

Scrum Results Sheet:

Team Number: L2C-C5

Date: January/30/2025

Scrum Master Initials: FM

Name #1	Adarsh Sood
	Since last scrum: <ul style="list-style-type: none">- Fixed the Stepper Motor & IR Sensor Homing Feature
	Working on today: <ul style="list-style-type: none">- Finishing the Soldering in-class assignment
	Roadblocks: <ul style="list-style-type: none">- Wire up the circuitry for the PWM to test the motor driver (with Samarr)
Name #2	Samarr Parmaar
	Since last scrum: <ul style="list-style-type: none">- Made progress on completing the robot build.
	Working on today: <ul style="list-style-type: none">- Finishing the Soldering in-class assignment
	Roadblocks: <ul style="list-style-type: none">- Rods are too long for our needs and need to 3D print a stopper to allow the 4 long rods to stay in place.- Wire up the circuitry for the PWM to test the motor driver (With Adarsh)
Name #3	Faaiz Majeed
	Since last scrum: <ul style="list-style-type: none">- Fixed 2-way Bluetooth communication.
	Working on today: <ul style="list-style-type: none">- Finishing the Soldering in-class assignment
	Roadblocks: <ul style="list-style-type: none">- Bluetooth receiving on the laptop from the robot is a little slow (perhaps some small issues need to be addressed).