Source images

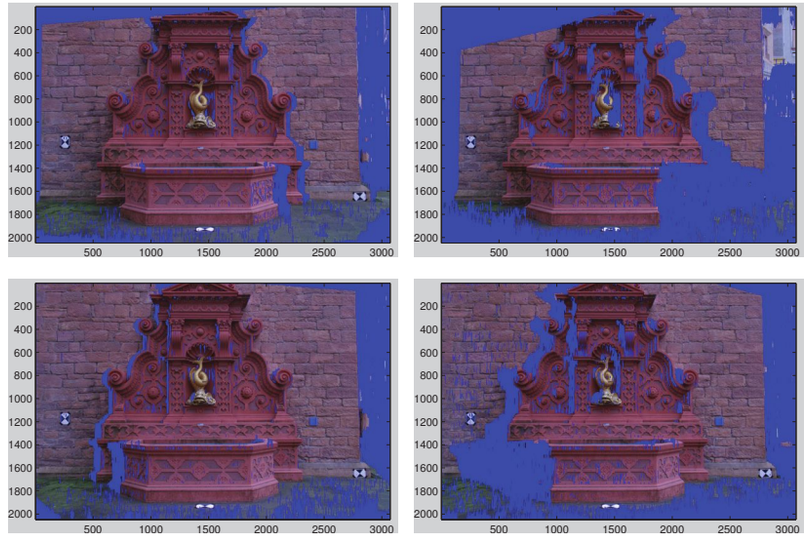
Reference image

Input

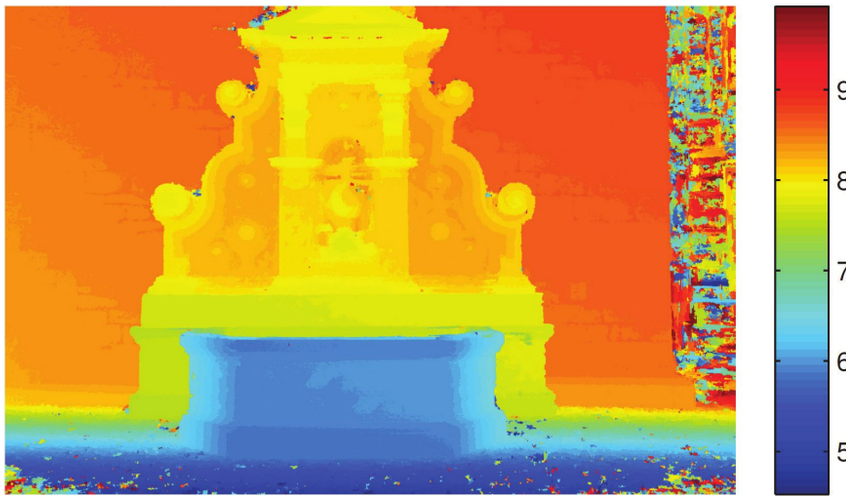
E step:
Image Selection
Probability
Inference

M step:
PatchMatch
Depth
Estimation

Output




Selection probability maps




Depthmap