

O.S LABORATORY

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SECTION: CSE - 16

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 Subject OPERATING SYSTEMS (OS LAB)

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LABORATORY
NO. 1

COMMANDS

- ① \$ pwd - shows the present working directory.
- ② \$ mkdir - used to create a directory
- ③ \$ touch filename - used to empty a file with 0 bytes
- ④ \$ cat > file1 - opens a file with name file1, creates file1 if it doesn't exist
- ⑤ \$ cat f1 f2 > f3 - concatenates f1 and f2 into f3
- ⑥ \$ cp file1 file2 → copies file1 contents into file2
- ⑦ \$ cp f1 f2 f3 → copies f1 and f2 into f3
- ⑧ \$ rm f1 → removes files and directories
- ⑨ \$ mv f1 f2 → renames file f1 to f2.
- ⑩ \$ mv t1 t2 t3 → moves t1 and t2 to t3.
- ⑪ \$ ls → lists all the files in the present directory.

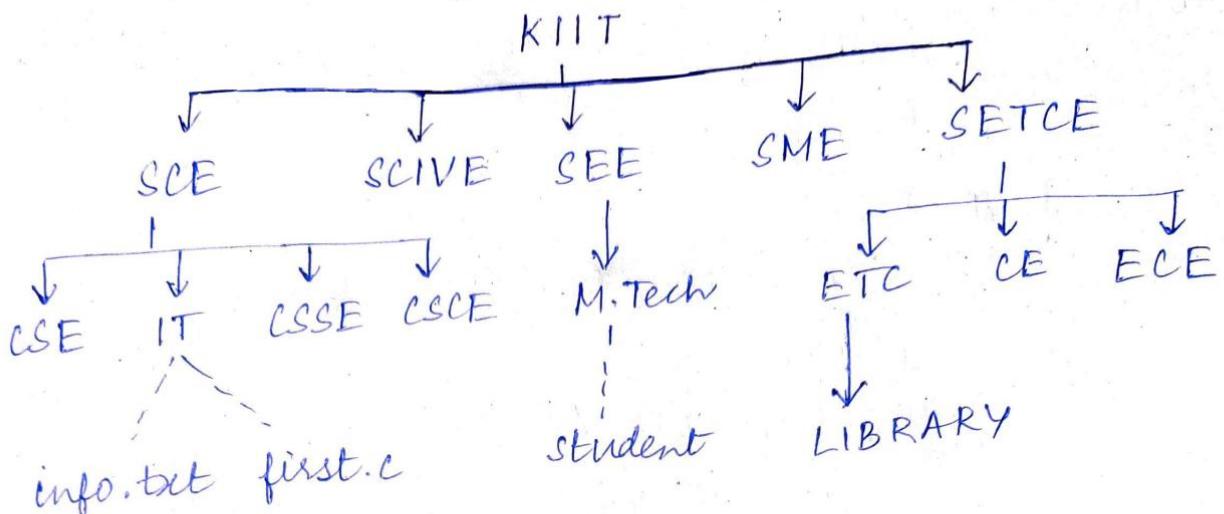
- (12) \$ ls -l → used to see the long listing of files and sub-directories inside current one.
- (13) \$ cd dir1 → changes directory to dir1.
- (14) \$ cd .. → moves back to the previous directory.
- (15) \$ chmod → used to change the mode to add or remove permissions of a particular file.
- (16) \$ bc → basic calculator, used to do operations which can be done using a calculator.
- (17) \$ sort f1 f2 f3 → used to sort multiple files.
- (18) \$ cut → a filter which cuts a given no. of char of fields from a specified file
- (19) \$ grep → searches specified input globally for a match, with the supplied pattern and display it.
- (20) \$ vi file1 / \$ gedit file1 → opens up the editor for a file, mostly used to write shell scripts into it.

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OS LABORATORY 1

Q. Create a directory 'Roll Number', under that.



a) Create files and directories according to the above structure:

\$ mkdir 2005643

\$ cd 2005643

\$ mkdir KIIT

\$ cd KIIT

\$ mkdir SCE SCIVE SEE SME SETCE

\$ cd SCE

\$ mkdir CSE IT CSSE CSCE

\$ cd IT

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\$ cat > info.txt

The name of this file is info.txt.

\$ cat > first.c

The name of this file is first.c

\$ cd ..

\$ cd ..

\$ cd SEE

\$ mkdir M.Tech

\$ cd M.Tech

\$ cat > student

The name of this file is student.

\$ cd ..

\$ cd ..

\$ cd SETCE

\$ mkdir ETC CE ECE

\$ cd ETC

\$ mkdir LIBRARY

\$ cd ..

\$ cd ..

b) Rename the file info.txt to itstudentdata.txt,

\$ cd SCE/IT

\$ mv info.txt itstudentdata.txt.

c) Copy the file first.c into directory CE with the same name:

\$ cp first.c /home/kiit/2005643/KIIT/SETCE/CE

d) Copy the file first.c into directory SME with a new name hello.c.

\$ cp first.c /home/kiit/2005643/KIIT/SME/hello.c

e) Transfer file student into SCIVE and check if transferred or not.

\$ cd ..

\$ cd ..

\$ cd SEE/M.Tech

\$ mv student /home/kiit/2005643/KIIT/SCIVE

\$ cd ..

\$ cd ..

\$ cd SCIVE

\$ ls

Student

LABORATORY
NO. 2

OS LABORATORY 2

Q1. Write a Shell Script (WASS) to do calculator program using Arithmetic operators.

PROGRAM CODE:

```
# to do the calculator program  
echo enter 2 numbers  
read a b  
c='expr $a + $b'  
d=$((a * b))  
e='expr $a - $b'  
f='expr $a / $b'  
echo Sum is $c  
echo Product is $d  
echo Difference is $e  
echo Quotient is $f
```

OUTPUT:

enter 2 numbers

10 5

Sum is 15

Product is 50

Difference is 5

Quotient is 2

Q2. WASS to find the average of 3 numbers.

PROGRAM CODE:

```
# TO find average of 3 numbers.  
echo Enter 3 numbers  
read a b c  
d='expr $a + $b + $c'  
e='expr $d / 3'  
echo Average of 3 numbers is $e
```

OUTPUT:

Enter 3 numbers

4 6 8

Average of 3 numbers is 6

Q3. WASS to find the Simple Interest, when P, R, T are given.

PROGRAM CODE:

```
# calculate the Simple Interest  
echo Enter P, R and T  
read P R T  
SI='expr $P \* $T \* $R / 100'  
echo Simple Interest is $SI
```

OUTPUT:

Enter P, R and T

2000 4 10

Simple Interest is 800.

Q4 WASS to find area of a triangle when base and height are given.

PROGRAM CODE:

```
# Area of a Triangle  
echo Enter base and height of Triangle  
read b h  
ar=$((b*h)/2))  
echo Area of Triangle is $ar.
```

OUTPUT:

Enter base and Height of Triangle

5 4

Area of Triangle is 10.

Q5 WASS to find area and circumference of a circle

PROGRAM CODE:

```
#Area and circumference of a circle  
echo Enter the Radius of circle  
read r  
ar=$(bc <<< "$r * $r * 3.14")  
c=$(bc <<< "2 * 3.14 * $r")  
echo circumference is $c  
echo Area is $ar.
```

OUTPUT

Enter the Radius of circle

5

circumference is 31.40

Area is 78.50

LABORATORY
NO. 3

OS LABORATORY - 3

Q1. WASS to calculate compound Interest when P, R, T are given.

PROGRAM CODE:

```
# program to calculate compound Interest
echo Enter values of P, R, T
read P R T
ci='echo "scale=2; $P*((1+$r*0.01)^$t)" | bc -l'
echo COMPOUND INTEREST is $ci
```

OUTPUT

Enter values of P, R, T

450 6.7 5

COMPOUND INTEREST IS 598.50

Q2. Calculate distance travelled by an object when acceleration, initial velocity and time are given.

PROGRAM CODE:

```
# calculate distance travelled by an object
```

echo Enter values of a, v, t

read a v t

s='echo "scale=2; (\$v * \$t) + (0.5 * \$a * \$t^2)" | bc -l'

echo DISTANCE travelled is \$s

OUTPUT

Enter values of a, v, t

4 6.6 7

DISTANCE travelled is 144.2

Q3 WASS to find the real roots of a quadratic equation

PROGRAM CODE:

to find real roots of quadratic equation

echo Enter a,b,c of polynomial

read a b c

```
r1='echo "scale=2; (-$b - sqrt($b * $b - 4 * $a * $c)) / (2 * $a)" | bc'
```

```
r2='echo "scale=2; (-$b + sqrt($b * $b - 4 * $a * $c)) / (2 * $a)" | bc'
```

echo The roots are \$r1 and \$r2

OUTPUT

Enter a,b,c of polynomial

1 11 30

The roots are -6.00 and -5.00

Q4 WASS to calculate area and perimeter of a rectangle.

PROGRAM CODE:

Area and Perimeter of a rectangle

echo Enter length and breadth

read l b

```
p='echo "scale=2; (2 * $l + 2 * $b)" | bc -l'
```

```
a='echo "scale=2; ($l * $b)" | bc -l'
```

echo Perimeter is \$p

echo Area is \$a

OUTPUT

Enter length and breadth

5.5 6

Perimeter is 23.0

Area is 33.0

Q5 WASS to convert Celsius to Fahrenheit

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PROGRAM CODE:

```
# Convert Celsius to Fahrenheit
echo Enter value of Celsius
read c
f='echo "scale=2; $c * (9/5) + 32" | bc -l '
echo The value of Fahrenheit is $f
```

OUTPUT:

Enter value of Celsius

32

The value of Fahrenheit is 89.60

LABORATORY

NO. 4

OS LABORATORY - 4.

- Q1. For an employee, if basic sal is less than 1500, then HRA = 10% of basic, DA = 90% of basic. If basic sal ≥ 1500 , HRA = 500, DA = 98%. Calculate Gross Sal using shell script.

PROGRAM CODE:

```
# to calculate gross salary of employee
echo Enter basic salary.
read s.
if [ $s -lt 1500 ]
then
    hra='echo "scale=2; (0.1 * $s)" | bc -l'
    da='echo "scale=2; (0.9 * $s)" | bc -l'
else
    hra=500
    da='echo "scale=2; (0.98 * $s)" | bc -l'
fi
g='echo "scale=2; ($s + $hra + $da)" | bc -l'
echo Gross Salary is $g
```

OUTPUT

Enter basic Salary

1800

Gross Salary is 4064.00

Q2. Find the greater between 2 numbers.

PROGRAM CODE:

```
#find greater between 2 numbers
echo Enter 2 numbers.
read a b
if test $a -lt $b
then
echo $b is greater than $a
else
echo $a is greater than $b
fi
```

OUTPUT

Enter 2 numbers.

5 6

6 is greater than 5

Q3 Find greatest of 3 numbers.

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PROGRAM CODE:

```
# NESTED IF ELSE
echo Enter 3 nos.
read a b c
if [ $a -gt $b ]
then
if [ $a -gt $c ]
then
echo $a is greatest
else
echo $c is greatest
fi
elif [ $b -gt $c ]
then
echo $b is greatest
else
echo $c is greatest
fi
```

OUTPUT

Enter 3 nos.

5 7 10

10 is greatest

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USING IF ELSE LADDER.

echo Enter 3 numbers.

read a b c

if [\$a -gt \$b -a \$a -gt \$c]

then

echo \$a is greatest

elif [\$b -gt \$a -a \$b -gt \$c]

then

echo \$b is greatest

else

echo \$c is greatest

fi

OUTPUT

Enter 3 numbers.

4 7 9

9 is greatest

Q4. To find if a number is odd or even

PROGRAM CODE:

```
# to find if odd or even
echo Enter a number
read x
p=`expr $x % 2`
if [ $p -eq 0 ]
then
    echo Even Number
else
    echo Odd Number.
fi
```

OUTPUT

```
Enter a number
5
Odd Number.
```

Enter a number

16

Even Number.

Q5 WASS to calculate electricity bill in different slabs.

PROGRAM CODE:

echo Enter number of units consumed

read n

if [\$n -lt 500]

then
bill = `echo "scale=2; \$n * 50 "/bc-l`

elif [\$n -eq 500 -a \$n -lt 1000]

then
bill = `echo "scale=2; \$n * 100 "/bc-l`

else
bill = `echo "scale=2; \$n * 150 "/bc-l`

fi

echo Bill is Rs \$bill .

OUTPUT :

Enter number of units consumed

650

Bill is 97500 .

Q6 WASS to find the real roots of a quadratic equation

PROGRAM CODE:

to find real roots of quadratic equation

echo Enter a,b,c of polynomial

read a b c

```
r1='echo "scale=2; (-$b - sqrt($b * $b - 4 * $a * $c))/(2 * $a)"|bc'  
r2='echo "scale=2; (-$b + sqrt($b * $b - 4 * $a * $c))/(2 * $a)"|bc'
```

echo The roots are \$r1 and \$r2

OUTPUT

Enter a,b,c of polynomial

1 11 30

The roots are -6.00 and -5.00

Q7 Check if a number is +ve, -ve or zero.

```
echo Enter the number  
read n  
if [ $n -lt 0 ]  
then  
echo NUMBER IS NEGATIVE  
elif [ $n -gt 0 ]  
then  
echo NUMBER IS POSITIVE  
else  
echo NUMBER is 0.  
fi
```

OUTPUT:

Enter the number

5

NUMBER IS POSITIVE

Enter the number

0

NUMBER IS 0

Enter the number

-5

NUMBER IS NEGATIVE

Q8 Show the days of the week from number which is input using case.

PROGRAM CODE:

```
echo Enter a number  
read n  
case $n in  
1)  
    echo Day is Monday  
;;  
2)  
    echo Day is Tuesday  
;;  
3)  
    echo Day is Wednesday  
;;  
4)  
    echo Day is Thursday  
;;  
5)  
    echo Day is Friday  
;;  
6)  
    echo Day is Saturday  
;;  
7)  
    echo Day is Sunday  
;;  
*)  
    echo WRONG INPUT  
;;  
esac.
```

OUTPUT:

Enter a number

5

Day is Friday

Q9. Enter an alphabet and check if it is vowel or consonant using case.

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PROGRAM CODE :

```
echo Enter an Alphabet
read $s
case $s in
    a)
        echo Alphabet is vowel
        ;;
    e)
        echo Alphabet is vowel
        ;;
    i)
        echo Alphabet is Vowel
        ;;
    o)
        echo Alphabet is Vowel
        ;;
    u)
        echo Alphabet is Vowel
        ;;
*)
    echo Alphabet is consonant
    ;;
esac
```

OUTPUT :

Enter an alphabet

f

Alphabet is consonant

Enter an alphabet

u

Alphabet is vowel.

Q10. Implement Simple Calculator using
switch case.

PROGRAM CODE:

```
echo Enter 2 numbers
read a b
echo 1 for ADD
echo 2 for SUBTRACT
echo 3 for MULTIPLY
echo 4 for DIVIDE
echo 5 for MODULUS

read c
case $c in
  1)
    c='expr $a + $b'
    echo SUM is $c
    ;;
  2)
    c='expr $a - $b'
    echo DIFFERENCE is $c
    ;;
  3)
    c='expr $a * $b'
    echo PRODUCT is $c
    ;;
  4)
    c='expr $a / $b'
    echo QUOTIENT is $c
    ;;
  5)
    c='expr $a % $b'
    echo MODULUS is $c
    ;;
  *)
    echo WRONG INPUT
    ;;
esac
```

OUTPUT:

Enter 2 numbers.

5 8

1 for ADD

2 for SUBTRACT

3 for MULTIPLY

4 for DIVIDE

5 for MODULUS

3

PRODUCT is 40

Enter 2 numbers.

5 8

1 for ADD

2 for SUBTRACT

3 for MULTIPLY

4 for DIVIDE

5 for MODULUS

1

SUM is 13

LABORATORY
NO. 5

OS LABORATORY 5

Q1. WASS to check if a given number is prime or not.

while loop.

```
echo Enter a number
read n
i=2
f=0
while [ $i -le `expr $n / 2` ]
do
if [ `expr $n % $i` -eq 0 ]
then
f=1
fi
i=`expr $i + 1`
done
if [ $f -eq 1 ]
then
echo NOT PRIME
else
echo PRIME
fi
```

until loop

```
echo Enter a number
read n
i=2
f=0
until [ $i -gt `expr $n / 2` ]
do
if [ `expr $n % $i` -eq 0 ]
then
f=1
fi
i=`expr $i + 1`
done
if [ $f -eq 1 ]
then
echo NOT PRIME
else
echo PRIME
fi
```

OUTPUT

Enter a number

5

PRIME

Enter a number

6

NOT PRIME

Q2 WASS to find the reverse of a number

PROGRAM CODE:

```
# using while loop  
echo Enter a number  
read n  
rev=0  
p=0  
while [ $n -gt 0 ]  
do  
p='expr $n % 10'  
rev='expr $rev \* 10 + $p'  
n='expr $n / 10'  
done  
echo Reverse Number $rev echo Reverse Number $rev
```

```
# using until loop  
echo Enter a number  
read n  
rev=0  
p=0  
until [ $n -le 0 ]  
do  
p='expr $n % 10'  
rev='expr $rev \* 10 + $p'  
n='expr $n / 10'  
done  
echo Reverse Number $rev echo Reverse Number $rev
```

OUTPUT:

Enter a number
567
Reverse Number 765

Enter a number
235
Reverse Number 532

Q3 WASS to find sum of digits of a number

PROGRAM CODE:

```
# using while loop
echo Enter a number
read num
sum=0
while [ $num -gt 0 ]
do
mod='expr $num % 10'
sum='expr $sum + $mod'
num='expr $num / 10'
done
echo Sum is $sum.
```

```
# using until loop
echo Enter a number
read num
sum=0
until [ $num -le 0 ]
do
mod='expr $num % 10'
sum='expr $sum + $mod'
num='expr $num / 10'
done
echo Sum is $sum.
```

OUTPUT:

Enter a number

234

Sum is 9.

Enter a number

532

Sum is 10.

Q4 WASS to find factorial of a number

PROGRAM CODE:

```
echo Enter a number
read num
f=1
while [ $num -gt 1 ]
# until [ $num -le 1 ]
do
f=`expr $num - 1`
done
echo $f is the factorial
```

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OUTPUT:

Enter a number

5

120 is the factorial

Q5. WASS to check if a number is a palindrome or not.

PROGRAM CODE:

```
echo Enter a number
read n
z=$n
rev=0
p=0
while [ $n -gt 0 ]
# until [ $n -le 0 ]
```

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```
do  
    p='expr $n % 10'  
    rev='expr $rev * 10 + $p'  
    n='expr $n / 10'  
done  
if [ $z -eq $rev ]  
then  
    echo PALINDROME  
else  
    echo NOT PALINDROME
```

OUTPUT:

① Enter a number

10101

PALINDROME

② Enter a number

11000

NOT PALINDROME

LABORATORY
NO. 6

OS LABORATORY 6

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Q1 Write shell script to print array elements in reverse order.

PROGRAM CODE:

```
echo Enter the size of Array
```

```
read n
```

```
i=0
```

```
while [ $i -lt $n ]
```

```
do
```

```
read a[$i]
```

```
i='expr $i + 1'
```

```
done
```

```
echo Reverse Array is :
```

```
i=$n
```

```
while [ $i -ge 0 ]
```

```
do
```

```
echo ${a[$i]}
```

```
i='expr $i - 1'
```

```
done
```

OUTPUT:

```
$ bash Array-Reverse  
Enter the size of the Array
```

```
5
```

```
1
```

```
2
```

```
3
```

```
4
```

```
6
```

```
Reverse Array is :
```

```
6
```

```
4
```

```
3
```

```
2
```

```
1
```

Q2 WASS to find largest of array elements

PROGRAM CODE:

```
echo Enter size:  
read n  
i=0  
while [ $i -lt $n ]  
do  
    read a[$i]  
    i=`expr $i + 1`  
done  
max=${a[0]}  
for i in ${a[@]}  
do  
    if [[ "$i" -gt "$max" ]]  
then  
    max=$i  
fi  
done  
echo Largest element: $max
```

OUTPUT:

```
$ bash Array-max  
Enter size  
3  
2  
7  
5  
Largest element: 7
```

Q3. WASS to find sum of odd and even numbers in an array.

PROGRAM CODE:

echo Enter the size of the Array:

read n

```
i=0  
while [ $i -lt $n ]  
do  
    read a[$i]  
    i=`expr $i + 1`  
done  
even=0  
odd=0  
i=0
```

```

while [ $i -lt $n ]
do
if [ `expr ${a[$i]} \% 2` -eq 0 ]
then
even =`expr ${a[$i]} + $even`
else
odd =`expr ${a[$i]} + $odd`
fi
i=`expr $i + 1`
done
echo Sum of odd Numbers is $odd
echo Sum of even Numbers is $even

```

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OUTPUT :

\$ bash Array-oddevensum

Enter the size of Array:

4
2
5
6
7

Sum of Odd Numbers is 12

Sum of Even Numbers is 8

Q4. Write a program to search particular element in array.

PROGRAM CODE :

echo Enter number of elements.

read n

echo Enter the Array elements.

i=1

while [\$i -le \$n]

do

read a[\$i]

i='expr \$i + 1'

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done

echo Enter element to be searched

read x

j=1

while [\$j -lt \$n -a \$item -ne \${a[\$j]}]

do

j='expr \$j + 1'

done

if [\$item -eq \${a[\$j]}]

then

echo \$item is at position \$j

else

echo \$item is not present in array

fi

OUTPUT:

Enter the number of elements.

5

Enter the array elements:

2

10

5

3

11

Enter the element to be searched

10

10 is present at location 2.

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Q5. WASS to sort an Array.

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PROGRAM CODE:

```
# sorting an array with Bubble Sort
echo Enter size:
read n
i=0
while [ $i -lt $n ]
do
    read a[$i]
    i='expr $i + 1'
done
i=0
while [ $i -lt $n ]
do
    c='expr $n - $i - 1'
    j=0
    while [ $j -lt $c ]
    do
        if [ ${a[$j]} -gt ${a[$j+1]} ]
        then
            t=${a[$j]}
            a[$j]=${a[$j+1]}
            a[$j+1]=$t
        fi
        j='expr $j + 1'
    done
    i='expr $i + 1'
done
echo Sorted Array:
while [ $i -lt $n ]
do
    echo ${a[$i]}
    i='expr $i + 1'
done
```

OUTPUT:

Enter size

3

2
7
3

Sorted Array :

2

3

7

LABORATORY
NO. 7

Q1. Write a program to implement FCFS algorithm using C.

```
#include <stdio.h>
void findWaitingTime(int processes[], int n,
                     int bt[], int wt[])
{
    wt[0] = 0;
    for (int i=0; i<n; i++)
        wt[i] = bt[i-1] + wt[i-1];
}

void findTurnAroundTime(int processes[],
                        int n, int bt[], int wt[],
                        int tat[])
{
    for (int i=0; i<n; i++)
        tat[i] = bt[i] + wt[i];
}

void findavgTime(int processes[], int n,
                  int bt[])
{
    int wt[n], tat[n], total_wt = 0;
    int total_tat = 0;
    findWaitingTime(processes, n, bt, wt);
    findTurnAroundTime(processes, n, bt, wt, tat);
    printf("\nProcesses | Burst Time | Waiting Time\n"
           " | Turn Around Time|\n");
    for (int i=0; i<n; i++)
    {
        total_wt = total_wt + wt[i];
        total_tat = total_tat + tat[i];
        printf(" %d ", (i+1));
    }
}
```

```
printf("\t | %d", bt[i]);
```

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```
printf("\t | %.d", wt[i]);
```

```
printf("\t | %.d\n", tat[i]);
```

```
}
```

```
int s = (float) total_wt / (float) n;
```

```
int t = (float) total_tat / (float) n;
```

```
printf("\n Avg. Waiting Time = %.d", s);
```

```
printf("\n Avg. Turn Around Time = %.d", t);
```

```
}
```

```
int main()
```

```
{ int processes[10], burst_time[10], n;
```

```
printf("Enter number of processes : ");
```

```
scanf("%d", &n);
```

```
for (int i=0; i<n; i++)
```

```
processes[i] = i+1;
```

```
printf("Enter burst times of %d processes : ",
```

n);

```
for (int i=0; i<n; i++)
```

```
{ int p=0;
```

```
scanf("%d", &p);
```

```
burst_time[i] = p;
```

```
}
```

```
findavgTime(processes, n, burst_time);
```

```
return 0;
```

OUTPUT: (FCFS Algorithm)

Enter the number of processes : 3

Enter burst times of 3 processes : 4 5 8

Processes	Burst Time	Waiting Time	TA Time
1	4	0	4
2	5	4	9
3	8	9	17

$$\text{Average Waiting Time} = 4$$

$$\text{Average Turnaround Time} = 10$$

Q2. Write a program in C to implement the SJF algorithm of scheduling.

```
#include <stdio.h>
int main()
{
    int bt[20], p[20], wt[20], tat[20], i, j;
    int n, total=0, pos, temp;
    float avg_wt, avg_tat;
    printf("Enter number of processes : ");
    scanf("%d", &n);
    printf("Enter Burst Time : \n");
    for(i=0; i<n; i++)
    {
        printf("p%d : ", i+1);
        scanf("%d", &bt[i]);
        p[i] = i+1;
    }
    for(i=0; i<n; i++)
    {
        pos = i;
        for(j=i+1; j<n; j++)
        {
            if(bt[j] < bt[pos])
                pos = j;
        }
        temp = bt[i];
        bt[i] = bt[pos];
        bt[pos] = temp;
        temp = p[i];
        p[i] = p[pos];
        p[pos] = temp;
    }
}
```

wt[0] = 0;

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for (i=1; i<n; i++)

{ wt[i] = 0;

 for (j=0; j < i; j++)

 { wt[i] += bt[j]; }

 total += wt[i];

}

avg-wt = (float) total / n;

total = 0;

printf ("\\nProcess Burst Time \\t Waiting Time
 \\t Turn Around Time");

for (i=0; i<n; i++)

{ tat[i] = bt[i] + wt[i];

 total += tat[i];

printf ("\\np%\\d \\t \\t %\\d \\t \\t
 %\\d \\t \\t \\t %\\d", p[i], bt[i], wt[i],
 tat[i]);

}

avg-tat = (float) total / n;

printf ("\\n\\n");

printf ("Average Waiting Time = %.f",
 avg-wt);

printf ("\\n");

printf ("Average Turn Around Time = %.f",
 avg-tat);

OUTPUT : (SJF Algorithm)

Enter number of processes : 3

Enter Burst Times :

P1 : 4

P2 : 5

P3 : 8

Process	Burst Time	Waiting Time	Turn Around Time
P1	4	0	4
P2	5	4	9
P3	8	9	17

$$\text{Average Waiting Time} = 4.333333$$

$$\text{Average Turn Around Time} = 10.000000$$

LABORATORY
NO. 8

Q1. Write a program in C to implement SRTF scheduling Algorithm.

```
#include <stdio.h>
int main()
{ int at[10], bt[10], rt[10], endTime, smallest;
int remain=0, i, n, time, sumWait=0;
int sumTurnaround=0;
printf("Enter number of processes : ");
scanf("%d", &n);
for(i=0; i<n; i++)
{
    printf("Enter arrival time for P%d : ", i+1);
    scanf("%d", &at[i]);
    printf("Enter burst time for P%d : ", i+1);
    scanf("%d", &bt[i]);
    rt[i] = bt[i];
}
printf("\n\nProcess | Turn Around Time |  
Waiting Time |\n");
rt[9] = 9999;
for(time=0; remain!=n; time++)
{
    smallest = 9;
    for(i=0; i<n; i++)
    {
        if(at[i] <= time && rt[i] < rt[smallest]
        && rt[i] > 0)
        {
            smallest = i;
        }
    }
    rt[smallest] = rt[smallest] - 1;
    if(rt[smallest] == 0)
        remain--;
}
```

}

at[smallest] --;

if (at[smallest] == 0)

 remain++;

endTime = time + 1;

printf ("%P[%d]\t|\t%.\d\t|\t%.\d",
 smallest + 1, endTime - at[smallest],
 endTime - at[smallest] - bt[smallest]);

sum_wait += endTime - bt[smallest]
 - at[smallest];

sum_turnaround += endTime -
 at[smallest];

}

}

printf ("\n\n");

printf ("Average Waiting Time = %.f\n",
 sum_wait * 1.0 / n);

printf ("\n");

printf ("Average Turnaround Time = %.f\n",
 sum_turnaround * 1.0 / n);

return 0;

OUTPUT: (SRTF Algorithm)

Enter no. of Processes : 3

Enter Arrival Time of Process P1 : 1

Enter Burst Time for Process P1 : 4

Enter Arrival Time for Process P2 : 2

Enter Burst Time for Process P2 : 5

Enter Arrival Time for Process P3 : 3

Enter Burst Time for Process P3 : 8

Process	Turn Around Time	Waiting Time
P[1]	4	0
P[2]	8	3
P[3]	15	7

Average Waiting Time = 3.333333

Average Turn Around Time = 5.400000

Q2. WAP to implement Round Robin Scheduling Algorithm in C.

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```
#include <stdio.h>
int main()
{ int i, limit, total=0, x, counter=0;
int time_quantum, wait_time=0;
int turnaround_time=0, arrival_time[10];
int burst_time[10], temp[10];
float average_wait_time;
float average_turnaround_time;
printf ("\nEnter Total Number of Processes : \t");
scanf ("%d", &limit);
x=limit;
for (i=0; i<limit; i++)
{ printf ("Enter details of Process [%d]\n", i+1);
printf ("Arrival Time : \t");
scanf ("%d", &arrival_time[i]);
printf ("Burst Time : \t");
scanf ("%d", &burst_time[i]);
temp[i]=burst_time[i];
}
printf ("\nEnter Time quantum : \t");
scanf ("%d", &time_quantum);
printf ("\nProcess ID \t\t Burst Time \t\t Turn Around Time \t\t Waiting Time\n");
for (total=0, i=0; x!=0; )
{ if (temp[i]<=time_quantum && temp[i]>0)
```

```

    total = total + temp[i];
    temp[i] = 0;
    counter = 1;
}

else if (temp[i] > 0)
{
    temp[i] = temp[i] - time quantum;
    total = total + time quantum;
}

if (temp[i] == 0 && counter == 1)
{
    x--;
    printf("In Process [%d]\t%d\t%d\t%d
           \t%d\t%d", i+1, burst_time[i],
           total - arrival_time[i],
           total - arrival_time[i] - burst_time[i]);
}

wait_time = wait_time + total - burst_time[i]
           - arrival_time[i];

turnaround_time = turnaround_time +
           total - arrival_time[i];

counter = 0;

if (i == limit - 1) i = 0;
else if (arrival_time[i+1] <= total) i++;
else i = 0;

average_wait_time = wait_time * 1.0 / limit;
average_turnaround_time = turnaround_time *
           * 1.0 / limit;

printf("Average Waiting Time : %f",
       average_wait_time);
printf("Avg Turnaround Time : %f",
       average_turnaround_time);
return 0;
}

```

OUTPUT : (Round Robin Algorithm)

Enter Total Number of Processes : 3

Enter details of Process [1]

Arrival Time : 1

Burst Time : 4

Enter details of Process [2]

Arrival Time : 2

Burst Time : 5

Enter details of Process [3]

Arrival Time : 3

Burst Time : 8

Enter Time Quantum : 3

Process Id	Burst Time	Turnaround Time	Waiting Time
Process [1]	4	9	5
Process [2]	5	10	5
Process [3]	8	14	6

Average Waiting Time : 5.33333
Average Turnaround Time : 11.00000

Q3. WAP to implement Priority Scheduling Algorithm using c programming.

```
#include <stdio.h>
#include <string.h>
int main()
{
    int et[20], at[10], n, i, j, temp, p[10], st[10];
    int ft[10], wt[10], ta[10], totwt = 0, totta = 0;
    float awt, ata;
    char pn[10][10], t[10];
    printf ("Enter the number of processes :");
    scanf ("%d", &n);
    for(i=0; i<n; i++)
    {
        printf ("Enter process name, arrival time,\n
                execution time and priority :");
        scanf ("%s %d %.d %.d", pn[i], &at[i],
               &et[i], &p[i]);
    }
    for(i=0; i<n; i++)
    {
        for(j=0; j<n; j++)
        {
            if(p[i] < p[j])
            {
                temp = p[i];
                p[i] = p[j];
                p[j] = temp;
                temp = at[i];
                at[i] = at[j];
                at[j] = temp;
                temp = et[i];
                et[i] = et[j];
                et[j] = temp;
                strcpy(t, pn[i]);
                strcpy(pn[i], pn[j]);
                strcpy(pn[j], t);
            }
        }
    }
}
```

```

for(i=0; i<n; i++)
{
    if (i==0)
    {
        st[i] = at[i];
        wt[i] = st[i] - at[i];
        ft[i] = st[i] + et[i];
        ta[i] = ft[i] - at[i];
    }
    else
    {
        st[i] = ft[i-1];
        wt[i] = st[i] - at[i];
        ft[i] = st[i] + et[i];
        ta[i] = ft[i] - at[i];
    }
    totwt += wt[i];
    totta += ta[i];
}
awt = (float)totwt/n;
ata = (float)totta/n;
printf("\n Pname \t Arrival Time \t Execution Time
       \t Priority \t Waiting Time \t TA Time");
for(i=0; i<n; i++)
printf("\n %s \t %.5d \t %.5d \t %.5d \t %.5d
       \t %.5d \t %.5d", pn[i], at[i],
et[i], p[i], wt[i], ta[i]);
printf("\n Average Waiting Time is : %.2f", awt);
printf("\n Average Turnaround Time is : %.2f", ata);
return 0;

```

OUTPUT: (Priority Scheduling Algorithm)

Enter number of processes: 3

Enter process, AT, ET and priority : 1 2 3 4

Enter process, AT, ET and priority : 2 3 4 5

Enter process, AT, ET and priority : 3 4 5 6

Pname	Arrival	Execution	Priority	Waiting	TA
1	2	3	4	0	3
2	3	4	5	2	6
3	4	5	6	3	10

Average Waiting Time : 2.333333

Average Turn Around Time : 6.333333

LABORATORY
NO. 9

NOTES:Process Creation Using Fork System Call.

- Fork system call is used for creation of child process. If fork is successfully executed, then its going to create a new child process, by duplicating call of parent process.
- Child Process and Parent Process run in separate memory spaces. At the time of fork, both memory space have same content.
- Child Process is the exact duplicate of Parent Process, except Child has its own PID, which doesn't match with the ID of any existing process group.

Header Files \rightarrow <sys/types.h>, <unistd.h>

Predefined Data Type \rightarrow pid_t \rightarrow value.

$q < 0 \rightarrow$ error

$q == 0 \rightarrow$ child process

$q = \text{fork}(); \rightarrow$ gives the value.

$q > 0 \rightarrow$ Parent Process

getpid() \rightarrow gives ID of current process

getppid() \rightarrow gives ID of parent process

Wait System Call in C

- A call to wait function blocks the calling process until one of its child process terminates or a signal is received.
- After child process terminates, parent process continues its execution, after wait system call instruction. If any process has more than 1 CP, then after calling wait(), parent process has to be in waiting state, if no child terminates. If only 1 child process is terminated, then wait() returns the pid of terminated child process. If many CP are terminates, it returns PID of any arbitrary child. If no CP is terminated, returns (-1). When wait returns, it also defines its exit status by a pointer.

Q1. Write a program to find sum of even numbers in parent process and sum of odd numbers in child process.

PROGRAM CODE:

```
#include <stdio.h>
#include <unistd.h>

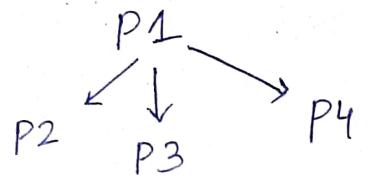
int main()
{
    int a[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10};
    int sumOdd = 0, sumEven = 0, n, i;
    n = fork();
    if (n > 0)
    {
        for (i = 0; i < 10; i++)
        {
            if (a[i] % 2 == 0)
                sumEven = sumEven + a[i];
        }
        printf("Parent Process: ");
        printf("Sum of even no.s is: %d\n", sumEven);
    }
    else
    {
        for (i = 0; i < 10; i++)
        {
            if (a[i] % 2 != 0)
                sumOdd = sumOdd + a[i];
        }
        printf("Child Process: ");
        printf("Sum of Odd nos. is: %d", sumOdd);
    }
    return 0;
}
```

OUTPUT:

Parent Process : Sum of Even nos. is : 30

58 Child Process : Sum of Odd nos. is : 25.

Q2 Create Process Tree using Fork System Call.



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PROGRAM CODE:

```
#include <stdio.h>
#include <sys/types.h>
#include <unistd.h>
#include <wait.h>

int main()
{
    pid_t q;
    for(int i=0 ; i<3 ; i++)
    {
        q = fork();
        if(q==0)
        {
            break;
        }
    }
    printf("Child PID - %d\n", getpid());
    printf("Parent PID - %d\n\n", getppid());
    wait(NULL);
    return 0;
}
```

OUTPUT:

Child PID - 24187

Parent PID - 24180

Child PID - 24188

Parent PID - 24187

Child PID - 24190

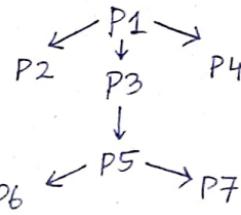
Parent PID - 24187

Child PID - 24189

59 Parent PID - 24187

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Q3. Create process tree using fork system call.



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PROGRAM CODE:

```
#include < stdio.h>
#include < sys/types.h>
#include < unistd.h>
#include < wait.h>

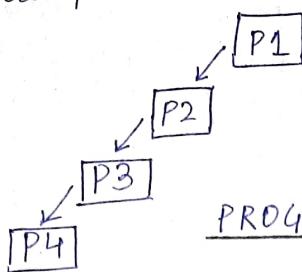
int main()
{
    pid_t q1, q2, q3;
    for(int i=0; i<3; i++)
    {
        q1 = fork();
        if(q1==0)
        {
            if(i==1)
                q2 = fork();
            if(q2>0) break;
            else
                for(int j=0; j<2; j++)
                {
                    q3 = fork();
                    if(q3==0) break;
                }
            break;
        }
        break;
    }
    printf("Pid - %d and PPid - %d\n",
           getpid(), getppid());
    wait(NULL);
    return 0;
}
```

OUTPUT:

Pid - 15676 and PPid - 15675
Pid - 15675 and PPid - 15668
Pid - 15677 and PPid - 15675
Pid - 15678 and PPid - 15675
Pid - 15679 and PPid - 15677
Pid - 15681 and PPid - 15679
Pid - 15680 and PPid - 15679

Q4 Create process tree using fork system call.

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PROGRAM CODE:

```
#include <stdio.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <unistd.h>

int main()
{
    pid_t p, c1, c2;
    printf("parent pid = %d\n", getpid());
    p = fork();
    if (p < 0) printf("error");
    else if (p == 0)
        printf("child-1 pid = %d, ppid = %d\n",
               getpid(), getppid());
    c1 = fork();
    if (c1 == 0)
        printf("child-2 pid = %d, ppid = %d\n",
               getpid(), getppid());
    c2 = fork();
    if (c2 == 0)
        printf("child-3 pid = %d, ppid = %d\n",
               getpid(), getppid());
    }
    else wait(NULL);
}
else wait(NULL);
}
else wait(NULL);
return 0;
}
```

OUTPUT :

```
parent pid = 5565
child-1 pid = 5569, ppid = 5565
child-2 pid = 5570, ppid = 5569
child-3 pid = 5571, ppid = 5570
```

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LABORATORY
NO. 10

NOTES:Pipe System Call : Process Communication

- A pipe is a technique used for interprocess communication. It is a mechanism by which the output of one process is directed towards the other. Thus it provides one way flow of data between related processes.
- Although pipe can be accessed as an ordinary file system, actually it occurs as a FIFO queue. A pipe file is created using pipe() system call. A pipe has an input end and output end. One can write into a pipe from input end, and read from output end.
- A pipe descriptors has an array that stores 2 pointers. (one for input, one for output) Input and Output end (we need to get location) so pointer is needed to access them.

Suppose 2 process A and B needs to communicate. In such case, it is important that process which writes, closes its read end, of the pipe, and process which reads closes its write end of the pipe. Essentially, for communication of A to B, process A should keep write end open and read end closed, (vice versa for B)

- Pipe is given fixed size in bytes. When a process attempts to write input to a pipe, the write request is immediately accessed if pipe is full, If full, the process is blocked, unless state of pipe changes.
- Only one process can be accessed at a time.

Limitations

- As a channel of communications, pipes operate in one direction only.
- Pipe cannot support broadcast (at a time, multiple processes not allowed)
- Read end, reads anyway (doesn't matter which process is connected to right end of pipe). So it is an insecure mode of communication.

* `#include <unistd.h>`

```
int pipe(int pipedes[2]);
```

The pipe system call has 2 pipedes:

`pipedes[0]` → Reading, `pipedes[1]` → writing

This call returns 0 as success, -1 as failure

To know the cause of failure, we can use error no. with `errno` variable or `perror` function

`#include <sys/types.h>`

`#include <sys/stat.h>`

① `#include <fcntl.h>`

```
int open(const char * pathname, int flags);
```

```
int open(const char * pathname, int flags,  
mode_t mode);
```

Even though the basic operations for file are read and write, it is essential to open the file before performing the operations and closing the file after completion of reqd. opt.

- By default, 3 descriptors opened for every process, used for input (standard input `stdin`) output (`stdout`) and error (`stderr`) having file descriptors 0, 1, 2 resp.

② `#include <unistd.h>`

```
int close(int fd)
```

The above system call closes already opened file descriptor. This implies the file is no longer in

use and resources associated can be reused by any other process.

System call return 0 on success.
return -1 on error.

include <unistd.h>

③

ssize_t write(int fd, void *buf, size_t count);

Above system call is used to write from specified file with arguments of file descriptor fd, proper buffer with allocated memory (static or dynamic) and size of buffer.

error : errno, perror; ;

④ # include <unistd.h>

size_t read(int fd, void *buf, size_t count)

File needs to be opened before writing to the file, automatically opens in case of calling pipe() sys. call.

Returns no. of bytes read (or zero in case of EOF) on success and -1 in failure.

error : errno, perror; ;

Q Write Algorithm to read and write 2 messages using pipe();

1. Create pipe
2. Send a message to the pipe.
3. Retrieve msg from pipe and write to stdout.
4. Repeat 2 and 3 steps

Q. Write Algorithm to do the above using parent child process.

1. Create pipe
2. Create child
3. Parent process writes to pipe
4. Child retrieves msg from pipe and writes to stdout

65. Repeat 3 and 4 steps

Q1. Read and Write 2 messages using pipe() system call

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PROGRAM CODE :

```
#include <stdio.h>
#include <unistd.h>
int main()
{
    int pipefds[2];
    int returnstatus;
    char writemessages[2][20] = {"ABC", "DEF"};
    char readmessage[20];
    returnstatus = pipe(pipefds);
    if (returnstatus == -1)
        printf("Unable to create pipe\n");
    return 1;
}
printf("Writing to pipe - Message 1 is %s\n",
       writemessages[0]);
write(pipefds[1], writemessages[0],
      sizeof(writemessages[0]));
read(pipefds[0], readmessage,
      sizeof(readmessage));
printf("Reading from pipe - Message 1 is %s\n",
       readmessage);
printf("Writing to pipe - Message 2 is %s\n",
       writemessages[1]);
write(pipefds[1], writemessages[1],
      sizeof(writemessages[1]));
read(pipefds[0], readmessage, sizeof(readmessage));
printf("Reading from pipe - Message 2 is %s\n",
       readmessage);
return 0;
}
```

OUTPUT

Writing to pipe - Message 1 is ABC
Reading from pipe - Message 1 is ABC
Writing to pipe - Message 2 is DEF
Reading to pipe - Message 2 is DEF

Q2. Read and Write 2 messages through parent child process.

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PROGRAM CODE :

```
#include <stdio.h>
#include <unistd.h>

int main()
{
    int pipefds[2]; returnstatus, pid;
    char writemessages[2][20] = {"Anirban", "Hazra"};
    char readmessage[20];
    returnstatus = pipe(pipefds);
    if (returnstatus == -1)
        printf("Unable to create pipe\n");
    return 1;
}

pid = fork();
if (pid == 0) // Child Process
{
    read(pipefds[0], readmessage, sizeof(readmessage));
    printf("Child Process: Reading : Message1 is %s\n",
          readmessage);
    read(pipefds[0], readmessage, sizeof(readmessage));
    printf("Child Process: Reading : Message2 is %s\n",
          readmessage);
}
else // Parent Process
{
    printf("Parent Process: Writing : Message1 is %s\n",
          writemessages[0]);
    write(pipefds[1], writemessages[0], sizeof(
          writemessages[0]));
    printf("Parent Process: Writing : Message2 is %s\n",
          writemessages[1]);
    write(pipefds[1], writemessages[1], sizeof(
          writemessages[1]));
}
return 0;
}
```

OUTPUT

Parent Process: Writing : Message 1 is Anirban
Parent Process: Writing : Message 2 is Hazra

Child Process: Reading : Message 1 is Anirban
Child Process: Reading : Message 2 is Hazra

LABORATORY
NO. 11

LABORATORY - 11

Inter Process Communication Using Pipe

- Q1. WAP in C to read and write a message using pipe() func.

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PROGRAM CODE :

```
#include <stdio.h>
#include <unistd.h>

int main()
{
    int pipefds[2], returnstatus;
    char writemessages[1][20] = {"Anirban"};
    char readmessage[20];
    returnstatus = pipe(pipefds);
    if (returnstatus == -1)
        printf("Unable to create pipe\n");
    return 1;
}
printf("Writing to pipe - Message 1 is %s\n",
       writemessages[0]);
write(pipefds[1], writemessages[0],
      sizeof(writemessages[0]));
read(pipefds[0], readmessage, sizeof(
      readmessage));
printf("Reading from pipe - Message 1 is %s\n",
       readmessage);
return 0;
}
```

OUTPUT :

Writing to pipe - Message 1 is Anirban

Reading from pipe - Message 1 is Anirban

Q2. Read and Write 2 messages using pipe system call.

PROGRAM CODE :

```
#include <stdio.h>
#include <unistd.h>
int main()
{
    int pipefds[2];
    int returnstatus;
    char writemessages[2][20] = {"ABC", "DEF"};
    char readmessage[20];
    returnstatus = pipe(pipefds);
    if (returnstatus == -1)
        printf("Unable to create pipe\n");
    return 1;
}
printf("Writing to pipe - Message 1 is %.s\n",
       writemessages[0]);
write(pipefds[1], writemessages[0],
      sizeof(writemessages[0]));
read(pipefds[0], readmessage,
     sizeof(readmessage));
printf("Reading from pipe - Message 1 is %.s\n",
       readmessage);
printf("Writing to pipe - Message 2 is %.s\n",
       writemessages[1]);
write(pipefds[1], writemessages[1],
      sizeof(writemessages[1]));
read(pipefds[0], readmessage, sizeof(readmessage));
printf("Reading from pipe - Message 2 is %.s\n",
       readmessage);
return 0;
}
```

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OUTPUT

Writing to pipe - Message 1 is ABC
 Reading from pipe - Message 1 is ABC
 Writing to pipe - Message 2 is ABC
 Reading to pipe - Message 2 is DEF

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Q3. WAP in C, in which read a message through pipe(), parent process writes message into pipe and child process retrieves and displays it.

PROGRAM CODE:

```
#include <stdio.h>
#include <unistd.h>

int main()
{
    int pipefds[2], returnstatus, pid;
    char writemessages[1][20] = {"Anirban"};
    char readmessage[20];
    returnstatus = pipe(pipefds);
    if (returnstatus == -1)
        printf("Unable to create pipe\n");
    return 1;
}

pid = fork();
if (pid == 0) // Child Process
{
    read(pipefds[0], readmessage, sizeof(readmessage));
    printf("Child Process - Reading from pipe:\n"
           "Message 1 is %s\n", readmessage);
}

else // Parent Process
{
    printf("Parent Process - Writing to pipe:\n"
           "Message 1 is %s\n", writemessages[0]);
    write(pipefds[1], writemessages[0], sizeof(writemessage[0]));
}
```

}

return 0;

OUTPUT:

Parent Process : Reading from Pipe: Message 1 is Anirban
Child Process : Writing to pipe: Message 1 is Anirban

Q 4 Read and Write 2 messages through parent child process, where CP writes message into pipe and parent process retrieves and displays it.

PROGRAM CODE:

```
#include <stdio.h>
#include <unistd.h>

int main()
{ int pipefds[2]; returnstatus, pid;
char writemessages[2][20] = {"Anirban", "Hazra"};
char readmessage[20];
returnstatus = pipe(pipefds);
if (returnstatus == -1)
{ printf("Unable to create pipe\n");
    return 1;
}
pid = fork();
if (pid == 0) // Child Process
{ read(pipefds[0], readmessage, sizeof(readmessage));
printf("child Process: Reading : Message1 is %s\n",
readmessage);
read(pipefds[0], readmessage, sizeof(readmessage));
printf("child Process: Reading : Message2 is %s\n",
readmessage);
}
else // Parent Process
{ printf("Parent Process: Writing : Message1 is %s\n",
writemessages[0]);
write(pipefds[1], writemessages[0], sizeof(
writemessages[0]));
printf("Parent Process: Writing : Message2 is %s\n",
writemessages[1]);
write(pipefds[1], writemessages[1], sizeof(
writemessages[1]));
}
return 0;
}
```

OUTPUT

Parent Process: Writing: Message 1 is Anirban

Parent Process: Writing: Message 2 is Hazra

Child Process: Reading: Message 1 is Anirban

72 Child Process: Reading: Message 2 is Hazra

Q 5 Write a program to achieve two-way comm. using pipes

PROGRAM CODE :

```
#include <stdio.h>
#include <unistd.h>
int main()
{ int pipefds[1], pipefds[2];
int returnstatus1, returnstatus2, pid;
char pipe1writemessage[20] = "Hi";
char pipe2writemessage[20] = "Hello";
char readmessage[20];
returnstatus1 = pipe(pipefds1);
returnstatus2 = pipe(pipefds2);
if (returnstatus1 == -1)
{ printf("Unable to create pipe1\n");
return 1;
}
if (returnstatus2 == -1)
{ printf("Unable to create pipe2\n");
return 1;
}
pid = fork();
if (pid != 0) // Parent process
{ close(pipefds1[0]);
close(pipefds2[1]);
printf("Parent : Writing : Pipe1 : Message is %s\n",
pipe1writemessage);
write(pipefds1[1], pipe1writemessage, sizeof
(pipe1writemessage));
read(pipefds2[0], readmessage, sizeof
(readmessage));
printf("Parent : Reading : Pipe2 : Message is %s\n",
readmessage);
}
```

else // Child Process

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```
    close(pipefds1[1]);
    close(pipefds2[0]);
    read(pipefds1[0], readmessage, sizeof(readmessage));
    printf("Child : Reading : Pipe1 : Message is %s\n",
           readmessage);
    printf("Child : Writing : Pipe2 : Message is %s\n",
           pipe2writemessage);
}
return 0;
}
```

OUTPUT :

Parent : Writing : Pipe1 : Message is Hi

Child : Reading : Pipe1 : Message is Hi

Child : Writing : Pipe2 : Message is Hello

Parent : Reading : Pipe2 : Message is Hello.

Q5 Write a program in C to write 2 numbers from parent and read by child and add those numbers and print the sum

PROGRAM CODE :

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/types.h>
#include <time.h>
#include <sys/wait.h>

int main()
{
    int p1[2], p2[2];
    if(pipe(p1) == -1) return 1;
    if(pipe(p2) == -1) return 1;
    int t = fork();
    if(t == 0)
        close(p1[0]);
        close(p2[1]);
        sleep(1);
        write(p1[1], "12345", 5);
        write(p2[0], "67890", 5);
        close(p1[1]);
        close(p2[0]);
        read(p1[0], readmessage, 5);
        read(p2[1], writemessage, 5);
        printf("Child : Reading : Pipe1 : Message is %s\n",
               readmessage);
        printf("Child : Writing : Pipe2 : Message is %s\n",
               writemessage);
        close(p1[0]);
        close(p2[1]);
    else
        read(p1[0], readmessage, 5);
        read(p2[1], writemessage, 5);
        printf("Parent : Reading : Pipe1 : Message is %s\n",
               readmessage);
        printf("Parent : Writing : Pipe2 : Message is %s\n",
               writemessage);
        close(p1[0]);
        close(p2[1]);
}
```

```
if (t == 0)
    close(p1[0]);
    close(p2[1]);
    int a, b;
    if (read(p2[0], &a, sizeof(a)) == -1) return 3;
    printf("1st number in child is %.d\n", a);
    if (read(p2[0], &b, sizeof(b)) == -1) return 3;
    printf("2nd number in child is %.d\n", b);
    int sum = a + b;
    printf("Sum in Parent Process is %.d\n", sum);
    if (write(p1[1], &sum, sizeof(sum)) == -1) return 4;
    printf("Wrote from Child Process %.d\n", sum);
    close(p1[1]);
    close(p2[0]);
}
else
    close(p1[1]);
    close(p2[0]);
    srand(time(NULL));
    int z = rand() % 100;
    int y = rand() % 100;
    if (write(p2[1], &y, sizeof(y)) == -1) return 5;
    printf("Wrote from parent process %.d\n", y);
    if (write(p2[1], &z, sizeof(z)) == -1) return 6;
    printf("Wrote from parent process %.d\n", z);
    int sum_p;
    if (read(p1[0], &sum_p, sizeof(sum_p)) == -1) return 7;
    printf("Result received in parent process: %.d\n",
          sum_p);
    wait(NULL);
    close(p1[0]);
    close(p2[1]);
}
return 0;
}
```

OUTPUT:

Wrote from Parent Process 24
Wrote from Parent Process 26
1st number in child is 24
2nd number in child is 26
Sum in parent process is 50
Wrote from Child Process 50
Result received in parent process is 50.

LABORATORY
NO. 12

LABORATORY - 12

Two Way Communication using Pipes()

2 pipes → Pipe 1 : Write → Parent Read → Child .
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Pipe 2 : Write → child
Read → Parent .

- Pipe communication is viewed as only one way communication i.e either parent writes and child reads or vice versa (not both)
- However for both parent and child needs to read and write pipe simultaneously, the solution is 2 way communication.

1. Create 2 pipes

Pipe 1 → Parent writes.
Child Reads

Pipe 2 → Parent Reads
child Writes

2. Create a Child Process

3. Close unwanted ends as only 1 end is reqd.
for each communication

4. Close Read End of Pipe 1 } Parent.
Write End of Pipe 2 }

5. Close Write End of Pipe 1 } child .
Read End of Pipe 2 }

Read → 0
write → 1

Thread Theory.

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POSIX Thread (p-thread) library)

- Posix libraries are standard thread API for C and C++. It allows us to create multiple threads for concurrent message flow. It is most effective on multi-processor or multicore systems, where threads can be implemented on kernel level.
- By exploiting the latency in I/O or other system func. that may halt a process
- `pthread.h` → header file.

`pthread-create`: used to create a new thread
`int pthread-create(pthread-t * thread,
const pthread_attr_t * attr, void * (* start_routine)(void *), void * arg);`

1. thread → pointer to an unsigned integer val that returns thread id of thread created.
2. attr → pointer to a structure used to define thread attributes (detached state, scheduling policy, stack address). It is set to null for default attributes.
3. start_routine → pointer to subroutine, i.e executed by the thread. The return type and the parameter type of the subroutine has to be `void *`. The func has a single attribute, but if multiple values need to be passed to the func, struct must be used.
4. args → pointer to void that contains argument to the function defined in earlier argument

1) void pthread_exit(void * retrval)

Pthread - exit :

This method accepts a mandatory parameter 'retrval' which is a pointer to an integer that stores return status of the thread terminated. The scope of this variable must be global so that any thread waiting to join may read the join status.

Used to terminate the thread.

2) int pthread_join(pthread_t th, void ** thread return);

- Used to wait for termination of the thread
- th - This is the ID for which the thread waits
- thread - return → It is a pointer to a location where exit status of the thread mentioned in ptr is stored.

3) int pthread_t pthread_self(void);

- used to get thread ID of unread thread

4) pthread_equal(pthread_t t1, pthread_t t2);

- It compares whether threads are same or not.
If 2 threads are equal the func. return non zero value otherwise 0.
- t1 and t2 are thread IDs of 2 threads.

5) int pthread_cancel(pthread_t thread);

- sends cancellation reqd. to thread
- accepts mandatory parameter which is the thread ID of thread of which cancellation request is sent.

6) int pthread_detach(pthread_t thread);

- used to detach a thread. A detached thread doesn't require a thread to join on terminating. The resources of the thread are automatically released after terminating if thread is detached.

- thread returns the thread ID of the thread that must be detached.

Q Write a program to achieve two-way comm.
1 using pipes

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PROGRAM CODE :

```
#include <stdio.h>
#include <unistd.h>
int main()
{ int pipefds[1], pipefds[2];
  int returnstatus1, returnstatus2, pid;
  char pipe1writemessage[20] = "Hi";
  char pipe2writemessage[20] = "Hello";
  char readmessage[20];
  returnstatus1 = pipe (pipefds1);
  returnstatus2 = pipe (pipefds2);
  if (returnstatus1 == -1)
  { printf ("Unable to create pipe1\n");
    return 1;
  }
  if (returnstatus2 == -1)
  { printf ("Unable to create pipe2\n");
    return 1;
  }
  pid = fork();
  if (pid != 0) // Parent process
  { close (pipefds1[0]);
    close (pipefds2[1]);
    printf ("Parent : Writing : Pipe1 : Message is %s\n",
           pipe1writemessage);
    write (pipefds1[1], pipe1writemessage, sizeof
           (pipe1writemessage));
    read (pipefds2[0], readmessage, sizeof
          (readmessage));
    printf ("Parent : Reading : Pipe2 : Message is %s\n",
           readmessage);
  }
```

```
else // Child Process
```

```
{ close(pipefds1[1]);
```

```
close(pipefds2[0]);
```

```
read(pipefds1[0], readmessage, sizeof(readmessage));
```

```
printf("Child : Reading : Pipe1 : Message is %s\n",
```

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```
readmessage);
```

```
printf("Child : Writing : Pipe2 : Message is %s\n",
```

```
pipe2writemessage);
```

```
}
```

```
return 0;
```

```
}
```

OUTPUT :

```
Parent : Writing : Pipe1 : Message is Hi
```

```
Child : Reading : Pipe1 : Message is Hi
```

```
Child : Writing : Pipe2 : Message is Hello
```

```
Parent : Reading : Pipe2 : Message is Hello
```

Q 2 Write a program in C to write 2 numbers from parent and read by child and add those numbers and print the sum

PROGRAM CODE :

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <unistd.h>
```

```
#include <sys/types.h>
```

```
#include <time.h>
```

```
#include <sys/wait.h>
```

```
int main()
```

```
{ int p1[2], p2[2];
```

```
if (pipe(p1) == -1) return 1;
```

```
if (pipe(p2) == -1) return 1;
```

```
int t = fork();
```

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```
if (t == 0)
    close(p1[0]);
    close(p2[1]);
    int a, b;
    if (read(p2[0], &a, sizeof(a)) == -1) return 3;
    printf("1st number in child is %.d\n", a);
    if (read(p2[0], &b, sizeof(b)) == -1) return 3;
    printf("2nd number in child is %.d\n", b);
    int sum = a + b;
    printf("Sum in Parent Process is %.d\n", sum);
    if (write(p1[1], &sum, sizeof(sum)) == -1) return 4;
    printf("Wrote from Child Process %.d\n", sum);
    close(p1[1]);
    close(p2[0]);
}
else
{
    close(p1[1]);
    close(p2[0]);
    srand(time(NULL));
    int z = rand() % 100;
    int y = rand() % 100;
    if (write(p2[1], &y, sizeof(y)) == -1) return 5;
    printf("Wrote from parent process %.d\n", y);
    if (write(p2[1], &z, sizeof(z)) == -1) return 6;
    printf("Wrote from parent process %.d\n", z);
    int sump;
    if (read(p1[0], &sump, sizeof(sump)) == -1) return 7;
    printf("Result received in parent process: %.d\n",
          sump);
    wait(NULL);
    close(p1[0]);
    close(p2[1]);
}
return 0;
}
```

OUTPUT:

wrote from Parent Process 24

wrote from Parent Process 26

1st number in child is 24

2nd number in child is 26

Sum in parent process is 50

Wrote from Child Process 50

82 Result received in parent process is 50.

THANK

you

- X -

- X -