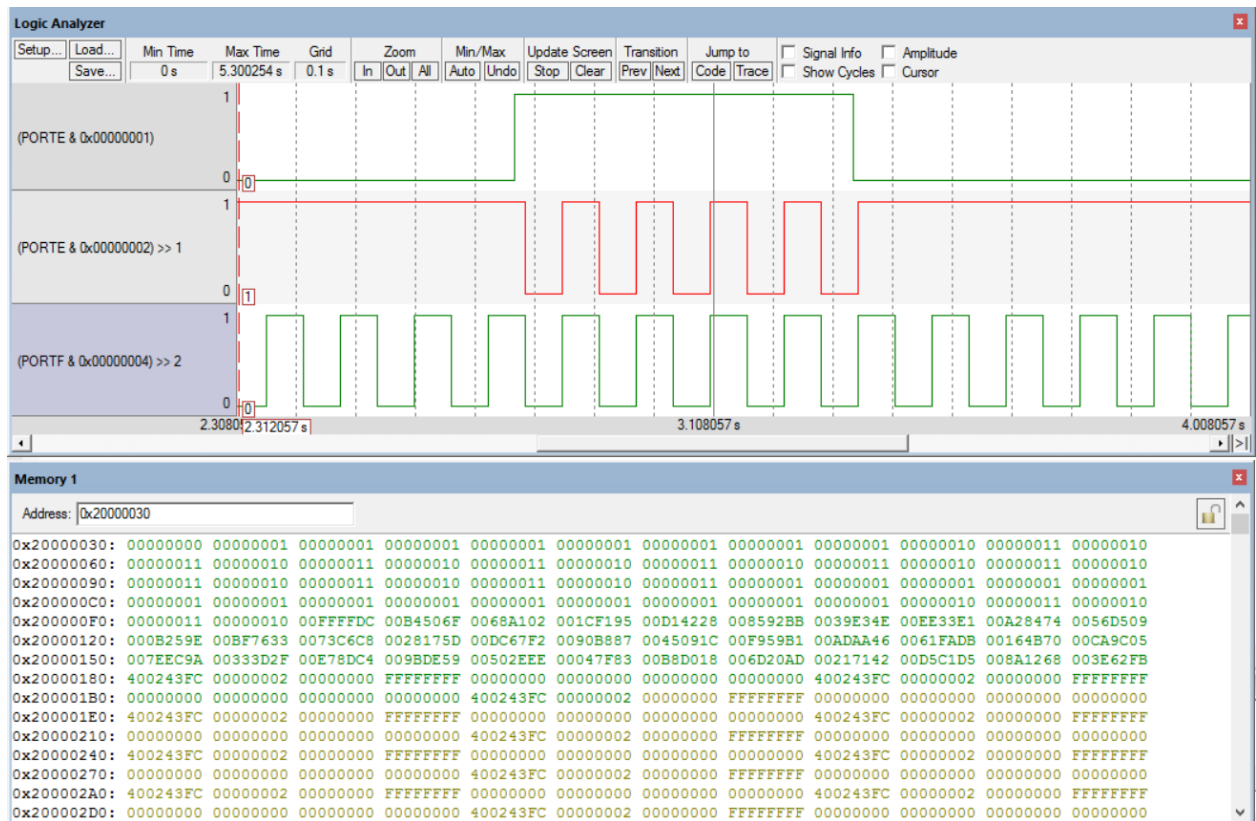


Logic and Memory Windows



Program

```
,***** main.s *****  
; Program written by: Eduardo Zueck Garces and Mai Phan  
; Date Created: 3/1/2015  
; Last Modified: 3/2/2015  
; Section 11am-12pm TA: Wooseok Lee  
; Lab number: 4  
; Brief description of the program  
; If the switch is presses, the LED toggles at 8 Hz  
; Hardware connections  
; PE0 is switch input (1 means pressed, 0 means not pressed)  
; PE1 is LED output (1 activates external LED on protoboard)  
; Overall functionality of this system is the similar to Lab 3, with four changes:  
;1- activate the PLL to run at 80 MHz (12.5ns bus cycle time)  
;2- initialize SysTick with RELOAD 0x00FFFFFF  
;3- add a heartbeat to PF2 that toggles every time through loop  
;4- add debugging dump of input, output, and time  
; Operation  
; 1) Make PE1 an output and make PE0 an input.  
; 2) The system starts with the LED on (make PE1 =1).  
; 3) Wait about 62 ms  
; 4) If the switch is pressed (PE0 is 1), then toggle the LED once, else turn the LED on.  
; 5) Steps 3 and 4 are repeated over and over
```

```
SWITCH      EQU 0x40024004 ;PE0  
LED          EQU 0x40024008 ;PE1  
SYSCTL_RCGCGPIO_R    EQU 0x400FE608  
SYSCTL_RCGC2_GPIOE    EQU 0x00000010 ; port E Clock Gating Control  
SYSCTL_RCGC2_GPIOF    EQU 0x00000020 ; port F Clock Gating Control  
GPIO_PORTE_DATA_R     EQU 0x400243FC  
GPIO_PORTE_DIR_R      EQU 0x40024400  
GPIO_PORTE_AFSEL_R    EQU 0x40024420  
GPIO_PORTE_PUR_R      EQU 0x40024510  
GPIO_PORTE_DEN_R      EQU 0x4002451C  
GPIO_PORTF_DATA_R     EQU 0x400253FC  
GPIO_PORTF_DIR_R      EQU 0x40025400  
GPIO_PORTF_AFSEL_R    EQU 0x40025420  
GPIO_PORTF_DEN_R      EQU 0x4002551C  
NVIC_ST_CTRL_R        EQU 0xE000E010  
NVIC_ST_RELOAD_R      EQU 0xE000E014  
NVIC_ST_CURRENT_R     EQU 0xE000E018
```

```
    THUMB
    AREA  DATA, ALIGN=4
SIZE    EQU   50
;You MUST use these two buffers and two variables
;You MUST not change their names
;These names MUST be exported
    EXPORT DataBuffer
    EXPORT TimeBuffer
    EXPORT DataPt [DATA,SIZE=4]
    EXPORT TimePt [DATA,SIZE=4]
DataBuffer SPACE SIZE*4
TimeBuffer SPACE SIZE*4
DataPt    SPACE 4
TimePt    SPACE 4

    ALIGN
    AREA  |.text|, CODE, READONLY, ALIGN=2
    THUMB
    EXPORT Start
    IMPORT TExaS_Init

Start BL  TExaS_Init ; running at 80 MHz, scope voltmeter on PD3
    BL PortInitE
    BL PortInitF
    BL Debug_Init
    CPSIE I  ; TExaS voltmeter, scope runs on interrupts

loop    BL Debug_Capture
        BL Heartbeat
        BL Delay

        ;We check the state of the switch PF4
        LDR R0, =GPIO_PORTE_DATA_R
        LDR R1, [R0]
        ANDS R2, R1, #0x01

        ;SwitchToggle if PF4 is 0
        BEQ SwitchOn
        BL Toggle
        B loop
SwitchOn
```

BL TurnOn

B loop

;------Debug_Init-----

; Initializes the debugging instrument

; Input: none

; Output: none

; Modifies: none

; Note: push/pop an even number of registers so C compiler is happy

Debug_Init

PUSH{R0-R3}

;Array Init

LDR R0, =DataBuffer

LDR R1, =TimeBuffer

LDR R2, =DataPt

LDR R3, =TimePt

STR R0, [R2] ; We initialize our pointers

STR R1, [R3]

LDR R2, =0xFFFFFFFF

MOV R3, #50

Erase STR R2, [R0] ;We write xFFF... in both of our arrays

STR R2, [R1]

ADD R1, #4

ADD R0, #4

SUBS R3, #1

BNE Erase

LDR R0, =DataBuffer

LDR R1, =TimeBuffer

LDR R2, =DataPt

LDR R3, =TimePt

STR R0, [R2]

STR R1, [R3]

;Systick Init

LDR R0, =NVIC_ST_CTRL_R

MOV R1, #0

STR R1, [R0]

LDR R0, =NVIC_ST_RELOAD_R

LDR R1, =0x0FFFFFFF

```
STR R1, [R0]
```

```
LDR R0, =NVIC_ST_CURRENT_R  
STR R1, [R0]
```

```
LDR R0, =NVIC_ST_CTRL_R  
MOV R1, #0x05  
STR R1, [R0]
```

```
POP{R0-R3}  
BX LR
```

```
;------Debug_Capture-----
```

```
; Dump Port E and time into buffers
```

```
; Input: none
```

```
; Output: none
```

```
; Modifies: none
```

```
; Note: push/pop an even number of registers so C compiler is happy
```

```
Debug_Capture
```

```
PUSH{R0-R7}
```

```
;Check if array is full
```

```
LDR R0, =DataPt
```

```
LDR R1, [R0]
```

```
LDR R2, [R1]
```

```
LDR R3, =0xFFFFFFFF
```

```
SUBS R2, R3
```

```
BNE Leave
```

```
;Dump - Get SysTick Data
```

```
LDR R0, =NVIC_ST_CURRENT_R
```

```
LDR R1, [R0]
```

```
;Get PortE Data and Mask
```

```
LDR R0, =GPIO_PORTE_DATA_R
```

```
LDR R2, [R0]
```

```
ADD R3, R2, #0
```

```
AND R2, #0x01
```

```
LSL R2, #4
```

```
AND R3, #0x02
```

```
LSR R3, #1
```

```
ADD R2, R2, R3
```

```
        ;Store Data
        LDR R0, =DataPt
        LDR R7, =TimePt
        LDR R5, [R0]
        LDR R6, [R7]
        STR R2, [R5]
        STR R1, [R6]

        ;Increment pointers
        ADD R5, #4
        ADD R6, #4
        STR R5, [R0]
        STR R6, [R7]

        POP{R0-R7}
Leave    BX LR

;*****Initialization Sequence*****
PortInitE
;Initialize the Clock for Port E
        LDR R1, =SYSCTL_RCGCGPIO_R ;Load the clock location
        LDR R0, [R1]                ;Load the clock setting
        ORR R0, R0, #0x10           ;Activate Port E
        STR R0, [R1]

;Wait two cycles
        NOP
        NOP

;Set inputs and outputs in the direction register
        LDR R1, =GPIO_PORTE_DIR_R ;Load the DIR location
        LDR R0, [R1]                ;Load the DIR setting for PortE
        MOV R0, #0x02               ;Set PE1 as output
        STR R0, [R1]                ;Store the DIR setting

;Disable alternate functions
        LDR R1, =GPIO_PORTE_AFSEL_R;Load AFSEL location
        LDR R0, [R1]
        BIC R0, R0, #0xFF           ;Disable the functions
        STR R0, [R1]
```

;Enable the digital port

```
LDR R1, =GPIO_PORTE_DEN_R
LDR R0, [R1]
MOV R0, #0xFF
STR R0, [R1]
```

;Go back

```
BX LR
```

,*****Initialization Sequence PortF*****

PortInitF

;Initialize the Clock for Port F

```
LDR R1, =SYSCTL_RCGCGPIO_R ;Load the clock location
LDR R0, [R1]                ;Load the clock setting
ORR R0, R0, #0x20           ;Activate Port E
STR R0, [R1]
```

;Wait two cycles

```
NOP
NOP
```

;Set inputs and outputs in the direction register

```
LDR R1, =GPIO_PORTF_DIR_R ;Load the DIR location
LDR R0, [R1]               ;Load the DIR setting for PortE
MOV R0, #0x04              ;Set PF2as output
STR R0, [R1]               ;Store the DIR setting
```

;Disable alternate functions

```
LDR R1, =GPIO_PORTF_AFSEL_R;Load AFSEL location
LDR R0, [R1]
BIC R0, R0, #0xFF          ;Disable the functions
STR R0, [R1]
```

;Enable the digital port

```
LDR R1, =GPIO_PORTF_DEN_R
LDR R0, [R1]
MOV R0, #0xFF
STR R0, [R1]
```

;Go back

```
BX LR
```

,*****Delay Subroutine for 8HZ*****

Delay

MOV R0, #20000 ;This gives a 1 ms delay

MOV R1, #62 ;Number of ms we want

MUL R0, R0, R1

Repeat

SUBS R0, R0, #1

BNE Repeat

BX LR

,*****Turn on the switch*****

TurnOn

LDR R0, =GPIO_PORTE_DATA_R

LDR R1, [R0]

ORR R1, R1, #0x02

STR R1, [R0]

BX LR

,*****Toggle the switch*****

Toggle

LDR R0, =GPIO_PORTE_DATA_R

LDR R1, [R0]

EOR R1, R1, #0x02

STR R1, [R0]

BX LR

,*****Heartbeat*****

Heartbeat

LDR R0, =GPIO_PORTF_DATA_R

LDR R1, [R0]

EOR R1, R1, #0x04

STR R1, [R0]

BX LR

ALIGN ; make sure the end of this section is aligned
END ; end of file

Estimation of Execution Time

Time in Debug = $0.00002455 - 0.00002374 = 0.00000081$

Time in Loop = $0.06202510 - 0.00002455 = 0.06200055$

Intrusiveness: 0.0013%

This means this debugging method is barely intrusive in our program.

Debugging Data

00000000010000000100000001000000
01000000010000000100000001000000
01000000010000000100000001000000
01000000010000000100000001000000
01000000010000000100000001000000
010000000100000001000000011000000
10000000110000001000000011000000
10000000110000001000000011000000
10000000110000001000000011000000
10000000110000001000000010000000
01000000010000000100000001000000
01000000010000000100000001000000
0100000001000000DCFFFF006F50B400
02A1680095F11C002842D100BB928500
4EE33900E133EE007484A20007D55600
9A250B002D76BF00C0C6730053172800
E667DC0079B890000C0945009F59F900
32AAAD00C5FA6100584B1600EB9BCA00
80EC7E00153D3300AA8DE7003FDE9B00
D42E5000697F0400FECFB80093206D00
28712100BDC1D50052128A00E7623E00
7CB3F2001104A700A6545B003BA50F00
CEF5C30061467800F4962C0087E7E000
1A389500AD88490040D9FD00D329B200
667A6600F9CA1A008C1BCF001F6C8300

00BF7631 → 0073C6C6

12547633 → 7587526

$4960107 * 12.5 \text{ nanoseconds} = 6.20013375 * E7 \text{ nanoseconds} = 62.0013375 \text{ milliseconds}$