FEILAN JIANG

3B Mechatronics Engineering

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EXPERIENCE

ML and Computer Vision Intern

Microsoft Corporation

Seattle, WA (Remote Internship)

 Using image processing and deep learning to automate key manufacturing quality checks

Infrastructure Engineering Intern

Uber ATG

San Francisco, CA

 Developed an AWS pipeline for storing and searching thousands of calibration files, helping to enable one-touch calibration for any internal LiDAR sensor

Localization and Mapping Developer

Avidbots Corp.

🛗 Jan. 2019 - Apr. 2019

- Created an automated ROS LiDAR calibration system used to prepare dozens of floorscrubbing robots for the company's clients
- Designed a custom visual SLAM algorithm that assists with cleaning-plan start-pose correction and map symmetry-breaking

ADAS Software Developer

BlackBerry QNX

May 2018 - Aug. 2018

Ottawa, ON

- Enhanced a LiDAR driver by developing a point-cloud joining feature that shortens each library usage by up to 100 lines of C++ code
- Created a LiDAR object-detector demo used to introduce developers to PCL library features such as point-cloud downsampling and object segmentation

PROJECTS & ACTIVITIES

WATonomous Perception Team Member %

- Serving as a computer vision engineer on a student team developing a level-4 autonomous vehicle for the SAE AutoDrive challenge
- Currently using OpenCV to implement detection and classification algorithms for lanes and roadlines

Autonomous Mobile Robot %

- Developing a wheeled robot that is controlled using various hand gestures
- Uses the ROS software stack and Gmapping SLAM algorithm for autonomous navigation
- Currently implementing hand gesture recognition using OpenCV and the Hand3D hand pose-estimation model

SKILLS



LANGUAGES

C++	~4 Years
Python	~3 Years
С	~2 Years
JavaScript	~1.5 Years

EDUCATION

BASc Mechatronics Eng. University of Waterloo

🗎 Sep. 2016 - Apr. 2021

INTERESTS

