

Interfacing a PIR Sensor with FireBird V Robot

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Agenda for Discussion

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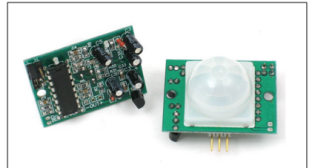


Introduction



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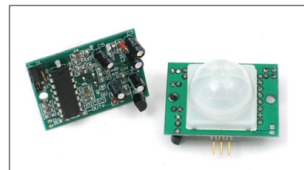
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- Everything emits some low level radiation and hotter something is, the more radiation is emitted.
- The pyroelectric sensor in the PIR is split into two slots. When a body moves in its field of view, one slot experiences more IR than the other, and a differential voltage is created, which indicates the motion of a human.



Specifications



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- Single bit output



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- Sensitivity: Pre-settable
- Size: Length 32mm, Width 24mm, Thickness 26mm



Working Principle



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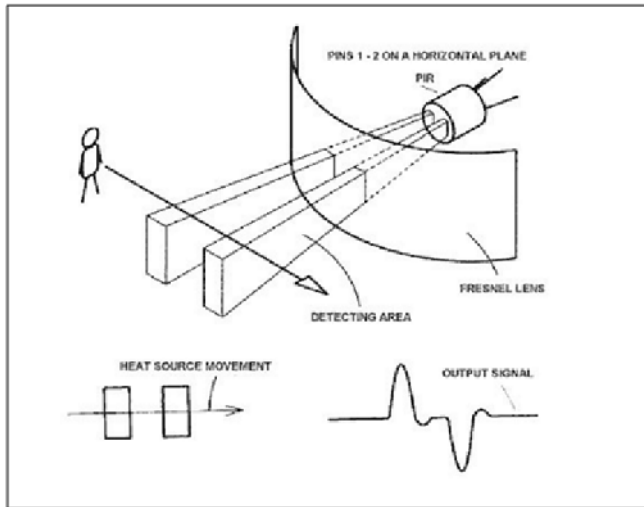
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- These change pulses are what is detected



Illustration of Working Principle



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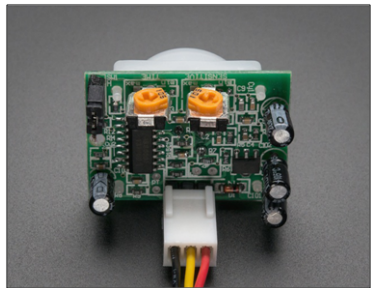


Connections of a PIR Sensor



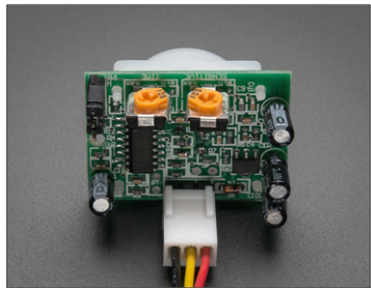
Connections of a PIR Sensor

- **+V** : This pin of the PIR sensor should be connected to an external 5V supply.



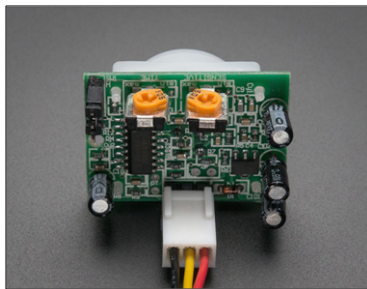
Connections of a PIR Sensor

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- **OUT** : This pin of the PIR sensor is the digital output. This pin is to be read by the microcontroller to detect the movement and decide the appropriate action that should be taken



Pin Connections between PIR Sensor and FireBird V Robot



Pin Connections between PIR Sensor and FireBird V Robot

Pins of PIR Sensor	Pins of ATmega2560 Microcontroller Board Expansion Socket
GND	Pin 23/24 (or any Ground pin)
+V	Pin 21/22 (or any 5 Volts pin)
Digital Output	Any GPIO Port Pin

Table: Pin Connections between PIR Sensor and FireBird V Robot



Jumper Settings



Jumper Settings

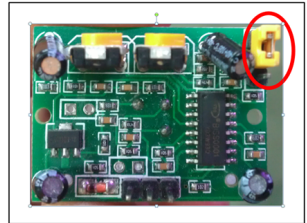
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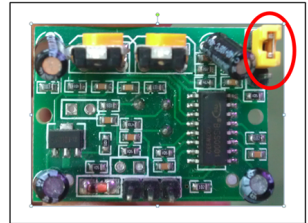
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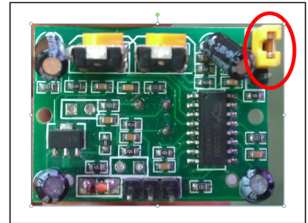
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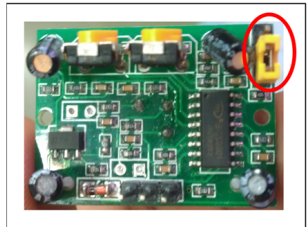
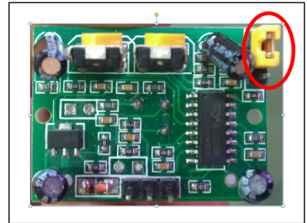
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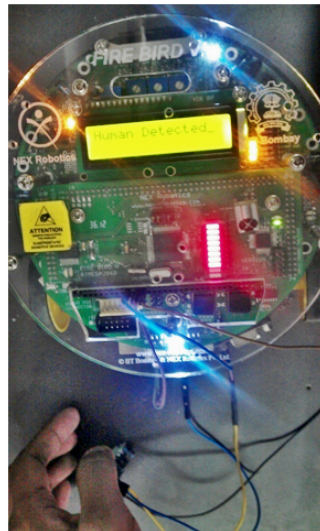
C Code



Output displayed on LCD & LED Bargraph



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Applications using PIR Sensor



Applications using PIR Sensor

- Human Detection Applications



Applications using PIR Sensor

- Human Detection Applications
- Thermal Imaging



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- Thermal Imaging
- Infrared Homing



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