

arm_init_devices

```
graph LR; A[arm_init_devices] --> B[arm_port_init]; A --> C[timer1_init]; B --> D[servo1_pin_config]; B --> E[servo2_pin_config]; B --> F[servo3_pin_config];
```

arm_port_init

timer1_init

servo1_pin_config

servo2_pin_config

servo3_pin_config