

Scrum Results Sheet:

Team Number: L2C-C5

Date: Jan/28/2025

Scrum Master Initials: SP

Name #1	Adarsh Sood
	Since last scrum: <ul style="list-style-type: none">- Fixed Python script for angle measurement.
	Working on today: <ul style="list-style-type: none">- Demonstrate angle measurement assignment with group.- Test out logic level shifter.
	Roadblocks: <ul style="list-style-type: none">- Stepper Motor cannot be powered with 3.3V, so test out logic level shifter.
Name #2	Samarr Parmaar
	Since last scrum: <ul style="list-style-type: none">- Fixed Python script for angle measurement as there were strange spikes in the graphing.
	Working on today: <ul style="list-style-type: none">- Begin assembling robot kit after demonstrating angle measurement with group.
	Roadblocks: <ul style="list-style-type: none">- None
Name #3	Faaiz Majeed
	Since last scrum: <ul style="list-style-type: none">- Verified the functionality of the ultrasonic sensor with Adarsh to see if it would be accurate enough.
	Working on today: <ul style="list-style-type: none">- Work on Bluetooth functionality to ensure 2-way communication is smooth.
	Roadblocks: <ul style="list-style-type: none">- Bluetooth is connecting between the laptop and Arduino but unable to send or receive data.