

# ALGORITHME DE RÉOLUTION DU PROBLÈME DU SAC À DOS MULTIDIMENSIONNEL

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# PRÉSENTATION DU PROBLÈME

- PROBLÈME DU SAC À DOS MULTIPLE

$$(SADM) \quad \left[ \begin{array}{ll} \max & \sum_{j=1}^n c_j x_j \\ \text{s.c. :} & \sum_{j=1}^n a_{ij} x_j \leq b_i, \quad i \in M = \{1, \dots, m\} \\ & x_j \in \{0, 1\} \quad j \in N = \{1, \dots, n\} \end{array} \right. \quad |$$

```
for j in range(m):
    if sum( x*weight[j] ) > constraints[j]:
        return 0

return 1
```



# ALGORITHME DE RÉOLUTION :

- LA RECHERCHE TABOU

Algorithme de base

- Engendrer une configuration initiale  $X$

-  $T = [ ]$

Répéter

- Calculer  $m$  = le meilleur mouvement parmi les mouvements non tabous .

-  $X = X (+) m$

- Mettre  $T$  à jour

Jusqu'à condition fin

Retourner  $X$

# CALCUL DU MOUVEMENT

## CONTRAINTES DE SUBSTITUTION

### 1. Recalcule de nouvelles contraintes

```
for i in range(m):  
    b[i] = constraints[i] - np.sum(weight[i]*x)
```

### 2 . Calcul de coefficients

```
if b[i] > 0 :  
    w[i] = (1/b[i])  
else:  
    w[i] = (2 + abs(b[i]))
```

### 3. Contrainte de substitution

```
for i in range(m):  
    s[i] = w[i]*weight[i]  
  
new_constraints[i]= w[i] * constraints[i]
```

```
s = np.sum(s,axis=0)  
s0 = sum(new_constraints)
```



# CALCUL DU MOUVEMENT

## CHOIX DU MOUVEMENT

```
values_over_weight = C/S
```

```
mov_index = values_over_weight.argsort()  
mov_index = values_over_weight.argsort()[::-1]
```

```
for tabu in tabu_list:  
    if tabu in mov_index:  
        mov_index.remove(tabu)
```

```
    i=0  
    while x[ mov_index[i] ] == 0:  
        i+=1
```

```
x[mov_index[i]] = 1
```

```
x[mov_index[i]] = 0
```

# LISTE TABOU

```
d_tabu_list.append(latest_move)
```

```
c_tabu_list.append(latest_move)
```

```
if iteration%7==0:  
    c_tabu_list=[]  
    d_tabu_list=[]
```



EVÈNEMENT CRITIQUE

PHASE CONSTRUCTIVE

ZONE INFAISABLE

PHASE DESTRUCTIVE

ZONE FAISABLE

# ALGORITHME GÉNÉRAL

```
while((time.time() -start_time) < exec_time-0.5):
    iteration+=1

    for _ in range(5):
        move_choice=best_move()
        latest_move=remove(move_choice,c_tabu_list)

    feasible = real_evaluate()
    d_tabu_list.append(latest_move)

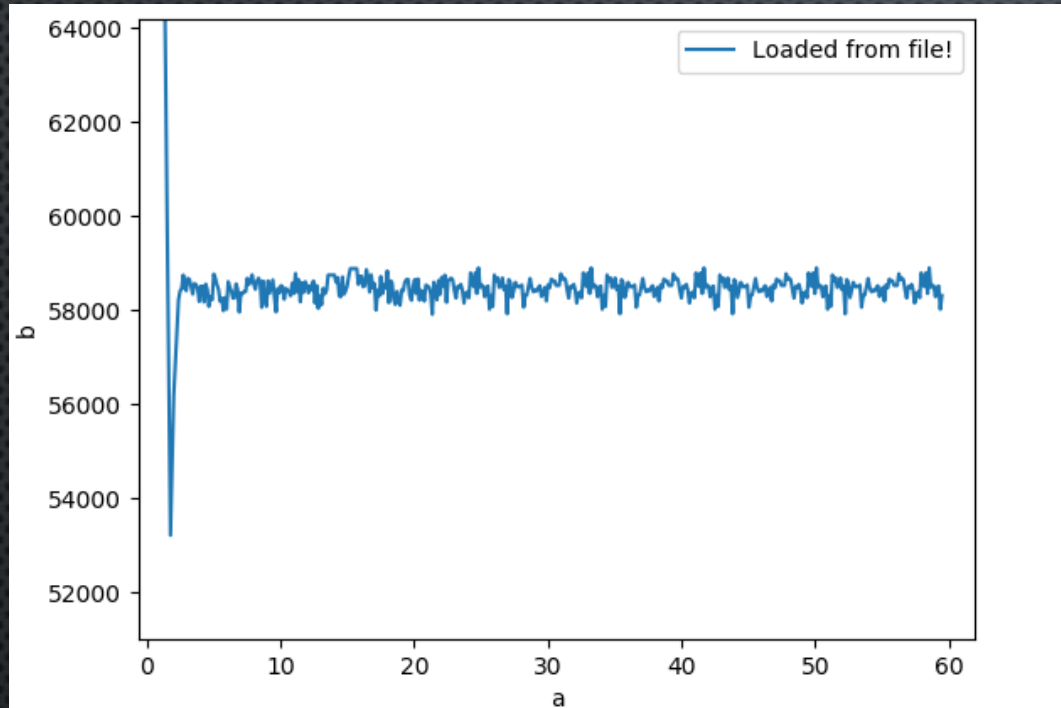
    while feasible :
        move_choice = best_move()
        latest_move = put(move_choice,d_tabu_list)
        feasible=real_evaluate()

    c_tabu_list.append(latest_move)
    critical_constructive_proc()

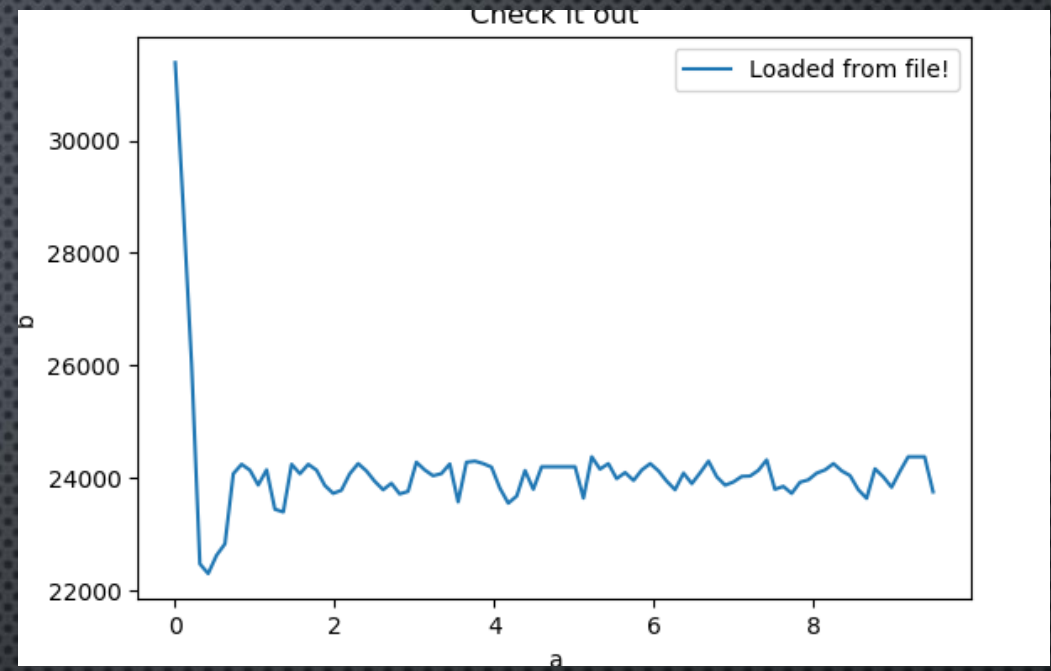
    if iteration%7==0:
        c_tabu_list=[]
        d_tabu_list=[]
```



# RÉSULTATS



250M5\_1.DAT



100M5\_1.DAT