

## Orthogonal Matrices

It will be really useful if we can make a transformation matrix, whose column vectors make a new basis

$\Rightarrow$  and whose component vectors are perpendicular, or orthogonal to each other.

Here:

- we will look at how to do this and WHY it's useful.

Let's define a new operation on a matrix, called a transpose.  
we interchange all of the elements of rows and columns of matrix.



②

$$A_{ij}^T = A_{ji}$$

Have matrix  $A$  with elements  $i, j$ , and transpose of it where I interchange  $i, j$ .

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$$

$\Rightarrow$  diagonal stays same (1, 4)  
 , But 2, 3 flips  $\odot \checkmark$   
 another way of looking at it.

Eg have:

$$A^{n \times n} \begin{bmatrix} \begin{pmatrix} \hat{a}_1 \\ a_{11} \end{pmatrix} \begin{pmatrix} \hat{a}_2 \\ a_{12} \end{pmatrix} \cdots \begin{pmatrix} \hat{a}_n \\ a_{1n} \end{pmatrix} \end{bmatrix}$$

A  $n \times n$  matrix, with series of column vectors, which will be the basis for new transformed vector space.



③

what can we say about vectors  $a_1, \dots, a_n$

- they are of unit length  $\therefore \hat{a}$ .

- and they are orthogonal to each other.

$$\therefore a_1 \cdot a_2 = 0$$

$$\therefore a_i \cdot a_j = 0 \quad \text{if } i \neq j$$

$$\text{and } = 1 \quad \text{if } i = j$$

Now let's pre-multiply  $A$ , with its Transpose  $A^T$

$$\begin{pmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_n^T \end{pmatrix} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

$A^T$  = Series of row vectors, which is  $\hat{a}$ , but  
now rows

what happens when we multiply  $A^T A$ ?



④

$$= \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ 0 & \dots & \ddots & \dots \\ 0 & \dots & \dots & 1 \end{bmatrix} \xrightarrow{ATA} = I$$

above  $1 = a_i \cdot a_j = 1$  if  $i=j$  [have we get 1.]  
above  $0 = a_j \cdot a_i = 0$  if  $i \neq j$  [have we get 0.] } orthonormal.

$\therefore$  find  $\Rightarrow$  ~~where~~ <sup>in</sup>  $A$ , where we have vectors that are normal to each other. in unit length. i.e. when they orthonormal, then  $A^T$  will be the identity.

But  $A^T = A^{-1}$  (is really inverse of  $A$ )

$\therefore$  orthonormal vector set, then transpose is inverse.

, that means don't have get inverse long way, can just do transpose and get the inverse.

A is then called an  
orthogonal matrix →

Another property of orthogonal matrix is, since  
all the basis vectors are of unit length,  
it will scale space by factor of 1.

∴ determinant of orthogonal matrix  
will either be 1 or -1

$$|A| = \pm 1$$

(minus 1 comes about if they flip new  
basis set flips space around, i.e.  
make it left handed, from right hand  
it was originally)

Notice:  $A^T = A^{-1}$ ; the following will be  
also be true

$$A A^T = \underline{I}$$

(previously  $A^T A = \underline{I}$ )

∴ pre or post multiply to get I

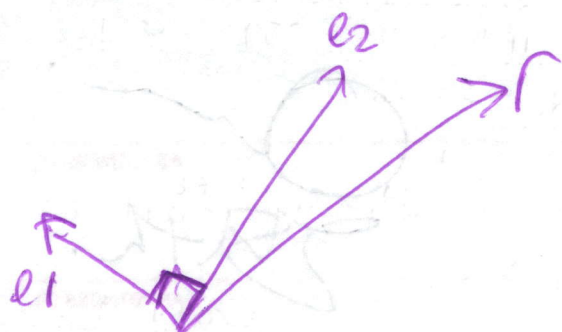


That then also mean, that the rows of the orthogonal matrix are also orthonormal to each other. (5)

$\therefore A^T$  is also orthonormal Basis set.)

Previously we said that transforming a vector onto a new coordinate system is just taking the projection or dot product of that vector onto each of the new basis vectors, as long as they are orthogonal to each other.

Eg of how vector: and project it into new set axes:



take dot product:  
①  $r \cdot e^2$   
②  $r \cdot e^1$   
and we'll have  
Component in new  
set axes.

⑦

In Data Science, what we saying ~~is~~, that  
 ↳ whenever possible we want to use an  
 orthonormal basis vector set when  
 we transform our data

That means  $A$  (our transformation matrix),  
 will be an orthogonal matrix, therefore  
 the transpose ( $A^T$ ) <sup>or inverse  $A^{-1}$</sup>  will be really easy  
 to compute

- Means transformation can be reversible  
 since space don't get collapsed
- means projection is just the dot product.  
 (all things, nice and lovely)
- and if we arrange the basis vector  
 in correct order, then the determinant  
 will be 1.



②

Recap

- we looked at transpose
- which allowed us to find the most convenient basis vector set of all, i.e. orthonormal basis vector set.
- which together gives us an orthogonal matrix
- whose inverse is its transpose