

# **A Brief Introduction to OpenCV and Computer Vision**

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# What this session is about

- Getting learner's acquainted with some basic concepts related to Image Processing
- Introduction to the OpenCV Library (using Python) and how to perform basic image processing operations
- Demonstration of a few applications of Image Processing in OpenCV



# What this session is NOT about

- Explanation of the mathematics behind image processing / computer vision algorithms
- Applications based on Machine Learning / Deep Learning etc.



# Prerequisites for this session

- Familiarity with Python syntax and the Numerical Python (numpy) library
- Software installation of all the required software for this session.
- A little bit of math

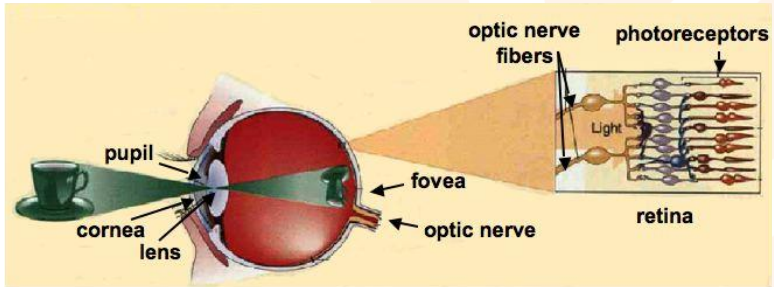


# Agenda

- What is Image Processing and Computer Vision?
- Getting started with OpenCV (using Python)
- Demo #1 - Object Detection
- Demo #2 - Building an Invisibility cloak.



# What is an Image ?

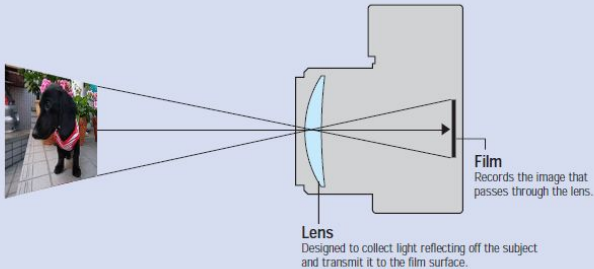


The human eye



# What is an Image ?

- A camera that records images passing through the camera's lens on film is called a film camera.

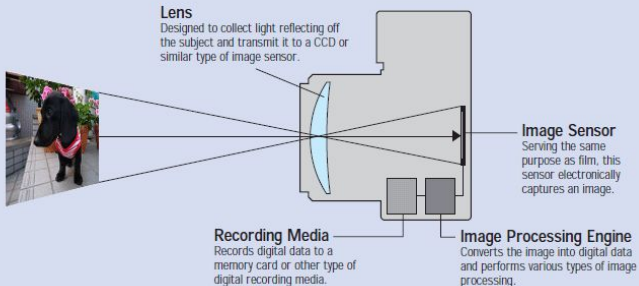


Camera - a “low tech” eye



# What is an Image ?

- The digital camera is designed to convert an image into digital data and record it.

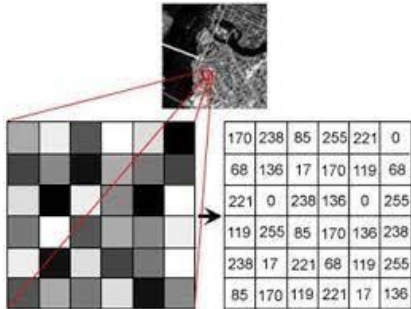


## Modern Digital Cameras





# What is an Image ?



**Image is a matrix**

**Grayscale Spectrum**



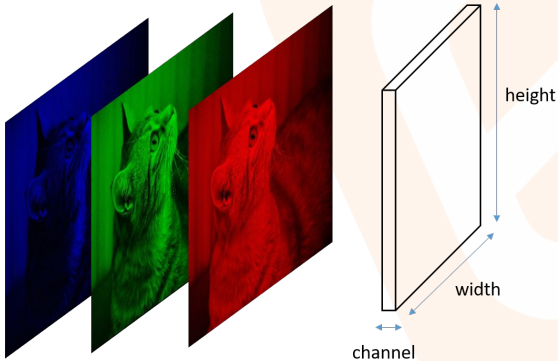
**Undergoes  
Quantisation**

0

255



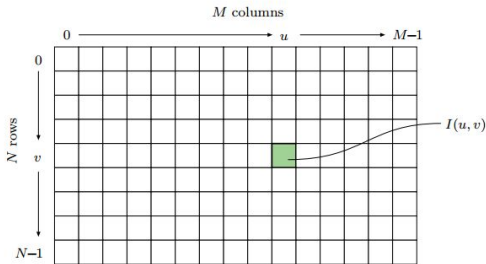
# What is an Image ?



**RGB images are represented in 3D matrices**



# What is a Pixel ?



- Pixel represents the smallest unit of an image
- Each pixel has a value between 0-255 based on color (represented by 8 bits in binary)
- Grayscale images are represented by  $M \times N$  matrices
- RGB images are represented by  $M \times N \times 3$  matrices



**What is the size of a grayscale image  
with dimensions 32x32 pixels?**

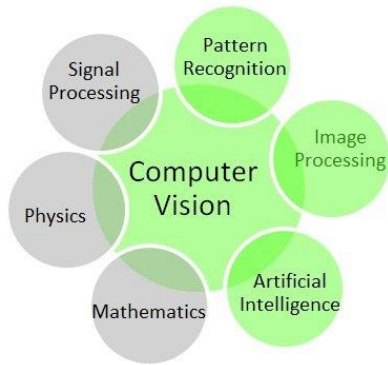
$32 \times 32 \times 1 \text{ byte} = 1024 \text{ bytes} = 1 \text{ KB}$



# Difference between Image Processing and Computer Vision



# Difference between Image Processing and Computer Vision



- Computer vision refers to high-level understanding of images - detecting faces , object tracking etc.
- Image Processing refers to low-level processing such as detecting shapes, removing noises, detecting edges or corners etc.



**Let's get down to coding...**



# **Part - 1**

## **Basic Image Processing Operations**





# Loading, Displaying and Saving Images

- Loading Image - `cv2.imread( )`
- Display Image - `cv2.imshow( )`
- Saving Image - `cv2.imwrite( )`



# Image resizing and rotation

- **Resize Image** - **cv2.resize( )**
- **Rotate Image** - **getRotationMatrix2D()**

$$R'_{\theta} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}.$$



# Drawing Functions in OpenCV

- Draw Line - `cv2.line( )`
- Draw Rectangle - `cv2.rectangle( )`
- Draw circle - `cv2.circle( )`
- Write Text - `cv2.putText( )`

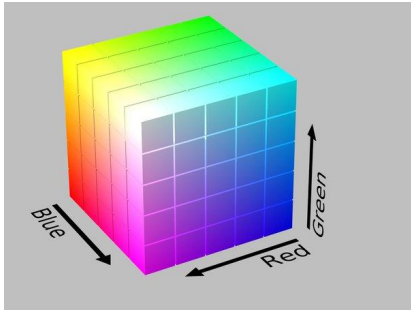


# Part - 2

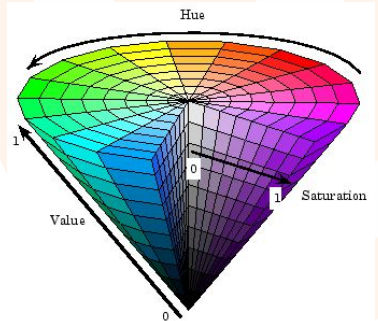
## Object Detection



# Different Color spaces



**RGB (Red, Green, Blue)**



**HSV (Hue, Saturation, Value)**



# Why use HSV over RGB?

- Different shades of a colour fall in the same range for HSV while in RGB they might be completely different ranges. Hence it makes thresholding easy.
- HSV is less sensitive to external light while RGB is more sensitive.



# Masking

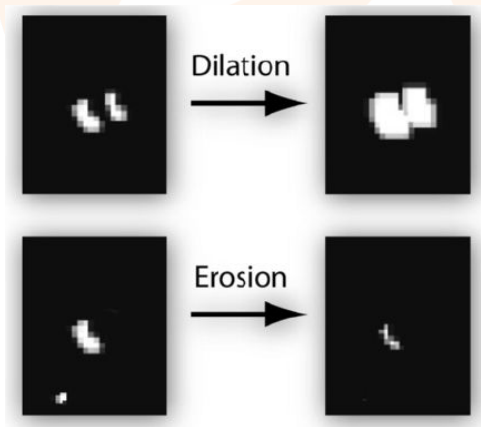


**Highlighting a specific object**



# Erosion and Dilation

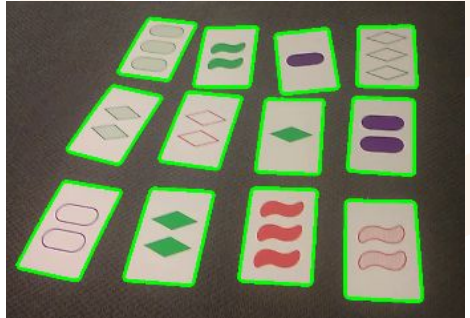
- Dilation expands the boundary of white areas
- Erosion decreases the boundary of white areas





# Contour Detection

- Contours can be explained simply as a curve joining all the continuous points (along the boundary), having same color or intensity.
- Contours are always closed curves, never open.



# **Part - 3**

## **Invisibility Cloak**



# Invisibility Cloak

- The same approach of colour filtering and noise reduction is used.
- A mask is created by applying colour filtering.
- All the area under the mask is replaced with the static background



**Thank You !!**

