

### Scrum Results Sheet:

Team Number: L2C-C5

Date: Feb-06-2025

Scrum Master Initials: AS

Name #1	Adarsh Sood
	Since last scrum: <ul style="list-style-type: none"><li>- Re-printed the 3<sup>rd</sup> level of the robot.</li></ul>
	Working on today: <ul style="list-style-type: none"><li>- Fix on the slip ring and sonar sensor.</li></ul>
	Roadblocks: <ul style="list-style-type: none"><li>- None</li></ul>
Name #2	Samarr Parmaar
	Since last scrum: <ul style="list-style-type: none"><li>- Finished attaching all the mechanical components of the robot.</li></ul>
	Working on today: <ul style="list-style-type: none"><li>- Re wire the motor drive circuit to make it easier to read.</li></ul>
	Roadblocks: <ul style="list-style-type: none"><li>- Have to retest the motors to make sure the forward direction is forward and the backward direction is backward.</li></ul>
Name #3	Faaiz Majeed
	Since last scrum: <ul style="list-style-type: none"><li>- Worked on the GUI of our robot controller python script.</li></ul>
	Working on today: <ul style="list-style-type: none"><li>- Figure out the RPM vs Duty Cycle characteristic curve of our DC motors.</li></ul>
	Roadblocks: <ul style="list-style-type: none"><li>- Figure out a method of actually measuring RPM vs Duty Cycle (perhaps IR sensors?)</li><li>-</li></ul>