Prototype networks for few-shot learning

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Summary

- ❖ Introduction
 - Challenge
 - Few-shot learning
- Project workflow
 - Datasets
 - Prototypical Networks
 - Centroids
 - NC, NS, NQ
 - Loss, Optimizer, scheduler
 - Training skeleton
 - Code
- Experiments
 - Omniglot
 - Mini Imagenet
 - ➤ Flowers102
 - Comparison
- Conclusion

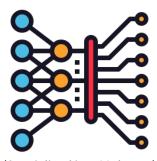
Intro

Challenge

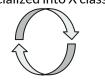
'classic' Classification Task







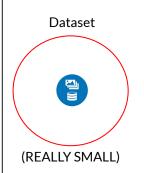
(Specialized into X classes)

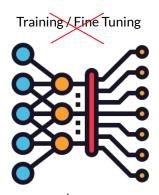


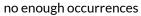
Deploy



Our Challenge Classification Task

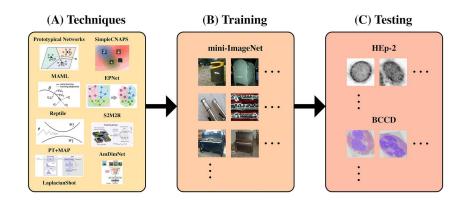




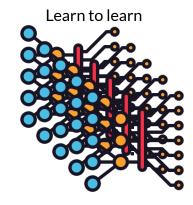


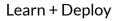
Few-shot learning

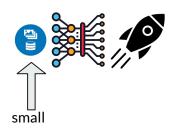
- A meta-learning technique to 'learn to learn'
- Uses **small amount** of occurrences
- Can perform with **high accurancies**



Dataset







Meta-learning definition

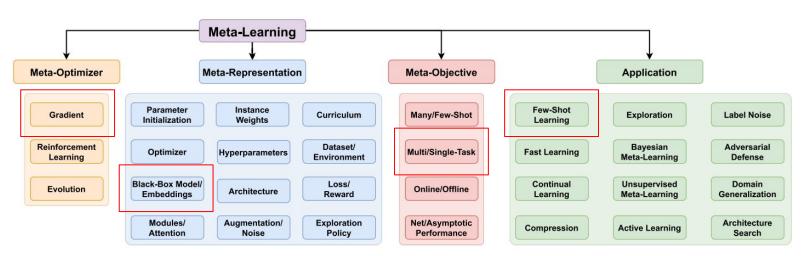


Fig. 1. Overview of the meta-learning landscape including algorithm design (meta-optimizer, meta-representation, meta-objective), and applications.

Project workflow

Datasets

- Omniglot: 1623 handwritten characters
 - 80 images per class
 - classes: (1032 train, 172 val, 464 test)
- Mini Imagenet: 100 objects
 - 600 images per class
 - classes: (64 train, 16 val, 20 test)
- Flowers 102: 102 flowers
 - 40-120 images per class
 - classes: (64 train, 16 val, 22 test)

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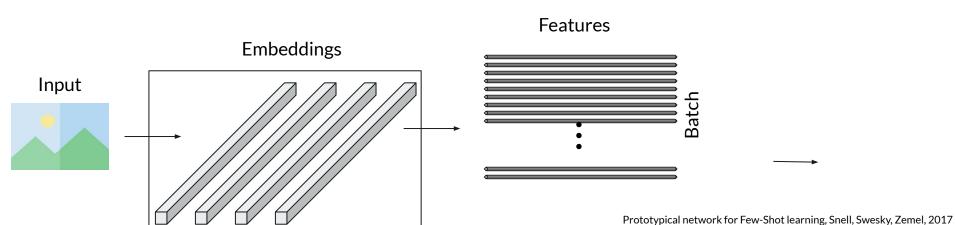






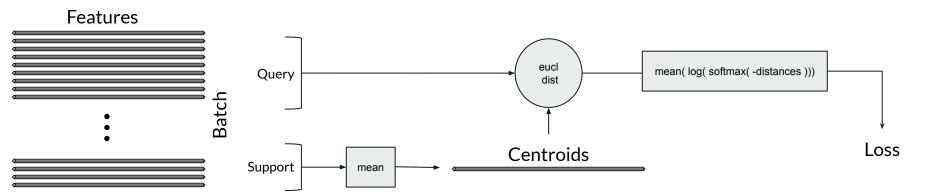
Prototypical Networks

- Extracts features with a neural network
 - 4 CNN blocks: Conv out=64, ks=3 / BatchNorm2D / ReLu / MaxPool2D
- Learning: embeddings learning
 - Trained 100 episodes/iterations per epochs (200 ep) to learn embeddings



Prototypical Networks - centroids

- Use a small part of output as support, other as query
- Centroids are mean(support)
- Calculate distances between query and centroids
- Calculate loss as mean of log_softmax of negative distances



Prototypical Networks - NC, NS, NQ

- NC: how many classes to use per each iteration on batch (or 'ways')
- NS: how many examples to use as support for centroids calculus (or 'shots')
- NQ: how many examples to use as queries for centroids calculus ('query')
 - 1 shots -> One-Shot Learning
 - 5 shots -> Few-Shot Learning ____ \mathbf{c}_1

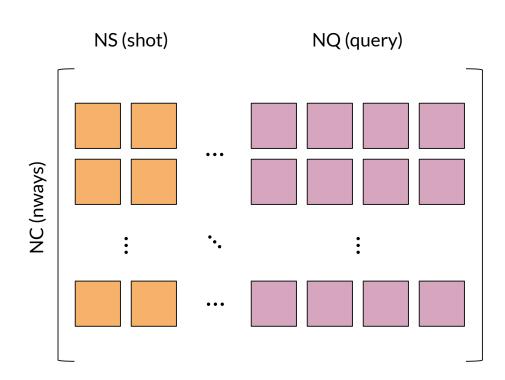
Loss, optimizer, scheduler

- Loss: mean(log_softmax(-distances(query, centroids), targets)
- Optimizer: Adam with Ir=0.001
- Scheduler: StepLr with step_size=20, gamma = 0.5

One batch

Training skeleton

```
model = PrototypicalNet()
loss = loss_function(x, y, NC, NS, NQ)
optim = StepLr()
for epoch in epochs:
for it in iterations:
 x, y = GetSample(NC, NS, NQ)
 out = model(x)
  ... loss
  backward()
for it in iterations:
 .... eval ....
```



Code

All code is available at github

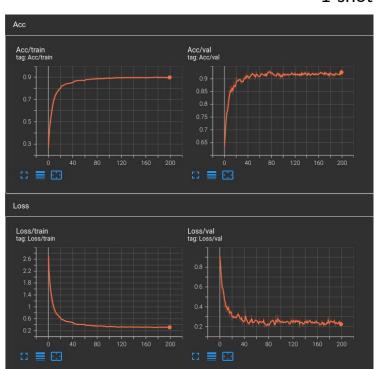
- Full hyperparams control
- 3 available datasets
- results and plots
- simple train.py and test.py scripts

```
python train.py --dataset mini_imagenet \
       --epochs 200 \
       --gpu∖
       --train-num-class 30 \
       --test-num-class 5 \
       --number-support 5 \
       --train-num-query 15\
       --episodes-per-epoch 100 \
       --adam-lr 0.001 \
       --opt-step-size 20 \
       --opt-gamma 0.5 \
       --distance-function "euclidean" \
       --save-each 5
```

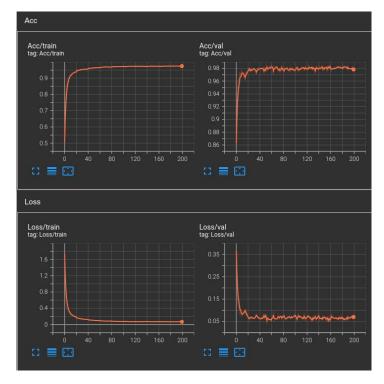
Experiments

Omniglot



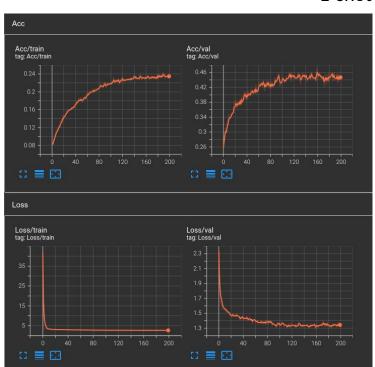


5-shot

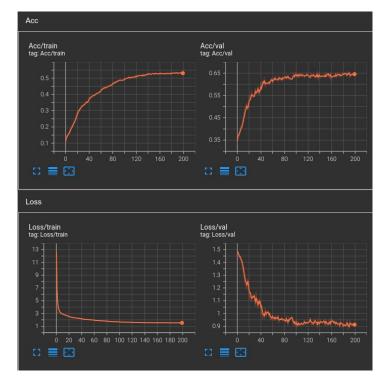


Mini Imagenet



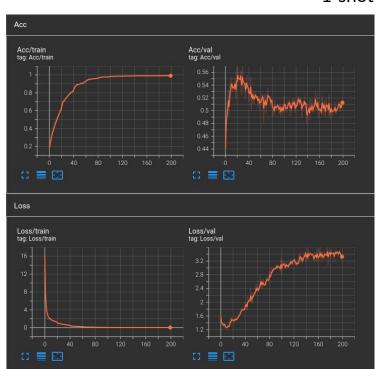


5-shot

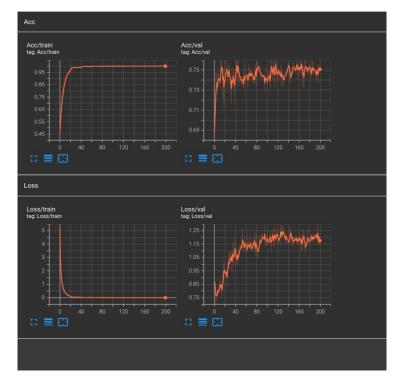


Flowers 102





5-shot



Comparison - distance metric

Dataset	Cosine (acc)	Euclidean (acc)	
mini_imagenet	22.36	63.62	
omniglot	23.48	97.77	
flowers102	82.89	84.48	

Comparison - one vs few shot vs paper

Dataset	Paper res 5-way 5-shot (Acc)	Our res 5-way 5-shot (Acc)	Paper res 5-way 1-shot (Acc)	Our res 5-way 1-shot (Acc)
mini_imagenet	68.20	63.62	49.42	46.13
omniglot	98.80	97.77	98.8	91.93
flowers102	1	84.48	1	56.08

Conclusions

Conclusion

- Euclidean distance performs better than cosine similarity
- Paper results were correctly replicated

Future studies

- Add custom dataset option for training
- Implement proper torch.nn.Dataset and torch.nn.Sampler + torch.nn.DataLoader
- Try different fields than CV