

Searching

Linear search $\rightarrow O(n)$

Binary search $\rightarrow O(\log(n)) \rightarrow$ need size before

if not known then

taken $O(n)$ time to

find the size first.

\rightarrow sorted array needed

Jump search \rightarrow on blocks checking

Exponential search - $O(\log(n))$ time

\rightarrow find range in the element

\rightarrow then perform binary search.

Sorting

Selection sort \rightarrow smallest element to first.

Inplace algorithm

$O(n^2)$

$O(n) \rightarrow$ swaps \rightarrow

not stable

Bubble sort \rightarrow Sorts neighbours. Worst case $(n+n)$ But $O(n^2)$
good for almost sorted arrays. In place. Yes stable.

Insertionsort → Picks an element and places it in sorted array.

Time complexity = $\Theta(n^2)$

space $\rightarrow \Theta(1)$

minimum when already sorted

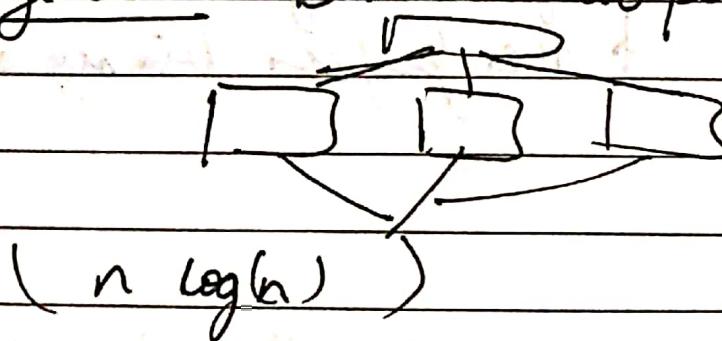
more when reverse order

Sorting in place
stable

Used for small no of elements.

Binary insertion sort.

Merge sort → Divide into part then merge.



$O(n)$ → extra space

~~used~~

Not in place

stable algorithm

for linked lists.

quicksort \rightarrow pick a pivot element partition
put all smaller element to left and
larger to right of the pivot

$O(n^2)$ worst case

$O(n \log n)$ best case

not stable

in place

merge sort using linked list no write

$O(n \log n)$ ~~and~~

insert any new element
easily

for almost sorted array use insertion sort
for $n \log(k)$ complexity.

↪ heap more efficient

quicksort \rightarrow pick a pivot element partition
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merge sort using linked list no write

$\Theta(n \log n)$ and
insert any new element
easily.

for almost sorted array use insertion sort
for $n \log(\frac{1}{\epsilon})$ complexity.

↪ heap more efficient

Data structures

linked list

- Dynamic size
- Ease of insertion/deletion
 - Random access not allowed.
 - Extra memory

Class

Node {

public:

int data;

Node* next;

}

Away from stack memory

linked list from heap.

stack

<stack>

DFS

LIFO

→ push ()

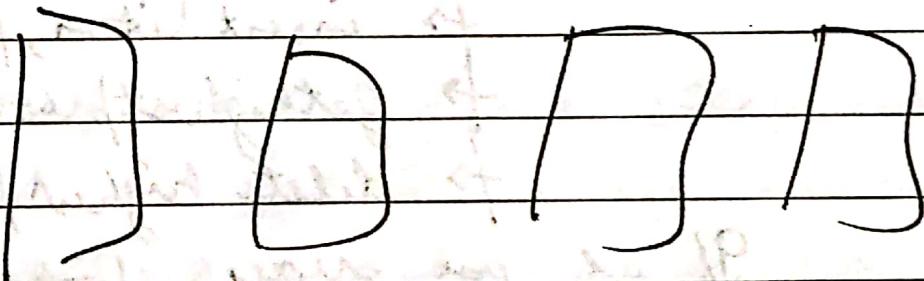
→ pop ()

empty()

stop()

normal method is $O(n^2)$

stack open problem



$S(n)$ where no of days
the price is less or equal.

To solve we

pop the stack till it is empty or
we find an element which is
greater than current.

$O(n)$

Queue :

FIFO

BFS

- enqueue
- dequeue

Priority queue

Highest priority dequeue first.

- insert (item, priority)
- gethighestpriority ()
- delete highest priority ()

If we use array, linked list - {only last
 $O(1)$, $O(n)$, ~~op. is off~~

we use heap generally

$O(\log n)$, $O(\log n)$

if we fibonacci heap

$O(\log n)$, $O(1)$, $O(\log n)$

dequeue ~~(double ended queue)~~

circular tour that visits all petrol pumps (Circular tour)

→ distance to next petrol & amount of petrol
find the first point from where truck
can complete all.

if we use brute force we need to
check for all petrol pump $O(n^2)$
but we will use queue.

We add to queue start and
add on petrol if we encounter
negative petrol we remove start and
increase it till the result becomes
positive then repeat - If we start
the initial start there is no result.
 $O(n)$ time complexity.

Maximum of all subarray of size K

find the maximum among the subarray of size K

Brut force

$\square D D D D D$

— — — — —

thus for one subarray sum
maximum

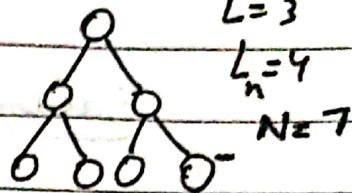
$O(n * k)$

using divide & Conquer
 $O(n)$

BST $O(n \log k)$

Method to print 'n' binary no (n binary)

- 1) Create an empty queue of strings.
- 2) Enqueue the first binary no '1'.
- 3) Now run a loop for generating binary,
 - a) Dequeue and print the front of queue.
 - b) Append '0' at end of a front string enqueue.
 - c) Append '1' at end of a front string enqueue it.

Binary tree→ ~~insertion/deletion~~

- Access faster than linked list stored than array.
- ~~Nodes~~ No upper limit on no of elements.
- Level \rightarrow no of nodes in path from root to node inclusive of both.
- The maximum no of nodes at level 'L' of a binary tree is 2^{L-1} .
- height \rightarrow no of edges b/w root and leaf nodes
- \therefore Maximum no of nodes = $2^h - 1$
- If N nodes minimum height is $\log_2(N+1)$
- If L leaves then $(\log_2 L) + 1$ levels
- Full binary tree \rightarrow Every node has 0 or 2 children

Complete binary tree \rightarrow All level except last are filled and last has all elements to atleast left as possible.

Perfect binary tree \rightarrow A binary tree in which all internal nodes have 2 children and all leaves at same level.

Balanced binary trees

A binary tree is balanced if the height of the tree is $O(\log n)$ where n is the no of nodes.

$$\rightarrow L = (K-1) * I + 1. \quad (\text{K-ary tree})$$

L = no of leaf nodes

I = no of internal nodes

$$\rightarrow \sum_{v \in V} \deg(v) = 2|E|$$

$$\rightarrow L = T + 1$$

where L = no of leaf nodes

T = no of internal nodes with 2 children

Tree traversals

DFS → inorder (left root right)

preorder (root left right)

postorder (left right root)

BFS

All traversals require $O(n)$.

for space, BFS ~~requires~~ $O(\omega)$ width of tree ($\geq \omega$)

for BFS

- 1) Create an empty queue q
- 2) $temp = root$;
- 3) Loop while $temp \neq \text{NULL}$
 - print $temp$'s data
 - add $temp$'s children to queue
 - Dequeue a node n and assign its value to $temp$

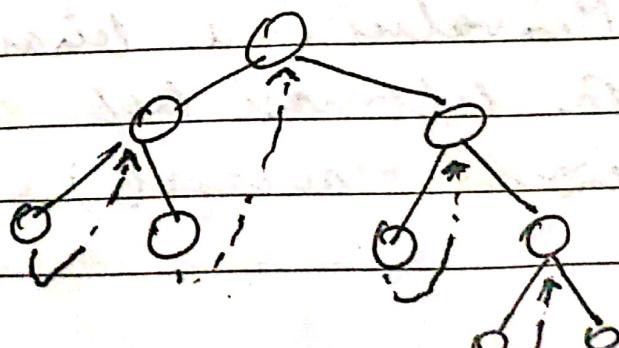
$O(n)$ time complexity

Diameter \rightarrow max distance b/w two leaf nodes through root.

Threaded binary trees

left/right child

The empty pointers of point to the inorder predecessor and successor respectively
in case of double threaded
in single threaded left child pointers point to successors.



Max height of binary tree $\rightarrow O(n)$

Binary Search tree

- left child only nodes less than the node
- right child only nodes greater than the node
-
- Search time complexity is $O(h)$ and
- insertion is also $O(h) = O(\log n)$

Inorder traversal of tree produces sorted result.

→ Deletion from binary tree is

- If it is leaf directly delete
- If it has only one child delete and move child there
- If it has two child move the inorder successor tree and move

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Min value in a binary search tree is the leftmost leaf element (first in the inorder traversal)

Heap

Binary heap

It is a complete tree.

→ It is either min heap or max heap.

It is usually represented as an array.

root $\rightarrow A[0]$

for node (i)

$(i+1)/2 \rightarrow$ parent

$(2^i + 1)$ left child

$(2i+2)$ right child

BFS \rightarrow to achieve array order

→ Heap sort $\rightarrow O(n \log n)$ to sort in array

→ priority queue \rightarrow insert(), delete(), extractmax(), decreasekey
 $\text{in } O(\log n)$ give. Binomial/Fibonacci heap
are variations of binary heap.

for problems like -

1) Kth largest element

→ sorting -

→ Merge K sorted arrays

→ Pair Min/Max spanning tree.

→ Dijkshtra's shortest path

Operations

→ get min() → returns the root element of min heap $O(1)$

→ extract min() → removes root $O(\log n)$

→ decrease key() → $O(\log n)$ decreases value of key

→ insert() → $O(\log n)$.

→ delete() → $O(\log n)$

To get n^{th} largest element $(n \log n) \cdot O(n)$

Hashing

Insert data using key $O(1)$

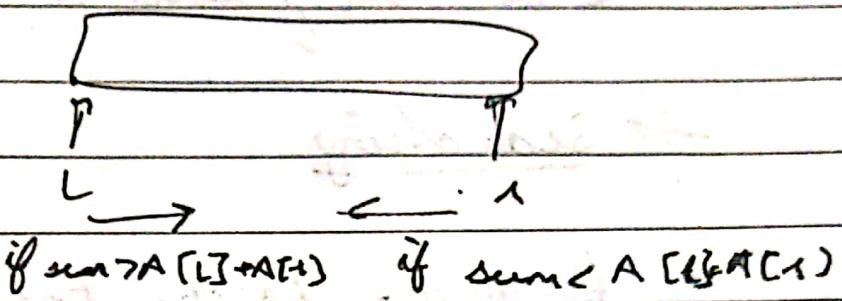
Get data using key $O(1)$

Delete data using a key $O(1)$

Hash function: A function that converts a given big phone no to a small practical no.

Hashtable: an array that stores pointers to records corresponding to phone no.

To find sum we need to
sort the array



STL library

- Algorithms
- Containers
- functions
- Iterators

Algorithms

Sorting

`sort(start, end)`
[start address, end address]

for descending order third argument
`greater<int> greater`

structure

for sorting for a third type argument
↳ used which is a comparator which is
a boolean function.

→ Searching

✗ Binary - search (start address, end address, value, sort array)

fourth argument is size
fifth argument is a comparator

→ void * bsearch (const void* key, const void* ph, std :: size_t count, std :: size_t size, & comp)
return pointer to the result

→ reverse (first iterator, last iterator)

→ * max_element (first iterator, last iterator)

→ * min_element (first iterator, last iterator)

→ accumulate (_____, _____, _____)

→ lower_bound (_____, _____, x)

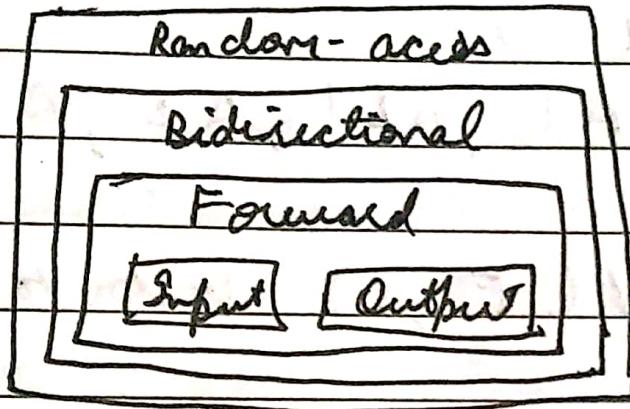
→ upper_bound (_____, _____, x)

→ next_permutation (_____, _____)

→ prev_permutation (_____, _____)

→ accumulate (_____, _____, initial)

Iterator



Vector → RA

list → bidirectional

vector< int> :: iterator i;

→ No need to keep track of max elements

→ Dynamically add or remove elements

Date _____ / _____ / _____

extra edge

is_sorted_until ()

is_sorted ()

merge (A1 , AL1 , A2 , AL2 , A3)

make_heap (F , S) → vector to heap { next
front () }

push_heap () → use push - back before

pop_heap () → use pop - back after

is_heap ()

is_heap_until ()

max → on list

minmax → pair < T ;

max_element on iterator

min_element → on iterator

minmax_element → on iterator

max → on list

Containess

Vector → It is same as dynamic arrays.

→ Data insertion at end.

→ Can be used with iterators.

→ Removing takes constant time

→ Insertion usually takes constant time

Functions on vectors are:-

Iterator

→ begin () → first point iterator

→ end () → last

→ rbegin → reverse begin (last)

→ rend → reverse

→ cbegin → constant iterator

→ cend → constant iterator

auto i = .begin()

Capacity:

→ size () → returns the size.

→ max_size () → returns max element size by default

→ capacity () → max elements

→ empty () → true/false

Element access:

$[g] \rightarrow$ get object
 $at(g) \rightarrow$

$front() \rightarrow$ reference to first element

$back() \rightarrow$ last element

$data() \rightarrow$ reference to internal data

Modifiers:

$assign(x, y) \rightarrow$ if x const then x value for all elements if x array then y is new row of array.

$push_back(value) \rightarrow$ pushes value to back

$pop_back() \rightarrow$ pops the last value

$insert(i, y) \rightarrow$ inserts a specified element before in position i .

$insert(position, size, val) \rightarrow$ inserts the value $size$ times

$front(position, begin, end) \rightarrow$ iterator

$clear() \rightarrow$ removes all elements $O(N)$

$erase(position) \rightarrow$ remove element at the position

$erase(starting\ position, ending\ position) \rightarrow$

$swap(vector1) \rightarrow$ swap two vectors (without) next elements

list

Algo some ~~ent~~ push-front, pop-front

merge()

sort()

queue

stack

empty()

empty() $O(1)$

size()

size()

swap()

top()

emplace()

push(g)

front()

pop(g)

back()

push(g)

pop()

priority-queue (used for heap)

< type, vector<type>, comparison-fn >

empty()

swap()

size()

value-type()

top()

push()

pop()

Algorithms

→ To find common element in all arrays

if $x < y$

then $i \leftarrow 1$

if $y < z$

then $j \leftarrow 1$

else

~~$i \leftarrow 1$~~

if $x = y = z$

$i \leftarrow 1, j \leftarrow 1, z \leftarrow 1$

→ Sorted array find a no whose sum is equal to x . (find sum x)

start from $i = 0$ & $j = n$

if sum < x increase i

if sum > x increase j .

Fibonacci numbers

$$F_n = \begin{cases} 0 & n=0 \\ 1 & n=1 \\ F_{n-1} + F_{n-2} & 2 \geq n \end{cases}$$

$$F_n = 2^{\frac{n-2}{2}} \quad n \geq 6$$

$$F_n = \frac{1}{\sqrt{5}} \left(\left(\frac{1+\sqrt{5}}{2} \right)^n - \left(\frac{1-\sqrt{5}}{2} \right)^n \right)$$

Naive algorithm

$$T(n) = 2 \quad \text{if } n=2$$

$$T(n) = T(n-1) + T(n-2) \quad \text{for } n > 2$$

Efficient algorithm

Store F_{n-2} and F_{n-1} and use them to solve F_n iteratively.

Greatest common divisor

Put a/b in simplest form.

$$\frac{a/d}{b/d}$$

Need to divide a and b by d as large as possible

Normal algorithm

Search all no from 1 to $a+b$ to check condition

Efficient algorithm

Let a' be remainder when a is divided by b .

Then

$$\gcd(a, b) = \gcd(a', b) = \gcd(b, a')$$

$\text{gcd}(a, b)$
if ($b=0$)

return a

$a' \leftarrow a \% b$

return $\text{gcd}(b, a')$

Big O notation

$$\begin{aligned}O(1) &< O(\lg(n)) < O(\log(n)) &< O(n^{\frac{1}{2}}) &< O(n) < O(n \lg n) < O(n^2) < O(n^3) \\&< O(C^n) < O(d^n)\end{aligned}$$

Sum of n fibonacci no

$$S(n) = F(n+2) - 1 \Rightarrow F_{n+1} = F_n + F_{n-1}$$

$$F_{n-2} = F_{n-1} - F_{n-3}$$

Sum of squares of fibonacci no

$$S(n^2) = f(n)f_{n+1}$$

fibonacci no modulo m

→ fibonacci no repeat after certain intervals when modulo is taken. The series starts with 0 1.
find period and reduce the loop.

Greedy algorithm

take the no that has the best outcome in the current situation.

car fueling problem (Gas station)

From farthest reachable gas station reduce the problem again.

Main ingredients of greedy algorithms

- greedy choice
- reduction to a subproblem
- safe move &
strategy

Analyze if problems have a greedy problem
then prove this greedy choice is a safe move

Children celebration problem

- divide children in minimum no of group
- age diff of any two kids in a group should not be more than one year

Consider the points on line as age of children.
select min no of segments of length 1 that cover all the children

long ride problem

Knapsack → maximum weight
energy of item , weight of item
fit maximum value per unit.

while knapsack is not full

choose item i with max $\frac{v_i}{w_i}$ to fill as much as possible

Greedy algorithm

used for optimization problems.

or getting approximation solution \rightarrow NP-hard problems
 \rightarrow Activity selection problem.

You are given n activities with start and end time.

Select the maximum no of activities one a person can perform.
not by first time.

\rightarrow Kruskal's minimum spanning tree.

$O(E \log V)$

find the edges that connect all vertices of a tree.

Vertices $V - 1$ edges

i) Sort all edges in non decreasing order of their weight

ii) Pick the smallest edge. Check if a cycle is formed. If no include this edge else discard.

iii) Repeat i till $V - 1$ edges there.

→ find a cycle in ~~an~~ directed graph

$O(V \cdot E)$

We need to detect a back edge

→ DFS traversal we keep track of vertices in recursion stack.

→ find a cycle in ~~an~~ undirected graph

$O(n)$

Using Disjoint set

\downarrow
 $O(\log n)$

data structure used to show disjoint sets.

it can perform two functions
union & find.

Huffman coding (priority queue use)

effort $O(n)$ ($n \log n$)

encoding of one character is not the prefix of another such that there is unique decompression.

→ Build huffman code

→ Traverse huffman tree and assign it to

Steps to build a huffman tree

- 1) Create a leaf node for each unique character and build a min heap * used as priority queue . The least frequent character is at root .
- 2) Extract two nodes with minimum frequency from heap
- 3) Create a new internal node with a frequency equal to the sum of nodes frequency .
Make first extracted node as left and second as right . Add this node to the heap
- 4) Repeat step 2 & 3 - until the heap contains one node . The remaining node is root node the tree is complete

To print code

* → move left add 0 . → move right add 1

Pri's minimum spanning trees $O(V^2)$
(for adjacency matrix)

- 1) Create a set MST that keeps track of vertices included in MST
- 2) Assign a key value to all vertices. All ∞ except
(vertices $\rightarrow 0$)
- 3) While MST set doesn't include all vertices
 - a) Pick a vertex v which is not in MST and has minimum key value
 - b) Include v to MST set
 - c) Update key value of all adjacent vertices of v . To update the key values, iterate through all adjacent vertices. For all adjacent vertex v - if weight of edge between $U \rightarrow V$ is less than key value update value.

(for adjacency list)

Covering segments by bad points

Sort the segments by bad points
select first segment end point as point -
remove all segments covered by the
points -

repeat till all segments are covered

Different commands

for $a^n \rightarrow a_1 + a_2$ — are such that $a_i + a_j$ for all $i, j \in \{1, 2, \dots, l\}$ is a

it is possible if and only if $l \geq 2k$ where
 k is the least operand we can use.

Dijkstra's Algorithm

- Create a Min heap of size V where V is the no of vertices in the given graph. Every node of the min heap contains vertex and its distance from source.
- Initialize Minheap with source vertex root. All other vertex are ~~zero~~ or infinity.
- While Minheap is not empty.
 - Extract the vertex with Minimum distance value node from Minheap. Let the extracted node be u .
 - for every adjacent vertex v of u , check if v is in heap. If v is in Minheap and distance is more than $u - v$ plus distance of u . update Distance value of v .

Job sequence problem

- Sort the jobs in order of their profit
- select jobs fit them in sequence at least of their deadline if they fit else discard.

Divide and conquer

Breaking one or more problems by splitting the problem
recursively solve the problem

Binary search

polynomial multiplication

naive algorithm → Break polynomial as

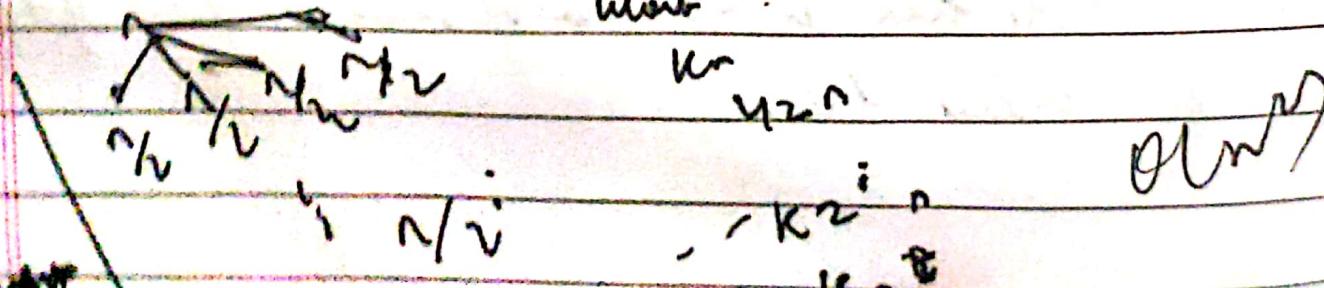
$$A(x) = A_0 + A_1 x^{n/2} + A_2 x^n$$

$$B(x) = B_0 + B_1 x^{n/2} + B_2 x^n$$

and multiply them we get

$$C(x) = C_0 + C_1 x^n$$

where



Karatsuba approach

$$A(x) = a_0 x + a_1$$

$$B(x) = b_0 x + b_1$$

$$C(x) = \dots a_1 b_1 x^2 + (a_1 b_0 + a_0 b_1) x + a_0 b_0$$

$$C(x) = a_1 b_1 x^2 + ((a_1 + a_0)(b_1 + b_0) - a_1 b_1 - a_0 b_0) x + a_0 b_0$$

$$A(x) = 4x^3 + 3x^2 + 2x + 1$$

$$B(x) = x^3 + 2x^2 + 3x + 4$$

$$D_1(x) = 4x + 3$$

$$D_0(x) = 2x + 1$$

$$E_1(x) = x + 2$$

$$E_0(x) = 3x + 4$$

$$D_1 E_1 = 4x^2 + 11x + 6$$

$$D_0 E_0 = 6x^2 + 11x + 4$$

$$(D_1 + D_0)(E_1 + E_0) = (6x + 4)(6x + 6) = 36x^2 + 52x + 24$$

$$\textcircled{2} \quad AB = (4x^2 + 11x + 6)x^4 + (24x^2 + 52x + 24 -$$

~~$$4x^2 + 11x + 6 - 6x^2 - 11x - 4 + 6x^2 + 11x + 4$$~~

$$= 4x^6 + 11x^5 + 20x^4 + 30x^3 + 20x^2 + 11x + 4$$

$$O(n^{1.5})$$

Master Theorem

$$g \text{f } T(n) = aT\left(\frac{n}{b}\right) + O(n^d) - (a \geq 0, b > 1, d \geq 0)$$

$T(n) = O(n^d)$ if $d > \log_b a$

$= O(n^{\log_b a})$ if $d = \log_b a$

$= O(n^{\log_b a})$ if $d < \log_b a$

Closest pair problem

- Partition the subset in two trees by a chosen point.
- Call for subset -
- Find maximum distance of the points in subset. by using points only inside the recd range.

Point and segment

sort the segment by start find the first element that is equal to or less than the key. (i) If equal then take the

sort of segment by end find the first

element that is equal to or less than key taken not
if no of segment is $i - j$.

Majority element

if size ≤ 1 return element.

find mid, split by mid

find the majority element in both
if agree for both then return
else count occurrences and return.

find inversions (measured of sorted array)

split the set in $N/2$

get inversions in both.

merge both sets.

merge is same as in merge sort.

we count the no of inversions. and return

Dynamic programming

Recursion grows a lot. But recursions of same element is used many time. So we store values of certain values by filling the matrix from small to large.

DP change (Money, coins)

Min Num Coins(0) $\leftarrow 0$

for m from 0 to money:

Min Num Coins(m) $\leftarrow \infty$

for i from 1 to (coins):

if $m \geq \text{coins}$:

NumCoins $\leftarrow \text{Min Num Coins}(m - \text{coins})$

if NumCoins < Min Num Coins(m):

Min Num Coins(m) = NumCoins

return Min Num Coins(money)

Greedy approach fails sometimes because if we take ~~some~~ a bigger amount the remaining might take more input.

Edit distance problem (minimum no of operations to transform a string to another)

$A[1 \dots n] \& B[1 \dots m]$ what is optimum algorithm of an i prefix $A[1 \dots i]$ of the first string and a $-j$ prefix $B[1 \dots j]$ of the second string last column is either.

[insertion] mismatch
deletion matrix

Common
Subsequence

$A[1 \dots j] - +$
 $B[1 \dots j-1] B[j]$

Matches in
or alignment of
two strings

~~Max~~ $A[1 \dots i-1] A[i] +$
 $B[1 \dots i-1] -$

longest common
subsequence

$A[i] + B[i]$ $A[1 \dots i-1] A[i] +$
 $B[1 \dots i-1] B[i] +$
 $- A[1 \dots i-1] A[i]$
 $B[1 \dots j-1] B[j]$

Maximum
 $M=0$ or ∞
min cost edit

Alignment goes \Rightarrow Remove all symbol from two strings such that your point are maximized.
scoring (insertion is $-i$ in first
deletion is $-i$ in secnd)

Alignment is two ∞ matrix

[same as edit
distance]

if we remove last column we are
left with optimal alignment of prefixes

let $D(i, j)$ be the edit distance of an i -prefix
 $A[-i:]$ and j -prefix $B[-j:]$

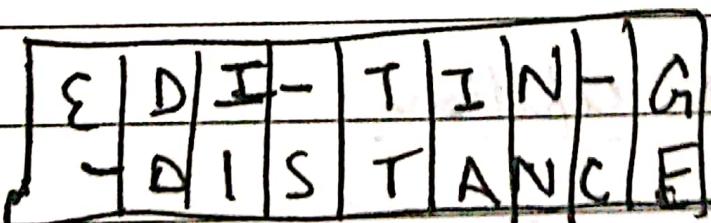
$$D(i, j) = \begin{cases} D(i, j-1) + 1 & \\ D(i-1, j) + 1 & \\ D(i-1, j-1) + 1 & A[i] \neq B[j] \\ D(i-1, j-1) & A[i] = B[j] \end{cases}$$

j D I S T A N C E

| | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|---|---|-------|-------|---|---|---|---|---|---|
| E | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| I | 1 | 1+2→3 | 4+5→6 | 7 | 7 | | | | |
| D | 2 | 1 | 2,3 | 4 | 5 | 6 | 7 | 8 | |
| T | 3 | 2 | 1+2→3 | 4 | 5 | 6 | 7 | | |
| F | 4 | 3 | 2 | 3 | 4 | 5 | 6 | | |
| N | 5 | 4 | 3 | 3 | 3 | 4 | 5 | 6 | |
| G | 6 | 5 | 4 | 4 | 4 | 3 | 4 | 5 | |
| J | 7 | 6 | 5 | 5 | 5 | 4 | 4 | 5 | |

How to construct alignment

E I - D I T I N G - G
 DIS - G A N C E



backtrack from last to start.

Knapsack problem

$$\text{Value}(w) = \max_{w_i \in W} \{\text{value}(W - w_i) + v_i\}$$

Fractional knapsack \rightarrow take fraction of items

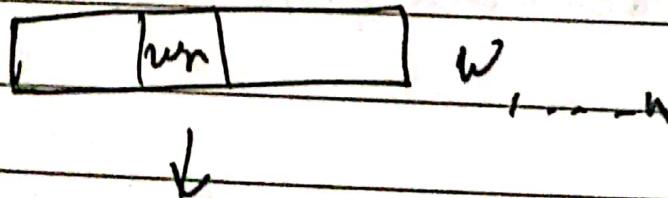
- discrete \rightarrow take whole or not
- \rightarrow with repetitions or not

with repetitions

$$\text{Value}(w) = \max_{w_i \in W} \{\text{value}(W - w_i) + v_i\}$$

without repetitions

single copy of each copy is given thus.



work on
with items

$$\text{Value}(w) = \max \{ \text{value}(w - w_i, i+1) + v_i, \\ \text{value}(w, i-1) \}$$

initializing all $\text{value}(0, j) \leftarrow 0$

initializing all $\text{value}(w, 0) \leftarrow 0$

for i from 1 to n

 for j from 1 to w

$\text{value}(w, j) \leftarrow \text{value}(w, j-1)$

 if $w_i \leq w$:

$\text{val} \leftarrow \text{value}(w - w_i, j-1) + v_i$

 if $\text{value}(w, j) < \text{val}$:

$\text{value}(w, j) \leftarrow \text{val}$

return $\text{value}(w, n)$.

Applying parentheses to an expression