

Competitive Mirror Descent

Competitive mirror descent

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arXiv preprint <https://arxiv.org/abs/2006.10179>



The Problem:

- Constrained Competitive Optimization:

$$\min_{x \in \mathcal{C}} f(x, y) \quad \min_{y \in \mathcal{K}} g(x, y)$$

- Convex problems: Find Nash equilibrium

$$(\bar{x}, \bar{y}) \in \mathcal{C} \times \mathcal{K}: \quad \begin{aligned} \bar{x} &= \operatorname{argmin}_{x \in \mathcal{C}} f(x, \bar{y}), \\ \bar{y} &= \operatorname{argmin}_{y \in \mathcal{K}} g(\bar{x}, y) \end{aligned}$$

- Non-convex problems: More complicated ...

Example: Lagrangian Duality

- Rewrite constraint as maximum:

$$\min_{\substack{x \in \mathbb{R}^m \\ h(x) \leq 0}} f(x) \Leftrightarrow \min_{x \in \mathbb{R}^m} \max_{\lambda \geq 0} f(x) + \lambda h(x)$$

- Replace by competitive problem

$$\min_{x \in \mathbb{R}^m} f(x) + \lambda h(x), \quad \min_{\lambda \geq 0} \lambda h(x)$$

- Generalization to general conic constraints

Example: Adversarial Learning

- In GAN: \mathcal{G} and \mathcal{D} compete

$$\min_{\mathcal{G}} f(\mathcal{G}, \mathcal{D}), \min_{\mathcal{D}} -f(\mathcal{G}, \mathcal{D})$$

- Originally, loss f defined as

$$\mathbb{E}_{x \sim P_{\text{data}}} [\log(\mathcal{D}(x))] + \mathbb{E}_{z \sim \mathcal{N}} [\log(1 - \mathcal{D}(\mathcal{G}(z)))]$$



Produced by StyleGan2 on
<https://thispersondoesnotexist.com/>

Constrained Competitive Optimization

	Single agent	Competitive
Unconstrained	Gradient Descent	???
Constrained	???	???

Constrained Competitive Optimization

	Single agent	Competitive
Unconstrained	Gradient Descent	Competitive gradient descent
Constrained	???	???

Competitive Gradient Descent

- Unconstrained competitive optimization

$$\min_x f(x, y), \quad \min_y g(x, y)$$

- Gradient descent solves linear approximation

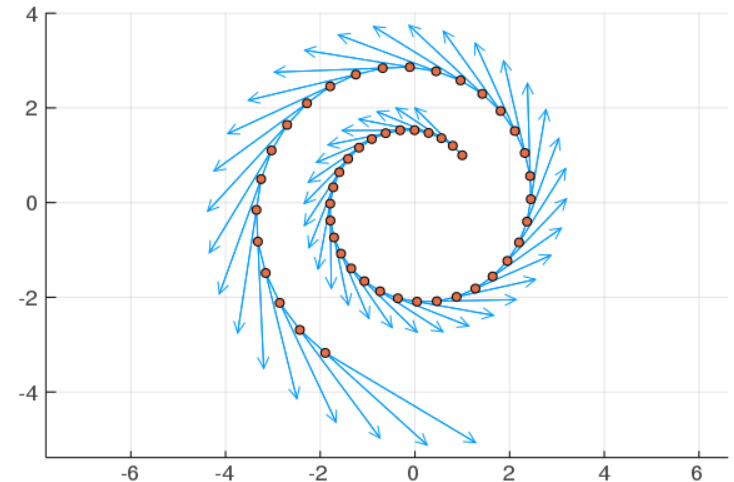
$$x_k - \eta \nabla f(x_k) = \operatorname{argmin}_x [Df(x_k)](x - x_k) + \frac{\|x - x_k\|^2}{2\eta}$$

Competitive Gradient Descent

- Naïve: Simultaneous Gradient Descent

$$\begin{aligned}x_{k+1} &= x_k - \eta \nabla_x f(x_k, y_k) \\ y_{k+1} &= y_k - \eta \nabla_y g(x_k, y_k)\end{aligned}$$

- Fails even on bilinear
 $f(x, y) = xy = -g(x, y)$
“Rock Paper Scissor...”



Competitive Gradient Descent

- Idea: Nash equilibrium of bilinear approximation:

[Schaefer and Anandkumar, 2019]

$$x_{k+1} = \min_x [D_x f](x - x_k) + (x^\top - x_k^\top)[D_{xy}^2 f](y - y_k) + [D_y f](y - y_k) + \frac{\|x - x_k\|^2}{2\eta}$$

$$y_{k+1} = \min_y [D_x g](x - x_k) + (x^\top - x_k^\top)[D_{xy}^2 g](y - y_k) + [D_y g](y - y_k) + \frac{\|y - y_k\|^2}{2\eta}$$

- Has closed form solution

$$\begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} = \begin{pmatrix} x_k \\ y_k \end{pmatrix} - \eta \begin{pmatrix} \text{Id} & \eta D_{xy}^2 f \\ \eta D_{yx}^2 g & \text{Id} \end{pmatrix}^{-1} \begin{pmatrix} \nabla_x f \\ \nabla_y g \end{pmatrix}$$

Constrained Competitive Optimization

	Single agent	Competitive
Unconstrained	Gradient Descent	Competitive Gradient Descent
Constrained	Mirror Descent	Competitive Mirror Descent