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Controller

PIDController

- -kp: double
- -kd: double
- -ki: double
- -setpoint: double
- -integral_error: double
- -out_min: double
- -out_max: double
- -sampling_time: double
- +PIDController(...)
- +calculate(in setpoint:double, in measurement:double): double

Responsibilities

-- Computes control signal using PID algorithm