

Module 6

General non linear least squares

In this session we going to look at how to
finally learn how to fit a distribution of
heights data

Then following exercise I am going to do it myself.

Then in next session, we'll wrap up and see
how to do it practically in matlab and python

So we looking at how to fit a function
that's extremely complicated, compared
to the simplest case of LA. $y = mx + c$
(that we looked at last time)

Of course, we're an intermediate possibility
between very complicated and simple as possible
But this gives you the general case.

2

Before how we move on to look at a computer using this
instead of writing our own.

So lets say we have a function $f(y)$, of some
variable x , and that function has parameters
 a_k , where k goes from $1 \dots m$

eg $y(x, a_k) = (x - a_1)^2 + a_2$

This function is not linear in a_1 ; in double a_1

& do not double the function

So as a non linearly least squares we going
to do.

Now I want to fit the parameters a_k to

Some data

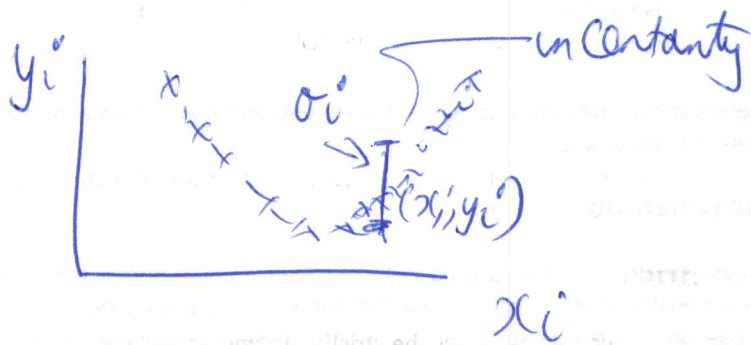
$$i = 1 \dots n$$

$$(y_i, x_i, \sigma_i)$$

and I have pairs of data y_i , and x_i , so
for every x , I have y .

3

and I have an associated uncertainty, σ_i
 that the more uncertain I am about data
 point y_i , the bigger the uncertainty σ_i will be
 I can sketch it and, something like:



Then I am going to define a goodness of fit
 parameter ~~χ^2~~ χ^2 as been the
 sum of all data points i , of difference
 y_i and model of x_i with parameter a_k

$$\chi^2 = \sum_{i=1}^n \frac{[y_i - y(x_i; a_k)]^2}{\sigma^2}$$

and divide all that by σ^2 , and take
 Squares of differences

4
So what I am doing here, is penalizing each difference by the uncertainty of σ^2

So, the uncertainty data points have low weight in my sum of χ^2 , so they don't affect the 'fit' too much.

If we do not know what the σ are we can assign them all to be 1, and just let them just drop out.

But if we have an idea about the uncertainty, then this gives us a way to include it

And my minima for χ^2 is when grad for χ^2 is equal to 0

In general case I may be able to write down an expression for grad here, but I may not be able to solve it algebraically

$$\nabla \chi^2 = 0$$

5
So instead I am going to look to solve:

$$\nabla x^2 = 0$$

By steepest descent, going down the contours simply by updating the vector of fitting ~~parameters~~ parameters.

So I have my vector a ; I am going to say that my next iteration is going to be my current iteration, minus some constant times the grad of x^2 .

$$\textcircled{A} \quad a_{\text{next}} = a_{\text{cur}} - c_{\text{st}} \nabla x^2$$

So I am going down the gradient here by an ^(const) amount given by the constant (going down steepest descent), then I am going to make my next guess what fitting parameters should be and write it down as a vector.

And I'll keep doing it until I reach the criteria $\nabla x^2 = 0$, which means I found minima, or finding that.

Until x^2 stops changing, which should be the same thing or I just give up, so many iterations, so get bored, something has gone wrong

To do the grad, I need to do:

$$\frac{dx^2}{da_k} = \sum_{i=1}^n -2 \frac{y_i - y[x_i; a_k]}{\sigma^2} \frac{dy}{da_k}$$

(for each k 's)

this will be my differential, -2 we can just take out.

so now we need to update (page 5) ①

$$\begin{aligned} a_{next} &= a_{cur} - \text{cost} \nabla x^2 \\ &= a_{cur} + \sum_{i=1}^n \frac{[y_i - y[x_i; a_k]]}{\sigma^2} \frac{dy}{da_k} \end{aligned}$$

evaluated at a_{cur}

(as I do not know a_{next} yet)

lets use the formula for car example
lets differentiate w.r.t a_1

$$y(x; a) = (x - a_1)^2 + a_2$$

$$\frac{dy}{da_1} = -2(x - a_1) \quad \frac{dy}{da_2} = 1$$

So that's the steepest descent formula for fitting a nonlinear function

when we try to minimize the sum of squares of residuals

this is henceforth called nonlinear least squares fitting

There are lots of more complicated methods than steepest descent for solving these sorts of problems, which will look at later, but first give this a go, and code it up for sandpit problem

8

So that's the simplest ^{version} ~~form~~ of doing a ~~general~~
general of how to do a general fitting
finding a minimum ~~of~~ or least value of \sum squares
of residuals for a model that is not linear
in both function and fitting parameters,
that's called GENERALISED NON LINEARISED
LEAST SQUARES FITTING.