EZRA KANG

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EDUCATION

Massachusetts Institute of Technology (MIT) GPA: 4.7

Cambridge, MA

Candidate for Bachelor of Science in Electrical Engineering and Computer Science

May 2024

Coursework Includes: Introduction to Algorithms, Fundamentals of Programming, Computation Structures,
Linear Algebra and Optimization, Machine Learning, Discrete Math, Circuits and Electronics,
Differential Equations, Computational Thinking and Data Science

WORK EXPERIENCE

Zoro

Software Engineer Intern | Chicago, IL | 06/22 - 08/22

- Designed and developed web frontends built in Vue to provide a user friendly UI for backend tools used by non-technical teams
- Improved a backend API utilizing Python with Flask to facilitate an efficient method of updating database information
- Worked within an Agile development team to develop internal tools with the purpose of improving the workflow of other teams within the company

FLI@MIT Committee

Co-Chair of Peer Support Committee | Cambridge, MA | 02/21 - 01/22

- Led a small committee to create projects to better support FLI (First-Gen/Low-Income) students at MIT
- Communicated with core leadership to report on project details and generate deliverables
- Delegated tasks to committee members and assisted in their execution

FRC Robotics Design Team

Lead Subsystem Designer | Cumming, GA | 08/16 - 3/20

- Coordinated development of a cohesive winch and hook deployment system for a competitive robot game
- Manufactured metal parts with machine shop tools such as a CNC router and lathe
- Collaborated with local manufacturing companies to produce aluminum parts that required fabrication processes outside of the capabilities of the in-house engineering lab
- Utilized communication tools such as Trello and Slack to organize development of the robot

PERSONAL PROJECTS

CAT-SOOP Web Scraper

02/22 - 06/22

- Developed a web scraper in Python for course websites using MIT's CAT-SOOP website framework
- Utilized Python with Selenium to facilitate scraping of content that general web scrapers fail to collect

Hexapod 01/22 - 2/22

Programmed an Arduino to control the walking functionality of a six legged robot

TECHNICAL SKILLS

Programming
Skills
Tools

Python, Javascript, Flask, Vue, RISC-V, Bluespec, Pytorch, HTML, CSS, MATLAB Data Structures, Algorithms, OOP, Machine Learning, Modular Design, Probability Visual Studio Code, Linux, Git, Bitbucket, Jenkins, Docker, GCP, Vim, Jira