\text{def}} A - 4I = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \in \text{singular matrix}$$

Matrix has now, the X's in nullspace.

$$X_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

E vector / hat
goes with eigenvalue.

$$\lambda = 4$$

E vector
E value

λ=2

$$\therefore A - 2I = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \rightarrow \text{singular matrix}$$

⑤ What vector is in its nullspace?

$$X_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\lambda = 2$$

E' vector
E' value

ANSWER

Orthogonalization in numerical linear algebra

Convergence of iterative methods and the conjugate gradient method

What is the relationship:

(b)

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \lambda = 1, x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \lambda = -1, x_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

one is just $3I$ more than other one

$$\begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}, \lambda = 4, x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \lambda = 2, x_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

λ 's value got now 3 added

$$\lambda = 1 + 3 = 4 \quad \lambda = -1 + 3 = 2$$

But eigenvectors stayed the same

$$A = A, \lambda = \lambda \Rightarrow \text{above.}$$

So if I add $3I$ to matrix,

its eigenvectors don't change.

\Rightarrow and eigenvalues are 3 bigger

Suppose: If $Ax = \lambda x$

3 added
↓

$$\text{then } (A+3I)x = \lambda x + 3x = (\lambda+3)x$$

λx stays same
for both matrices.

But what's Not so GREAT?

If $Ax = \lambda x$, B has eigenvalues

$A+B$

or AxB

→ If we have eigenvalues of one matrix, there's
no reason to believe that its value (x) is
also a eigenvalue of B

B has eigenvalues, but it has different eigenvectors.

so $Bx = \lambda x$ Caution! ↗

Eg: Rotation Matrix: [matrix that rotates every vector by 90°] ①

$$Q = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

it's orthogonal matrix.

$$\therefore \text{trace} = 0+0 = \lambda_1 + \lambda_2.$$

$$\det = 1 = \lambda_1 \lambda_2 \quad \boxed{\det}$$

$$\det(Q - \lambda I) = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$$

$$\therefore \text{eigenvalues } \lambda_1 = i, \lambda_2 = -i$$

But they're not real numbers, even though
the matrix was real.

Now we need to start using Complex numbers

Even worse: (that can happen)

$$A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$$

what are λ_1, λ_2 [Eigenvalues]
 v_1, v_2 [Eigenvectors]

\therefore Matrix is triangular.

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$$\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ 0 & 3-\lambda \end{vmatrix} = (3-\lambda)(3-\lambda)$$

- $\lambda_1 = 3$ $\lambda_2 = 3$

- But problem here is the eigenvectors:

- $(A - \lambda I)x = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix}$

looking for x

independent (NOT)

$$x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$x_2 = \begin{bmatrix} ? \\ ? \end{bmatrix}$$

- only has 1 linear
eigenvector; instead of 2

shortage of eigenvectors

- x_2 - there \rightarrow NO second independent vector for x_2 .