

FEILAN JIANG

Versatile software-oriented maker

Goal-oriented problem solver

Inquisitive multidisciplinary learner

Phone 1-519-574-3317

Email feilanjjiang@gmail.com

My Site f-jiang.me

LinkedIn bit.ly/2pobuOq

GitHub github.com/f-jiang

GrabCAD grabcad.com/f-jiang-1

QUALIFICATIONS

Software

C, C++, Python, Java, JavaScript, HTML, CSS

OpenCV, ncurses, Kivy, Plotly, Tkinter, Swing, JavaFX, jQuery, AngularJS, Node.js, Express.js

Git, GitHub, BitBucket

Proficient with Linux and Bash commands

Mechanical

AutoCAD, SOLIDWORKS

General machining

Robotics

Arduino, Raspberry Pi

Common sensors, PID loops, finite state machines

EDUCATION

BASc Mechatronics Engineering, University of Waterloo

EXPERIENCE

Software Developer

Nanometrics Inc.

1/2017-4/2017

- **Devised** an SD card wear rate testing methodology involving SMART data and standard SD controller commands
- **Optimized** performance on Linux-based seismometers by fine-tuning JVM memory consumption
- **Automated** cross-compilation of internal software tools using the Autotools suite

Programming Lead

FRC Team 4783

9/2015-5/2016

- **Mentored** inexperienced younger students on the fundamentals of WPILib robotics programming in C++
- **Coordinated** team logistics with other department leads to ensure the robot was competition-ready

PROJECTS & ACTIVITIES

Fog-screen Hologram

Collaborative Project

1/2017-present

- Goal is to produce a low-cost, hyper-realistic volumetric display with applications in augmented reality, CAD, etc.
- Has a rotating aluminum base, internal reservoir, and ultrasonic mist maker; electrical connections to stepper motors are preserved using a waterproofed slip ring
- Currently working on displaying pre-rendered 3D scenes in a Tkinter GUI, as well as updating the viewing perspective in real-time by using OpenCV to track changes in the observer's position

Robotics

UW Robotics Team

9/2016-present

- Currently designing LIDAR and SoC mounts in SOLIDWORKS and machining them for the Robot Racing competition
- Oversaw the creation of an Arduino-powered, line-following robot that used photoresistors to detect the line shade and play the corresponding musical note

Mobile Game Dev

Independent Project

6/2014-6/2015

- Conceptualized, implemented, and published a cross-platform, colour-based puzzle game designed to please the eye and stimulate the mind
- App won top prize for game design and technical sophistication at the 2015 TechU.me AppJam finals in Ottawa