# FEILAN JIANG

Versatile softwareoriented maker

Goal-oriented problem solver

Inquisitive multidisciplinary learner

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### **QUALIFICATIONS**

#### Software

C, C++, Python, Java, JavaScript, HTML, CSS

OpenCV, ncurses, Kivy, Plotly, Tkinter, Swing, JavaFX, jQuery, AngularJS, Node.js, Express.js

Git, GDB, Valgrind, npm

Proficient with Linux and Bash commands

#### Mechanical

AutoCAD, SOLIDWORKS

General machining

#### **Robotics**

Arduino, Raspberry Pi

Common sensors, PID loops, finite state machines

#### **EDUCATION**

BASc Mechatronics Engineering, University of Waterloo

#### **WORK EXPERIENCE**

#### **Software Developer**

**Ford Motor Company** 

9/2017-12/2017

- Developed core components of upcoming Ford vehicles' power management systems in a Linux-based environment
- Designed and implemented an inter-process messaging system based on POSIX message queues and Google Protocol Buffers
- Ensured software quality by refactoring the codebase according to the MISRA C and C++ coding standard

#### Software Developer

Nanometrics Inc.

1/2017-4/2017

- Developed a C-based command-line utility for estimating the remaining lifespan of an MMC device
- Devised an SD card wear rate testing methodology involving SMART data and standard SD controller commands
- Automated cross-compilation of internal software tools by using the Autotools suite to generate the appropriate Makefile

## **PROJECTS & ACTIVITIES**

## Fog-screen Hologram

**Collaborative Project** 

1/2017-present

- Low-cost volumetric display with applications in augmented reality and CAD
- Uses an IR camera that tracks the viewer's position and is timed using the ATmega32U4's 16-bit timer overflow interrupt vector

# Random Movie Finder

**Independent Project** 

8/2016

- Created a Bootstrap and AngularJS-based interactive movie recommendation tool
- Implemented a simple Express.js-powered RESTful API that provides form selection options and movie suggestions
- Stays updated with the latest movie trends through The Movie Database API

# Electromechanical Team Member

**UW Robotics Team** 

9/2016-7/2017

- Designed sensor and computer mounts in SOLIDWORKS and machined them for the university Robot Racing competition
- Oversaw the creation of an Arduino-powered, line following robot that used photoresistors to detect the line shade and play the corresponding musical note