

approximation

tauchen

Discretizes Gaussian linear AR(1) processes via Tauchen's method

quantecon.markov.approximation.rouwenhorst(*n, ybar, sigma, rho*) [\[source\]](#)

Takes as inputs n , p , q , ψ . It will then construct a markov chain that estimates an AR(1) process of: $y_t = \bar{y} + \rho y_{t-1} + \varepsilon_t$ where ε_t is i.i.d. normal of mean 0, std dev of σ

The Rouwenhorst approximation uses the following recursive definition for approximating a distribution:

$$\theta_2 = \begin{bmatrix} p & 1-p \\ 1-q & q \end{bmatrix}$$

$$\theta_{n+1} = p \begin{bmatrix} \theta_n & 0 \\ 0 & 0 \end{bmatrix} + (1-p) \begin{bmatrix} 0 & \theta_n \\ 0 & 0 \end{bmatrix} + q \begin{bmatrix} 0 & 0 \\ \theta_n & 0 \end{bmatrix} + (1-q) \begin{bmatrix} 0 & 0 \\ 0 & \theta_n \end{bmatrix}$$

Parameters:

n:int

The number of points to approximate the distribution

ybar:float

The value \bar{y} in the process. Note that the mean of this AR(1) process, y , is simply $\bar{y}/(1 - \rho)$

sigma:float

The value of the standard deviation of the ε process

rho:float

By default this will be 0, but if you are approximating an AR(1) process then this is the autocorrelation across periods

Returns:

mc:MarkovChain

An instance of the MarkovChain class that stores the transition matrix and state values returned by the discretization method

quantecon.markov.approximation.std_norm_cdf [\[source\]](#)

Computes a Markov chain associated with a discretized version of the linear Gaussian AR(1) process

$$y_{t+1} = b + \rho y_t + u_{t+1}$$

using Tauchen's method. Here u_t is an i.i.d. Gaussian process with zero mean.

Parameters: `b:scalar(float)`

The constant term of $\{y_t\}$

`rho:scalar(float)`

The autocorrelation coefficient

`sigma_u:scalar(float)`

The standard deviation of the random process

`m:scalar(int), optional(default=3)`

The number of standard deviations to approximate out to

`n:scalar(int), optional(default=7)`

The number of states to use in the approximation

Returns: `mc:MarkovChain`

An instance of the MarkovChain class that stores the transition matrix and state values returned by the discretization method