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## - MatLab Exam Version 5

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### Problem 1 - A

```
C = 7; % set C
D = -7; % set D
E = 0; % set E
F = -2; % set F

% part i
A1 = [C 0 0 D -3; 2 0 1 2 -2; 5 0 0 7 3; 7 1 0 5 -1; 2 E 1 2 F]; % set
A1
B = [15; -7; 5; 4; -7]; % set B
augA1B = [A1, B] % combine and form augmented matrix

% part ii
rrefA1B = rref(augA1B) % rref of A1B
%{
solution is consistent as there is no row of 0s in the RREF
coefficeient
matrix A1 with a nonzero in the "solution" b matrix as seen in row 5
with
the entire row being 0
%}

% part iii
free = rrefA1B(:,5) % displaying free variable column from rref
% column 5, or X5, is the free variable

% part iv
A1^(-1) % computing inverse
% The coefficient matrix is not invertible

augA1B =

    7     0     0    -7    -3    15
    2     0     1     2    -2    -7
    5     0     0     7     3     5
    7     1     0     5    -1     4
    2     0     1     2    -2    -7
```

*rrefA1B =*

1.0000	0	0	0	0	1.6667
0	1.0000	0	0	-3.1429	-5.2857
0	0	1.0000	0	-2.8571	-9.3810
0	0	0	1.0000	0.4286	-0.4762
0	0	0	0	0	0

*free =*

0  
-3.1429  
-2.8571  
0.4286  
0

*Warning: Matrix is singular to working precision.*

*ans =*

Inf	Inf	Inf	Inf	Inf
Inf	Inf	Inf	Inf	Inf
Inf	Inf	Inf	Inf	Inf
Inf	Inf	Inf	Inf	Inf
Inf	Inf	Inf	Inf	Inf

## Problem 1 - B

```
C = 5; % set C
D = 2; % set D
E = 3; % set E
F = 4; % set F
A2 = [C 0 0 D -3; 2 0 1 2 -2; 5 0 0 7 3; 7 1 0 5 -1; 2 E 1 2 F];

% part i
inv(A2) % computing inverse

% part ii
I = eye(5); % setting 5x5 identity matrix
A2I = [A2, I]; % setting AI augmented matrix
rref(A2I) % rref A2I

% part iii
gA2 = A2;
gA2(1,:) = gA2(1,:) - gA2(3,:);
gA2(4,:) = gA2(4,:) - gA2(3,:);
gA2(4,:) = gA2(4,:) - gA2(2,:);
gA2(3,:) = gA2(3,:) - 2 * gA2(2,:);
gA2(2,:) = gA2(2,:) - 2 * gA2(3,:);
```

```

gA2(5,:) = gA2(5,:) - 2 * gA2(3,:);
gA2(5,:) = gA2(5,:) - 3 * gA2(4,:);
gA2(5,:) = gA2(5,:) / 8;
gA2(2,:) = gA2(2,:) - 5 * gA2(5,:);
gA2(3,:) = gA2(3,:) + 2 * gA2(5,:);
gA2(3,:) = gA2(3,:) + gA2(1,:);
gA2(1,:) = gA2(1,:) / (-5);
gA2(5,:) = gA2(5,:) - gA2(1,:);
gA2(2,:) = gA2(2,:) + 9 * gA2(1,:);
gA2(2,:) = gA2(2,:) / (-2.7);
gA2(1,:) = gA2(1,:) - 1.2 * gA2(2,:);
gA2(5,:) = gA2(5,:) + 1.7 * gA2(2,:);
gA2(4,:) = gA2(4,:) + gA2(5,:);
gA2(4,:) = gA2(4,:) + 4 * gA2(1,:);
gA2(4,:) = gA2(4,:) + 2 * gA2(2,:);
sol = [gA2(3,:); gA2(4,:); gA2(5,:); gA2(1,:); gA2(2,:)]

```

ans =

1.0000	-0.2500	0.2500	-0.7500	0.2500
-1.3333	0.1296	-0.6111	1.3889	-0.1296
1.3333	0.4815	0.4444	-1.5556	0.5185
-1.0000	0.2778	-0.1667	0.8333	-0.2778
0.6667	-0.2315	0.3056	-0.6944	0.2315

ans =

Columns 1 through 7

1.0000	0	0	0	0	1.0000	-0.2500
0	1.0000	0	0	0	-1.3333	0.1296
0	0	1.0000	0	0	1.3333	0.4815
0	0	0	1.0000	0	-1.0000	0.2778
0	0	0	0	1.0000	0.6667	-0.2315

Columns 8 through 10

0.2500	-0.7500	0.2500
-0.6111	1.3889	-0.1296
0.4444	-1.5556	0.5185
-0.1667	0.8333	-0.2778
0.3056	-0.6944	0.2315

sol =

1.0000	0	0	0	0
0	1.0000	0	0	0
0	0	1.0000	0	0.0000
0	0	0	1.0000	-0.0000
0	0	0	0	1.0000

## Problem 2

```
part i

load('leastSq5.mat');

% part ii
type linefit.m

% part iii
[N, XT, D, YT, beta_est, Y_est] = linefit(X, Y); % running linefit
func

% part iv
% done in the linefit function

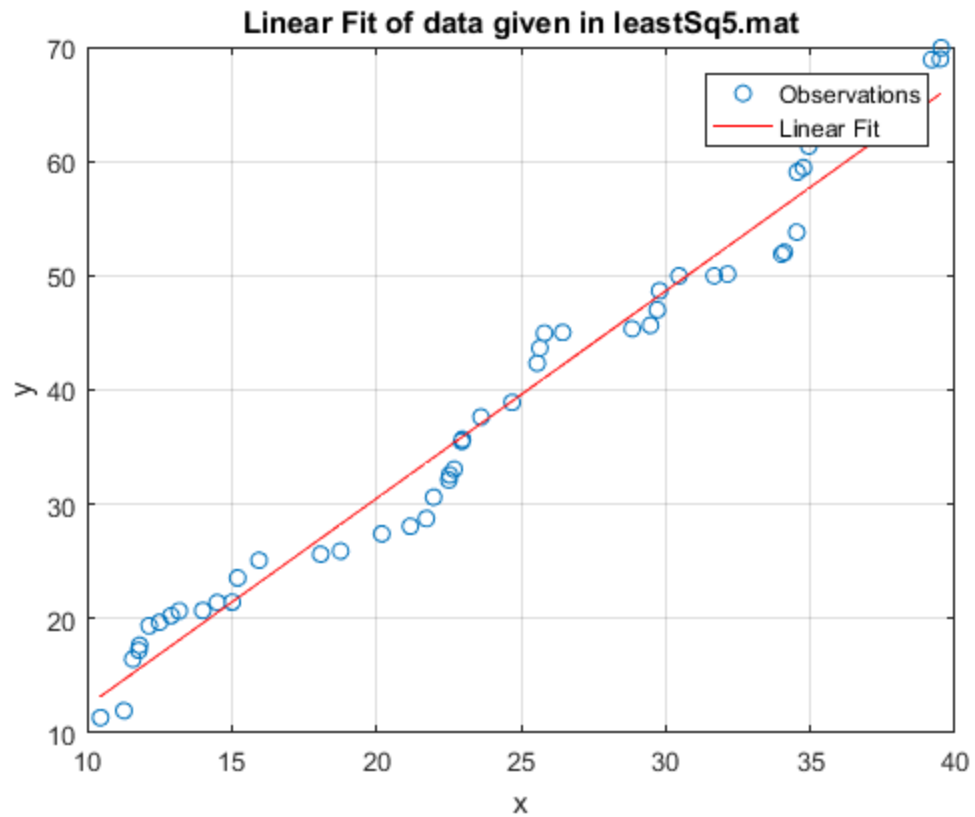
% part v
plot(X, Y, 'o'), hold on, grid on % plotting data points of
pts_setA(1)
plot(X, Y_est, 'r'); % plotting line of best fit
legend('Observations', 'Linear Fit'); % labeling legend
xlabel('x'); % labeling x axis
ylabel('y'); % labeling y axis
title('Linear Fit of data given in leastSq5.mat');

% part vi
err = YT - Y_est; % calculating error of each Y value
RMSEL = (err'*err/N)^0.5 % calculating RMS error

function[N, XT, D, YT, beta_est, Y_est] = linefit(X, Y)
N = length(X);
XT = X';
D = [ones(N,1), XT];
YT = Y';
beta_est = (D'*D)^-1*(D'*YT);
Y_est = D*beta_est;
end

RMSEL =

2.4916
```



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