Practical Deep Learning Workshop assignments 2

- 1) a.
 - i. The dataset is tabular data representing time-series measurements from wearable sensors. It contains acceleration data (x, y, z) collected for various activities performed by individuals. Each record corresponds to a specific activity, labeled for classification tasks, with metadata like the user ID, sensor type, body part, and side.
 - ii. The data is heterogeneous, varying in several ways:

Sensors: Data is recorded using 2 different sensor types (smartwatch and vicon).

Users: Data is collected from 8 distinct individuals, each contributing a varying number of samples (from 5571 to 7387).

Activities: The dataset includes 18 unique activities with varying frequencies, creating a class imbalance.

Sequence Length: The number of measurements per activity varies, introducing variability in the time-series data (3000, 3500 or 4000).

Body Part: The body part where the sensor was placed.

Side: The side of the body where the sensor was placed.

- iii. Each record is labeled with one of 18 activities, such as "walking," "stairs down," or "using phone." These labels represent the movement or action being performed during the recording session.
- iv. The activity distribution shows significant class imbalance. Activities like "using phone," "walking freely," and "walking holding a tray" are much more frequent, while others like "stairs down," "stairs up," and "brushing teeth" are underrepresented.

Treating all labels equally without addressing the imbalance might bias the model toward predicting the dominant classes. Techniques like over sampling, under sampling, or class weights should be applied during model training. One option is to sample from each combination of the data so no class will be underrepresented.

Certain activities might have more practical importance in real-world applications. For example:

"Stairs down" and "stairs up" could be critical for fall detection systems.

"Walking with hands in pockets" could be relevant for ergonomic or safety analysis.

v. In the data we have 8 users in the train section and 21 users in the test section. The competition data was split in the way that in the train we have 50,248 rows, and in the test 74,744 rows.

b.

This task is a **classification problem** where the goal is to predict the type of activity performed based on movement data.

We are not predicting future events or forecasting but rather classifying an activity based on sensor readings.

c.

Autoencoders:

Train an autoencoder to compress and reconstruct the data, learning meaningful representations in the process.

Anomaly Detection

Train the model to identify unusual patterns in the sensor data as anomalies. To do that we need to learn the typical structure of movement data.

2) a.

For our validation strategy, we allocated 20% of the data as the validation set, ensuring that samples were proportionally taken from all activity types and sensor categories to maintain a representative distribution. This approach guarantees that the model is evaluated in diverse scenarios, reflecting real-world variability. Additionally, we decided to build two separate models: one dedicated to processing data from the Vicon sensor and the other for the smartwatch sensor. This separation allows each model to specialize in the unique characteristics of its respective sensor data, maximizing performance and interpretability.

b. For a naive baseline we used:

most common label - Train accuracy: 0.08267431018406603 Validation accuracy: 0.08258403651957394

Last Observation Carried Forward -

Train accuracy: 0.06212660151258763 Validation accuracy: 0.06280260063632591

c. In this section we used random forest which predicted much better.

Validation Accuracy: 0.7985969014907922

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	brushing_teeth								0.83							101		
	idle							0.85			0.8		0.83			185		
preparing_sandwich							0.81				0.8	2				149		
	reading_book							0.89			0.8		0.88			174		
	stairs_down							0.90			0.90	3	0.90			80		
	stairs_up							0.88			0.8	5	0.87			87		
	typing							0.89			0.89	9 0.89			84			
	using phone							0.81			0.79 0.			.80 287				
using remote control							0.78				0.78 0.78			.78	173			
walking freely							0.74							.77 313				
walking holding a tray							0.84				0.86			0.85		298		
walking with handbag							0.76				0.79			0.78		303		
walking with hands in pockets								0.83			0.82			0.83		288		
walking with object underarm								0.79			0.7							
washing_face_and_hands								0.68			0.74				172			
washing mug								0.74			0.7				176			
washing plate								0.70			0.7					166		
writing							0.88				0.7		0.81			85		
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d. From here we decided to separate the two sensors and build a separate model for each sensor.

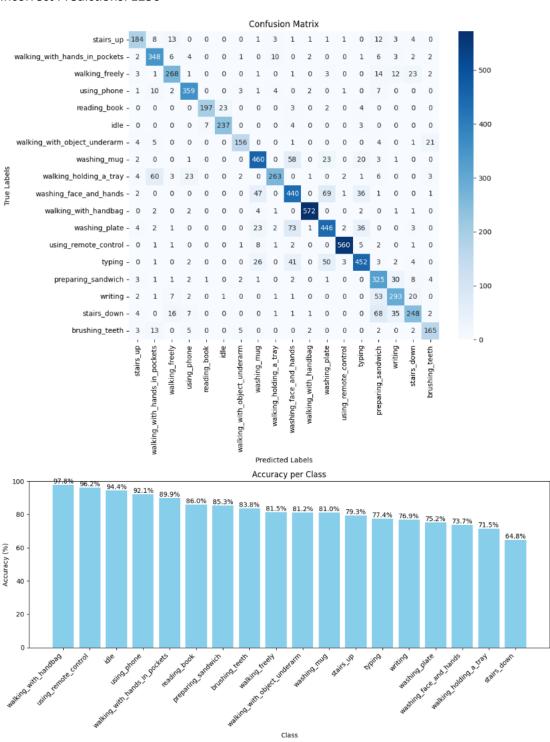
I. 1D-CNN

For Smart Watch:

Accuracy: 82.63%

Correct Predictions: 5973

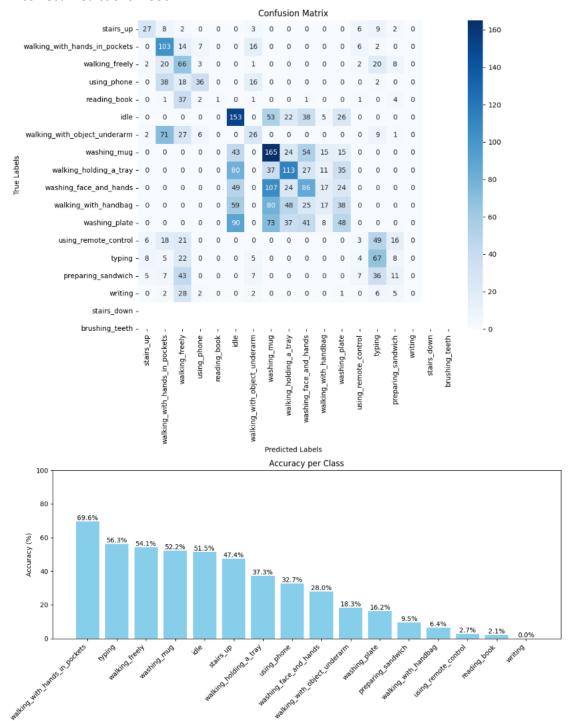
Incorrect Predictions: 1256



For Vicon:

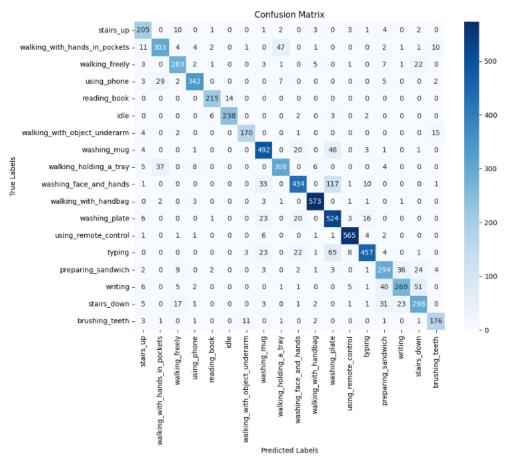
Accuracy: 32.83%

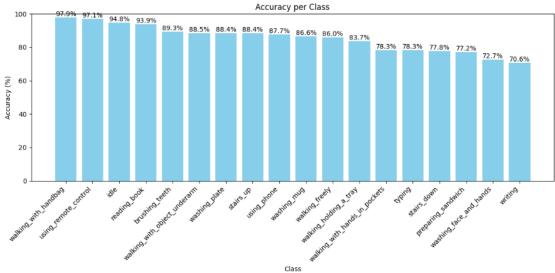
Correct Predictions: 922 Incorrect Predictions: 1886



2. LSTM: Smart Watch Accuracy: 85.02%

Correct Predictions: 6146 Incorrect Predictions: 1083

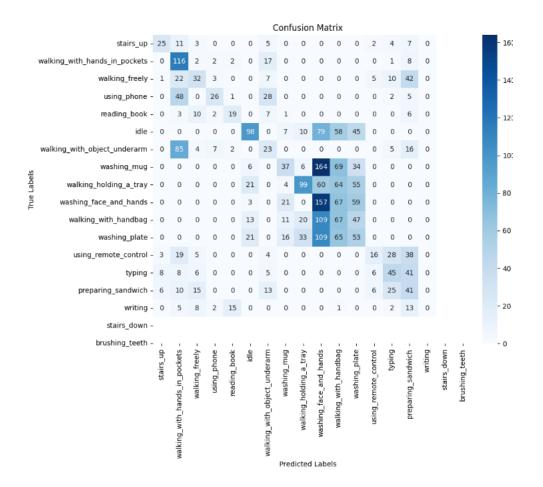


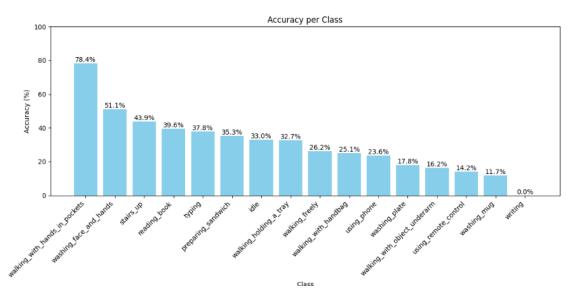


Vicon

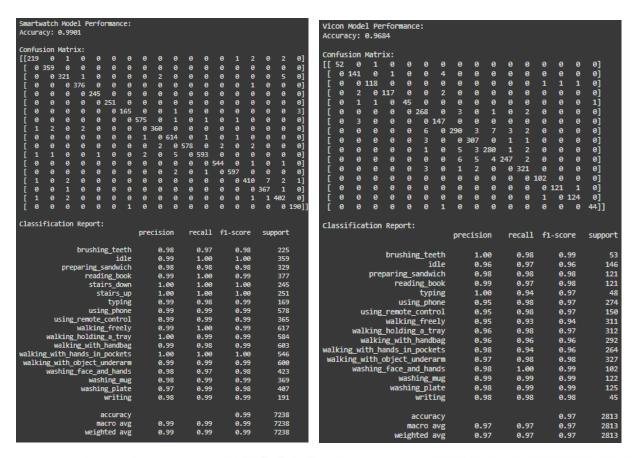
Accuracy: 30.41%

Correct Predictions: 854 Incorrect Predictions: 1954





We used anomaly detection and normalized the data, we analyzed the data and extracted a lot of features from the data such as mean, variance, skew and much more, we tried different types of models from random forest to complex neural networks. And the best results we got are:



Log Loss on Validation Set: 0.18023187367516463

f.

In general, The Vicon model predicted a bit less good, the hardest thing to predict for him was similar activities. I was mistaken in things like walking freely with walking with object under the arm or using remote control and using phone. There are things that the mode predicted perfectly like brushing teeth, probably because it is unique movement.

3 ways to improve the model are:

<u>Feature importance</u>: we will reduce some of the features and try to send only the most influent parameters so the model will be more efficient.

<u>Dimensional reduction methods</u>: we tried methods like PCA.

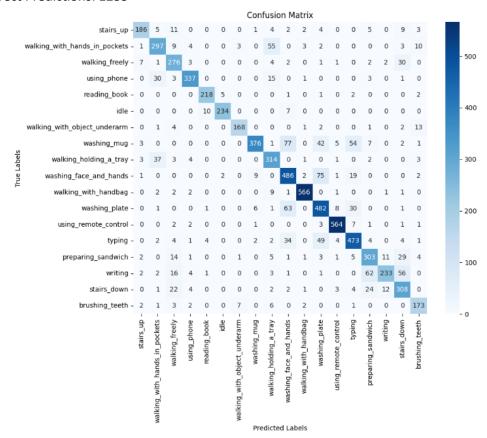
<u>Normalization methods</u>: we used several different methods to normalize the data from Standard Scaler to minmax to try and find the best normalization methods for the data.

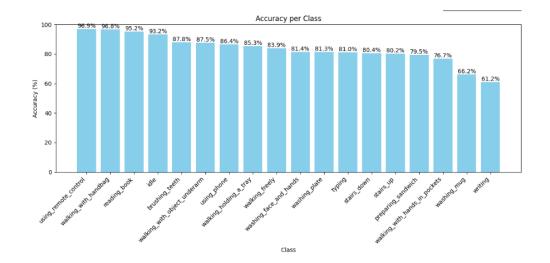
We prioritized the suggestions and decided that feature importance and Normalization are more important, and we focused on them more. We also tried dimensional reduction, but it worked a bit less good.

After these improvements we got:

1. 1D-CNN: **Smart Watch** Accuracy: 83%

Correct Predictions: 5994 Incorrect Predictions: 1235

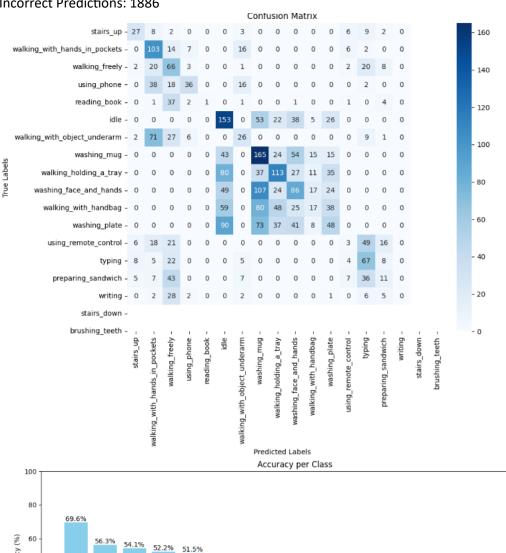


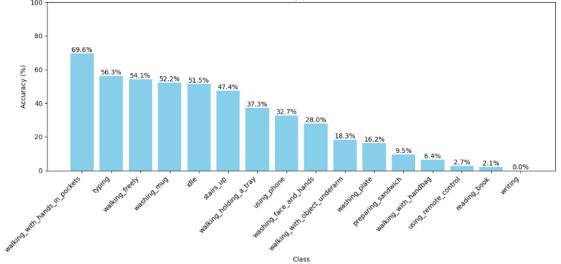


Vicon

Accuracy: 33%

Correct Predictions: 922 Incorrect Predictions: 1886





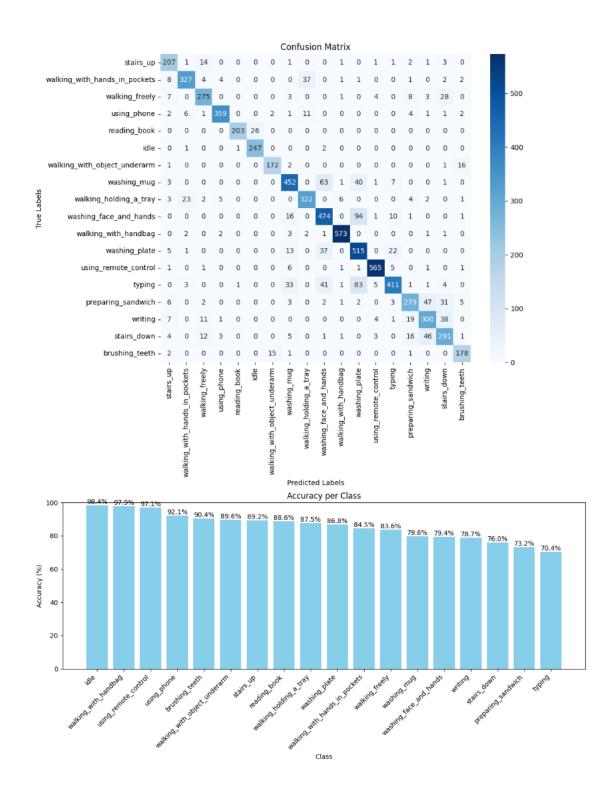
LSTM:

For Smart Watch:

Accuracy: 85.07%

Correct Predictions: 6150

Incorrect Predictions: 1079

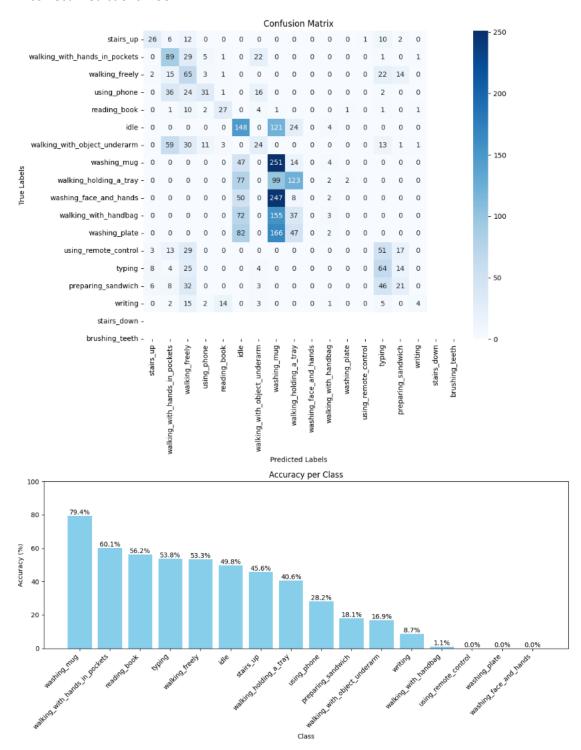


For vicon:

Accuracy: 31.20%

Correct Predictions: 876

Incorrect Predictions: 1932



We received minor changes in the results that does not determine in Distinction that the changes have helped.

In this project, we focused on classifying human activities based on sequences of numerical data that represent the movement. To achieve this, we conducted an informative analysis to better understand the behavior of the data. We began by splitting the dataset into two parts based on the type of sensor, as each sensor measures activities differently. This required us to address the gap between the two measurement methods and analyze the statistical variables.

The dataset consisted of a total of 175 million records, which posed a significant computational challenge. Following the data analysis, we decided to represent the data through feature vectors composed of various statistical metrics. This allowed us to condense the information into a more compact and manageable format. We normalized the data, identified the most impactful statistical features, and performed statistical tests to examine correlations and variances.

Next, we applied dimensionality reduction techniques such as PCA and statistical tests to further streamline the data. The processed data was then fed into two different models: a 1D-CNN and an LSTM. Each sensor type was assigned to its own model, and the results from both were later compared. To optimize performance and reduce the log loss, we incorporated additional models, including a Multi-Layer Perceptron (MLP) and a Random Forest.

This project enhanced our ability to process and analyze large datasets, address challenges, and identify the optimal methods for achieving the best-performing model.