

Computerized drive for permanent magnets

Kavod Raam, Kapel Eylon

Advisors: Dr. Ilan Shalish

1. Introduction

Design of an ARM microcontroller-based system for moving permanent magnets in a spectroscopic measurement setup. The design includes driving step motors, reading position sensors, providing local control from a controller box having a local display and panel indicators and an alternative remote control from a computer using a LabView program.

2. The Classic Approach

Use of an electromagnet - A type of magnet in which the magnetic field is produced by an electric current.

Since an electromagnet heats up due to the power it dissipates, it requires a cooling system that can satisfy those demands, which increases its complexity, in addition to its typically large size, rendering this solution expensive.

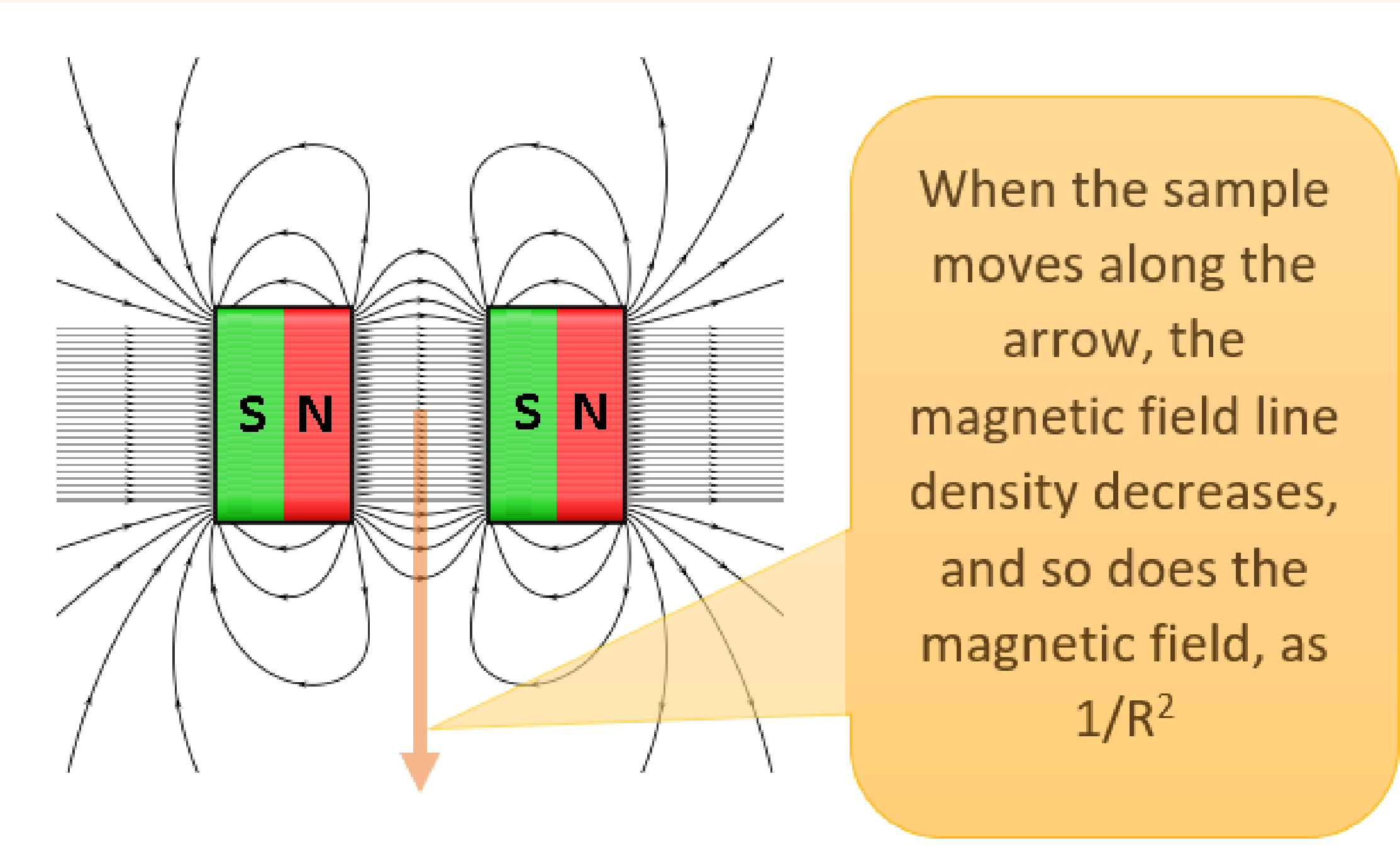
3. Goal

Build a remote-controlled system that can change a magnetic field while taking measurements inside an isolated faraday cage box without exposure to light.

4. Motivation

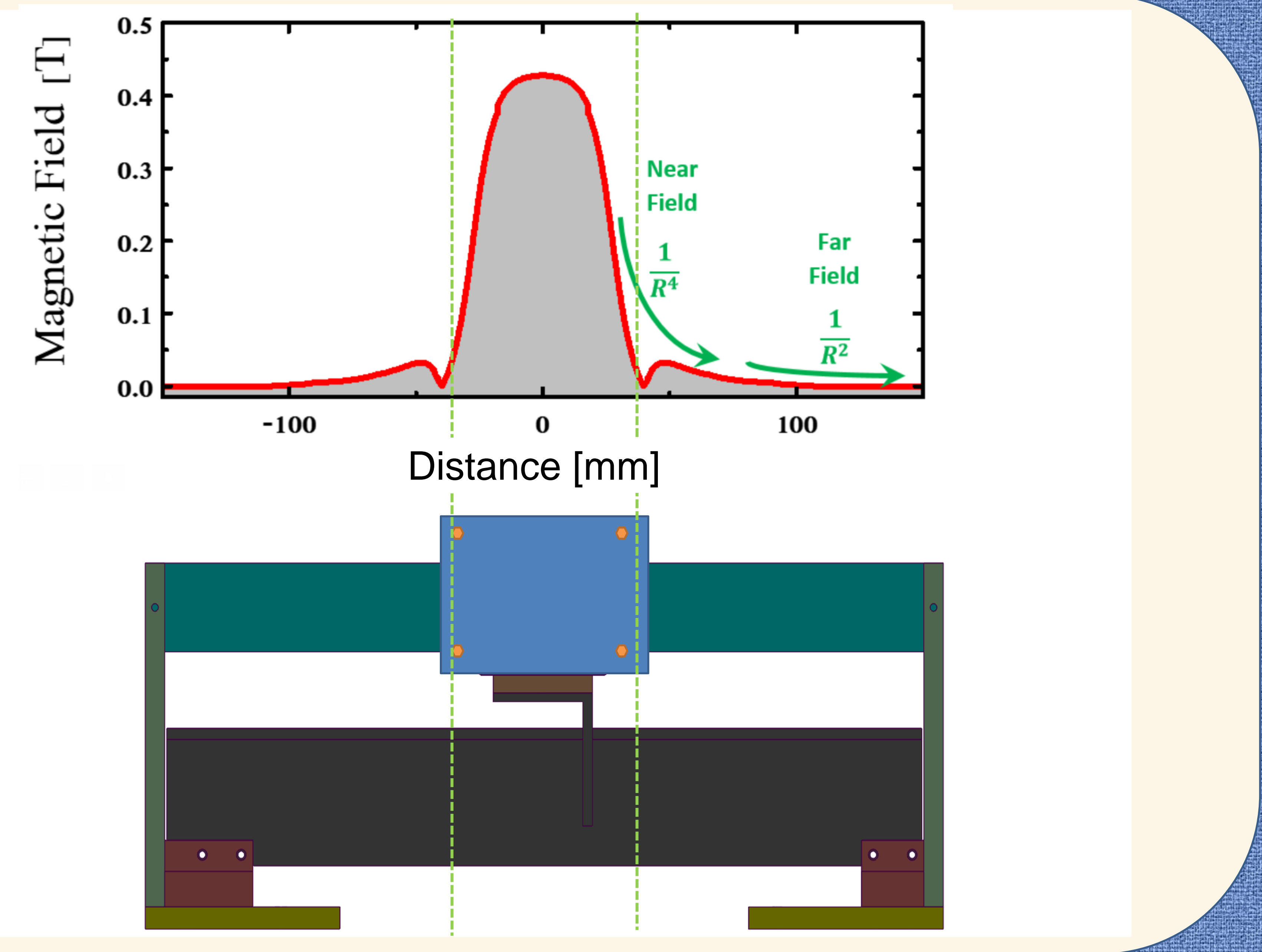
The motivation arises from need to research a variety of materials using a set-up that allows control over several independent variables, (in our case) including an on-off control over a magnetic field.

5. Magnetic Field as a function of distance from source



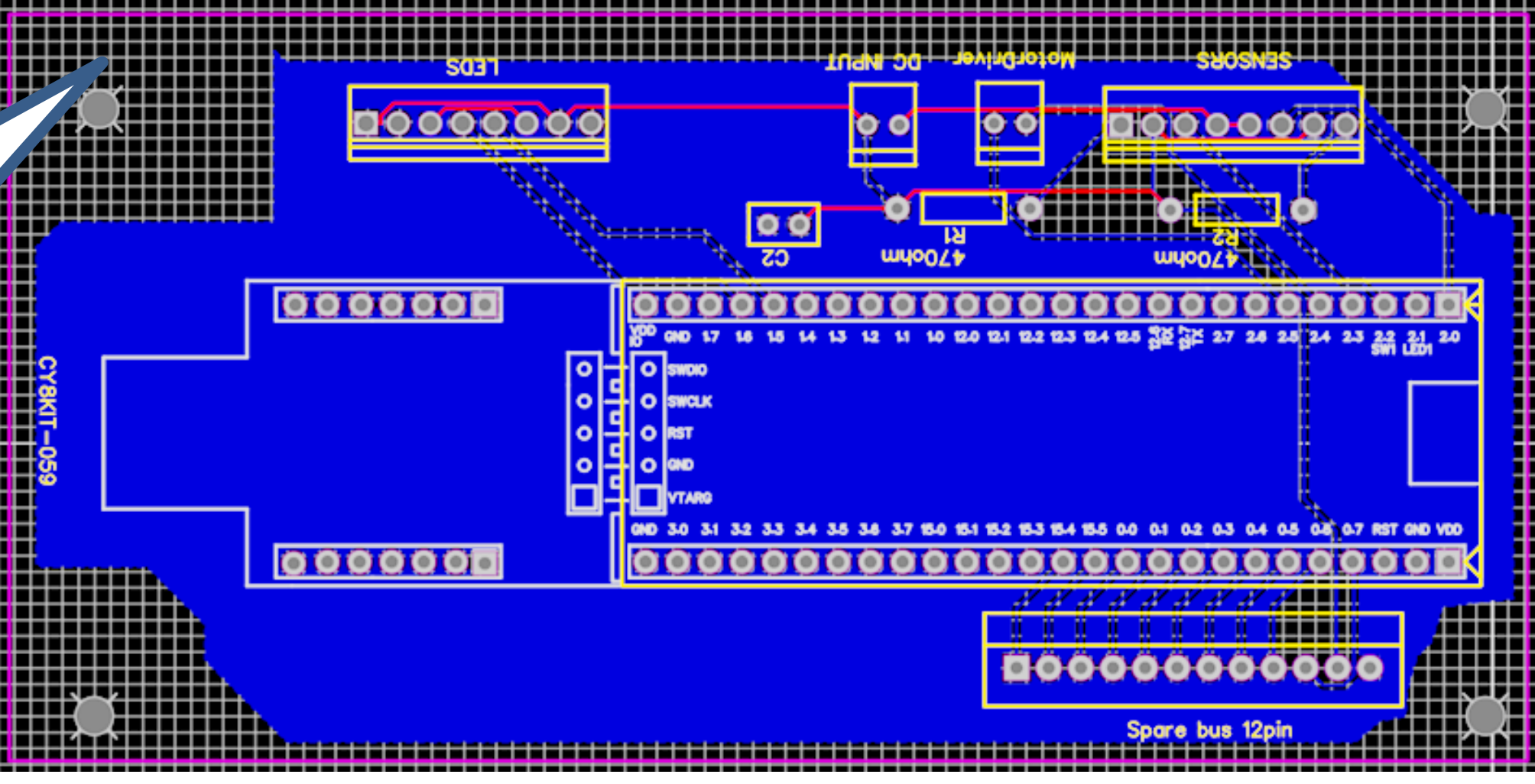
When the sample moves along the arrow, the magnetic field line density decreases, and so does the magnetic field, as  $1/R^2$

For the first 43 mm, the probe is still between the magnet plates, therefore because it is in the “Near field”, the magnetic field decreases like  $1/R^4$ , better than we anticipated. When It reaches the edges of the plates, the magnets’ magnetic fields cancel each others in a specific area because of edge effects. Beyond that point, the field decreases like  $1/R^2$ , perfectly appropriate to our necessities.



6. Design

Printed Circuit Board



Mechanical schematic

