VALIDAÇÃO de RESULTADOS TP1

Parâmetros:

- Downsampling 4:2:2; interpolação linear
- QF = 75

Resultados a obter:

- **Imagens** (encoder e decoder)
- Matrizes correspondentes no bloco de coordenadas [8: 16, 8: 16]
- **Erros** na imagem recuperada





Encoder

R



В



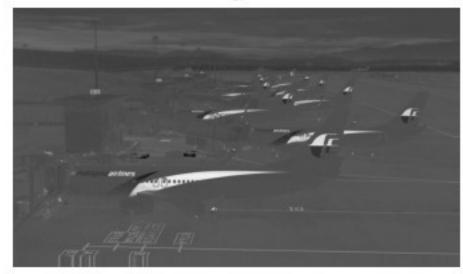
R [8:16, 8:16]

[[209 212 210 208 208 210 210 207] [209 210 210 208 208 210 210 208] [209 211 211 210 210 211 212 210] [210 212 212 212 212 215 215 213] [212 213 213 215 215 216 216 216] [216 214 216 217 217 217 217 217] [219 218 218 221 221 218 218 218] [223 220 220 223 223 219 219 219]]

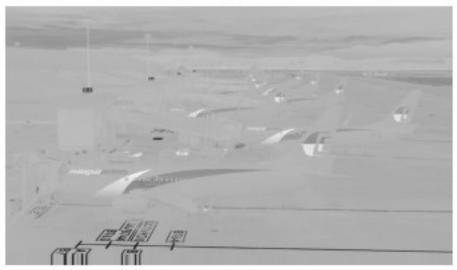








Cb



Y [8:16, 8:16]

[[222.758 223.068 223.057 223.046 223.046 223.057 223.057 222.046]
[222.758 223.057 223.057 223.046 223.046 223.057 223.057 223.046]
[222.758 224.057 224.057 223.758 223.758 224.057 225.057 223.758]
[224.117 224.829 224.829 224.829 224.829 225.84 225.84 226.057]
[224.829 225.829 225.829 225.84 225.84 226.84 226.84]
[227.313 226.715 227.313 227.025 227.025 228.313 228.313 227.025]
[228.797 229.085 229.085 229.395 229.036 229.313 229.313 228.025]
[231.395 231.085 231.085 230.107 230.107 230.085 230.085 228.797]]

Cb[8:16, 8:16]

[[136.037 135.862 135.869 135.875 135.875 135.869 135.869 135.875]
[136.037 135.869 135.869 135.875 135.875 135.869 135.869 135.875]
[136.037 135.869 135.869 136.037 136.037 135.869 135.869 136.037]
[134.706 134.869 134.869 134.869 134.862 134.862 134.862 135.869]
[134.869 134.869 134.869 134.862 134.862 134.862 134.862]
[134.031 134.369 134.031 134.194 134.194 134.031 134.031 134.194]
[133.194 133.031 133.031 132.856 134.187 134.031 134.031 134.194]
[132.856 133.031 133.031 133.019 133.019 133.031 133.031 133.194]]

Y downsampling 4:2:2



Cb downsampling 4:2:2

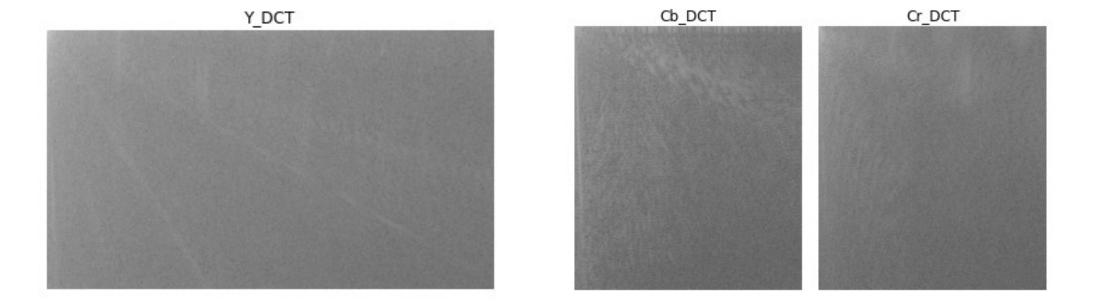


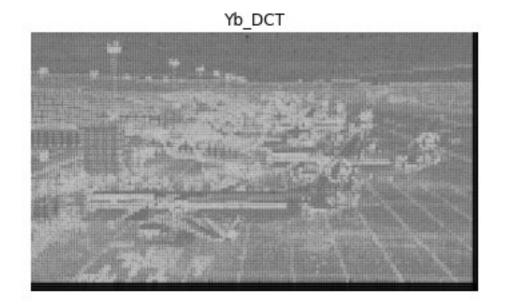
Cr downsampling 4:2:2

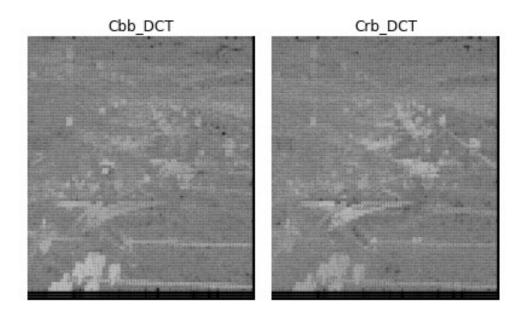


Cb [8:16, 8:16]

[[136.037 135.862 135.869 135.875 135.875 135.869 135.869 135.875]
[136.037 135.869 135.869 135.875 135.875 135.869 135.869 135.875]
[136.037 135.869 135.869 136.037 136.037 135.869 135.869 136.037]
[134.706 134.869 134.869 134.869 134.862 134.862 134.862 135.869]
[134.869 134.869 134.869 134.862 134.862 134.862 134.862]
[134.031 134.369 134.031 134.194 134.194 134.031 134.031 134.194]
[133.194 133.031 133.031 132.856 134.187 134.031 134.031 134.194]
[132.856 133.031 133.031 133.019 133.019 133.031 133.031 133.194]

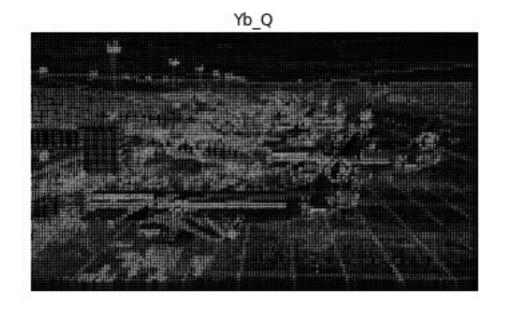


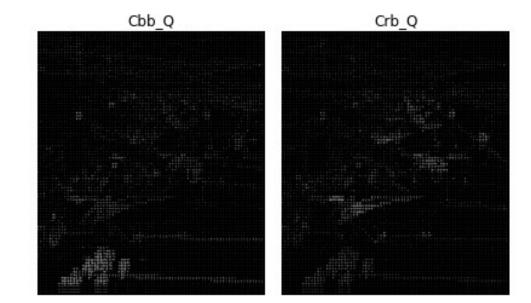




Yb_DCT8x8 [8:16, 8:16]

[[1.80777663e+03 -9.23242261e-01 -5.29636497e-01 3.59445648e-01 -1.76362500e+00 5.55083588e-01 -2.98406749e-01 -4.60890519e-02] [-2.03673479e+01 -9.82171542e-01 -8.86593039e-02 -5.92479366e-01 2.05786124e-01 -4.40442200e-01 -2.79880553e-01 -8.09695807e-02] [3.01421591e+00 2.96358656e+00 -5.05785655e-01 5.32572109e-01 2.78262642e-01 2.64984553e-01 -1.70624815e-01 4.42421783e-01] [-1.55397910e+00 -5.90294119e-01 -2.27573528e-01 4.87826728e-01 1.58910590e-01 2.61243202e-01 3.27367962e-01 -2.07981922e-01] [1.15787500e+00 2.03021506e-01 2.68178989e-01 -1.23757464e-01 7.06250000e-02 -4.00909176e-01 1.85897985e-01 -9.99756393e-02] [3.91716121e-01 -2.49542185e-01 -3.88121070e-01 8.46698258e-02 -1.12999755e-01 1.77816633e-01 -2.46778824e-01 -1.26352968e-01] [1.25161893e-01 2.41893572e-01 1.28375185e-01 3.35478925e-01 -5.71082576e-01 4.37425155e-01 -4.84643446e-02 3.97998520e-01] [-1.29250561e-01 -1.08042957e-01 -4.65970112e-01 -3.52498952e-01 -3.18990577e-01 -1.04955260e-01 -5.53132343e-01 -1.24718188e-02]]





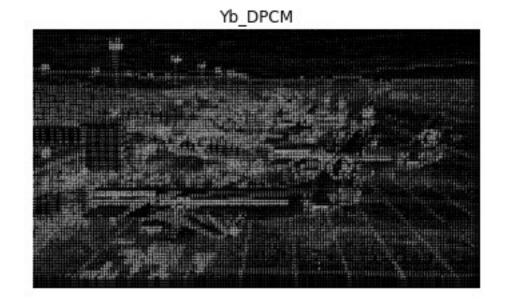
QY

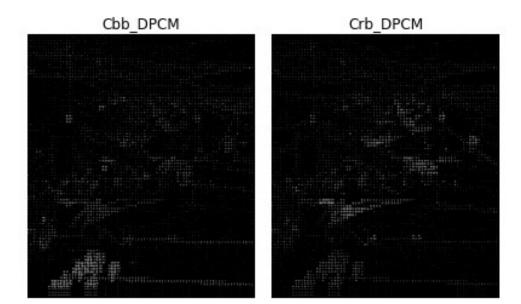
[[8 6 5 8 12 20 26 30] [6 6 7 10 13 29 30 28] [7 6 8 12 20 28 34 28] [7 8 11 14 26 44 40 31] [9 11 18 28 34 54 52 38] [12 18 28 32 40 52 56 46]

[9 11 18 28 34 54 52 38] [12 18 28 32 40 52 56 46] [24 32 39 44 52 60 60 50] [36 46 48 49 56 50 52 50]]

Yb_Q [8:16, 8:16]

 $\begin{bmatrix} \begin{bmatrix} 226 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \end{bmatrix} \\ \begin{bmatrix} -3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

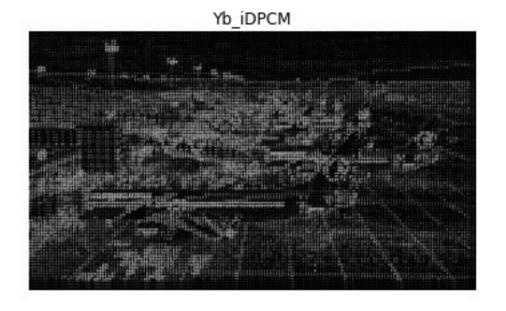


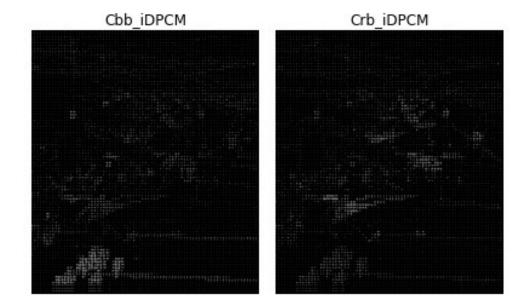


Yb_DPCM [8:16, 8:16]

[[0	0	0	0	0	0	0	0]
[-3	0	0	0	0	0	0	0]
[0	0	0	0	0	0	0	0]
[0	0	0	0	0	0	0	0]
[0	0	0	0	0	0	0	0]
[0	0	0	0	0	0	0	0]
[0	0	0	0	0	0	0	0]
Γ	0	0	0	0	0	0	0	01

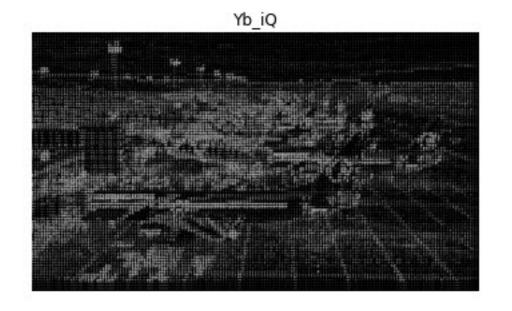
Decoder

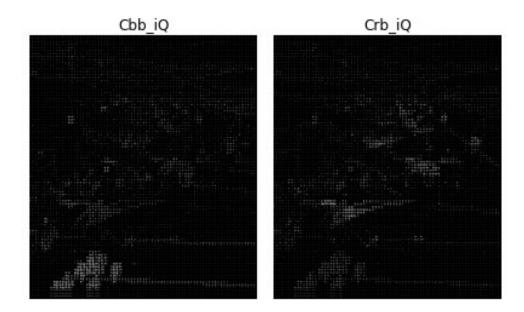




Yb_iDPCM [8:16, 8:16]

 $\begin{bmatrix} [226 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ [-3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

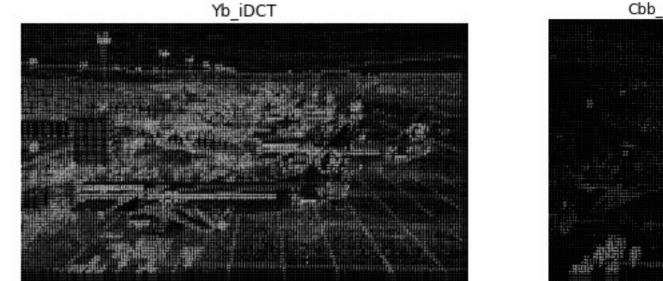


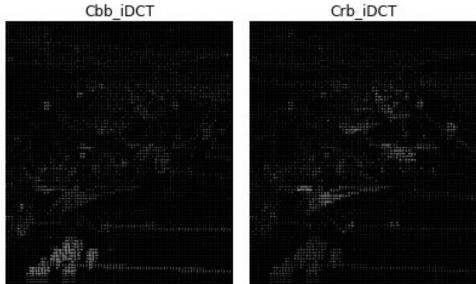


QY

[[8 6 5 8 12 20 26 30] [6 6 7 10 13 29 30 28] [7 6 8 12 20 28 34 28] [7 8 11 14 26 44 40 31] [9 11 18 28 34 54 52 38] [12 18 28 32 40 52 56 46] [24 32 39 44 52 60 60 50] [36 46 48 49 56 50 52 50]] Yb_iQ [8:16, 8:16]

[[1808. 0. 0. 0. 0. 0. 0. 0. 0. 0.]
[-18. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0.]





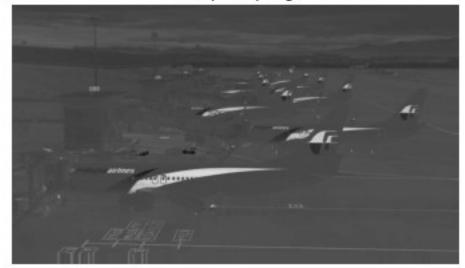
Yb_iDCT8x8 [8:16, 8:16]

[[222.87916035 223.35427989 223.3542798 223.35427989 223.3542798 223.3

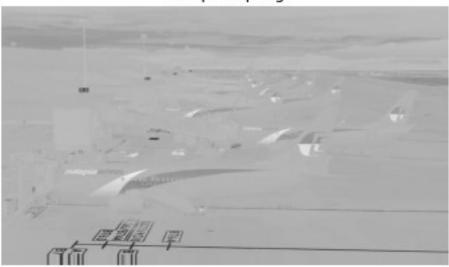
Y upsampling



Cr upsampling



Cb upsampling



Cb_UP [8:16, 8:16]

[136.56 136.56 136.56 136.56 136.56 136.56 136.56 136.56] [136.323 136.323 136.323 136.323 136.323 136.323 136.323 136.323] [135.884 135.884 135.884 135.884 135.884 135.884 135.884 135.884] [135.31 135.31 135.31 135.31 135.31 135.31 135.31 135.31] [134.69 134.69 134.69 134.69 134.69 134.69 134.69] [134.116 134.116 134.116 134.116 134.116 134.116 134.116] [133.677 133.677 133.677 133.677 133.677 133.677 133.44 133.44 133.44 133.44]]

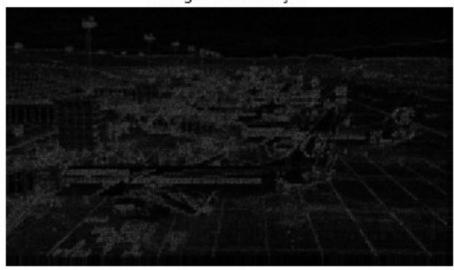
Img Reconstr



R_decoded [8:16, 8:16]

[[209 209 209 209 209 209 209 209]
[210 210 210 210 210 210 210 210 210]
[212 212 212 212 212 212 212 212 211]
[214 214 214 214 214 214 214 214 213]
[216 216 216 216 216 216 216 216 215]
[218 218 218 218 218 218 218 218 217]
[219 219 219 219 219 219 219 219 219]
[220 220 220 220 220 220 220 220]

Imagem diferenças



Erros na imagem de 3 canais reconstruída:

MSE = 91.10299012345679 RMSE = 9.544788636918934 SNR = 30.055578935200067 PSNR = 28.53547729528211

Erros

Erros no canal Y:

Max diff: 42.59069819768291 Avg diff: 2.6200078911493367