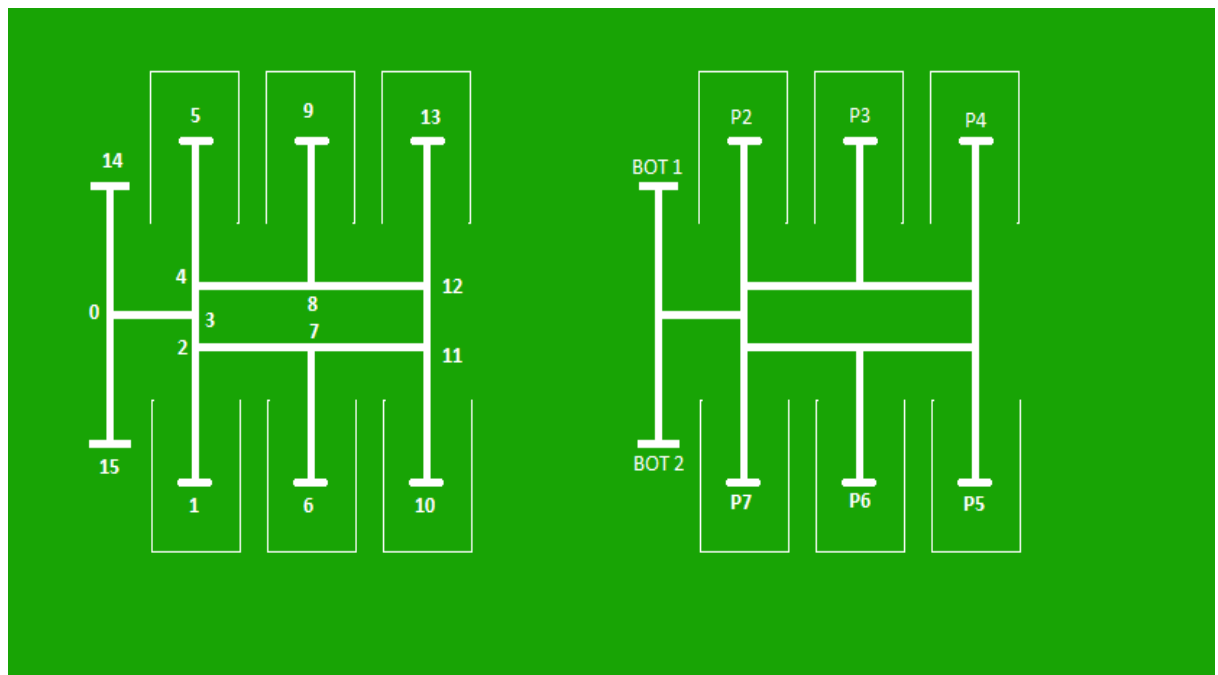


CS308 README



CS308 – 2011 Project

Project: Patient Service System



Project Title: Patient Service System

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Project Objective

The project aims at helping the patients and hospital management by providing automated service bots, who can be called by the patient simply by using a cheap TV remote, and who provide a guarantee of no-deadlock/race conditions. The server uses a full fledged database (MySQL) to maintain the queue and manages the bot wisely using a perfectly scalable design. The bots are fair to all the patients. The bot notifies the guards if it is blocked by an SMS.

* For more details, see the code documentation.

Hardware Platform

1. 2 x Firebird V ATMEGA2560
2. Programmer, Linux(Ubuntu) system
3. X-Bee and TSOP sensor in the bots
4. TV Remote

Software

1. avrdude
2. avr-libc
3. gcc-avr
4. JDK
5. MySQL
6. All the software can be installed using `./install`

It will install all the dependencies on an ubuntu system.

Code Description

Filename	Purpose	Executes on
Src/BOT_CODE/*	Code required for bot	Robots
Src/SERVER_CODE/*	Server code	PC
Install	Install dependencies and generate makefile to run the project	PC

Deliverables

Filename	Contains
cs308_group13.tar.gz	SourceCode of programs to be burnt on Robot as well as to be executed on PC. Contains documentation of the code as well. Install script (details below), Makefile

Execution Instructions (Ubuntu)

To execute the code for the first time, run the install script as

sudo ./install

(requires proxy settings)

This will install all the dependencies and drivers required for the project and generate a Makefile.

Note :

1.The properties file **config/config.properties** might require a change. (e.g. Zigbee COM port, Database settings)

Then to

compile the server code - **make server**

To run the server code - **make run**

To compile and program the serving bot no 1.

- make bot

To compile and program the serving bot no 1.

- make bot1

To compile and program the patient IR handler bot

- make patient

To clean - make clean

To open the documentation - **make doc**

Execution Instructions (Windows)

It will require changing the jar files and the makefile. We do not provide any configuration for windows system.

The code has been written and tested on Ubuntu 10.10 and 11.04.