# Topic 1: Course Introduction, Math Review, and Software

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#### **Course Overview**

INSTRUCTOR XIE Tian

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xietian001@hotmail.com

LOCATION Online via ZOOM

(ZOOM info will be posted regularly)

CLASS HOUR Monday 7:00pm to 10:00pm

(ten minutes break between each hour)

#### **Course Contents**

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- ▶ We gonna use GitHub instead!!
- The link for this course is:

github.com/xietian001/SMU.ML.Course

- All the course related contents (outline, schedule, homework, codes, data, video, etc.) are available via the above link.
- You don't need to register. Just download the files.
- Contents are updated on a weekly basis.
- GitHub is a vastly popular website for codes sharing and project collaborating. Checkout github.com for further details.

# **Purposes of Our Course**

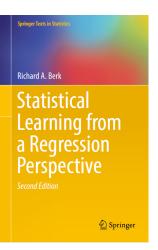
- Know the basics of the machine learning (ML) theory and practice of ML algorithms.
- ► Carry out simple empirical exercises using classic ML methods.
- Summarize and interpret ML results.
- Discuss the differences between alternative methods commonly used in ML projects.

#### **Assessment Method**

- ► Assignments (40%)
  - ▶ There will be two assignments handing out.
  - You are allowed to work in a group of no more than 5 (including 5) students and submit one copy of your assignments.
  - ▶ Of course, you can work the assignment just by yourself.
  - You need send the electronic version of your assignments to tianxie@smu.edu.sg.
  - You must state all the group members' names clearly on the cover page.
  - You must include the program codes in the assignment.
  - ▶ You can switch groups between the assignments.
- ► Class Performance (10%)
- ► Final exam (50%)

#### Recommended Textbook

- Statistical Learning from a Regression Perspective (2nd Edition) by Richard A. Berk.
- ► ISBN-13: 978-3319440477
- ► ISBN-10: 3319440470

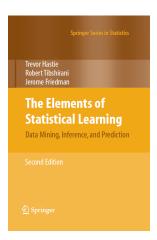


# **Supplementary Textbook**

► The Elements of Statistical Learning (2nd Edition) by Trevor Hastie, Robert Tibshirani, and Jerome Friedman

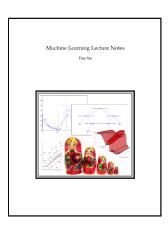
► ISBN-13: 978-0387848570

► ISBN-10: 0387848576



#### **Supplementary Lecture Notes**

- I also uploaded my own lecture notes for you guys.
- Machine Learning Lecture Notes by Tian Xie.
- For those who don't want have a copy of the textbook, you can read my lecture notes instead.
- ► The course slides are abstracted from the notes.
- We will test contents from the slides only.
- ► Slides <- My Notes <- Textbook



#### **Contents**

- ► Splines and Smoothing
- Classification and Regression Trees
- Bootstrap and Bagging Tree
- Random Forest
- Boosting Tree
- Support Vector Machine

# **Machine Learning Concept**

#### A Conventional Introduction

- Machine learning (ML) is the scientific study of algorithms and statistical models that computer systems use to perform a specific task without using explicit instructions, relying on patterns and inference instead.
- It is seen as a subset of artificial intelligence.
- ► The learning process can be categorized as supervised learning and unsupervised learning.
  - What is the difference?

# Supervised and or Unsupervised?

▶ In a typical econometric analysis, we have a pair of **X** and **y**. For example,

$$y = X\beta + \epsilon$$

#### where

- X can be called the regressors, input variables, input variables, independent variables, or features.
- y can be called the regressand, output variable, dependent variable, or response.
- $\triangleright$   $\beta$  is the coefficient vector, and  $\epsilon$  is the error term.
- Supervised learning means, you have both features and the response.
  - You have input and output. You can a goal to help you decide/evaluate.
- Unsupervised learning means, you only have features.
  - You only have X.
  - You try to learn the pattern lurking inside of a data set.
- Most of the economic problems we study require supervised learning.

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  - forecast stock price using capitalization, liquidity, age of CEO...
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  - Which problem is more frequently encountered in economics?
  - Regression analysis is more popular in economics and finance.

# Nonlinearity and Flexiblility

- Huge hype about machine learning in Economics and Finance now.
- Many people apply fancy ML algorithms to economic problem brutally without even knowing the reason and logic.
- Remember that we are studying Economics and Finance. There has to be some motivation.
- Of course, every data is unique. However, Economics and Finance data do have universal patterns.
  - For example, stocks prices are very hard to forecast, but stock volatilities are easy to predict.
  - lt is common that certain algorithms have better performance than others.

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  - ▶ It is common that certain algorithms have better performance than others.
- Many ML algorithms are nonlinear and flexible. They break the barriers of linearity and parametric formulation.
  - ▶ That is why they have good performance.
  - But say the data is super linear, a nonlinear algorithm shouldn't have a huge advantage.

# **Coding**

# The Role of Coding

- ► Coding is very **important** in studying ML.
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- Coding is very important in studying ML.
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- But our course is not called "ML in R or ML in MATLAB".
  - ▶ The primary concern of the course is not coding.
  - We will NOT test your coding skills in the final.
- Learning ML without coding is like learning swimming without getting wet.
- ▶ Following the Dean's "suggestion", we mainly use R in this course to demonstrate coding and estimation, therefore, you are recommended to follow our choice of software.
  - You are free to use whatever software you like, for example, Eviews, Stata, Matlab, R, Python, Java, C, C++, or even MS Excel, as long as you can deliver qualified course work.

# R and RStuido - The Old-school Way

- ▶ To use R, you need to the R source files first.
  - ▶ You can obtain the files from https://www.r-project.org/.
  - It has many different versions that can generate various instability/incompatibility problems.
  - Have fun!
- Then, you need a good R composer with nice UI. The most popular one is RStudio.
  - You can obtain the free open source version from https://rstudio.com/products/rstudio/download/
- ▶ They are free and small size (less than 300M in total).
- You can install them in your own computer or in a flashdrive.
  - For flashdrive installation, you can plug-in and use immediately.
- But we are not gonna do any of the above in this course.

#### RStudio Cloud

- ▶ In this course, you are highly recommend to use the **RStudio Cloud** to learn R syntax, practice exercises, and do homeworks.
  - Visit the link:

#### rstudio.cloud

- Register a free account and start coding!
- Cloud computing has lots of merits:
  - No installation needed! Simply open a browser and stay online!
  - No instability or incompatibility.
  - The cloud records every steps of your coding process, so you never lose your codes, data, etc.
- Perhaps, the only drawback of cloud computing is that you have to stay online.

#### **Console Window**

- In the Console window, R responses to any input immediately, like a calculator. Try
  - > 1+1 [1] 2

Notice that R immediately responses to your input and [1] implies the results are listed in the first row.

- ▶ R didn't record the result, since you didn't assign a variable. You can assign a variable to complicate calculation for re-use purpose. Try
  - > x = 1+1

Checkout the **Environment window**. You may notice a variable x with value 2.

► (?)Try y <- 1+1. What is the difference between = and <-?

#### **Functions**

- R can do way more than calculators. Try rnorm(3).
  - > rnorm(3)
    [1] 2.2461109 0.6867319 -0.7039494
- ▶ I am sure your results are different than mine. (?)Do you know why?
- To fully understand this command, its meaning, function, syntax, etc. Use help(rnorm) or simply type ?rnorm.
- Its information is presented in the help window. Try to digest its meaning.
- (?) Generate 20 random results from N(10, 25).
- If your Console is messy, try Ctrl+L to clean the window.

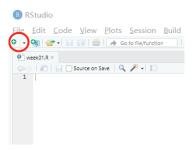
#### **Exercise**

- 1. Let us generate 10 random variables from standard normal distribution and compute their **mean** and **variance**.
  - \* Note that you may need the functions: mean, var.
- Let us generate 100 random variables from standard normal distribution and compute their mean and variance.
- 3. Let us generate 10000 random variables from standard normal distribution and compute their **mean** and **variance**.

Notice any pattern?

### **Script Files**

- Using the Console window to execute commands is rather inefficient.
- Like many other programmable software, we can use create a script file that consists of multiple lines of command and execute them in sequence.
- Click this icon to create an empty script and save this file in a designated location with proper file name.



We can write the following lines to the script.

```
# Mean and Variance of normal RVs
x1 = rnorm(10)
x2 = rnorm(1000)
x3 = rnorm(10000)
m1 = mean(x1)
m2 = mean(x2)
m3 = mean(x3)
v1 = var(x1)
v2 = var(x2)
v3 = var(x3)
```

- Select the lines you want to execute and click Run or use Ctrl+Enter.
   You should notice the new results in the Environment Window.
- ▶ You can use # to add comments. Contents after # are not executed.

#### Loops

- Now let us consider the following exercise: generate 100, 200, 300, ..., 100000 random variables from N(1, 1.5) and compute their means and variances.
- ▶ If you manually type up 100, 200, 300, ..., 100000, it will take forever to complete.
- Command for can repeat a pre-defined process multiple times. We usually refer this procedure as loops. The syntax of for is

```
code
}
where indicator can be any parameters, i, j, ...
sequence represents a sequence of data
code can any estimating function you design
```

for (indicator in sequence){

► Here is a demo code:

```
# use loop to obtain mean and variance
MEAN = 0;
VAR = 1;
n = seq(100,100000,by=100);
for (i in 1:length(n)){
    x = rnorm(n[i],mean=1,sd=sqrt(1.5))
    MEAN[i] = mean(x)
    VAR[i] = var(x)
}
```

## **Figures**

▶ It is more intuitive to plot variables MEAN and VAR in figures.

Or you can plot both lines in the same figure.

#### **Exercise**

- ▶ Plot the PDF of N(0,1).
- ▶ Plot the PDF of  $t_2^2$ .
- ▶ Plot the CDF of t<sub>25</sub>.
- ▶ Merge all three plots in one figure.
- You may need the command dnorm, dt, pt.

#### **Answers**

#### **Import Data**

- In practice, it is quite common to performance analysis on given data set.
- ▶ Here we use the movie.csv data file to demonstrate.
  - First, you need to download the data movie.csv from github.com/xietian001/SMU.ML.Course.
  - ► Then, you need to upload the data to the cloud.
  - ► This data consists of 94 movies with their open box office and related variables. (?) What do you think determine a movie's sales?
- We can use read.csv command to import the data. We need tell R the exact location of the file.

```
# import movie data
LOC = "/cloud/project/movie.csv"
dat = read.csv(LOC,header=TRUE)
summary(dat)
```

- (?) What is the functionality of summary()?
- The variable dat is a stored in a list format.
  - Click the dat to see its contents
  - ▶ To access each element, for example, OpenBox, you can use dat\$OpenBox.

#### **Exercise**

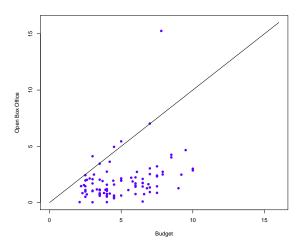
► Plot open box office against budgets and add a 45° line. What can you conclude?

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▶ Plot open box office against budgets and add a 45° line. What can you conclude?

# **Movie Plot**

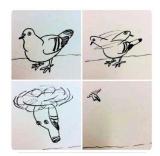
▶ Here is the plot using movie data.



### How to Code?

- ► There is **no simple** answer.
- Remember, you are not professional programmer.
- You (probably) will not code for a living.

Figure: Here is my expectation



# **Math Review**

## Linear algebra

- We denote the set of all n-tuples of real numbers by ℝ<sup>n</sup>. The set of n-tuples of nonnegative real numbers is denoted by ℝ<sup>n</sup><sub>n</sub>.
- ▶ The elements of these sets will be referred to as points or **vectors**.
- ▶ If  $x = (x_1, ..., x_n)$  is a vector, we denote then its  $i^{th}$  component is  $x_i$ .
- We can add two vectors by adding their components:  $x + y = (x_1 + y_1, ..., x_n + y_n)$ .
- We can perform scalar multiplication on a vector by multiplying every component by a fixed real number t:  $tx = (tx_1, ..., tx_n)$ .

- A vector x is a linear combination of a set of n vectors A if  $x = \sum_{i=1}^{n} t_i y_i$ , where  $y_i \in A$  and the  $t_i$ 's are scalars.
- A set A of n vectors is linearly independent if there is no set  $(t_i, x_i)$ , with some  $t_i \neq 0$  and  $x_i \in A$ , such that  $\sum_{i=1}^{n} t_i x_i = 0$ .
- An equivalent definition is that no vector in A can be represented as a linear combination of vectors in A.
- ▶ Given two vectors their **inner product** is given by  $xy = \sum_i x_i y_i$ . The norm of a vector x is denoted by |x| and defined by  $|x| = \sqrt{xx}$ .
- ▶ Note that by the Pythagorean theorem, the norm of x is the distance of the point x from the origin; that is, it is the length of the vector x.
- If xy = 0, then x and y are said to be orthogonal.

- Let  $\theta$  be the angle between x and y. It is clear  $t|x| = |y|cos\theta$ . Moreover,  $xy = |x||y|cos\theta$ .
- ▶ We can consider maps from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  that send vectors into vectors. We denote such maps by  $f: \mathbb{R}^n \to \mathbb{R}^m$ .
- A map is a linear function if f(tx + sy) = tf(x) + sf(y) for all scalars s and t and vectors x and y.
- ▶ If f is a linear function to  $\mathbb{R}^1$ , we call it a linear functional. If p is a linear functional we can represent it by a vector  $p = (p_1, ..., p_n)$ , and write p(x) = px.
- A set of points of form  $H(p, a) = \{x : px = a\}$  is called a hyperplane.

#### **Definite and semidefinite matrices**

▶ Let A be a symmetric square matrix. Then if we post-multiply A by some vector x and pre-multiply it by the **transpose of the** same vector x, we have a quadratic form.

$$(x_1 \quad x_2)$$
 $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = a_{11}x_1^2 + (a_{21} + a_{12})x_1x_2 + a_{22}x_2^2.$ 

- Suppose that A is the identity matrix. In this case it is not hard to see that whatever the values of x<sub>1</sub> and x<sub>2</sub>, the quadratic form must be nonnegative.
- ▶ In fact, if  $x_1$  and  $x_2$  are not both zero,  $xAx^{\top}$  will be strictly positive. The identity matrix is an example of a positive definite matrix.

- **Definite matrices**. A square matrix *A* is:
  - (a) positive definite if  $x^{\top}Ax > 0$  for all  $x \neq 0$ ;
  - (b) negative definite if  $x^{\top}Ax < 0$  for all  $x \neq 0$ ;
  - (c) positive semidefinite if  $x^{\top}Ax \ge 0$  for all x;
  - (d) negative semidefinite if  $x^{\top}Ax \leq 0$  for all x.
- We say A is positive definite subject to constraint bx = 0 if  $x^{\top}Ax > 0$  for all  $x \neq 0$  such that bx = 0. The other definitions extend to the constrained case in a natural manner.

- If a matrix is positive semidefinite, then it must have nonnegative diagonal terms.
- ▶ The minor matrices of a matrix A are the matrices formed by eliminating k columns and the same numbered k rows. The naturally ordered or nested principal minor matrices of A are the minor matrices given by

$$a_{11} \quad \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

► The minor determinants or minors of a matrix are the determinants of the minors. We denote the determinant of a matrix A by det A or |A|.

#### Cramer's rule

 Here is a convenient rule for solving linear systems of equations of the form

$$\left(\begin{array}{ccc} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{array}\right) \left(\begin{array}{c} x_1 \\ \vdots \\ x_n \end{array}\right) = \left(\begin{array}{c} b_1 \\ \vdots \\ b_n \end{array}\right)$$

We can write his system more conveniently as Ax = b.

▶ Cramer's rule. To find the component  $x_i$  of the solution vector to this system of linear equations, replace the  $i^{th}$  column of the matrix A with the column vector b to form a matrix  $A_i$ . Then  $x_i$  is the determinant of  $A_i$ , divided by the determinant of A:

$$x_i = \frac{|A_i|}{|A|}.$$

#### **Calculus**

▶ Given a function  $f : \mathbb{R} \to \mathbb{R}$ , we define its derivative at a point  $x^*$  by

$$\frac{df(x^*)}{dx} = \lim_{t \to 0} \frac{f(x^* + t) - f(x^*)}{t}$$

if that limit exists.

- ▶ The derivative  $df(x^*)/dx$  is also denoted by  $f'(x^*)$ . If the derivative of f exists at  $x^*$ , we say that f is **differentiable** at  $x^*$ .
- ▶ Consider the linear function F(t) defined by

$$F(t) = f(x^*) + f'(x^*)t.$$

This is a good approximation to f near  $x^*$  since

$$\lim_{t\to 0} \frac{f(x^*+t)-F(t)}{t} = \lim_{t\to 0} \frac{f(x^*+t)-f(x^*)-f'(x^*)t}{t} = 0.$$

▶ In the same way, given an arbitrary function  $f: \mathbb{R}^n \to \mathbb{R}^m$ , we can define its derivative at  $x^*$ ,  $D_f(x^*)$ , as being that linear map from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  that approximates f close to  $x^*$  in the sense that

$$\lim_{|t| \to 0} \frac{|f(x^* + t) - f(x^*) - D_f(x^*)t|}{|t|} = 0.$$

We use norm signs since both the numerator and denominator are vectors. The map  $f(x^*) + D_f(x^*)$  is a good approximation to f at  $x^*$  in the sense that for small vectors t,

$$f(x^*+t)\approx f(x^*)+D_f(x^*)t.$$

- ▶ Given a function  $f : \mathbb{R}^n \to \mathbb{R}$ , we can also define the partial derivatives of f with respect to  $x_i$  evaluated at  $x^*$ .
- ▶ To do this, we hold all components fixed except for the i<sup>th</sup> component, so that f is only a function of x<sub>i</sub>, and calculate the ordinary one-dimensional derivative.
- ▶ We denote the partial derivative of f with respect to  $x_i$  evaluated at  $x^*$  by  $\partial f(x^*)/\partial x_i$ .
- Since  $D_f(x^*)$  is a linear transformation, we can represent it by a matrix, which turns out to be

$$D_f(x^*) = \begin{pmatrix} \frac{\partial f_1(x^*)}{\partial x_1} & \cdots & \frac{\partial f_1(x^*)}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_m(x^*)}{\partial x_1} & \cdots & \frac{\partial f_m(x^*)}{\partial x_n} \end{pmatrix}.$$

The matrix representing  $D_f(x)$  is called the **Jacobian matrix** of f at  $x^*$ . We will often work with functions from  $\mathbb{R}^n$  to  $\mathbb{R}$  in which case  $D_f(x^*)$  will be an n-by-1 matrix, which is simply a vector.

# **Higher-order derivatives**

▶ If we have a function  $f: \mathbb{R}^n \to \mathbb{R}$ , the Hessian matrix of that function is the matrix of mixed partial derivatives

$$D^2f(x)=\frac{\partial^2f(x)}{\partial x_i\partial x_j}.$$

Note that  $D^2 f(x)$  is a symmetric matrix.

▶ Let  $f: \mathbb{R}^n \to \mathbb{R}$  be a differentiable function and let x and y be two vectors in  $\mathbb{R}^n$ . Then it can be shown that

$$f(y) = f(x) + D_f(z)(y - x)$$
  

$$f(y) = f(x) + D_f(x)(y - x) + \frac{1}{2}(y - x)^{\top}D^2f(w)(y - x).$$

where z and w are points on the line segment between x and y. These expressions are called **Taylor series expansions** of f at x.

▶ If x and y are close together and the derivative functions are continuous, then Df(z) and  $D^2f(w)$  are approximately equal to Df(x) and  $D^2f(x)$ , respectively. We therefore often write the Taylor series expansions as

$$\begin{split} f(y) &= f(x) + D_f(x)(y-x) \\ f(y) &= f(x) + D_f(x)(y-x) + \frac{1}{2}(y-x)^\top D^2 f(x)(y-x). \end{split}$$

# **Analysis**

- ▶ Given a vector x in  $\mathbb{R}^n$  and a positive real number e, we define an open ball of radius e at x as  $B_e(x) = \{y \in \mathbb{R}^n : |y x| < e\}$ .
- ▶ A set of points A is a **open set** if for every x in A there is some  $B_e(x)$  which is contained in A.
- If x is in an arbitrary set and there exists an e > 0 such that B<sub>e</sub>(x) is in A, then x is said to be in the interior of A.
- ▶ The complement of a set A in  $\mathbb{R}^n$  consists of all the points in  $\mathbb{R}^n$  that are not in A; it is denoted by  $\mathbb{R}^n \setminus A$ .
- A set is a closed set if R<sup>n</sup>\A is an open set. A set A is bounded if there is some x in A and some e > 0 such that A is contained in B<sub>e</sub>(x). If a nonempty set in R<sup>n</sup> is both closed and bounded, it is called compact.
- A infinite sequence in  $\mathbb{R}^n$ ,  $(x^i) = (x^1, x^2, ...)$  is just an infinite set of points, one point for each positive integer.

- A sequence  $(x^i)$  is said to converge to a point  $x^*$  if for every e > 0, there is an integer m such that, for all i > m,  $x^i$  is in  $B_e(x^*)$ . We sometimes say that  $x^i$  gets arbitrarily close to  $x^*$ . We also say that  $x^*$  is the **limit** of the sequence  $(x^i)$  and write  $\lim_{i \to \infty} x^i = x^*$ . If a sequence converges to a point, we call it a **convergent sequence**.
- ▶ Closed set. A is a closed set if every convergent sequence in A converges to a point in A.
- Compact set. If A is a compact set, then every sequence in A has a convergent subsequence.
- A function f(x) is continuous at  $x^*$  if for every sequence  $(x^i)$  that converges to  $x^*$ , we have the sequence  $(f(x^i))$  converging to  $f(x^*)$ . A function that is continuous at every point in its domain is called a **continuous function**.

# Random Variables and Probability Distributions

- Random variables. A random variable is a numerical summary of a random outcome.
  - Discrete random variable: takes on only a discrete set of values (toss coins, roll dice,...). Countable output.
  - Continuous random variable takes on a continuum of possible values (stock return, GDP growth rate, ...). Non-countable output.
- The probability of an outcome is the proportion of the time that the outcome is expected to occur in the long run.
  - ▶ <sup>(?)</sup>Question: what is difference between probability and frequency?

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  - (?) Question: what is difference between probability and frequency?
    (?) or say, what is difference between 0% and never gonna happen?

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  - Continuous random variable takes on a continuum of possible values (stock return, GDP growth rate, ...). Non-countable output.
- The probability of an outcome is the proportion of the time that the outcome is expected to occur in the long run.
  - (?)Question: what is difference between probability and frequency? (?)or say, what is difference between 0% and never gonna happen? In probability space, they are 0 and Ø

- ▶ Probability distribution. The probability distribution of a discrete random variable is the list of all possible values of the variable and the probability that each value will occur. These probabilities sum to 1.
- ► The cumulative probability distribution is the probability that the random variable is less than or equal to a particular value.
  - It is also referred to as a cumulative distribution function (CDF).

Table: Probability of Donald Trump Tweeting X Times Per Day

	Number of Tweets						
	0	1	2	3	4	5	
Probability Distribution	0.1	0.2	0.2	0.3	0.1	0.1	
Cumulative Probability Distribution	0.1	0.3	0.5	8.0	0.9	1.0	

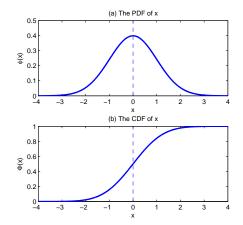
#### Bernoulli distribution

- A binary random variable is called a Bernoulli random variable, and its probability distribution is called the Bernoulli distribution.
- ▶ The outcome of a Bernoulli random variable can only take two values.
  - For example, 1 and 0, True and False, etc.
- For a Bernoulli random variable X with two outcomes 1 and 0, the probability distribution can be expressed as

$$f(X) = \begin{cases} 1 & \text{with probability } p \\ 0 & \text{with probability } (1-p) \end{cases}$$

#### **Continuous Random Variable**

- A continuous random variable can have infinite number of outcomes.
- It can be constrained within a certain range or unconstrained.
- ▶ A typical example is the standard **Gaussian** random variable with probability **density** function (PDF) and CDF shown below:



### Expectation

► The expectation of a random variable X measures its long-run average value. It is the sum of the any outcome times its respective probability.

$$\mathbb{E}(X) = \sum_{i=1}^{N} X_i \cdot p_i,$$

where  $X_i$  is one outcome and  $p_i$  is the associated probability.

Recall the Tweeting example:

	Number of Tweets						
	0	1	2	3	4	5	
Probability	0.1	0.2	0.2	0.3	0.1	0.1	

- (?) What is the expectation of Trump's tweets per day?
- ▶ If a is a constant,  $\mathbb{E}(aX) = a\mathbb{E}(X)$ .
- ▶ We also have  $\mathbb{E}(X + Y) = \mathbb{E}(X) + \mathbb{E}(Y)$  for any X and Y.

#### **Variance**

The variance measures the dispersion or the spread of a probability distribution:

$$\operatorname{Var}(X) = \mathbb{E}\left[\left(X - \mathbb{E}(X)\right)^2\right] = \sum_{i=1}^N \left(X_i - \mathbb{E}(X)\right)^2 \cdot p_i.$$

- (?)What is the variance of Trump's daily tweets?
- Standard deviation is simply the square-root of variance.
- ▶ If a and b are constant,  $Var(aX) = a^2 Var(X)$  and Var(X + b) = Var(X).
- (?)Skewness and Kurtosis.

#### Joint Distribution

- The joint probability distribution of multiple random variables is the probability that the random variables simultaneously take on certain values.
- Let us now think about the two sentimental stage of D. Trump and relate to his tweeting behavior.
- Assume Trump's sentiment follows a Bernoulli distribution with two outcomes: Rage and Calm.



Rage Vs. Calm?

# Marginal Distribution

Now, Trump's tweeting behavior is measured by two random variables

Table: Joint Distribution of Donald Trump's Tweeting and Sentiment

Sentiment		Number of Tweets					Total
	0	1	2	3	4	5	
Rage	0.1	0.15	0.1	0.2	0.05	0.1	0.7
Calm	0	0.05	0.1	0.1	0.05	0	0.3
Total	0.1	0.2	0.2	0.3	0.1	0.1	1.0

- Marginal probability distribution is the sum of individual probabilities associated with one specific outcome of a certain random variable.
  - For example, Pr(Rage) = 0.1 + 0.15 + ... + 0.1 = 0.7.

#### **Conditional Distribution**

- ▶ Conditional distribution is the distribution of a random variable Y conditional on another random variable X taking on a specific value, usually denoted as Pr(Y = y | X = x).
- ▶ The conditional probability can be estimated by

$$\Pr(X = x | Y = y) = \frac{\Pr(X = x, Y = y)}{\Pr(Y = y)}.$$

► Conditional Expectation and Conditional Variance are

$$\mathbb{E}(X|Y=y) = \sum_{i=1}^{N} X_i \cdot \Pr(X=X_i|Y=y),$$

$$\operatorname{Var}(X|Y=y) = \sum_{i=1}^{N} (X_i - \mathbb{E}(X|Y=y))^2 \cdot \Pr(X=X_i|Y=y),$$

### Independence, Covariance, and Correlation

- Two random variables X and Y are independent, if knowing the value of one of the variables provides no information about the other.
  - If X and Y are independent, for all values of x and y, we have Pr(Y = y|X = x) = Pr(Y = y).
- One measure of the extent to which two random variables move together is their covariance.
  - Specifically,  $Cov(X, Y) = \mathbb{E}[(X \mathbb{E}(X))(Y \mathbb{E}(Y))] = \mathbb{E}(XY) \mathbb{E}(X)\mathbb{E}(Y).$
- The correlation is an alternative measure of dependence between X and Y that follows unity.
  - Specifically,

$$\operatorname{Corr}(X, Y) = \frac{\operatorname{Cov}(X, Y)}{\sqrt{\operatorname{Var}(X) \cdot \operatorname{Var}(Y)}}$$

# Independence, Covariance, and Correlation

- Independence implies both Covariance and Correlation equal 0.
  - (?) vice versa?
  - ▶ Try to the Covariance of  $\mathbb{E}(X) = \mathbb{E}(X^3) = 0$ ,  $Y = X^2$ .
- We usually denote the variance as  $\sigma^2$ , for example  $\operatorname{Var}(X) = \sigma_X^2$ .
  - $ightharpoonup \operatorname{Cov}(X,Y) = \sigma_{XY}$
  - ▶ Standard Deviation of X is  $\sigma_X$
- $\operatorname{Var}(aX + bY) = a^2 \sigma_X^2 + b^2 \sigma_Y^2 + 2ab \cdot \sigma_{XY}.$
- ▶ By definition,  $|\operatorname{corr}(X, Y)| \leq 1$ .
- ▶ (?) If X and Y are independent, what is Var(X + Y)?