


CameraLeft



```
graph LR; CameraLeft[CameraLeft] --> servo_3[servo_3]
```

A diagram showing a horizontal flow from left to right. On the left is a gray rectangular box with a black border containing the text "CameraLeft". A blue arrow points from the right side of this box to the left side of a white rectangular box with a black border on the right. This second box contains the text "servo_3".

servo_3