

Changing the default I2C bus speed on the Raspberry Pi can help improve the performance of some projects. This is particularly important when using the I2C interface to control a display module. In the newer versions of Raspbian this change must be made using a Device Tree parameter.

The bus speed is sometimes referred to as “baudrate” although the two aren’t actually the same thing.

### **Step 1 – Enable the I2C Interface**

Before the interface baudrate can be changed the I2C interface must be enabled. This can be done using “raspi-config” on the command line or “Raspberry Pi Configuration” on the Raspbian desktop.

For step-by-step instructions on how to do this please take a look at the [Enable I2C Interface on the Raspberry Pi](#) post.

### **Step 2 – Edit Config.txt File to set I2C Bus Speed**

Using the following command the config.txt file can be edited :

```
sudo nano /boot/config.txt
```

Find the line containing “dtparam=i2c\_arm=on”.

Add “,i2c\_arm\_baudrate=400000” where 400000 is the new speed (400 Kbit/s). Note the comma.

This should give you a line looking like :

```
dtparam=i2c_arm=on,i2c_arm_baudrate=400000
```

This enables the bus and sets the baudrate at the same time with a comma separating both parameters.

Use CTRL-X, then Y, then RETURN to save the file and exit.

### **Step 3 – Reboot**

Finally, reboot the Pi for the new setting to take effect :

```
sudo reboot
```

### **I2C Baudrate Values**

The [BCM2835 ARM Peripherals specification](#) (page 28) says that the Pi has a “fast-mode” (400Kb/s) driver. For this reason I would recommend using 100000 or 400000 as baudrate values. The default is usually set to 100000. I successfully used 400000 with an OLED display module to increase the rate at which images could be updated.