	101123	SIOI	1 P	Idl	I M	issio	n Plar	nner(	(s): _							Da	te:						
0	10	20	30	40	50	60	70	80	90	100	110	120	130	140	150 16	50 170	) 180 ´	190	200				
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100		<b>a</b> /							21.6			23.		0									
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70		3	19		<b>(3)</b>				97			•				• •			70				
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(	Goals, C	bject	ive(s)	•						Б.		1.					100 -1 0. 75 -0.5 0. 50 0 1.	.0 .3					
-											t Goa						40 0.2 1.   30 0.4 2.   25 0.5 3.   20 0.6 4.	.0 10 cr	m 14.14 cm				
_									Estir	mated	d Tim	ne:					17 0.66 4. 15 0.7 5.	.7	10 cm		+ move		
	Results	, Feed	lback	•								1		2	3		14 0.72 6.   13 0.74 6.   12 0.76 7.   11 0.78 8.	.7 .3 \	Wheel Dia.: 5.56 Wheel Circ.: 17.	6 cm	<b>†</b>	otate	
-									Tri	ial Tin	ne:						10 0.8 9. 9 0.82 10	0.1	π = 3.1416 2πr = πD = 360°			, cate	
_									Tria	ıl Poir	nts:						7 0.86 13 6 0.88 15 3 0.94 32 2 0.96 49	i.3 i.7 !.3	R <sub>Bot</sub> :	_	- move		

Title: \_\_\_\_\_

Otter Bot