

# C 语言排序算法性能测试

## 摘要

本实验主要探讨堆排序,冒泡排序,斐波那契堆排序的性能

通过在不同的编译优化条件下分别对10,100,1000,10000,100000个数据排序所用时间和空间的对比来判堆算法的性能

最后结果表明:

1. 堆排序最快
2. 数据量小于100时冒泡排序比斐波那契堆排序
3. 数据量大于1000时三种算法速度有**堆排序>斐波那契堆排序>冒泡排序**的关系

## 前言

什么样的程序才是好的程序?

对于用户来,说好的程序往往代表着人性化的交互界面,高效率,安全等等.

而效率就像货币一样,通过牺牲效率我们可以换来更安全的程序,更方便的图形界面.

一个好的算法往往可以带来更高的效率.本次实验将实现三个经典的排序算法:

**冒泡排序,堆排序和斐波那契堆排序**并测试这三种算法在不同数据量下的性能.

## 环境配置

- 下载VMware和Ubuntu22.04 LTS  
本实验在Linux虚拟机中进行所以先安装虚拟机软件.在[VMware官网](#)下载VMware并进行安装,再到[ubuntu官网](#)下载Ubuntu22.04 LTS.
- 安装Linux系统  
打开VMware创建新的虚拟机,选择自定义后按下一步至选择系统文件处.选择下载好的Ubuntu系统并按下一步安装.  
设置密码后设置虚拟机安装位置.选择合适的配置后安装虚拟机.按推荐方式安装Ubuntu后将自动进行网络配置.
- 安装gcc,vscode  
待Ubuntu安装完成后在终端中执行

```
sudo apt install gcc
```

```
sudo apt install build-essential
```

安装gcc.  
通过

```
gcc --version
```

检查gcc是非安装成功.  
并于[vscode官网](#)安装vscode安装包, 下载完后双击安装.

## 算法实现

- 冒泡排序

```
#include "bubbleSort.h"
```

```

void bubbleSort(int* array, int length){
    int flag = 1;
    for (int i = 0; i < length - 1; i++){
        flag = 1;
        for (int j = 0; j < length - 1 - i; j++){
            if (array[j] > array[j + 1]){
                int tmp = array[j];
                array[j] = array[j + 1];
                array[j + 1] = tmp;
                flag = 0;
            }
        }
        if (flag) break;
    }
}

```

- 堆排序

```

#include<stdlib.h>

int* heapSort(int* array, int length){
    //堆化
    for (int i = length; i > 1; i--){
        int index = i;
        while (index > 1) {
            if (array[index] < array[index / 2]){
                int tmp = array[index];
                array[index] = array[index / 2];
                array[index / 2] = tmp;
                index /= 2;
            }else break;
        }
    }

    int length2 = length;
    int* result = (int*)(malloc((length2 + 1) * sizeof(int)));
    result[0] = 0;
    //取出堆中最小值
    for (int i = 1; i < length2 + 1; i++){
        int min = 1;
        int smallChilden = min * 2;
        result[i] = array[1];
        array[1] = array[length]; //将最后一个叶子节点放至根节点
        length -= 1;
        //当有子结点时进行循环，维持堆结构
        while (min * 2 < length + 1) {
            if (smallChilden < length && array[smallChilden] >
array[smallChilden + 1]) smallChilden += 1; //如果有右孩且右孩子比左孩子小
            if (array[min] > array[smallChilden]) {
                int tmp = array[min];
                array[min] = array[smallChilden];
                array[smallChilden] = tmp;
            }
        }
    }
}

```

```

        min = smallChilden;
        smallChilden *= 2;
    }else{
        break;
    }
}

return result;
}

```

- 斐波那契堆排序

► 点击展开代码

```

#include <stdio.h>
#include <stdlib.h>
#include <math.h>

typedef int Type;

typedef struct FibNode {
    Type key;                //关键字(键值)
    int degree;              //度数
    struct FibNode* left;    //左兄弟
    struct FibNode* right;   //右兄弟
    struct FibNode* child;   //第一个孩子结点
    struct FibNode* parent;  //父结点
}FibNode;

typedef struct FibHeap {
    int keyNum;              //堆中结点的总数
    int maxDegree;           //最大度
    struct FibNode* min;     //最小结点(某个最小堆的根结点)
    struct FibNode** cons;   //最大度的内存区域
}FibHeap;

//将node从双链表移除
void fibNodeRemove(FibNode* node) {
    node->left->right = node->right;
    node->right->left = node->left;
}

//将单个结点node加入双向链表root之前
void fibNodeAdd(FibNode* node, FibNode* root) {
    node->left = root->left;
    root->left->right = node;
    node->right = root;
    root->left = node;
}

//将双向链表b链接到双向链表a的后面

```

```
void fibNodeCat(FibNode* a, FibNode* b) {
    FibNode* tmp;
    tmp = a->right;
    a->right = b->right;
    b->right->left = a;
    b->right = tmp;
    tmp->left = b;
}

//创建斐波那契堆
FibHeap* fibHeapMake() {
    FibHeap* heap;
    heap = (FibHeap*)malloc(sizeof(FibHeap));
    if (heap == NULL) {
        printf("Error: make FibHeap failed\n");
        return NULL;
    }
    heap->keyNum = 0;
    heap->maxDegree = 0;
    heap->min = NULL;
    heap->cons = NULL;
    return heap;
}

//创建斐波那契堆的结点
FibNode* fibNodeMake(Type key) {
    FibNode* node;
    node = (FibNode*)malloc(sizeof(FibNode));
    if (node == NULL) {
        printf("Error: make Node failed\n");
        return NULL;
    }
    node->key = key;
    node->degree = 0;
    node->left = node;
    node->right = node;
    node->parent = NULL;
    node->child = NULL;
    return node;
}

//将结点node插入到斐波那契堆heap中
void fibHeapInsert_node(FibHeap* heap, FibNode* node) {
    if (heap->keyNum == 0) {
        heap->min = node;
    }
    else {
        fibNodeAdd(node, heap->min);
        if (node->key < heap->min->key) {
            heap->min = node;
        }
    }
    heap->keyNum++;
}
```

```
//新建键值为key的结点，并将其插入到斐波那契堆中
void fibHeapInsert_key(FibHeap* heap, Type key) {
    FibNode* node;
    if (heap == NULL) {
        printf("The heap does not exist\n");
        return;
    }
    node = fibNodeMake(key);
    if (node == NULL) {
        printf("Cannot make node\n");
        return;
    }
    fibHeapInsert_node(heap, node);
}

//将"堆的最小结点"从根链表中移除，即"将最小结点所属的树"从堆中移除
FibNode* fibHeapRemove_min(FibHeap* heap) {
    FibNode* min = heap->min;
    if (heap->min == min->right) {
        heap->min = NULL;
    }
    else {
        fibNodeRemove(min);
        heap->min = min->right;
    }
    min->left = min->right = min;
    return min;
}

//将node链接到root根结点
void fibHeapLink(FibHeap* heap, FibNode* node, FibNode* root) {
    //将node从双链表中移除
    fibNodeRemove(node);
    //将node设为root的孩子
    if (root->child == NULL) {
        root->child = node;
    }
    else {
        fibNodeAdd(node, root->child);
    }
    node->parent = root;
    root->degree++;
}

//创建fib_heap Consolidate所需空间
void fibHeapConsInit(FibHeap* heap) {
    int old = heap->maxDegree;
    //计算log2(x)，向上取整
    heap->maxDegree = (int)(log((double)(heap->keyNum)) / log(2.0)) +
1;
    //如果原本空间不够，则再次分配内存
    if (old >= heap->maxDegree) {
        return;
    }
}
```

```

    }
    //因为度为heap->maxDegree可能被合并，所以要maxDegree+1
    heap->cons = (FibNode**)realloc(heap->cons, sizeof(FibHeap*) *
(heap->maxDegree + 1));
}

//合并斐波那契堆的根链表中左右相同度数的树
void fibHeapConsolidate(FibHeap* heap) {
    //开辟所用空间
    fibHeapConsInit(heap);
    int i;
    int D = heap->maxDegree + 1;
    for (i = 0; i < D; i++) {
        heap->cons[i] = NULL;
    }
    //合并相同度的根结点，使每个度数的树唯一
    while (heap->min != NULL) {
        FibNode* x = fibHeapRemove_min(heap);    //取出堆中的最小树(最小结
点所在的树)
        int d = x->degree;                        //获取最小树的度数
        //heap->cons[d] != NULL，意味着有两棵树(x和y)的"度数"相同。
        while (heap->cons[d] != NULL) {
            FibNode* y = heap->cons[d];           //y是"与x的度数相同的树"
            if (x->key > y->key) {                 //保证x的键值比y小
                FibNode* tmp = x;
                x = y;
                y = tmp;
            }
            fibHeapLink(heap, y, x);              //将y链接到x中
            heap->cons[d] = NULL;
            d++;
        }
        heap->cons[d] = x;
    }
    heap->min = NULL;
    //将heap->cons中的结点重新加到根表中
    for (i = 0; i < D; i++) {
        if (heap->cons[i] != NULL) {
            if (heap->min == NULL) {
                heap->min = heap->cons[i];
            }
            else {
                fibNodeAdd(heap->cons[i], heap->min);
                if ((heap->cons[i])->key < heap->min->key) {
                    heap->min = heap->cons[i];
                }
            }
        }
    }
}

//移除最小结点min
FibNode* fibHeapExtractMin_node(FibHeap* heap) {
    if (heap == NULL || heap->min == NULL) {

```

```

        return NULL;
    }
    FibNode* child = NULL;
    FibNode* min = heap->min;
    //将min每一个儿子(儿子和儿子的兄弟)都添加到"斐波那契堆的根链表"中
    while (min->child != NULL) {
        child = min->child;
        fibNodeRemove(child);
        if (child->right == child) { //感觉可以优化
            min->child = NULL;
        }
        else {
            min->child = child->right;
        }
        fibNodeAdd(child, heap->min);
        child->parent = NULL;
    }
    //将min从根链表中移除
    fibNodeRemove(min);
    if (min->right == min) { //若min是堆中唯一结点，则设置堆的最小结点为
        NULL;
        heap->min = NULL;
    }
    else { //否则，设置堆的最小结点为一个非空结点(min-
        >right)，然后再进行调节。
        heap->min = min->right;
        fibHeapConsolidate(heap);
    }
    heap->keyNum--;
    return min;
}

int fibHeapExtractMin(FibHeap* heap) {
    FibNode* node;
    if (heap == NULL || heap->min == NULL) {
        return 0;
    }
    node = fibHeapExtractMin_node(heap);
    if (node != NULL) {
        int a = node->key;
        free(node);
        return a;
    }
}
//从node开始销毁结点
void fibNodeDestroy(FibNode* node) {
    FibNode* start = node;
    if (node == NULL) {
        return;
    }
    do {
        fibNodeDestroy(node->child);
        // 销毁node，并将node指向下一个
        node = node->right;
    }

```

```
        free(node->left);
    } while (node != start);
}

//销毁斐波那契堆
void fibHeapDestroy(FibHeap* heap) {
    fibNodeDestroy(heap->min);
    free(heap->cons);
    free(heap);
}

int* fibSort(FibHeap* heap) {
    int* a = (int*)malloc(sizeof(int) * heap->keyNum);
    int length = heap->keyNum;
    for (int i = 0; i < length; i++) {
        a[i] = fibHeapExtractMin(heap);
    }
    return a;
}
```

## 测试数据生成

```
srand(time(NULL)); //设置随机种子
int n = 10;
FILE *f = fopen("../data/1_1.txt", "w");
for (int i = 0; i < n; i++) {
    int random_num = rand() % 10000; // 生成0到9999之间的随机数
    fprintf(f, "%d ", random_num);
}
fclose(f);
/*
在main函数中使用以上代码随机生成一些数并储存在data文件夹中, 每次手动改变n数量为
10, 100, 1000, 10000, 100000后运行三次分别生成 1_1.txt, 1_2.txt, 1_3.txt以及
2_1.txt, 2_2.txt等等
*/
```

## 编译与性能测试

修改.vscode文件夹下task.json确保编译器正确链接文件

通过在-g下方添加-o1,-o2等进行不同程度编译优化

```
{
  "tasks": [
    {
      "type": "cppbuild",
      "label": "C/C++: gcc-13 生成活动文件",
      "command": "/usr/bin/gcc-13",
      "args": [
        "-fdiagnostics-color=always",

```



```

        "-g",
        "${fileDirname}/main.c",
        "${fileDirname}/bubbleSort.c",
        "${fileDirname}/heapSort.c",
        "${fileDirname}/fibSort.c",
        "-o",
        "${fileDirname}/${fileBasenameNoExtension}",
        "-lm"
    ],
    "options": {
        "cwd": "${fileDirname}"
    },
    "problemMatcher": [
        "$gcc"
    ],
    "group": {
        "kind": "build",
        "isDefault": true
    },
    "detail": "调试器生成的任务。"
}
],
"version": "2.0.0"
}

```

- 冒泡排序数据测试

```

#include "bubbleSort.h"
#include <stdio.h>
#include <sys/resource.h>
#include <time.h>

void main(){
    struct rusage usage;
    getrusage(RUSAGE_SELF, &usage);
    const int length = 10;
    int a[length];
    int index = 0;
    FILE* f = fopen("../data/1_1.txt", "r");
    while(fscanf(f, "%d", &a[index]) == 1){
        index++;
    }
    fclose(f);

    clock_t start = clock();
    bubbleSort(a, length);
    clock_t end = clock();
    double timeUsed = ((double)(end - start)) / CLOCKS_PER_SEC;

    FILE* file = fopen("../data/00/bubbleSort_1_1.txt", "w");
    fprintf(file, "用时:%fs\n占用内存%ldKB\n排序结果为:\n", timeUsed,

```

```
usage.ru_maxrss);
    for(int i = 0; i < length; i++){
        fprintf(file, "%d ",a[i]);
    }
}
```

- 堆排序数据测试

```
#include"heapSort.h"
#include<stdio.h>
#include <sys/resource.h>
#include<time.h>
#include <stdlib.h>

void main(){

    struct rusage usage;
    getrusage(RUSAGE_SELF, &usage);
    const int length = 10;
    int a[length];
    int index = 0;
    FILE* f = fopen("../data/1_1.txt","r");
    while(fscanf(f,"%d",&a[index]) == 1){
        index++;
    }
    fclose(f);

    clock_t start = clock();
    int* b = (int*)malloc(sizeof(int) * length);
    b = heapSort(a, length);
    clock_t end = clock();
    double timeUsed = ((double)(end - start)) / CLOCKS_PER_SEC;
    FILE* file = fopen("../data/0fast/heapSort_1_1.txt","w");
    fprintf(file, "用时:%fs\n占用内存%ldKB\n排序结果为:\n", timeUsed,
usage.ru_maxrss);
    for(int i = 0; i < length; i++){
        fprintf(file, "%d ",b[i]);
    }
    fclose(file);

}
```

- 斐波那契堆排序数据测试

```
#include"fibSort.h"
#include<stdio.h>
#include <sys/resource.h>
#include<time.h>
```

```
#include <stdlib.h>

void main(){
    struct rusage usage;
    getrusage(RUSAGE_SELF, &usage);
    const int length = 10;
    int a[length];
    int index = 0;
    FibHeap* heap = fibHeapMake();
    FILE* f = fopen("../data/1_1.txt", "r");
    while(fscanf(f, "%d", &a[index]) == 1){
        fibHeapInsert_key(heap, a[index]);
        index++;
    }
    fclose(f);
    int* b = (int*)malloc(sizeof(int) * length);
    clock_t start = clock();
    b = fibSort(heap);
    clock_t end = clock();
    double timeUsed = ((double)(end - start)) / CLOCKS_PER_SEC;
    FILE* file = fopen("../data/00/fibSort_1_1.txt", "w");
    fprintf(file, "用时:%fs\n占用内存%ldKB\n排序结果为:\n", timeUsed,
usage.ru_maxrss);
    for(int i = 0; i < length; i++){
        fprintf(file, "%d ", b[i]);
    }
    fclose(file);
}
```

## 结果与分析

对实验结果求平均值并存在data/result文件夹下

使用matlab绘制图像并保存在data/result文件夹下

```
types = ["bubbleSort", "fibSort", "heapSort"];
options = ["00", "01", "02", "03", "0fast"];
times = [];
memory = [];

% 读取文件内容并提取数据
for i = 1:75
    % 计算类型索引，并生成路径
    index = ceil(i / 15);
    index2 = i - (index - 1) * 15;
    route = sprintf('../data/result/%s/%s%d.txt', options(index),
types(ceil(index2 / 5)), mod(i - 1, 5) + 1);

    % 打开文件并检查是否成功
```

```

fileID = fopen(route, 'r');
if fileID == -1
    warning('无法打开文件: %s', route);
    continue;
end

% 逐行读取文件内容
while ~feof(fileID)
    line = fgetl(fileID);
    if contains(line, '平均用时')
        time_value = sscanf(line, '平均用时:%fs');
        times = [times; time_value * 1000]; % 追加时间数据
    elseif contains(line, '占用')
        memory_value = sscanf(line, '占用%dKB内存');
        memory = [memory; memory_value]; % 追加内存数据
    end
end

% 关闭文件
fclose(fileID);
end

data_sizes = [10, 100, 1000, 10000, 100000];

for i = 1:5
    bubbleSort_times = times(1 + 15 * (i - 1):5 + 15 * (i - 1));
    heapSort_times = times(6 + 15 * (i - 1):10 + 15 * (i - 1));
    fibheapSort_times = times(11 + 15 * (i - 1):15 + 15 * (i - 1));
    bubbleSort_mem = memory(1 + 15 * (i - 1):5 + 15 * (i - 1));
    heapSort_mem = memory(6 + 15 * (i - 1):10 + 15 * (i - 1));
    fiboheapSort_mem = memory(11 + 15 * (i - 1):15 + 15 * (i - 1));
    figure;
    subplot(1, 2, 1); % 左侧绘制时间曲线
    hold on;
    plot(data_sizes, bubbleSort_times, '-o', 'DisplayName', '冒泡排序');
    plot(data_sizes, heapSort_times, '-x', 'DisplayName', '斐波那契堆排序');
    plot(data_sizes, fibHeapSort_times, '-s', 'DisplayName', '堆排序');
    set(gca, 'XScale', 'log'); % 将X轴设为对数刻度
    set(gca, 'YScale', 'log'); % 将Y轴设为对数刻度
    xlabel('数据量');
    ylabel('所用时间 (ms)');
    title('时间');

    subplot(1, 2, 2); % 右侧绘制内存曲线
    hold on;
    plot(data_sizes, bubbleSort_mem, '-o', 'DisplayName', '冒泡排序');
    plot(data_sizes, heapSort_mem, '-x', 'DisplayName', '斐波那契堆排序');
    plot(data_sizes, fibHeapSort_mem, '-s', 'DisplayName', '堆排序');
    hold off;
    set(gca, 'XScale', 'log'); % 将X轴设为对数刻度

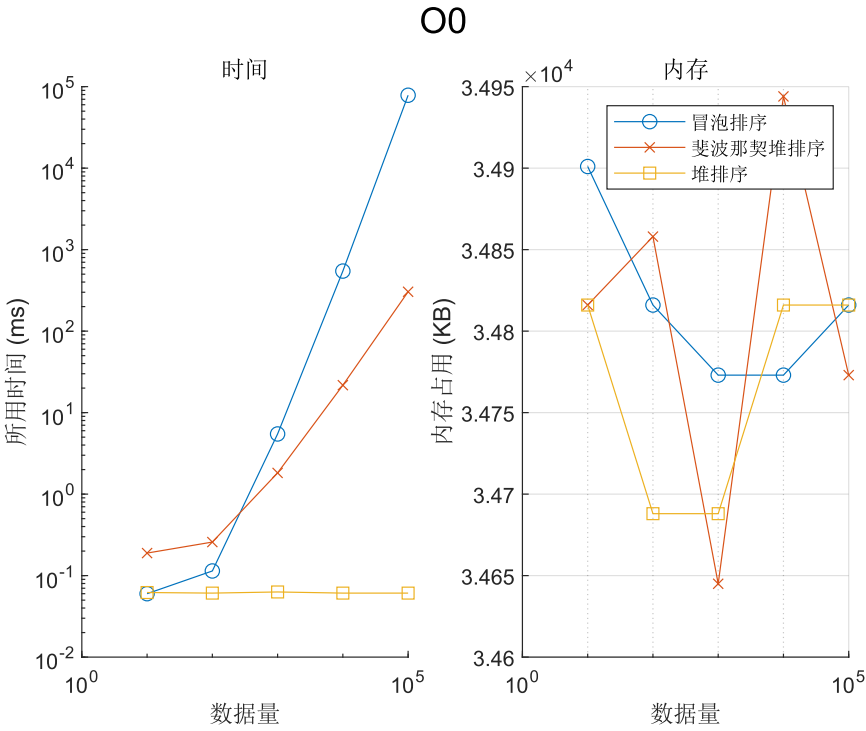
    xlabel('数据量');
    ylabel('内存占用 (KB)');
    title('内存');
end

```

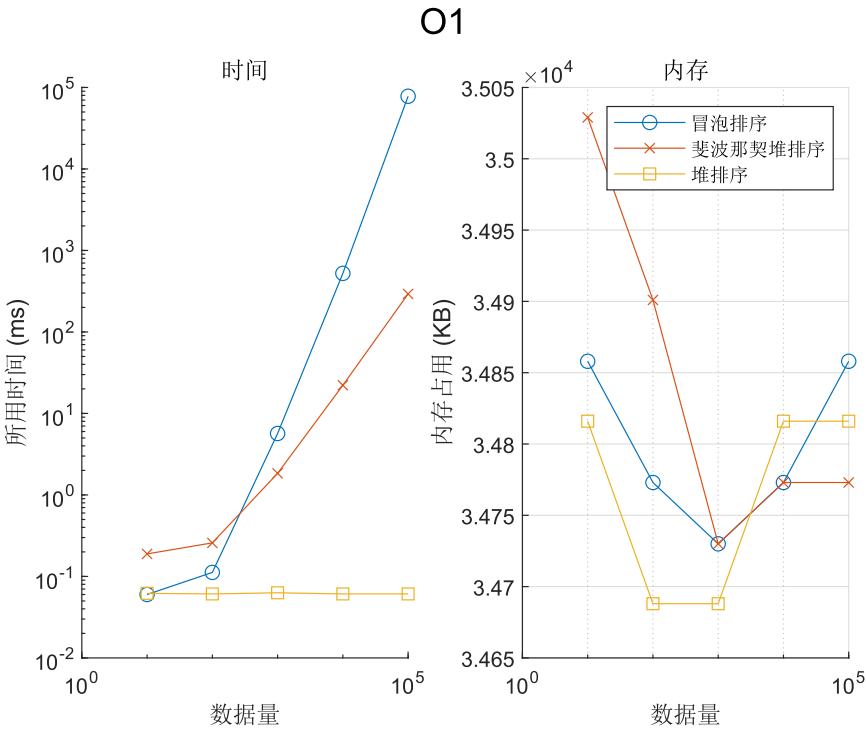
```
legend('show');
grid on;

% 调整布局
sgtitle(options(i));
route2 = sprintf('../data/result/%s.svg', options(i));
print(route2, '-dsvg');
end
```

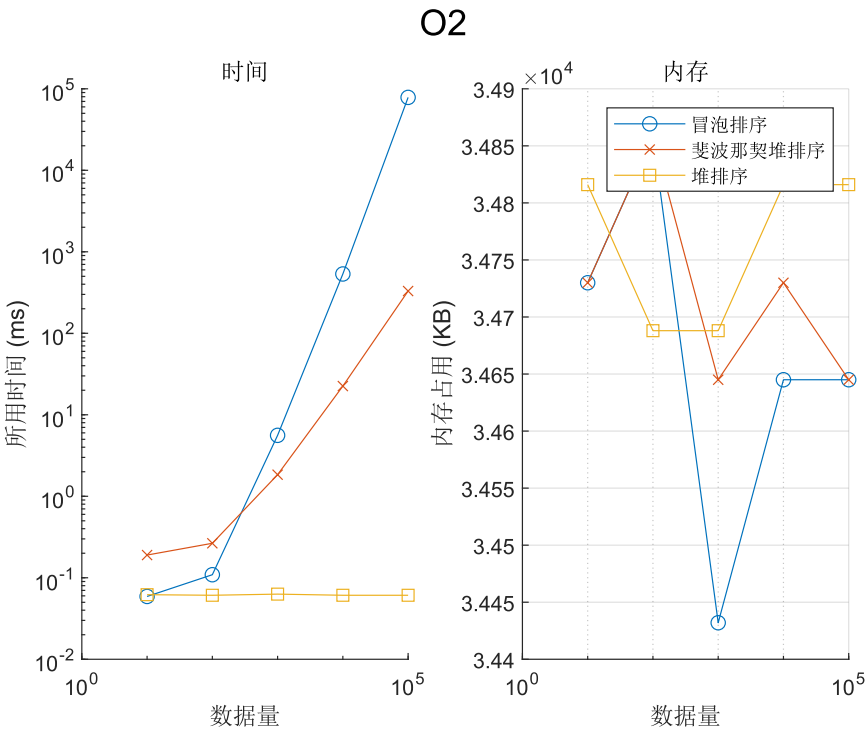
O0



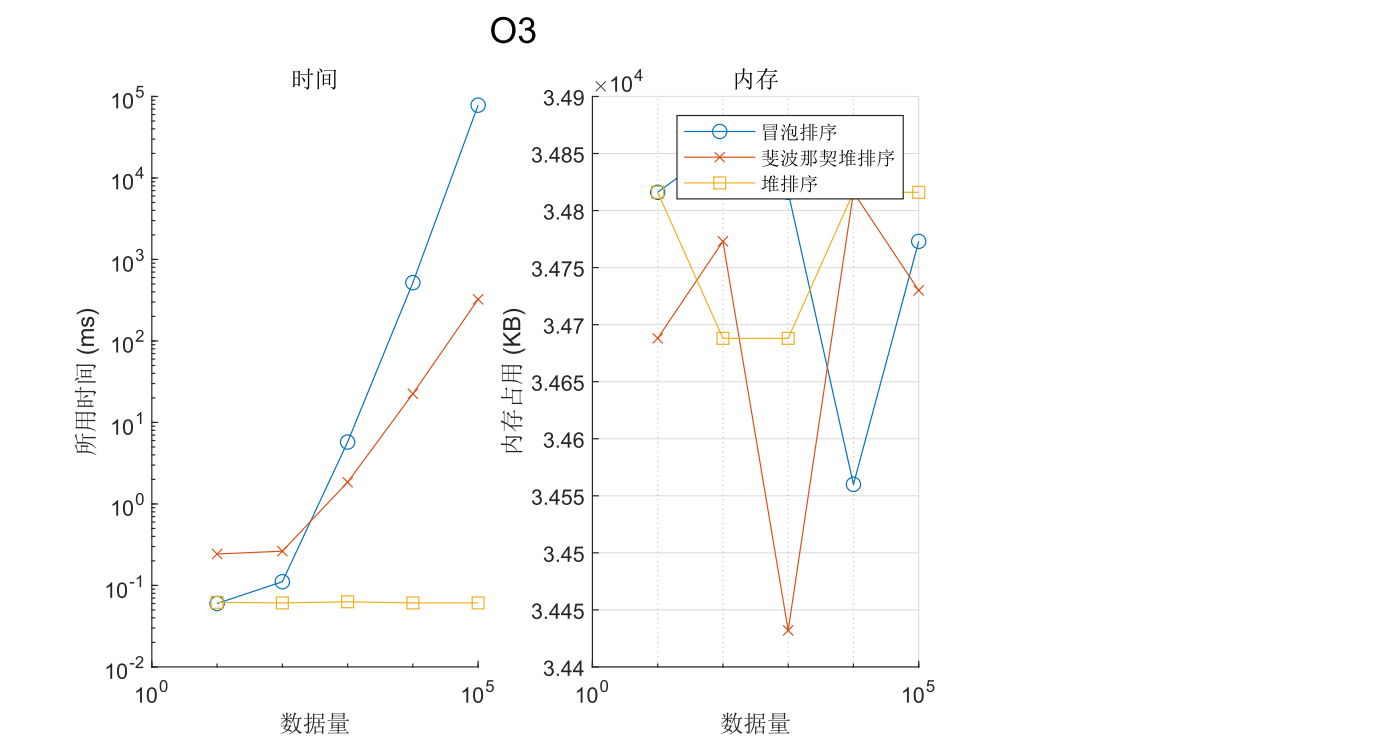
O1



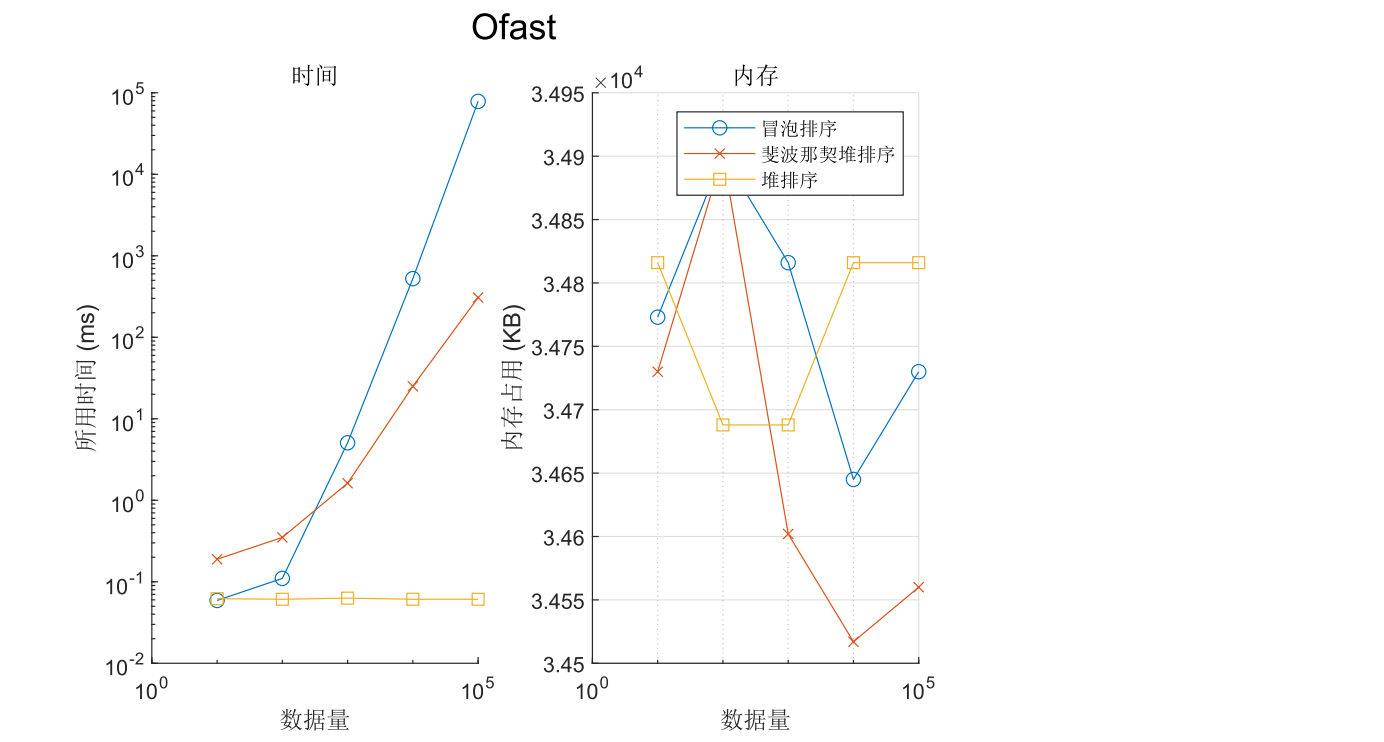
O2



O3



Ofast



分析

三个算法在不同优化条件下运行时间基本相同,占用内存大小略有波动都在34000到35000KB之间.  
因程序运行时间不同,占用内存大小的波动可视为误差  
且在不同优化条件下各算法运行速度无明显改变  
其中冒泡排序在数据量低于100时运行速度比斐波那契堆排序快  
在此之后三种排序算法速度呈现堆排序>斐波那契堆排序>冒泡排序的趋势  
而堆排序一直有着较快的排序速度  
结果与各个排序算法的时间复杂度略有出路

冒泡排序: $O(n^2)$

斐波那契堆排序: $O(n \log n)$

堆排序: $O(n \log n)$

推测可能是因为斐波那契堆排序过程中**代码优化差**

或因为斐波那契堆生成过程中**其他代码消耗了过多时间**导致最后排序速度慢.

## 结论

在数据量小于100000的情况下gcc的优化等级并无多大影响

在算法速度方面**堆排序最快**,当数据量小于100时冒泡排序比斐波那契堆排序快

之后算法速度呈现**堆排序>斐波那契堆排序>冒泡排序**的规律

## 讨论

- 启示

从代码实现难易程度来看冒泡排序无疑是最简单的,斐波那契堆排序是最复杂的.

而当数据量小于100000时冒泡排序所用的时间并非不可接受,所以根据数据量来选择算法或许是个好主意.

斐波那契堆排序就并不适用于较小数据量的排序.

- 改进方向

1. 数据的处理,生成和测试应选用for循环自动处理,手动处理过于枯燥和浪费时间
2. 斐波那契堆的实现还有优化空间
3. 未测试Os优化下算法运行情况数据可能不全面
4. 本次测试数据范围略小,得出的结论可能并不全面

## 参考文献

- [https://blog.csdn.net/baidu\\_40395808/article/details/138541629](https://blog.csdn.net/baidu_40395808/article/details/138541629) 斐波那契堆的C语言实现
- <https://www.cnblogs.com/luanxm/p/10848032.html> clash verge安装
- <https://chatgpt.com> 代码书写帮助

## 附录

本实验所有代码都在github上托管

[代码地址](#)

## 实验过程所遇问题

- gcc无法自动链接源文件  
解决方法:修改位于.vscode文件下的task.json文件
- 手搓斐波那契堆失败  
解决方法:CV CSDN上fufufunny的代码
- git push总是无法连接到github  
解决方法:因为手动在github上修改README.md导致需要pull.因过于麻烦故重新clone.
- 在终端push时需要passwd但远程认证服务已停止  
解决方法:在github申请token用于登录.