

Dynamic Learning

Neural Networks and Backpropagation

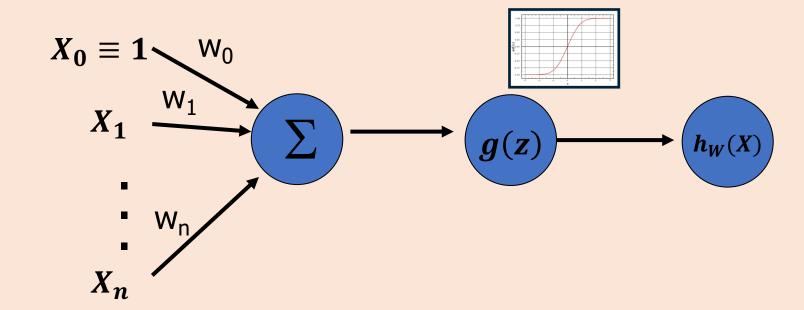
Plan for Class

- ☐ Perceptron Algorithm
 - Multi layered perceptron
- ☐ Regression
 - Linear
 - Logistic
- ☐ Gradient Descent
 - Batch Gradient Descent
 - Stochastic Gradient Descent
- ☐ Introduction to Neural Networks
 - Feedforward Neural Networks

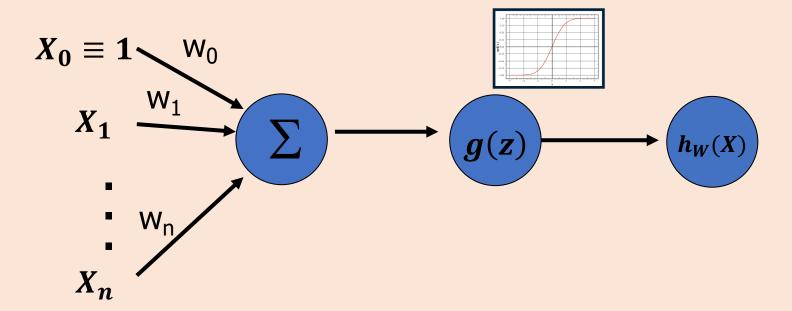
Logistic Regression

$$g(z) = \frac{1}{1 + e^{-z}}$$

$$h_w(x) = g(\sum w_i x_i) = g(W \cdot X)$$



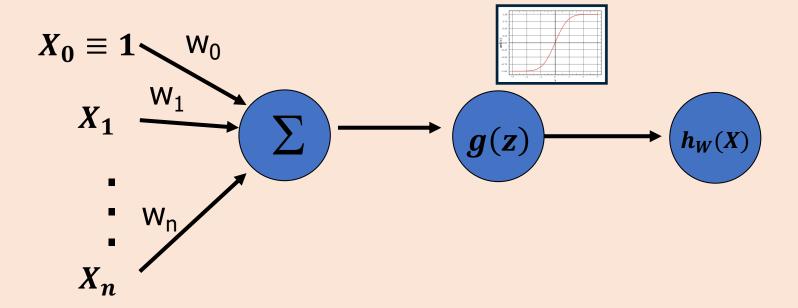
Input



Inputs To Neurons

- ☐ Arise from other neurons or from outside the network
- □ Nodes whose inputs arise outside the network are called *input nodes* and simply copy values
- An input may *excite* or *inhibit* the response of the neuron to which it is applied, depending upon the weight of the connection

Weights



Weights

- Represent synaptic efficacy and may be excitatory or inhibitory
- Normally, positive weights are considered as excitatory while negative weights are thought of as inhibitory
- **Learning** is the process of modifying the weights in order to produce a network that performs some function

Preparation

☐ Training Set

A collection of input-output patterns that are used to train the network

☐ Testing Set

A collection of input-output patterns that are used to assess network performance

 \Box Learning Rate- η

A scalar parameter, analogous to step size in numerical integration, used to set the rate of adjustments

Pseudo-Code Algorithm

- ☐ Randomly choose the initial weights
- ☐ While error is too large
 - For each training pattern (presented in random order)

Propagate

- Apply the inputs to the network
- Calculate the output for every neuron from the input layer, through the hidden layer(s), to the output layer
- Calculate the error at the outputs

Optimize

- Use the output error to compute error signals for pre-output layers
- Use the error signals to compute weight adjustments
- Apply the weight adjustments
- Periodically evaluate the network performance

Gradient Descent

Given a training set $(X_0, y_0), ... (X_k, y_k)$

Assume:

$$P(y_j = 1 | X_j, W) = h_W(X_j)^{y_j} (1 - h_W(X_j)^{1-y_j})$$

$$L(W) = \prod_{j} P(y_{j} = 1 | X_{j}, W) = \prod_{j} h_{W}(X_{j})^{y_{j}} (1 - h_{W}(X_{j})^{1 - y_{j}})$$

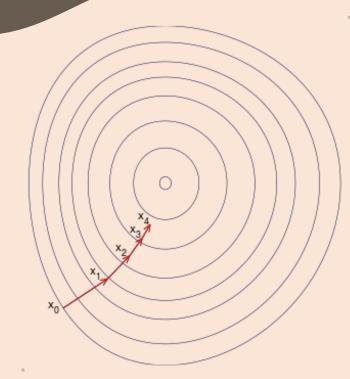
$$J(W) = \log L(W) = \sum_{j} y_{j} \log(h_{W}(X_{j}) + (1 - y_{j}) \log(1 - h_{W}(X_{j}))$$

$$\vdots \qquad \partial g$$

$$\frac{\partial J}{\partial w_i}(X) = (y - h_W(X_j)x_i$$
 using
$$\frac{\partial g}{\partial z} = g(z)(1 - g(z))$$

Gradient Descent

Given a training set $(X, y) \in (X_0, y_0), ...(X_k, y_k)$



$$W \leftarrow (w_{0,1}, ... w_{0,n})$$

for
$$(X, y)$$
 in $(X_0, y_0), ... (X_k, y_k)$:

$$h \leftarrow g(\sum w_i x_i)$$

$$w_i \leftarrow w_i + \eta \cdot \frac{\partial J}{\partial w_i}(X) = w_i + \eta \cdot x_i \cdot (y - h)$$

Propagate

```
In [13]: #Create a function that calculates the current SSE
         def propagate(w, b, X, Y):
             m = X.shape[1]
             A = sigmoid(np.dot(w.T,X)+b)
             cost = -1/m * np.sum(Y*np.log(A)+(1-Y)*np.log(1-A))
             dw = (1/m) * (np.dot(X, (A-Y).T))
             db = (1/m) * (np.sum(A-Y))
             cost = np.squeeze(cost)
             grads = {"dw": dw, "db": db}
             return grads, cost
```

Optimize

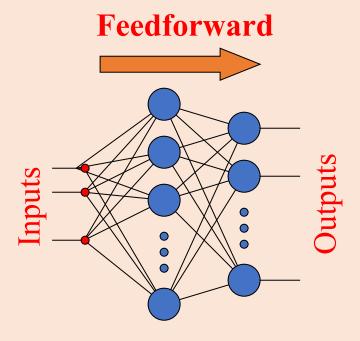
```
In [14]: #Create a function that moves the estimates around and calculates the SSE to find optimal w and b
         def optimize(w, b, X, Y, num iterations, learning rate, print cost = False):
             costs = []
             for i in range(num iterations):
                 grads, cost = propagate(w,b,X,Y)
                 dw = grads["dw"]
                 db = grads["db"]
                 w = w-learning rate*dw
                 b = b-learning_rate*db
                 if i % 100 == 0:
                     costs.append(cost)
                 if print_cost and i % 100 == 0:
                     print("Cost after iteration %i: %f" %(i, cost))
             params = {"w":w, "b":b}
             grads = {"dw":dw, "db":db}
             return params, grads, costs
```

Predict

```
-----Build the Logisitic Regression framework-----
In [15]: #---
         def predict(w, b, X):
            m = X.shape[1]
             Y_prediction = np.zeros((1,m))
            w = w.reshape(X.shape[0],1)
            A = sigmoid(np.dot(w.T,X)+b)
             for i in range(A.shape[1]):
                if A[0,i] \leftarrow 0.5:
                    Y prediction[0,i] = 0
                else:
                    Y_{prediction[0,i]} = 1
             return Y_prediction
```

Feedforward Neural Networks

- Apply the value of each input parameter to each input node
- Input nodes compute only the identity function



Feedforward Neural Networks

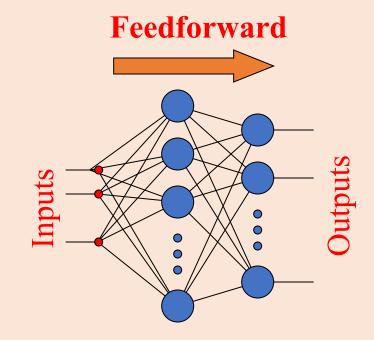
The output from neuron j for pattern p is O_{pj} where

$$O_{pj}(n_j) = g(-\lambda \cdot n_j)$$

and

$$n_j = bias \cdot W_{bias} + \sum_k O_{pk} \cdot W_{kj}$$

k ranges over the input indices and W_{jk} is the weight on the connection from input k to neuron j

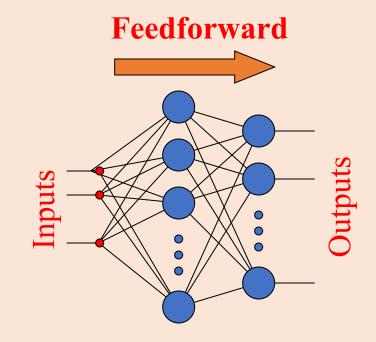


Error Signal For Each Output Neuron

• The output neuron error signal d_{pj} is given by

$$d_{pj} = (T_{pj} - O_{pj}) O_{pj} (1 - O_{pj})$$

- T_{pj} is the target value of output neuron j for pattern p
- O_{pj} is the actual output value of output neuron j for pattern p

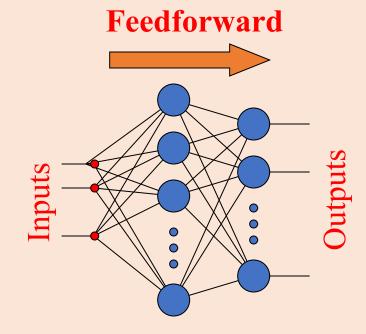


Error Signal For Each Output Neuron

• The hidden neuron error signal δ_{pj} is given by

$$\delta_{pj} = O_{pj}(1 - O_{pj}) \sum_{k} \delta_{pk} \cdot W_{kj}$$

• where δ_{pk} is the error signal of a post-synaptic neuron k and W_{kj} is the weight of the connection from hidden neuron j to the post-synaptic neuron k



Error Signal For Each Output Neuron

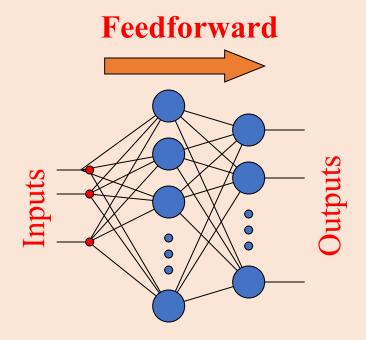
• Compute weight adjustments ΔW_{ji} at time t by

$$\Delta W_{ji}(t) = \eta \ \delta_{pj} \ O_{pi}$$

Apply weight adjustments according to

$$W_{ji}(t+1) = W_{ji}(t) + \Delta W_{ji}(t)$$

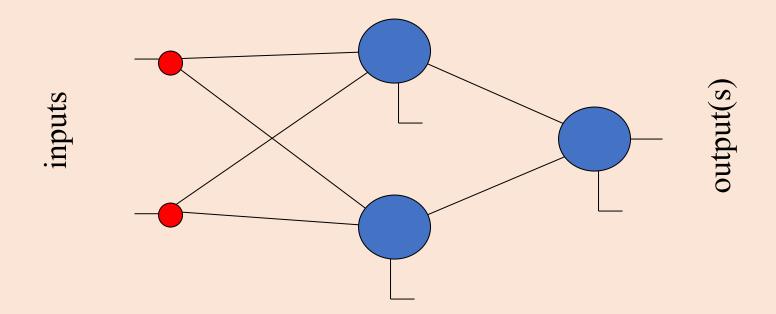
• Some add a momentum term $\alpha*\Delta W_{ii}(t-1)$



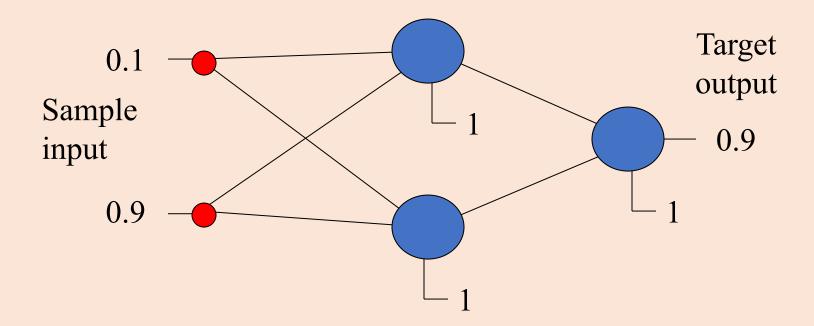
Example

- Training set
 - ((0.1, 0.1), 0.1)
 - ((0.1, 0.9), 0.9)
 - ((0.9, 0.1), 0.9)
 - ((0.9, 0.9), 0.1)
- Testing set
 - Use at least 121 pairs equally spaced on the unit square and plot the results
 - Omit the training set (if desired)

Example



Example



Feedforward Network Training by Backpropagation

- Select an architecture
- Randomly initialize weights
- While error is too large
 - Select training pattern and feedforward to find actual network output
 - Calculate errors and backpropagate error signals
 - Adjust weights
- Evaluate performance using the test set