aDCLoad 2.4

Generated by Doxygen 1.8.6

Tue Jan 6 2015 17:30:51

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Arduino Programmable Constant Current Power Resistance Load

This is all of the code, datasheets and design files for my instructable

- Arduino It contains the Arduino code that we will be talking about here, within the dummy load folder. It also contains all of the 3rd party libraries I have used.
- · Datasheets It contains all of the datasheets for the major components used within the project.
- DesignSpark I have used the opensource schematic and PCB design software for this project, its a fantastic free tool that has no limitations and I find it easier to uses than Eagle http://www.rs-online.-com/designspark/electronics/eng/page/designspark-pcb-home-page The rev 1 folder contains all of my initial designs, please don't use this as there are 2 or 3 errors in the footprints plus I have completely revised the layout for rev 2, please only use these files. the gerber files are in there should you wish to have your own board done. See the next step for more information on this.
- · LTSpice This contains all of the LtSpice files from simulating the operation of the MOSFET.

Please checkout my instructable as it describes all of this code and the operation of the dummy load.

2	Arduino Programmable Constant Current Power Resistance Load

ATmega32U4 fuses settings

Unlike the Arduino™ Leornardo board, the ATmega32U4 MCU used in this DC Load needs some special fuses settings.

The following command line defines them to the correct values:

You can also invoke the provided Makefile, as:

make fuses

	ATmed	ıa32U4	fuses	settings
--	-------	--------	-------	----------

User interface overview

- The DC load control is done using a simple rotary encoder, which integrates a push button.
- When the DC Load displays the input value (left aligned values), a single encoder detents turns the DC Load's display in settings mode (right aligned values), without any setting value changes.
- There are two display modes, input values and settings values.
 - When you rotate the encoder, the DC Load switches automatically to settings mode.
 - You just need to rotate the encoder to define the desired value, accordingly to the focus: Current or Power.
- In both display modes, a double click changes the focus (delimited by '[' and ']' symbols) to the next value parameter, Current (I) or Power (P).
- · A simple click changes the tuning step.

Next to the ']' delimiter symbol, an icon displays the tuning step multiplier, as following:

Multiplier	Glyph
x1	
x10	
x100	
x1000	

 By default, the DC Load displays Input Voltage, Current load, Power dissipation values and heatsink temperature. 6 User interface overview

Note

The Voltage is measured on the input connectors of the DC Load and may differs from the measured value out of the power supply source.

After 3 seconds in settings mode, without any encoder action, the DC Load returns to the input values display
mode.

· According to the actual status of the DC Load, some icons may be shown:

Feature	Glyph
Logging is running	
Encoder is locked	
USB remote controlled	
Over-Current alam	
Over-Voltage alarm	
Over-Temperature alarm (in place of "°C")	

• To access to the options configuration, you need to press the button for more than 3 seconds. In this *window*, you can enable or disable the **backlight's auto-dimmer** and the **rotary encoder's auto-lock** features.

A double click changes the option focus, a simple click changes the option enability and a long press exits the options *window*.

- When auto-lock is turned on and triggered, a double click unlocks the rotary encoder (the key icon disappear).
- When **auto-dimmer** is turned on and triggered, any rotary encoder action will turn the backlight on, without any change to the defined settings.
- There are 3 differents kind of alarms:
 - 1. **OC** for over-current:

When **Over-Current** is triggered, Current setting is defined to 0mA, **OC** icon is displayed. Over-Current alarm will be cleared once the encoder is used to set a new Current value.

2. **OV** for over-voltage:

When **Over-Voltage** is trig<gered, Current setting is defined to 0mA, **OV** icon is displayed. Encoder will have no action until the input voltage drops below to its maximum value (24V).

3. **OT** the over-temperature:

When **Over-Temperature** is triggered, Current setting is defined to 0mA, **OT** icon is displayed. Encoder will have no action until the internal temperature drops below to its maximum value (80 °C).

• The DC Load can be remotely controlled, see Remote Commands

8 User interface overview

Remote Commands

See also Logging data format

Note

Serial port configuration: 57600,8,N,1

Warning

Commands and arguments are case sensitive, ALL in UPCASE

4.1 Get Identification

- :*IDN?:
 - Returns firmware informations

See Return value

4.2 Current setting getter

- · :ISET?:
 - Returns current setting (in mA)

See Return value.

4.3 Current setting setter

- :ISET:value
 - Set current value (in mA)

See Return value.

10 Remote Commands

4.4 Calibration

- · :CAL:toggle
 - Turns **ON** or **OFF** the logging feature.
- · :CAL:section:slope,offset
 - section could be V, C, D or VD, standing for Voltage, Current, DAC and Voltage Drop.
 - slope and offset are floating point values, with US period decimal separator ('.'). These values could
 be calculated using the LibreOffice's spreadsheet file aDCLoadCalibration.ods.
- · :CAL:SAVE
 - Backup calibation datas into EEPROM.

See Return value

See Calibration Process

4.5 DAC value setter (calibration purpose)

- · :DAC:value
 - Set DAC value (from 0 to 4095).

Note

This command has no effect outside calibration mode

See Calibration

See Calibration Process

4.6 Current readed getter

- · :l?:
 - Returns current readed from the load (in mA)

See Return value.

4.7 Voltage readed getter

- · :U?:
 - Returns voltage readed from the load (in mV)

See Return value.

4.8 Logging enability

- :LOG?:
 - Printout if logging is ON or OFF.

See Return value.

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4.9 Logging enability

- · :LOG:toggle
 - Turns **ON** or **OFF** the logging feature.

Note

If *toggle* value is not specified, a single logging line is returned.

See Return value.

4.10 Return value

:value:status:

- · Where:
 - value if any expected. INVALID on unknown command.
 - status could be OK on success or ERR on failure.

12 **Remote Commands**

Logging data format

See also Remote Commands

Note

fields are comma separated

5.1 CSV logging format

 $time stamp, voltage, current\ sets, current\ read, temperature \verb||r|| n$

- · Where:
 - timestamp in hundred of milliseconds,
 - voltage in mV,
 - current sets in mA,
 - current read in mA,
 - temperature in Celcius degrees.

14	Logging data format

Calibration Process

· Prerequisites:

– Hardware:

- * Amp-meter,
- * Volt-meter,
- * Power supply (0..24V, 8A)

- Software:

- * A serial terminal emulator (e.g. "HyperTerminal" or "Tera Term" on Windows, "minicom" or "cute-com" on Linux).
- * The calibration spreadsheet file aDCLoadCalibration.ods
- * A software able to open the calibration spreadsheet, like "LibreOffice", "OpenOffice" and so on. The serial communication settings are: **57600**, **8**, **N**, **1**

• Process Description:

- Step 1: Maximum Current

Select "Step 1" tab in the calibration spreadsheet file.

Connect the amp-meter and the power supply to the DC load, for current measurements. Open your serial terminal emulator, connect the DC load, then type:

```
:DAC:4095
```

Write down the **mA** value readed on the amp-meter to the "**mA** max" column. Now, type:

```
:DAC:0
```

Edit the aDCLoad.h source file, browse down the file, looking for the following line:

```
static const float CURRENT_MAXIMUM = 7.845; ///< Maximum value of
```

If necessary, change the 7.845 value to the one you've got on your amp-meter (don't forget to convert it from **mA** to **A**), then reflash the board with new code (using *Code::Blocks IDE* or the provided *Makefile*, running "*make burn*" command).

Remember, if you have to reflash the board, that could be only done using ICSP programming. There is no bootloader flashed on the MCU, due to flash space restriction.

Calibration step 1 is now done.

- Step 2: Voltage

Select "Step 2" tab in the calibration spreadsheet file.

Connect your power supply to the DC load, sets to **0V**. The DC Load should the sets to **0mA**. In the serial terminal emulator, type:

```
:CAL:ON
```

16 Calibration Process

Set your power supply voltage output for each value in " V_{set} " column, and write down the readed value in " V_{read} " column.

Once you went through the whole array, the calibration string should be entered into the serial terminal emulator, like:

```
:CAL:V:x.xxx,y.yyy
```

Please note that the decimal separator **HAS TO BE** a period ('.'), as in US format.

Calibration step 2 is now done.

- Step 3: Current

Select "Step 3" tab in the calibration spreadsheet file.

Connect the amp-meter and the power supply to the DC load, for current measurements. Sets the output voltage to 5V.

Using the DAC command, try to adjust its value to match each value in the "*A Amp-Meter*" column, and write down the readed value, on the LCD or serial terminal emulator output, into the "*A LCD/Term.*" column.

You can change the values in the "A Amp-Meter" column to strictly match the ones you're reading on the amp-meter.

The DAC command syntax is:

```
:DAC:value
```

where value is an integer from 0 to 4095.

Once you went through the whole array, set DAC value to 0:

```
:DAC:0
```

The calibration string should be entered into the serial terminal emulator, like:

```
:CAL:C:x.xxx,y.yyy
```

Please note that the decimal separator **HAS TO BE** a period ('.'), as in US format.

Calibration step 3 is now done.

- Step 4: DAC

Select "Step 4" tab in the calibration spreadsheet file.

Connect the amp-meter and the power supply to the DC load, for current measurements. Sets the output voltage to 5V.

Set the DAC value for each value in "Steps" column, and write down the readed value on the amp-meter into the " mA_{read} " column.

The DAC command syntax is:

```
:DAC:value
```

where value is an integer from 0 to 4095.

Once you went through the whole array, set DAC value to 0:

```
:DAC:0
```

The calibration string should be entered into the serial terminal emulator, like:

```
:CAL:D:x.xxx,y.yyy
```

Please note that the decimal separator **HAS TO BE** a period ('.'), as in US format.

Calibration step 4 is now done.

- Step 5: Voltage Drop

Select "Step 5" tab in the calibration spreadsheet file.

Connect the amp-meter, the volt-meter and the power supply to the DC load, for current **AND** voltage measurements. Sets the output voltage to **5V** (the last entry in the array should be set around **12V**).

Using the DAC command, try to adjust the its value to match each value in the "*mA*" column on the amp-meter, and write down the voltage readed value on the volt-meter into the "*mV meter*" column, and the readed value on the LCD and/or serial terminal emulator to the "*mV LCD/Term.*" column.

The DAC command syntax is:

:DAC:value

where value is an integer from 0 to 4095.

You can change the values in the "mA" column to strictly match the ones you're reading on the ampmeter.

For the last row on the array, set the output voltage to around 12V.

Once you went through the whole array, set DAC value to 0:

:DAC:0

The calibration string should be entered into the serial terminal emulator, like:

:CAL:VD:x.xxx,y.yyy

Please note that the decimal separator **HAS TO BE** a period ('.'), as in US format.

Calibration step 5 is now done.

- Last Step: Backup

Once the full calibration is done, you **HAVE** to save the values into the EEPROM, using the following command:

:CAL:SAVE

Now, the calibration is done. You can use your DC load.

18 **Calibration Process**

Hierarchical Index

7.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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aDCSettings	35
aDCSettings::CalibrationData_t	59
LiquidCrystal	
aLCD	54
aDCDisplay	25
aDCEngine	29

20 **Hierarchical Index**

Class Index

8.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

aDCSettings::_eepromCalibrationValue_t	
Union to manipulate float/uint8_t [] calibration values	25
aDCDisplay	
Class that handle LCD displaying	25
aDCEngine	
Main class	29
aDCSettings	
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aLCD	
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Class that handle increase/decrease step multiplier	56
aDCSettings::CalibrationData_t	
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File Index

9.1 File List

Here is a list of all files with brief descriptions:

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aDCLoad.h	66
CDC.cpp	78
HardwareSerial.cpp	78
HID.cpp	78
IPAddress.cpp	79
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main.cpp	79
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Print.cpp	79
sketch.cpp	79
Stream.cpp	80
Tone.cpp	80
USBCore.cpp	80
WInterrupts.c	80
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wiring_digital.c	80
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Chapter 10

Class Documentation

10.1 aDCSettings::_eepromCalibrationValue_t Union Reference

Union to manipulate float/uint8_t [] calibration values.

Public Attributes

- float v
- uint8 t c [sizeof(float)]

10.1.1 Detailed Description

Union to manipulate float/uint8_t [] calibration values.

10.1.2 Member Data Documentation

10.1.2.1 uint8_t aDCSettings::_eepromCalibrationValue_t::c[sizeof(float)]

10.1.2.2 float aDCSettings::_eepromCalibrationValue_t::v

The documentation for this union was generated from the following file:

• aDCLoad.h

10.2 aDCDisplay Class Reference

Class that handle LCD displaying.

#include <aDCLoad.h>

Inherits aLCD.

Inherited by aDCEngine.

Public Member Functions

• aDCDisplay (aDCEngine *, uint8_t, uin

Constructor.

∼aDCDisplay ()

Destructor.

· void setup ()

Setup function. Should be called before any other member.

• void showBanner ()

Display small banner.

• void updateField (aDCSettings::OperationMode_t, float, uint8_t, uint8_t)

Update displayed field according to operation mode.

• void updateDisplay ()

Update LCD display management function.

void pingBacklight ()

Reset backlight dimmer.

bool isBacklightDimmed ()

Check if backlight is dimmed.

Private Member Functions

void dimBacklight (bool)

Dim/undim backlight helper function.

void dimmingBacklight ()

Backlight dimming.

void _wakeupBacklight ()

Backlight waker.

Private Attributes

• aDCEngine * m_Parent

Pointer to aDCEngine parent.

bool m_dimmed

Dimmed state storage.

• unsigned long m_dimmerTick

Dimmer timeout tick counter.

• unsigned long m_nextUpdate

10.2.1 Detailed Description

Class that handle LCD displaying.

10.2.2 Constructor & Destructor Documentation

10.2.2.1 aDCDisplay::aDCDisplay (aDCEngine * parent, uint8_t rs, uint8_t enable, uint8_t d0, uint8_t d1, uint8_t d2, uint8_t d3, uint8_t d4, uint8_t d5, uint8_t d6, uint8_t d7, uint8_t cols, uint8_t rows)

Constructor.

Class to manage display output

Parameters

parent	aDCEngine*: Parent engine
rs	uint8_t : LCD RS pin
enable	uint8_t : LCD ENABLE pin
d0	uint8_t : LCD d0 pin
d1	uint8_t : LCD d1 pin
d2	uint8_t : LCD d2 pin
d3	uint8_t : LCD d3 pin
d4	uint8_t : LCD d4 pin
d5	uint8_t : LCD d5 pin
d6	uint8_t : LCD d6 pin
d7	uint8_t : LCD d7 pin
cols	uint8_t : LCD columns
rows	uint8_t : LCD rows

10.2.2.2 aDCDisplay:: \sim aDCDisplay ()

Destructor.

10.2.3 Member Function Documentation

10.2.3.1 void aDCDisplay::_dimBacklight(bool up) [private]

Dim/undim backlight helper function.

Parameters

ир	bool : dimmer direction

Returns

void

10.2.3.2 void aDCDisplay::_dimmingBacklight() [private]

Backlight dimming.

Returns

void

10.2.3.3 void aDCDisplay::_wakeupBacklight() [private]

Backlight waker.

Returns

void

10.2.3.4 bool aDCDisplay::isBacklightDimmed ()

Check if backlight is dimmed.

```
Returns
     bool
10.2.3.5 void aDCDisplay::pingBacklight ( )
Reset backlight dimmer.
Returns
      void
10.2.3.6 void aDCDisplay::setup ( )
Setup function. Should be called before any other member.
Returns
     void
10.2.3.7 void aDCDisplay::showBanner ( )
Display small banner.
Returns
     void
10.2.3.8 void aDCDisplay::updateDisplay ( )
Update LCD display management function.
Draw/Redraw on screen datas
Returns
      void
```

10.2.3.9 void aDCDisplay::updateField (aDCSettings::OperationMode_t opMode, float vSet, float vRead, uint8_t row, uint8_t unit)

Update displayed field according to operation mode.

Parameters

opMode	OperationMode_t : Operation mode
vSet	float : Settings value
vRead	float : Readed value
row	uint8_t : LCD row position

unit uint8_t : Unit character

Returns

void

10.2.4 Member Data Documentation

```
10.2.4.1 bool aDCDisplay::m_dimmed [private]
```

Dimmed state storage.

10.2.4.2 unsigned long aDCDisplay::m_dimmerTick [private]

Dimmer timeout tick counter.

10.2.4.3 unsigned long aDCDisplay::m_nextUpdate [private]

10.2.4.4 aDCEngine* aDCDisplay::m_Parent [private]

Pointer to aDCEngine parent.

The documentation for this class was generated from the following files:

- · aDCLoad.h
- aDCLoad.cpp

10.3 aDCEngine Class Reference

Main class.

#include <aDCLoad.h>

Inherits aDCDisplay.

Public Member Functions

- aDCEngine (uint8_t, uint8_t, uint8_t,
- ∼aDCEngine ()

Destructor.

• void setup (ISRCallback)

Setup function, should be called before any other member.

• void run ()

Main loop function.

• void service ()

Caller callback function that manages encoder clicking and so on.

Private Member Functions

void <u>handleButtonEvent</u> (ClickEncoder::Button)

Function that handles button clicking.

float _getInputVoltage ()

Function to read the input voltage and return a float number represention volts.

float <u>getADC</u> (uint8_t)

Function to read the ADC, accepts the channel to be read.

• void <u>setDAC</u> (uint16_t, uint8_t)

Function to set the DAC, Accepts the Value to be sent and the channel of the DAC to be used.

• int16_t _getTemp ()

Function that read temperature from ADC channels.

void updateFanSpeed ()

Function to set the fan speed depending on the temperature sensors value.

• float _getMeasuredCurrent ()

Function to measure the actual load current.

void _updateLoadCurrent ()

Function to calculate and set the required load current. Accepts the mode variable to determine if the constant current, resistance or power mode is to be used.

void _adjustLoadCurrent ()

Adjust current settings.

• const aDCSettings * _getSettings () const

Return a pointer to settings instantiated class.

void _handleLoggingAndRemote ()

Check and handle remote control and data logging.

Private Attributes

• aDCSettings m_Data

Settings object.

• ClickEncoder * m encoder

Encoder object.

uint8_t m_RXbuffer [RXBUFFER_MAXLEN]

USB rx buffer.

· uint8 t m RXoffset

USB rx buffer offset counter.

Static Private Attributes

static const uint8_t RXBUFFER_MAXLEN = 64

Friends

· class aDCDisplay

10.3.1 Detailed Description

Main class.

10.3.2 Constructor & Destructor Documentation

10.3.2.1 aDCEngine::aDCEngine (uint8_t rs, uint8_t enable, uint8_t d0, uint8_t d1, uint8_t d2, uint8_t d3, uint8_t d4, uint8_t d5, uint8_t d6, uint8_t d7, uint8_t cols, uint8_t rows, uint8_t enca, uint8_t encb, uint8_t encpb, uint8_t encsteps = 1

Class to manage settings

Parameters

rs	uint8_t : LCD RS pin
enable	uint8_t : LCD ENABLE pin
d0	uint8_t : LCD d0 pin
d1	uint8_t : LCD d1 pin
d2	uint8_t : LCD d2 pin
d3	uint8_t : LCD d3 pin
d4	uint8_t : LCD d4 pin
d5	uint8_t : LCD d5 pin
d6	uint8_t : LCD d6 pin
d7	uint8_t : LCD d7 pin
cols	uint8_t : LCD Columns number
rows	uint8_t : LCD Rows number
enca	uint8_t : Encoder A pin
encb	uint8_t : Encoder B pin
encpb	uint8_t : Encoder push button pin
encsteps	uint8_t : Encoder steps per notch

10.3.2.2 aDCEngine:: ∼aDCEngine ()

Destructor.

10.3.3 Member Function Documentation

10.3.3.1 void aDCEngine::_adjustLoadCurrent() [private]

Adjust current settings.

Returns

void

10.3.3.2 float aDCEngine::_getADC (uint8_t channel) [private]

Function to read the ADC, accepts the channel to be read.

Parameters

channel uint8_t : ADC channel

Returns

float : readed value

10.3.3.3 float aDCEngine::_getInputVoltage() [private]

Function to read the input voltage and return a float number represention volts.

Returns

float : readed input voltage

```
10.3.3.4 float aDCEngine::_getMeasuredCurrent( ) [private]
Function to measure the actual load current.
Returns
     float: readed current
10.3.3.5 const aDCSettings * aDCEngine::_getSettings() const [private]
Return a pointer to settings instantiated class.
Returns
     const aDCSettings*
10.3.3.6 int16_t aDCEngine::_getTemp() [private]
Function that read temperature from ADC channels.
Returns
     int16_t: temperature
10.3.3.7 void aDCEngine::_handleButtonEvent ( ClickEncoder::Button button ) [private]
Function that handles button clicking.
Parameters
                     ClickEncoder::Button
            button
Returns
     void
10.3.3.8 void aDCEngine::_handleLoggingAndRemote( ) [private]
Check and handle remote control and data logging.
Returns
     void
10.3.3.9 void aDCEngine::_setDAC ( uint16_t value, uint8_t channel ) [private]
Function to set the DAC, Accepts the Value to be sent and the channel of the DAC to be used.
Parameters
```

value	uint16_t : value to send to DAC
channel	uint8_t : DAC channel

Returns

void

```
10.3.3.10 void aDCEngine::_updateFanSpeed( ) [private]
```

Function to set the fan speed depending on the temperature sensors value.

Returns

void

```
10.3.3.11 void aDCEngine::_updateLoadCurrent( ) [private]
```

Function to calculate and set the required load current. Accepts the mode variable to determine if the constant current, resistance or power mode is to be used.

Returns

void

10.3.3.12 void aDCEngine::run ()

Main loop function.

Returns

void

```
10.3.3.13 void aDCEngine::service ( )
```

Caller callback function that manages encoder clicking and so on.

Returns

void

10.3.3.14 void aDCEngine::setup (ISRCallback isr)

Setup function, should be called before any other member.

Parameters

isr | ISRCallback : pointer to callback function that may call service()

Returns

void

10.3.4 Friends And Related Function Documentation 10.3.4.1 friend class aDCDisplay [friend] 10.3.5 Member Data Documentation 10.3.5.1 aDCSettings aDCEngine::m_Data [private] Settings object. 10.3.5.2 ClickEncoder* aDCEngine::m_encoder [private] Encoder object. 10.3.5.3 uint8_t aDCEngine::m_RXbuffer[RXBUFFER_MAXLEN] [private] USB rx buffer. 10.3.5.4 uint8_t aDCEngine::m_RXoffset [private] USB rx buffer offset counter.

The documentation for this class was generated from the following files:

10.3.5.5 const uint8_t aDCEngine::RXBUFFER_MAXLEN = 64 [static], [private]

- aDCLoad.h
- · aDCLoad.cpp

10.4 aDCSettings Class Reference

```
Class that handle settings.
```

```
#include <aDCLoad.h>
```

Inherits aStepper.

Classes

union _eepromCalibrationValue_t

Union to manipulate float/uint8_t [] calibration values.

· struct CalibrationData t

Calibration values.

Public Types

 enum OperationMode_t { OPERATION_MODE_READ, OPERATION_MODE_SET, OPERATION_MODE_-UNKNOWN }

Operation mode enumeration.

 enum SelectionMode_t { SELECTION_MODE_CURRENT, SELECTION_MODE_POWER, SELECTION_M-ODE_UNKNOWN }

Selection settings mode enumeration.

enum DisplayMode_t { DISPLAY_MODE_VALUES, DISPLAY_MODE_SETUP, DISPLAY_MODE_UNKNO-WN }

Display mode enumeration.

enum SettingError_t { SETTING_ERROR_OVERSIZED, SETTING_ERROR_UNDERSIZED, SETTING_ERROR_VALID }

Setting error enumeration.

enum CalibrationValues_t {

CALIBRATION_VOLTAGE, CALIBRATION_READ_CURRENT, CALIBRATION_DAC_CURRENT, CALIBRATION_VOLTAGE_DROP,
CALIBRATION_MAX }

Calibration offset enumeration.

Public Member Functions

• aDCSettings ()

Constructor.

∼aDCSettings ()

Destructor.

SettingError_t setVoltage (float)

Voltage setter.

· float getVoltage ()

Voltage getter.

SettingError_t setCurrent (float, OperationMode_t)

Current setter.

float getCurrent (OperationMode_t)

Current getter.

• SettingError t setPower (float, OperationMode t)

Power setter.

float getPower (OperationMode_t)

Power getter.

void updateValuesFromMode (float, SelectionMode t)

Update values setting (Current, Resistance, Power) according to selection mode. Sanity checking is also performed.

void setTemperature (uint16_t)

Temperature readed setter.

• uint16_t getTemperature ()

Temperature readed getter.

void setFanSpeed (uint16_t)

Fan speed setter.

• uint16_t getFanSpeed ()

Fan speed getter.

void setCurrentDAC (uint16_t)

Current DAC value setter.

uint16_t getCurrentDAC ()

Current DAC value getter.

void setSelectionMode (SelectionMode t, bool=false)

Selection mode setter.

SelectionMode_t getSelectionMode ()

Selection mode getter.

SelectionMode_t getPrevNextMode (SelectionMode_t=SELECTION_MODE_UNKNOWN, bool=true)

Get the next selection mode, according to "origin", if any provided.

void setDisplayMode (DisplayMode_t)

Display mode setter.

• DisplayMode_t getDisplayMode ()

Display mode getter.

void setEncoderPosition (int32_t)

Encoder position setter.

void incEncoderPosition (int32_t=1)

Increment stored encoder position by "p" (default = 1)

• int32_t getEncoderPosition ()

Encoder position getter.

void setOperationMode (OperationMode_t)

Operation mode setter.

OperationMode_t getOperationMode ()

Operation mode getter.

void updateOperationMode ()

Automatic timeouted toggle between OPERATION_SET and OPERATION_READ.

void pingOperationMode ()

Reset timeout while in OPERATION_SET mode.

void pingAutolock ()

Reset autolock timeout.

bool isAutolocked ()

Check if autolock is enabled and performs.

void setCalibationMode (bool=true)

Calibration mode enability setter.

• bool getCalibrationMode ()

Calibration mode enability getter.

void getCalibrationValues (CalibrationValues_t, CalibrationData_t &)

Calibration data getter, according to calsection argument.

void setCalibrationValues (CalibrationValues_t, CalibrationData_t)

Calibration data setter, according to calsection argument.

void backupCalibration ()

Backup calibration data into EEPROM.

void restoreCalibration ()

Restore calibration data from EEPROM.

void enableAlarm (uint16_t bit)

Turn alarm (OVP, OCP or OTP) on, sets output current to zero.

void enableFeature (uint16_t, bool=true)

Helper function to manage bit-field features.

• bool isFeatureEnabled (uint16 t)

Check if FEATURE is enabled.

bool isDataEnabled (uint16_t)

Get bit enability in m_datas bit-field storage.

void syncData (uint16_t)

Clear a bit in m_datas bit-field storage.

Static Public Attributes

```
    static const uint16_t DATA_VOLTAGE = 1

     bit-field storage: Voltage readed

    static const uint16_t DATA_CURRENT_SETS = 1 << 1</li>

      bit-field storage: Current sets

    static const uint16 t DATA CURRENT READ = 1 << 2</li>

     bit-field storage: Current readed

    static const uint16 t DATA POWER SETS = 1 << 5</li>

     bit-field storage: Power sets

    static const uint16_t DATA_POWER_READ = 1 << 6</li>

     bit-field storage: Power readed

    static const uint16 t DATA TEMPERATURE = 1 << 7</li>

     bit-field storage: Temperature readed

    static const uint16 t DATA SELECTION = 1 << 8</li>

     bit-field storage: Selection mode sets

    static const uint16_t DATA_DISPLAY = 1 << 9</li>

     bit-field storage: Display mode sets
```

static const uint16 t DATA ENCODER = 1 << 10

bit-field storage: Encoder position sets

static const uint16_t DATA_OPERATION = 1 << 11

bit-field storage: Operation mode sets

static const uint16_t DATA_IN_CALIBRATION = 1 << 12

bit-field storage: In calibration mode

Private Member Functions

• SettingError_t _setValue (OperationMode_t, uint16_t, float &, float &, float)

Value setter.

• uint8 t crc8 (const uint8 t *, uint8 t)

CRC8 computation.

void _eepromCalibrationRestore (int16_t, CalibrationData_t &)

Read data from EEPROM, used to restore calibration data.

void _eepromCalibrationBackup (int16_t, CalibrationData_t)

Save data to EEPROM, used to restore calibration data.

bool _eepromCheckForMagicNumbers ()

Check for EEPROM magic numbers.

void _eepromWriteMagicNumbers ()

Write magic numbers into EEPROM.

void _eepromReset ()

Reset all stored parameters into EEPROM.

void _eepromRestore ()

Restore value from EEPROM.

void _enableData (uint16_t, bool)

Enable a bit in the m_datas bit-field storage.

• void enableDataCheck (uint16 t, bool)

Enable a bit in the m_datas bit-field storage, checking for previous state.

Private Attributes

float m_readVoltage

voltage storage

- float m setsCurrent
- float m readCurrent

current storage

- float m_setsPower
- float m_readPower

power storage

• uint16_t m_readTemperature

temperature storage

uint16_t m_fanSpeed

fan speed storage

uint16_t m_currentDAC

current DAC value

OperationMode_t m_operationMode

operation mode

SelectionMode_t m_mode

selection mode

• int32 t m encoderPos

encoder position (yeah, 32bits, due to resistance max val (12000 * 1000);

• DisplayMode_t m_dispMode

display mode

• unsigned long m_lockTick

tick count storage, for autolock feature

unsigned long m_operationTick

tick count storage, for SET/READ operation

uint16_t m_features

boolean features storage

uint16_t m_datas

boolean displayes data storage

CalibrationData_t m_calibrationValues [CALIBRATION_MAX]

Calibration datas, restored from EEPROM.

10.4.1 Detailed Description

Class that handle settings.

10.4.2 Member Enumeration Documentation

10.4.2.1 enum aDCSettings::CalibrationValues_t

Calibration offset enumeration.

Used to get/set calibration values

Enumerator

CALIBRATION_VOLTAGE Voltage calibration offset value.

CALIBRATION_READ_CURRENT Readed Current calibration offset value.

CALIBRATION_DAC_CURRENT DAC Current calibration offset value.

CALIBRATION_VOLTAGE_DROP Voltage drop calibration offset value.

CALIBRATION_MAX Maximum offset in calibration array.

```
10.4.2.2 enum aDCSettings::DisplayMode_t
Display mode enumeration.
Enumerator
    DISPLAY_MODE_VALUES Display read/set values mode.
    DISPLAY_MODE_SETUP Display settings mode.
    DISPLAY_MODE_UNKNOWN Display in undefined (internal)
10.4.2.3 enum aDCSettings::OperationMode t
Operation mode enumeration.
Enumerator
    OPERATION_MODE_READ Reading values.
    OPERATION_MODE_SET Settings values.
     OPERATION_MODE_UNKNOWN Unset (internal)
10.4.2.4 enum aDCSettings::SelectionMode_t
Selection settings mode enumeration.
Enumerator
    SELECTION_MODE_CURRENT Current selected.
    SELECTION_MODE_POWER Power selected.
    SELECTION_MODE_UNKNOWN Nothing selected (internal)
10.4.2.5 enum aDCSettings::SettingError_t
Setting error enumeration.
Enumerator
    SETTING_ERROR_OVERSIZED Setting value is oversized.
    SETTING_ERROR_UNDERSIZED Setting value is undersized.
     SETTING_ERROR_VALID Setting value is valid.
10.4.3 Constructor & Destructor Documentation
10.4.3.1 aDCSettings::aDCSettings()
Constructor.
10.4.3.2 aDCSettings:: ∼aDCSettings ( )
```

Destructor.

10.4.4 Member Function Documentation

10.4.4.1 uint8_t aDCSettings::_crc8 (const uint8_t * addr, uint8_t len) [private]

CRC8 computation.

Code took from http://www.pjrc.com/teensy/td_libs_OneWire.html

Parameters

addr	const uint8_t*: Data source
len	uint8_t : Data source length

Returns

uint8_t : CRC

10.4.4.2 void aDCSettings::_eepromCalibrationBackup (int16_t addr, CalibrationData_t cal) [private]

Save data to EEPROM, used to restore calibration data.

Parameters

addr	int16_t : start address location
cal	CalibrationData_t&: destination

Returns

void

10.4.4.3 void aDCSettings::_eepromCalibrationRestore(int16_t addr, CalibrationData_t & cal) [private]

Read data from EEPROM, used to restore calibration data.

Parameters

addr	int16_t : start address location
cal	CalibrationData_t&: destination

Returns

void

10.4.4.4 bool aDCSettings::_eepromCheckForMagicNumbers() [private]

Check for EEPROM magic numbers.

Returns

bool

Used to check if some data has already been wrote in the EEPROM.

10.4.4.5 void aDCSettings::_eepromReset() [private]

Reset all stored parameters into EEPROM.

Returns

void

10.4.4.6 void aDCSettings::_eepromRestore() [private]

Restore value from EEPROM.

Returns

void

10.4.4.7 void aDCSettings::_eepromWriteMagicNumbers() [private]

Write magic numbers into EEPROM.

Returns

void

10.4.4.8 void aDCSettings::_enableData (uint16_t bit, bool enable) [private]

Enable a bit in the m datas bit-field storage.

Parameters

bit	uint16_t : Bit to set
enable	bool : Bit enability

Returns

void

10.4.4.9 void aDCSettings::_enableDataCheck(uint16_t bit, bool enable) [private]

Enable a bit in the m_datas bit-field storage, checking for previous state.

If the bit is already sets to TRUE, we don't touch his state, syncData() should be called for this.

Parameters

bit	uint16_t : Bit to set
enable	bool : Bit enability

Returns

void

10.4.4.10 aDCSettings::SettingError_t aDCSettings::_setValue(OperationMode_t mode, uint16_t bit, float value, float & sets, float & read, float maximum) [private]

Value setter.

Parameters

mode	OperationMode_t : Operation mode (SET/READ)
bit	uint16_t : DATA_* bit to set
value	float : value to store
sets	float& : destination variable for OPERATION_SET
read	float& : destination variable for OPERTION_READ
maximum	float : maximum value, used for boundaries checking

Returns

SettingError_t : validity result

10.4.4.11 void aDCSettings::backupCalibration ()

Backup calibration data into EEPROM.

Returns

void

10.4.4.12 void aDCSettings::enableAlarm (uint16_t aBit)

Turn alarm (OVP, OCP or OTP) on, sets output current to zero.

Parameters

aBit uint16_t : alarm bit to set	
----------------------------------	--

Returns

void

10.4.4.13 void aDCSettings::enableFeature (uint16_t feature, bool enable = true)

Helper function to manage bit-field features.

Parameters

feature	uint16_t : FEATURE to enable/disable
enable	bool : FEATURE enability (default = enable)

Returns

void

10.4.4.14 bool aDCSettings::getCalibrationMode ()

Calibration mode enability getter.

Returns

bool: enability

10.4.4.15 void aDCSettings::getCalibrationValues (CalibrationValues_t calsection, CalibrationData_t & data)

Calibration data getter, according to calsection argument.

Parameters

calsection	CalibrationValues_t : calibration parameter
data	CalibrationData_t&: calibration data

Returns

void

10.4.4.16 float aDCSettings::getCurrent (OperationMode_t mode)

Current getter.

Parameters

```
mode OperationMode_t : READ/SET mode storage access
```

Returns

float : current

10.4.4.17 uint16_t aDCSettings::getCurrentDAC ()

Current DAC value getter.

Returns

uint16_t : current DAC value

10.4.4.18 aDCSettings::DisplayMode_t aDCSettings::getDisplayMode ()

Display mode getter.

Returns

DisplayMode t: Display mode

10.4.4.19 int32_t aDCSettings::getEncoderPosition ()

Encoder position getter.

Returns

int32_t: encoder position

10.4.4.20 uint16_t aDCSettings::getFanSpeed ()

Fan speed getter.

Returns

uint16_t : DAC speed value

10.4.4.21 aDCSettings::OperationMode_t aDCSettings::getOperationMode()

Operation mode getter.

Returns

OperationMode_t : operation mode

10.4.4.22 float aDCSettings::getPower (OperationMode_t mode)

Power getter.

Parameters

mode OperationMode_t : READ/SET mode storage access

Returns

float: power

10.4.4.23 aDCSettings::SelectionMode_t aDCSettings::getPrevNextMode(aDCSettings::SelectionMode_t origin = SELECTION_MODE_UNKNOWN, bool next = true)

Get the next selection mode, according to "origin", if any provided.

Parameters

origin	SelectionMode_t : origin starter selection mode
next	bool : Next or Previous mode

Returns

SelectionMode_t : next selection mode

10.4.4.24 aDCSettings::SelectionMode_t aDCSettings::getSelectionMode ()

Selection mode getter.

Returns

SelectionMode_t : current selection mode

10.4.4.25 uint16_t aDCSettings::getTemperature ()

Temperature readed getter.

Returns

uint16_t: temperature

10.4.4.26 float aDCSettings::getVoltage ()

Voltage getter.

Returns

float: voltage

```
10.4.4.27 void aDCSettings::incEncoderPosition (int32_t v = 1)
Increment stored encoder position by "p" (default = 1)
Parameters
                  v int32_t : increment value, 1 by default
Returns
      void
10.4.4.28 bool aDCSettings::isAutolocked ( )
Check if autolock is enabled and performs.
Returns
      bool
10.4.4.29 bool aDCSettings::isDataEnabled ( uint16_t bit )
Get bit enability in m_datas bit-field storage.
Parameters
                 bit | uint16_t : Bit to check
Returns
      bool
10.4.4.30 bool aDCSettings::isFeatureEnabled ( uint16_t feature )
Check if FEATURE is enabled.
Parameters
            feature | uint16_t : FEATURE to check against
Returns
      bool
10.4.4.31 void aDCSettings::pingAutolock ( )
Reset autolock timeout.
Returns
      void
```

10.4.4.32 void aDCSettings::pingOperationMode ()

Reset timeout while in OPERATION_SET mode.

Returns

void

10.4.4.33 void aDCSettings::restoreCalibration ()

Restore calibration data from EEPROM.

Returns

void

10.4.4.34 void aDCSettings::setCalibationMode (bool enable = true)

Calibration mode enability setter.

Parameters

enable	bool : enability
--------	------------------

Returns

void

10.4.4.35 void aDCSettings::setCalibrationValues (CalibrationValues_t calsection, CalibrationData_t data)

Calibration data setter, according to calsection argument.

Parameters

calsection	CalibrationValues_t : calibration parameter
data	CalibrationData_t&: calibration data

Returns

void

10.4.4.36 aDCSettings::SettingError t aDCSettings::setCurrent (float v, OperationMode t mode)

Current setter.

Parameters

V	float : current
mode	OperationMode_t : READ/SET mode storage access

Returns

aDCSettings::SettingError_t

10.4.4.37 void aDCSettings::setCurrentDAC (uint16_t dac)

Current DAC value setter.

Parameters

dac uint16_t : current DAC value

Returns

void

10.4.4.38 void aDCSettings::setDisplayMode (DisplayMode_t d)

Display mode setter.

Parameters

d DisplayMode_t : **display mode**

Returns

void

10.4.4.39 void aDCSettings::setEncoderPosition (int32_t v)

Encoder position setter.

Parameters

v int32_t : encoder position

Returns

void

10.4.4.40 void aDCSettings::setFanSpeed (uint16_t ν)

Fan speed setter.

Parameters

v uint16_t : DAC speed value

Returns

void

10.4.4.41 void aDCSettings::setOperationMode (OperationMode_t m)

Operation mode setter.

Parameters

m OperationMode_t : new operation mode

Returns

void

10.4.4.42 aDCSettings::SettingError_t aDCSettings::setPower (float v, OperationMode_t mode)

Power setter.

Parameters

V	float : power
mode	OperationMode_t : READ/SET mode storage access

Returns

aDCSettings::SettingError_t

10.4.4.43 void aDCSettings::setSelectionMode (SelectionMode_t m, bool force = false)

Selection mode setter.

Parameters

т	SelectionMode_t : new selection mode
force	bool : force the bit setting in m_datas to be set (default : false)

Returns

void

10.4.4.44 void aDCSettings::setTemperature (uint16_t v)

Temperature readed setter.

Parameters

ν	uint16_t : temperature

Returns

void

10.4.4.45 aDCSettings::SettingError_t aDCSettings::setVoltage (float v)

Voltage setter.

Parameters

v float : voltage	V
-------------------	---

Returns

aDCSettings::SettingError_t

10.4.4.46 void aDCSettings::syncData (uint16_t bit)

Clear a bit in m_datas bit-field storage.

Parameters

1	1 1 1 0 1
bit	Lunt16 t
	amero_e

Returns

void

10.4.4.47 void aDCSettings::updateOperationMode ()

Automatic timeouted toggle between OPERATION_SET and OPERATION_READ.

Returns

void

10.4.4.48 void aDCSettings::updateValuesFromMode (float v, SelectionMode_t mode)

Update values setting (Current, Resistance, Power) according to selection mode. Sanity checking is also performed. Parameters

V	float : updated value
mode	SelectionMode_t : selection mode (CURRENT, RESISTANCE, POWER)

Returns

void

10.4.5 Member Data Documentation

10.4.5.1 const uint16_t aDCSettings::DATA_CURRENT_READ = 1 << 2 [static]

bit-field storage: Current readed

10.4.5.2 const uint16_t aDCSettings::DATA_CURRENT_SETS = 1 << 1 [static]

bit-field storage: Current sets

10.4.5.3 const uint16_t aDCSettings::DATA_DISPLAY = 1 << 9 [static]

bit-field storage: Display mode sets

10.4.5.4 const uint16_t aDCSettings::DATA_ENCODER = 1 << 10 [static]

bit-field storage: Encoder position sets

10.4.5.5 const uint16_t aDCSettings::DATA_IN_CALIBRATION = 1 << 12 [static]

bit-field storage: In calibration mode

10.4.5.6 const uint16_t aDCSettings::DATA_OPERATION = 1 << 11 [static]

bit-field storage: Operation mode sets

```
10.4.5.7 const uint16_t aDCSettings::DATA_POWER_READ = 1 << 6 [static]
bit-field storage: Power readed
10.4.5.8 const uint16_t aDCSettings::DATA_POWER_SETS = 1 << 5 [static]
bit-field storage: Power sets
10.4.5.9 const uint16_t aDCSettings::DATA_SELECTION = 1 << 8 [static]
bit-field storage: Selection mode sets
10.4.5.10 const uint16_t aDCSettings::DATA_TEMPERATURE = 1 << 7 [static]
bit-field storage: Temperature readed
10.4.5.11 const uint16_t aDCSettings::DATA_VOLTAGE = 1 [static]
bit-field storage: Voltage readed
10.4.5.12 CalibrationData_t aDCSettings::m_calibrationValues[CALIBRATION_MAX] [private]
Calibration datas, restored from EEPROM.
10.4.5.13 uint16_t aDCSettings::m_currentDAC [private]
current DAC value
10.4.5.14 uint16_t aDCSettings::m_datas [private]
boolean displayes data storage
10.4.5.15 DisplayMode_t aDCSettings::m_dispMode [private]
display mode
See Also
     DisplayMode
10.4.5.16 int32_t aDCSettings::m_encoderPos [private]
encoder position (yeah, 32bits, due to resistance max val (12000 * 1000);
10.4.5.17 uint16_t aDCSettings::m_fanSpeed [private]
fan speed storage
```

```
10.4.5.18 uint16_t aDCSettings::m_features [private]
boolean features storage
10.4.5.19 unsigned long aDCSettings::m_lockTick [private]
tick count storage, for autolock feature
10.4.5.20 SelectionMode_t aDCSettings::m_mode [private]
selection mode
See Also
     SelectionMode
10.4.5.21 OperationMode_t aDCSettings::m_operationMode [private]
operation mode
See Also
     OperationMode
10.4.5.22 unsigned long aDCSettings::m_operationTick [private]
tick count storage, for SET/READ operation
10.4.5.23 float aDCSettings::m_readCurrent [private]
current storage
10.4.5.24 float aDCSettings::m_readPower [private]
power storage
10.4.5.25 uint16_t aDCSettings::m_readTemperature [private]
temperature storage
10.4.5.26 float aDCSettings::m_readVoltage [private]
voltage storage
10.4.5.27 float aDCSettings::m_setsCurrent [private]
10.4.5.28 float aDCSettings::m_setsPower [private]
```

The documentation for this class was generated from the following files:

- aDCLoad.h
- · aDCLoad.cpp

10.5 aLCD Class Reference

```
LiquidDisplay extension class.
```

```
#include <aDCLoad.h>
```

Inherits LiquidCrystal.

Inherited by aDCDisplay.

Public Member Functions

- aLCD (uint8_t, uint8_t, uint
- ~aLCD ()

Destructor.

void begin (uint8_t, uint8_t)

Initialize LCD screen size.

• void setCursor (uint8_t, uint8_t)

Set cursor positon.

void printCenter (const char *)

Print centered string to current row.

void printCenter (const FlashStringHelper *)

Print centered string to current row.

• void clearValue (uint8_t, int=0)

Clear displayed value, from given row, stopping at value end field - destMinus.

Private Attributes

- uint8_t m_cols
- uint8_t m_rows

LCD sizes.

- uint8_t m_curCol
- uint8 t m curRow

Current cursor position.

10.5.1 Detailed Description

LiquidDisplay extension class.

10.5.2 Constructor & Destructor Documentation

10.5.2.1 aLCD::aLCD (uint8_t rs, uint8_t enable, uint8_t d0, uint8_t d1, uint8_t d2, uint8_t d3, uint8_t d4, uint8_t d5, uint8_t d6, uint8_t d7, uint8_t rows)

Constructor.

LiquidDisplay extension

Parameters

rs	uint8_t : LCD RS pin
enable	uint8_t : LCD ENABLE pin
d0	uint8_t : LCD d0 pin
d1	uint8_t : LCD d1 pin
d2	uint8_t : LCD d2 pin
d3	uint8_t : LCD d3 pin
d4	uint8_t : LCD d4 pin
d5	uint8_t : LCD d5 pin
d6	uint8_t : LCD d6 pin
d7	uint8_t : LCD d7 pin
cols	uint8_t : LCD columns number
rows	uint8_t : LCD rows number

10.5.2.2 aLCD:: \sim aLCD()

Destructor.

10.5.3 Member Function Documentation

10.5.3.1 void aLCD::begin (uint8_t cols, uint8_t lines)

Initialize LCD screen size.

Parameters

cols	uint8_t : Columns
lines	uint8_t : Rows

Returns

void

10.5.3.2 void aLCD::clearValue (uint8_t row, int destMinus = 0)

Clear displayed value, from given row, stopping at value end field - destMinus.

Parameters

row	uint8_t : field row
destMinus	int : minus end field position (default = 0)

Returns

void

10.5.3.3 void aLCD::printCenter (const char * str)

Print centered string to current row.

Parameters

str	const char* : String to display
-----	---------------------------------

Returns

void

10.5.3.4 void aLCD::printCenter (const __FlashStringHelper * ifsh)

Print centered string to current row.

Parameters

```
ifsh const __FlashStringHelper*: string to display
```

Returns

void

10.5.3.5 void aLCD::setCursor (uint8_t col, uint8_t row)

Set cursor positon.

Parameters

col	uint8_t : Column
row	uint8_t : Row

Returns

void

10.5.4 Member Data Documentation

```
10.5.4.1 uint8_t aLCD::m_cols [private]
```

10.5.4.2 uint8_t aLCD::m_curCol [private]

10.5.4.3 uint8_t aLCD::m_curRow [private]

Current cursor position.

```
10.5.4.4 uint8_t aLCD::m_rows [private]
```

LCD sizes.

The documentation for this class was generated from the following files:

- · aDCLoad.h
- · aDCLoad.cpp

10.6 aStepper Class Reference

Class that handle increase/decrease step multiplier.

```
#include <aDCLoad.h>
```

Inherited by aDCSettings.

Public Member Functions

```
• aStepper ()
      Constructor.

    ∼aStepper ()

     Destructor.
• void increment ()
     Increment value, check for boundaries.
• uint8_t getValue ()
      Value getter.
· void reset ()
      Reset value.
• int16 t getMult ()
      Value getter, according to multiple.

    int16_t getValueFromMode (uint8_t)

      Get value according to selection mode.
• bool isSynced ()
      Synchronize value.
```

Private Member Functions

• void sync ()

int16_t _pow (int, int)
 Small implementation of pow() math function.

Check if value is synchronized.

Private Attributes

```
    uint8_t m_inc
    uint8_t m_incPrev
    Stepper counters.
```

Static Private Attributes

• static const uint8_t MAX_VALUE = 3

10.6.1 Detailed Description

Class that handle increase/decrease step multiplier.

Classes declarations

Destructor.

10.6.2 Constructor & Destructor Documentation

```
10.6.2.1 aStepper::aStepper()

Constructor.

10.6.2.2 aStepper::∼aStepper()
```

10.6.3 Member Function Documentation

```
10.6.3.1 int16_t aStepper::_pow(int base, int exp) [inline], [private]
```

Small implementation of pow() math function.

Parameters

base	int : base radix
exp	int : exponent value

```
Returns
```

```
int16_t: result
```

```
10.6.3.2 int16_t aStepper::getMult ( )
```

Value getter, according to multiple.

Returns

int16_t

10.6.3.3 uint8_t aStepper::getValue ()

Value getter.

Returns

uint8_t

10.6.3.4 int16_t aStepper::getValueFromMode (uint8_t mode)

Get value according to selection mode.

Parameters

mode | uint16_t : Selection mode (will be typecasted to aDCSettings::SelectionMode_t)

Returns

int16_t

10.6.3.5 void aStepper::increment ()

Increment value, check for boundaries.

Returns

void

```
10.6.3.6 bool aStepper::isSynced ( )
Synchronize value.
Returns
     bool
10.6.3.7 void aStepper::reset ( )
Reset value.
Returns
     void
10.6.3.8 void aStepper::sync ( )
Check if value is synchronized.
Returns
     void
10.6.4 Member Data Documentation
10.6.4.1 uint8_t aStepper::m_inc [private]
10.6.4.2 uint8_t aStepper::m_incPrev [private]
Stepper counters.
10.6.4.3 const uint8_t aStepper::MAX_VALUE = 3 [static], [private]
The documentation for this class was generated from the following files:
    · aDCLoad.h

    aDCLoad.cpp
```

10.7 aDCSettings::CalibrationData_t Struct Reference

```
Calibration values.
```

```
#include <aDCLoad.h>
```

Public Attributes

float slope

Slope value.

float offset

Offset value.

10.7.1 Detailed Description

Calibration values.

Contains Slope and Offset float values

10.7.2 Member Data Documentation

10.7.2.1 float aDCSettings::CalibrationData_t::offset

Offset value.

10.7.2.2 float aDCSettings::CalibrationData_t::slope

Slope value.

The documentation for this struct was generated from the following file:

• aDCLoad.h

Chapter 11

File Documentation

11.1 aDCLoad.cpp File Reference

void serialPrint (char c)
 Serial printing.

Serial printing.
• void serialFlush ()

• void serialPrintln ()

Serial printing.

Serial printing.

Serial printing.

• void serialPrintln (char c)
Serial printing.

• int16_t serialAvailable ()

uint8 t serialRead ()

Flush serial buffer (TX)

• void serialPrint (double n, int digits)

· void serialPrintln (double n, int digits)

Reads incoming serial data.

Get the number of bytes (characters) available for reading from the serial port.

void serialPrint (int n, int16_t base=DEC)

int8_t getNumericalLength (float n, uint8_t len=3)

Get float string length, according to decimal man length.

float floatRounding (float f)

Float number rounding, extensively used.

11.1.1 Detailed Description

Copyright

```
Copyright (C) 2014-2015 F1RMB, Daniel Caujolle-Bert f1rmb.daniel@gmail.com
Copyright (C) 2014 Lee Wiggins lee@wigweb.com.au
```

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Warning

BIG FAT WARNING

Should be compiled with "-Os" flag.

Bootloader couldn't be flashed, ISP programming ONLY

-=- use Code::Blocks or the included Makefile to compile -=-

Author

```
F1RMB, Daniel Caujolle-Bert f1rmb.daniel@gmail.com Lee Wiggins lee@wigweb.com.au
```

11.1.2 Function Documentation

11.1.2.1 float floatRounding (float f)

Float number rounding, extensively used.

Float rounding functionWe just get rid of +4 decimal values

Parameters

f | float : Float to rounding

Returns

float : rounded value

11.1.2.2 int8_t getNumericalLength (float n, uint8_t len = 3)

Get float string length, according to decimal man length.

Our float to string format function

Parameters

n	float : Float number to analyse
len	uint8_t : decimal max length (3 as default)

Returns

```
int8_t : numeric value length
```

```
11.1.2.3 int16_t serialAvailable ( )
```

Get the number of bytes (characters) available for reading from the serial port.

Returns

int16_t

11.1.2.4 void serialFlush ()

Flush serial buffer (TX)

Returns

void

11.1.2.5 void serialPrint (unsigned long n, int base = DEC)

Serial printing.

Implement our serial print function to save \sim 300ko

Parameters

n	unsigned long
base	int

Returns

void

11.1.2.6 void serialPrint (const char str[])

Serial printing.

Parameters

str	char[]
-----	--------

Returns

void

11.1.2.7 void serialPrint (char c)

Serial printing.

Parameters

С	char
---	------

Returns

void

11.1.2.8 void serialPrint (int n, int16_t base = DEC)

Serial printing.

Parameters

n	int
base	int16_t

Returns

void

11.1.2.9 void serialPrint (double n, int digits)

Serial printing.

Parameters

n	double
digits	int

Returns

void

11.1.2.10 void serialPrintln ()

Serial printing.

Returns

void

11.1.2.11 void serialPrintln (double n, int digits)

Serial printing.

Parameters

n	double
digits	int

Returns

void

11.1.2.12 void serialPrintln (char c)

Serial printing.

Parameters

```
c char
```

Returns

void

```
11.1.2.13 uint8_t serialRead ( )
```

Reads incoming serial data.

Returns

uint8 t

11.1.2.14 void serialWrite (char c)

Serial printing.

Parameters

c char

Returns

void

11.2 aDCLoad.h File Reference

```
#include <float.h>
#include <LiquidCrystal.h>
#include <ClickEncoder.h>
#include <EEPROM.h>
```

Classes

· class aStepper

Class that handle increase/decrease step multiplier.

· class aDCSettings

Class that handle settings.

struct aDCSettings::CalibrationData_t

Calibration values.

• union aDCSettings::_eepromCalibrationValue_t

Union to manipulate float/uint8_t [] calibration values.

• class aLCD

LiquidDisplay extension class.

class aDCDisplay

Class that handle LCD displaying.

• class aDCEngine

Main class.

Macros

#define MAX_POWER 1

Define this if you want 192W support (otherwise 50W)

Typedefs

typedef void(* ISRCallback)()

Function prototype for ISR callback.

Variables

```
    static const uint8_t ADC_CHIPSELECT_PIN = 8
    set pin 8 as the chip select for the ADC:
```

static const uint8_t ADC_INPUTVOLTAGE_CHAN = 0

set the ADC channel that reads the input voltage.

• static const uint8 t ADC MEASUREDCURRENT CHAN = 1

set the ADC channel that reads the input current by measuring the voltage on the input side of the sense resistors.

static const uint8_t ADC_TEMPSENSE1_CHAN = 2

set the ADC channel that reads the temperature sensor 1 under the heatsink.

• static const uint8_t ADC_TEMPSENSE2_CHAN = 3

set the ADC channel that reads the temperature sensor 2 under the heatsink.

• static const uint8_t DAC_CHIPSELECT_PIN = 9

set pin 9 as the chip select for the DAC:

static const uint8_t DAC_CURRENT_CHAN = 0

set The DAC channel that sets the constant current.

• static const uint8_t DAC_FAN_CHAN = 1

set The DAC channel that sets the fan speed.

• static const uint8_t LCD_RS_PIN = 10

LCD RS pin.

• static const uint8 t LCD ENABLE PIN = 12

LCD ENABLE pin.

• static const uint8_t LCD_D0_PIN = A0

LCD d0 pin.

static const uint8_t LCD_D1_PIN = A1

LCD d1 pin.

• static const uint8_t LCD_D2_PIN = A2

LCD d3 pin.

• static const uint8_t LCD_D3_PIN = A3

LCD d2 pin.

• static const uint8_t LCD_D4_PIN = 4

LCD d4 pin.

• static const uint8_t LCD_D5_PIN = 13

LCD d5 pin.

• static const uint8_t LCD_D6_PIN = 6

LCD d6 pin.

• static const uint8_t LCD_D7_PIN = 5

LCD d7 pin.

• static const uint8_t LCD_COLS_NUM = 20

LCD columns size.

```
    static const uint8_t LCD_ROWS_NUM = 4

     LCD rows size.
• static const uint8 t ENCODER A PIN = 3
     Encoder Channel A pin, INT 0.

    static const uint8_t ENCODER_B_PIN = 2

     Encoder Channel B pin, INT 1.
• static const uint8_t ENCODER_PB_PIN = 0
     Encoder push button pin, INT 2.

    static const uint8 t ENCODER STEPS PER NOTCH = 4

     Depending on the type of your encoder, you can define use the constructors parameter stepsPerNotch an set it
     to either 1, 2 or 4 steps per notch, with 1 being the default.

    static const uint8 t LED BACKLIGHT PIN = 11

     LCD backlight pin.

    static const uint8 t OFFSET UNIT = 1

     Unit column LCD offset.

    static const uint8 t OFFSET VALUE = 4

      Value column LCD offset.
• static const uint8_t OFFSET_TEMP = 12
     Temperature column LCD offset.

    static const uint8_t OFFSET_MARKER_LEFT = 0

     Column LCD offset for left marker '['.
static const uint8_t OFFSET_MARKER_RIGHT = 14
     Column LCD offset for right marker ']'.

    static const uint8 t OFFSET SETUP MARKER LEFT = 1

     Column LCD offset for left marker '[' in setup mode.
• static const uint8_t OFFSET_SETUP_MARKER_RIGHT = 18
     Column LCD offset for right marker ']' in setup mode.

    static const uint8_t LOGGING_ICON_X_COORD = 17

     Logging icon LCD X coord.
• static const uint8_t LOGGING_ICON_Y_COORD = 3
     Logging icon LCD Y coord.

    static const uint8_t USB_ICON_X_COORD = 18

     USB icon LCD X coord.
• static const uint8_t USB_ICON_Y_COORD = 3
     USB icon LCD Y coord.

    static const uint8 t LOCK ICON X COORD = 19

     LOCK icon LCD X coord.

    static const uint8 t LOCK ICON Y COORD = 3

     LOCK icon LCD Y coord.

    static const uint8_t ALARM_OV_X_COORD = 18

     Over-voltage 'OV' text LCD X coord.
• static const uint8_t ALARM_OV_Y_COORD = 1
     Over-voltage 'OV' text LCD Y coord.

    static const uint8_t ALARM_OC_X_COORD = 18

     Over-current 'OC' text LCD X coord.

    static const uint8_t ALARM_OC_Y_COORD = 2

     Over-current 'OC' text LCD Y coord.

    static const uint8 t ALARM OT X COORD = 18

     Over-temperature 'OT' text LCD X coord.

    static const uint8 t ALARM OT Y COORD = 2
```

Over-temperature 'OT' text LCD Y coord.

```
    static const unsigned long AUTOLOCK_TIMEOUT = 60000

     Autolock timeout value (60 seconds)

    static const unsigned long OPERATION SET TIMEOUT = 3000

     Automatic toggle settings->reading timeout (3 seconds)

    static const unsigned long BACKLIGHT_TIMEOUT = 600000

     Backlight dimmer timeout (10 minutes)

    static const unsigned long LOGGING RATE = 100

      CSV data-logging rate (ms)

    static const unsigned long DISPLAY_UPDATE_RATE = 200

     Display update rate (ms)

    static const float VOLTAGE MAXIMUM = 24.000

     Maximum handled voltage (V)

    static const float CURRENT_MAXIMUM = 7.845

     Maximum value of load current (A)

    static const float POWER MAXIMUM = VOLTAGE MAXIMUM * CURRENT MAXIMUM

     Maximum power dissipated (W)

    static const uint16_t TEMPERATURE_MAXIMUM = 80

     Over-temperature threshold.

    static const int8_t SOFTWARE_VERSION_MAJOR = 2

     Software major version.

    static const int8_t SOFTWARE_VERSION_MINOR = 4

     Software minor version.

    static const uint16 t FEATURE LOGGING = 1

     Bitfield logging feature.

    static const uint16_t FEATURE_LOGGING_VISIBLE = 1 << 1</li>

     Bitfield logging icon feature.

 static const uint16_t FEATURE_USB = 1 << 2</li>

     Bitfield USB feature.

    static const uint16_t FEATURE_USB_VISIBLE = 1 << 3</li>

     Bitfield USB icon feature.

    static const uint16_t FEATURE_LOCKED = 1 << 4</li>

     Bitfield locking feature.

    static const uint16_t FEATURE_LOCKED_VISIBLE = 1 << 5</li>

     Bitfield locking icon feature.

    static const uint16_t FEATURE_AUTOLOCK = 1 << 6</li>

     Bitfield auto-lock setting feature.

    static const uint16 t FEATURE AUTOLOCK VISIBLE = 1 << 7</li>

     Bitfield auto-lock setting icon feature.

    static const uint16 t FEATURE AUTODIM = 1 << 8</li>

     Bitfield auto-dimmer setting feature.

    static const uint16 t FEATURE AUTODIM VISIBLE = 1 << 9</li>

     Bitfield auto-dimmer setting icon feature.

    static const uint16_t FEATURE_OVP = 1 << 10</li>

     Bitfield over-voltage protection feature.

    static const uint16_t FEATURE_OVP_VISIBLE = 1 << 11</li>

     Bitfield over-voltage protection icon feature.
• static const uint16_t FEATURE_OCP = 1 << 12
     Bitfield over-current protection feature.

    static const uint16 t FEATURE OCP VISIBLE = 1 << 13</li>

     Bitfield over-current protection icon feature.

    static const uint16_t FEATURE_OTP = 1 << 14</li>
```

Bitfield over-temperature protection feature.

static const uint16_t FEATURE_OTP_VISIBLE = 1 << 15

Bitfield over-temperature protection icon feature.

static const uint8 t GLYPH X1 = 0

Offset of *1 icon in LCD HD44780 controller memory.

static const uint8 t GLYPH X10 = 1

Offset of *10 icon in LCD HD44780 controller memory.

• static const uint8_t GLYPH_X100 = 2

Offset of *100 icon in LCD HD44780 controller memory.

• static const uint8 t GLYPH X1000 = 3

Offset of *1000 icon in LCD HD44780 controller memory.

static const uint8 t GLYPH USB = 4

Offset of USB icon in LCD HD44780 controller memory.

static const uint8_t GLYPH_LOCK = 5

Offset of LOCK icon in LCD HD44780 controller memory.

• static const uint8_t GLYPH_CHECKBOX_UNTICKED = 6

Offset of unticked checkbox icon in LCD HD44780 controller memory.

static const uint8 t GLYPH CHECKBOX TICKED = 7

Offset of ticked checkbox icon in LCD HD44780 controller memory.

static const int16 t EEPROM ADDR MAGIC = 0

EEPROM start offset to magic numbers (0xDEAD)

static const int16_t EEPROM_ADDR_AUTODIM = 4

EEPROM start offset for autodimming setting.

static const int16 t EEPROM ADDR AUTOLOCK = 5

EEPROM start offset for autolocking setting.

static const int16 t EEPROM CALIBRATION SIZE = (sizeof(float) * 2) + sizeof(uint8 t)

EEPROM calibration size: 2 float (slope & offset), and one uint8_t for crc.

static const int16_t EEPROM_ADDR_CALIBRATION_VOLTAGE = EEPROM_ADDR_AUTOLOCK + 1

EEPROM start offset for voltage calibration values.

• static const int16_t EEPROM_ADDR_CALIBRATION_READ_CURRENT = EEPROM_ADDR_CALIBRATION_N_VOLTAGE + EEPROM_CALIBRATION_SIZE

EEPROM start offset for current calibration values.

static const int16_t EEPROM_ADDR_CALIBRATION_DAC_CURRENT = EEPROM_ADDR_CALIBRATIONNUMBER
 N READ CURRENT + EEPROM CALIBRATION SIZE

EEPROM start offset for DAC calibration values.

static const int16_t EEPROM_ADDR_CALIBRATION_VOLTAGE_DROP = EEPROM_ADDR_CALIBRATION_N_DAC_CURRENT + EEPROM_CALIBRATION_SIZE

EEPROM start offset for DAC calibration values.

11.2.1 Detailed Description

Copyright

```
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Copyright (C) 2014 Lee Wiggins lee@wigweb.com.au
```

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Author

```
F1RMB, Daniel Caujolle-Bert f1rmb.daniel@gmail.com
Lee Wiggins lee@wigweb.com.au
```

11.2.2 Macro Definition Documentation

11.2.2.1 #define MAX_POWER 1

Define this if you want 192W support (otherwise 50W)

11.2.3 Typedef Documentation

11.2.3.1 typedef void(* ISRCallback)()

Function prototype for ISR callback.

11.2.4 Variable Documentation

```
11.2.4.1 const uint8_t ADC_CHIPSELECT_PIN = 8 [static]
```

set pin 8 as the chip select for the ADC:

```
11.2.4.2 const uint8_t ADC_INPUTVOLTAGE_CHAN = 0 [static]
```

set the ADC channel that reads the input voltage.

```
11.2.4.3 const uint8_t ADC_MEASUREDCURRENT_CHAN = 1 [static]
```

set the ADC channel that reads the input current by measuring the voltage on the input side of the sense resistors.

```
11.2.4.4 const uint8_t ADC_TEMPSENSE1_CHAN = 2 [static]
```

set the ADC channel that reads the temperature sensor 1 under the heatsink.

```
11.2.4.5 const uint8_t ADC_TEMPSENSE2_CHAN = 3 [static]
```

set the ADC channel that reads the temperature sensor 2 under the heatsink.

```
11.2.4.6 const uint8_t ALARM_OC_X_COORD = 18 [static]
```

Over-current 'OC' text LCD X coord.

```
11.2.4.7 const uint8_t ALARM_OC_Y_COORD = 2 [static]
```

Over-current 'OC' text LCD Y coord.

```
11.2.4.8 const uint8_t ALARM_OT_X_COORD = 18 [static]
Over-temperature 'OT' text LCD X coord.
11.2.4.9 const uint8_t ALARM_OT_Y_COORD = 2 [static]
Over-temperature 'OT' text LCD Y coord.
11.2.4.10 const uint8_t ALARM_OV_X_COORD = 18 [static]
Over-voltage 'OV' text LCD X coord.
11.2.4.11 const uint8_t ALARM_OV_Y_COORD = 1 [static]
Over-voltage 'OV' text LCD Y coord.
11.2.4.12 const unsigned long AUTOLOCK_TIMEOUT = 60000 [static]
Autolock timeout value (60 seconds)
11.2.4.13 const unsigned long BACKLIGHT_TIMEOUT = 600000 [static]
Backlight dimmer timeout (10 minutes)
11.2.4.14 const float CURRENT_MAXIMUM = 7.845 [static]
Maximum value of load current (A)
11.2.4.15 const uint8_t DAC_CHIPSELECT_PIN = 9 [static]
set pin 9 as the chip select for the DAC:
11.2.4.16 const uint8_t DAC_CURRENT_CHAN = 0 [static]
set The DAC channel that sets the constant current.
11.2.4.17 const uint8_t DAC_FAN_CHAN = 1 [static]
set The DAC channel that sets the fan speed.
11.2.4.18 const unsigned long DISPLAY_UPDATE_RATE = 200 [static]
Display update rate (ms)
11.2.4.19 const int16_t EEPROM_ADDR_AUTODIM = 4 [static]
EEPROM start offset for autodimming setting.
```

```
11.2.4.20 const int16_t EEPROM_ADDR_AUTOLOCK = 5 [static]
```

EEPROM start offset for autolocking setting.

11.2.4.21 const int16_t EEPROM_ADDR_CALIBRATION_DAC_CURRENT = EEPROM_ADDR_CALIBRATION_READ_C-URRENT + EEPROM_CALIBRATION_SIZE [static]

EEPROM start offset for DAC calibration values.

11.2.4.22 const int16_t EEPROM_ADDR_CALIBRATION_READ_CURRENT = EEPROM_ADDR_CALIBRATION_VOLTA-GE+EEPROM_CALIBRATION_SIZE [static]

EEPROM start offset for current calibration values.

11.2.4.23 const int16_t EEPROM_ADDR_CALIBRATION_VOLTAGE = EEPROM_ADDR_AUTOLOCK + 1 [static]

EEPROM start offset for voltage calibration values.

11.2.4.24 const int16_t EEPROM_ADDR_CALIBRATION_VOLTAGE_DROP = EEPROM_ADDR_CALIBRATION_DAC_C-URRENT + EEPROM_CALIBRATION_SIZE [static]

EEPROM start offset for DAC calibration values.

11.2.4.25 const int16_t EEPROM_ADDR_MAGIC = 0 [static]

EEPROM start offset to magic numbers (0xDEAD)

11.2.4.26 const int16_t EEPROM_CALIBRATION_SIZE = (sizeof(float) * 2) + sizeof(uint8_t) [static]

EEPROM calibration size: 2 float (slope & offset), and one uint8_t for crc.

11.2.4.27 const uint8_t ENCODER_A_PIN = 3 [static]

Encoder Channel A pin, INT 0.

11.2.4.28 const uint8_t ENCODER_B_PIN = 2 [static]

Encoder Channel B pin, INT 1.

11.2.4.29 const uint8_t ENCODER_PB_PIN = 0 [static]

Encoder push button pin, INT 2.

11.2.4.30 const uint8_t ENCODER_STEPS_PER_NOTCH = 4 [static]

Depending on the type of your encoder, you can define use the constructors parameter stepsPerNotch an set it to either 1, 2 or 4 steps per notch, with 1 being the default.

```
11.2.4.31 const uint16_t FEATURE_AUTODIM = 1 << 8 [static]
Bitfield auto-dimmer setting feature.
11.2.4.32 const uint16_t FEATURE_AUTODIM_VISIBLE = 1 << 9 [static]
Bitfield auto-dimmer setting icon feature.
11.2.4.33 const uint16_t FEATURE_AUTOLOCK = 1 << 6 [static]
Bitfield auto-lock setting feature.
11.2.4.34 const uint16_t FEATURE_AUTOLOCK_VISIBLE = 1 << 7 [static]
Bitfield auto-lock setting icon feature.
11.2.4.35 const uint16_t FEATURE_LOCKED = 1 << 4 [static]
Bitfield locking feature.
11.2.4.36 const uint16_t FEATURE_LOCKED_VISIBLE = 1 << 5 [static]
Bitfield locking icon feature.
11.2.4.37 const uint16_t FEATURE_LOGGING = 1 [static]
Bitfield logging feature.
11.2.4.38 const uint16_t FEATURE_LOGGING_VISIBLE = 1 << 1 [static]
Bitfield logging icon feature.
11.2.4.39 const uint16_t FEATURE_OCP = 1 << 12 [static]
Bitfield over-current protection feature.
11.2.4.40 const uint16_t FEATURE_OCP_VISIBLE = 1 << 13 [static]
Bitfield over-current protection icon feature.
11.2.4.41 const uint16_t FEATURE_OTP = 1 << 14 [static]
Bitfield over-temperature protection feature.
11.2.4.42 const uint16_t FEATURE_OTP_VISIBLE = 1 << 15 [static]
Bitfield over-temperature protection icon feature.
```

```
11.2.4.43 const uint16_t FEATURE_OVP = 1 << 10 [static]
Bitfield over-voltage protection feature.
11.2.4.44 const uint16_t FEATURE_OVP_VISIBLE = 1 << 11 [static]
Bitfield over-voltage protection icon feature.
11.2.4.45 const uint16_t FEATURE_USB = 1 << 2 [static]
Bitfield USB feature.
11.2.4.46 const uint16_t FEATURE_USB_VISIBLE = 1 << 3 [static]
Bitfield USB icon feature.
11.2.4.47 const uint8_t GLYPH_CHECKBOX_TICKED = 7 [static]
Offset of ticked checkbox icon in LCD HD44780 controller memory.
11.2.4.48 const uint8_t GLYPH_CHECKBOX_UNTICKED = 6 [static]
Offset of unticked checkbox icon in LCD HD44780 controller memory.
11.2.4.49 const uint8_t GLYPH_LOCK = 5 [static]
Offset of LOCK icon in LCD HD44780 controller memory.
11.2.4.50 const uint8_t GLYPH_USB = 4 [static]
Offset of USB icon in LCD HD44780 controller memory.
11.2.4.51 const uint8_t GLYPH_X1 = 0 [static]
Offset of *1 icon in LCD HD44780 controller memory.
11.2.4.52 const uint8_t GLYPH_X10 = 1 [static]
Offset of *10 icon in LCD HD44780 controller memory.
11.2.4.53 const uint8_t GLYPH_X100 = 2 [static]
Offset of *100 icon in LCD HD44780 controller memory.
11.2.4.54 const uint8_t GLYPH_X1000 = 3 [static]
Offset of *1000 icon in LCD HD44780 controller memory.
```

```
11.2.4.55 const uint8_t LCD_COLS_NUM = 20 [static]
LCD columns size.
11.2.4.56 const uint8_t LCD_D0_PIN = A0 [static]
LCD d0 pin.
11.2.4.57 const uint8_t LCD_D1_PIN = A1 [static]
LCD d1 pin.
11.2.4.58 const uint8_t LCD_D2_PIN = A2 [static]
LCD d3 pin.
11.2.4.59 const uint8_t LCD_D3_PIN = A3 [static]
LCD d2 pin.
11.2.4.60 const uint8_t LCD_D4_PIN = 4 [static]
LCD d4 pin.
11.2.4.61 const uint8_t LCD_D5_PIN = 13 [static]
LCD d5 pin.
11.2.4.62 const uint8_t LCD_D6_PIN = 6 [static]
LCD d6 pin.
11.2.4.63 const uint8_t LCD_D7_PIN = 5 [static]
LCD d7 pin.
11.2.4.64 const uint8_t LCD_ENABLE_PIN = 12 [static]
LCD ENABLE pin.
11.2.4.65 const uint8_t LCD_ROWS_NUM = 4 [static]
LCD rows size.
11.2.4.66 const uint8_t LCD_RS_PIN = 10 [static]
LCD RS pin.
```

```
11.2.4.67 const uint8_t LED_BACKLIGHT_PIN = 11 [static]
LCD backlight pin.
11.2.4.68 const uint8_t LOCK_ICON_X_COORD = 19 [static]
LOCK icon LCD X coord.
11.2.4.69 const uint8_t LOCK_ICON_Y_COORD = 3 [static]
LOCK icon LCD Y coord.
11.2.4.70 const uint8_t LOGGING_ICON_X_COORD = 17 [static]
Logging icon LCD X coord.
11.2.4.71 const uint8_t LOGGING_ICON_Y_COORD = 3 [static]
Logging icon LCD Y coord.
11.2.4.72 const unsigned long LOGGING_RATE = 100 [static]
CSV data-logging rate (ms)
11.2.4.73 const uint8_t OFFSET_MARKER_LEFT = 0 [static]
Column LCD offset for left marker '['.
11.2.4.74 const uint8_t OFFSET_MARKER_RIGHT = 14 [static]
Column LCD offset for right marker ']'.
11.2.4.75 const uint8_t OFFSET_SETUP_MARKER_LEFT = 1 [static]
Column LCD offset for left marker '[' in setup mode.
11.2.4.76 const uint8_t OFFSET_SETUP_MARKER_RIGHT = 18 [static]
Column LCD offset for right marker ']' in setup mode.
11.2.4.77 const uint8_t OFFSET_TEMP = 12 [static]
Temperature column LCD offset.
11.2.4.78 const uint8_t OFFSET_UNIT = 1 [static]
Unit column LCD offset.
```

```
11.2.4.79 const uint8_t OFFSET_VALUE = 4 [static]
Value column LCD offset.
11.2.4.80 const unsigned long OPERATION_SET_TIMEOUT = 3000 [static]
Automatic toggle settings->reading timeout (3 seconds)
11.2.4.81 const float POWER_MAXIMUM = VOLTAGE_MAXIMUM * CURRENT_MAXIMUM [static]
Maximum power dissipated (W)
11.2.4.82 const int8_t SOFTWARE_VERSION_MAJOR = 2 [static]
Software major version.
11.2.4.83 const int8_t SOFTWARE_VERSION_MINOR = 4 [static]
Software minor version.
11.2.4.84 const uint16_t TEMPERATURE_MAXIMUM = 80 [static]
Over-temperature threshold.
11.2.4.85 const uint8_t USB_ICON_X_COORD = 18 [static]
USB icon LCD X coord.
11.2.4.86 const uint8_t USB_ICON_Y_COORD = 3 [static]
USB icon LCD Y coord.
11.2.4.87 const float VOLTAGE_MAXIMUM = 24.000 [static]
Maximum handled voltage (V)
```

11.3 CDC.cpp File Reference

```
#include <CDC.cpp>
```

11.4 HardwareSerial.cpp File Reference

#include <HardwareSerial.cpp>

11.5 HID.cpp File Reference

#include <HID.cpp>

11.6 IPAddress.cpp File Reference

```
#include <IPAddress.cpp>
```

11.7 libraries.cpp File Reference

```
#include <Arduino.h>
#include "ClickEncoder.cpp"
#include "TimerOne.cpp"
```

11.8 main.cpp File Reference

```
#include <main.cpp>
```

11.9 new.cpp File Reference

```
#include <new.cpp>
```

11.10 Print.cpp File Reference

```
#include <Print.cpp>
```

11.11 README.md File Reference

11.12 sketch.cpp File Reference

```
#include <Arduino.h>
#include "aDCLoad.h"
```

Functions

- void isr ()
- void setup ()
- void loop ()

Variables

• aDCEngine engine (LCD_RS_PIN, LCD_ENABLE_PIN, LCD_D0_PIN, LCD_D1_PIN, LCD_D2_PIN, LCD_D3_PIN, LCD_D4_PIN, LCD_D5_PIN, LCD_D6_PIN, LCD_D7_PIN, LCD_COLS_NUM, LCD_ROWS_NUM, ENCODER_A_PIN, ENCODER_B_PIN, ENCODER_PB_PIN, ENCODER_STEPS_PER_NOTCH)

11.12.1 Function Documentation

```
11.12.1.1 void isr ( )
```

```
11.12.1.2 void loop ( )
11.12.1.3 void setup ( )
```

11.12.2 Variable Documentation

11.12.2.1 aDCEngine engine(LCD_RS_PIN, LCD_ENABLE_PIN, LCD_D0_PIN, LCD_D1_PIN, LCD_D2_PIN, LCD_D3_PIN, LCD_D4_PIN, LCD_D5_PIN, LCD_D6_PIN, LCD_D7_PIN, LCD_COLS_NUM, LCD_ROWS_NUM, ENCODER_A_PIN, ENCODER_B_PIN, ENCODER_PB_PIN, ENCODER_STEPS_PER_NOTCH)

!!!!! BIG FAT WARNING !!!!! Should be compiled with "-Os" flag. Bootloader couldn't be flashed, ISP programming ONLY -=- use Code::Blocks or the included Makefile to compile -=-

11.13 Stream.cpp File Reference

```
#include <Stream.cpp>
```

11.14 Tone.cpp File Reference

```
#include <Tone.cpp>
```

11.15 USBCore.cpp File Reference

```
#include <USBCore.cpp>
```

11.16 WInterrupts.c File Reference

```
#include <WInterrupts.c>
```

11.17 wiring.c File Reference

```
#include <wiring.c>
```

11.18 wiring_analog.c File Reference

```
#include <wiring_analog.c>
```

11.19 wiring_digital.c File Reference

```
#include <wiring_digital.c>
```

11.20 wiring_pulse.c File Reference

```
#include <wiring_pulse.c>
```

11.21 wiring_shift.c File Reference

#include <wiring_shift.c>

11.22 WMath.cpp File Reference

#include <WMath.cpp>

11.23 WString.cpp File Reference

#include <WString.cpp>

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