Collaboration1::Interaction1::SequenceDiagram interaction SequenceDiagram ConveyorBelt SystemControl RotaryTable Generator Robot 1: arrive 2 : detect 3 : leave 4 : arrive 5 : right 6: moveUp 8 : ready 7 : up 9 : pick 10 : picked 11 : rotateLeft 12 : left 13: moveDown 14 : down 15 : start