

Border Surviellance Bot
Group V

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Chapter 1

Namespace Index

1.1 Namespace List

Here is a list of all documented namespaces with brief descriptions:

erts	3
opencv (Importing opencv for face detection)	6
serial (Importing pyserial for serial communication)	7
sys (Importing system for handling signals for exit)	7
time (For sleep function)	7

Chapter 2

Namespace Documentation

2.1 erts Namespace Reference

Functions

- def `detect`
The function to get the frame.

Variables

- tuple `ser`
configure the serial connections (the parameters differs on the device you are connecting to)
- tuple `image_size` = cv.GetSize(image)
- tuple `grayscale` = cv.CreateImage(`image_size`, 8, 1)
- tuple `storage` = cv.CreateMemStorage(0)
- tuple `cascade` = cv.Load('haarcascade_frontalface_alt.xml')
- tuple `faces` = cv.HaarDetectObjects(`grayscale`, `cascade`, `storage`, 1.2, 2, cv.CV_HAAR_DO_CANNY_PRUNING)
- int `device` = 1
- tuple `capture` = cv.CaptureFromCAM(device)
- int `faceBeep` = 0
- int `firstFaceDetected` = 0
- int `falseDetection` = 0
- int `faceNotDetected` = 0
- int `multipleFaces` = 0
- int `multipleFacesInit` = 0
- int `forward` = 0
- int `left` = 0
- int `right` = 0
- tuple `frame` = cv.QueryFrame(capture)

- **x** = left-right
- tuple **k** = cv.WaitKey(10)

2.1.1 Detailed Description

```

*****
Platform: Python 2.x and 2.x.x
Title: Border Surveillance Bot
Author:
    1.Harish Tummalacherla
    2.Sameer Mohammed
*****

```

2.1.2 Function Documentation

2.1.2.1 `def erts::detect (image)`

The function to get the frame.

Parameters

<i>image</i>	the image input
--------------	-----------------

Definition at line 102 of file erts.py.

2.1.3 Variable Documentation

2.1.3.1 `erts::cascade = cv.Load('haarcascade_frontalface_alt.xml')`

Parameters

<i>haarcascade</i>	for face detection detect objects loading the Haar Cascade
--------------------	--

Definition at line 130 of file erts.py.

2.1.3.2 `int erts::faceBeep = 0`

Parameters

<i>Used</i>	for beeping control
-------------	---------------------

Definition at line 173 of file erts.py.

2.1.3.3 `int erts::faceNotDetected = 0`

Parameters

<i>used</i>	for checking if no face is found
-------------	----------------------------------

Definition at line 179 of file erts.py.

```
2.1.3.4 tuple erts::faces = cv.HaarDetectObjects(grayscale, cascade, storage, 1.2, 2,  
cv.CV_HAAR_DO_CANNY_PRUNING)
```

Parameters

<i>cascade</i>	haarcascade for face detection detecting the faces in the image These parameters are tweaked to RGB video captures, please refer to http://opencv.willowgarage.com/documentation/python/objdetect_cascade_classification.html for tweaking your parameters.
----------------	---

Definition at line 136 of file erts.py.

```
2.1.3.5 int erts::falseDetection = 0
```

Parameters

<i>For</i>	false detection
------------	-----------------

Definition at line 177 of file erts.py.

```
2.1.3.6 int erts::firstFaceDetected = 0
```

Parameters

<i>Used</i>	for face detection
-------------	--------------------

Definition at line 175 of file erts.py.

```
2.1.3.7 erts::grayscale = cv.CreateImage(image_size, 8, 1)
```

Parameters

<i>image_size</i>	create grayscale version
-------------------	--------------------------

Definition at line 112 of file erts.py.

```
2.1.3.8 erts::image_size = cv.GetSize(image)
```

Parameters

<i>image</i>	image input Getting size of the image for handling generic image resolution, i.e. handling webcam with arbitrary resolution
--------------	--

Definition at line 107 of file erts.py.

2.1.3.9 int erts::multipleFaces = 0

Parameters

<i>for</i>	indicating that multiple faces
------------	--------------------------------

Definition at line 181 of file erts.py.

2.1.3.10 tuple erts::ser

Initial value:

```
1 serial.Serial(
2     port='/dev/ttyUSB0',
3     baudrate=9600,
4     parity=serial.PARITY_NONE,
5     stopbits=serial.STOPBITS_ONE,
6     bytesize=serial.EIGHTBITS
7 )
```

configure the serial connections (the parameters differs on the device you are connecting to)

Parameters

<i>port</i>	The port where the serial communication usb is present.
<i>baudrate</i>	Set the baud rate to 9600
<i>parity</i>	Parity Bit Disabled
<i>stopbits</i>	Use one stop bit
<i>bytesize</i>	Number of Data Bits = 8

Definition at line 89 of file erts.py.

2.1.3.11 erts::storage = cv.CreateMemStorage(0)

Parameters

<i>0</i>	create required storage for face detection
----------	--

Definition at line 119 of file erts.py.

2.2 opencv Namespace Reference

importing opencv for face detection

2.2.1 Detailed Description

importing opencv for face detection

2.3 serial Namespace Reference

importing pyserial for serial communication

2.3.1 Detailed Description

importing pyserial for serial communication

2.4 sys Namespace Reference

importing system for handling signals for exit

2.4.1 Detailed Description

importing system for handling signals for exit

2.5 time Namespace Reference

for sleep function

2.5.1 Detailed Description

for sleep function

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