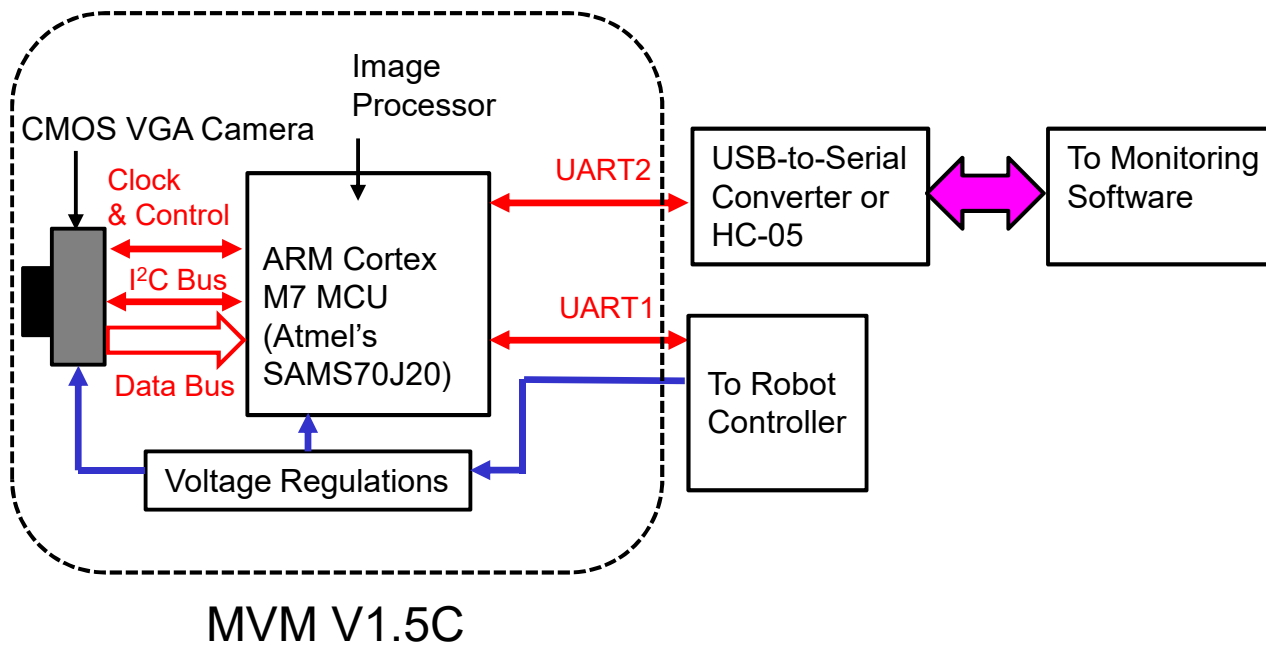
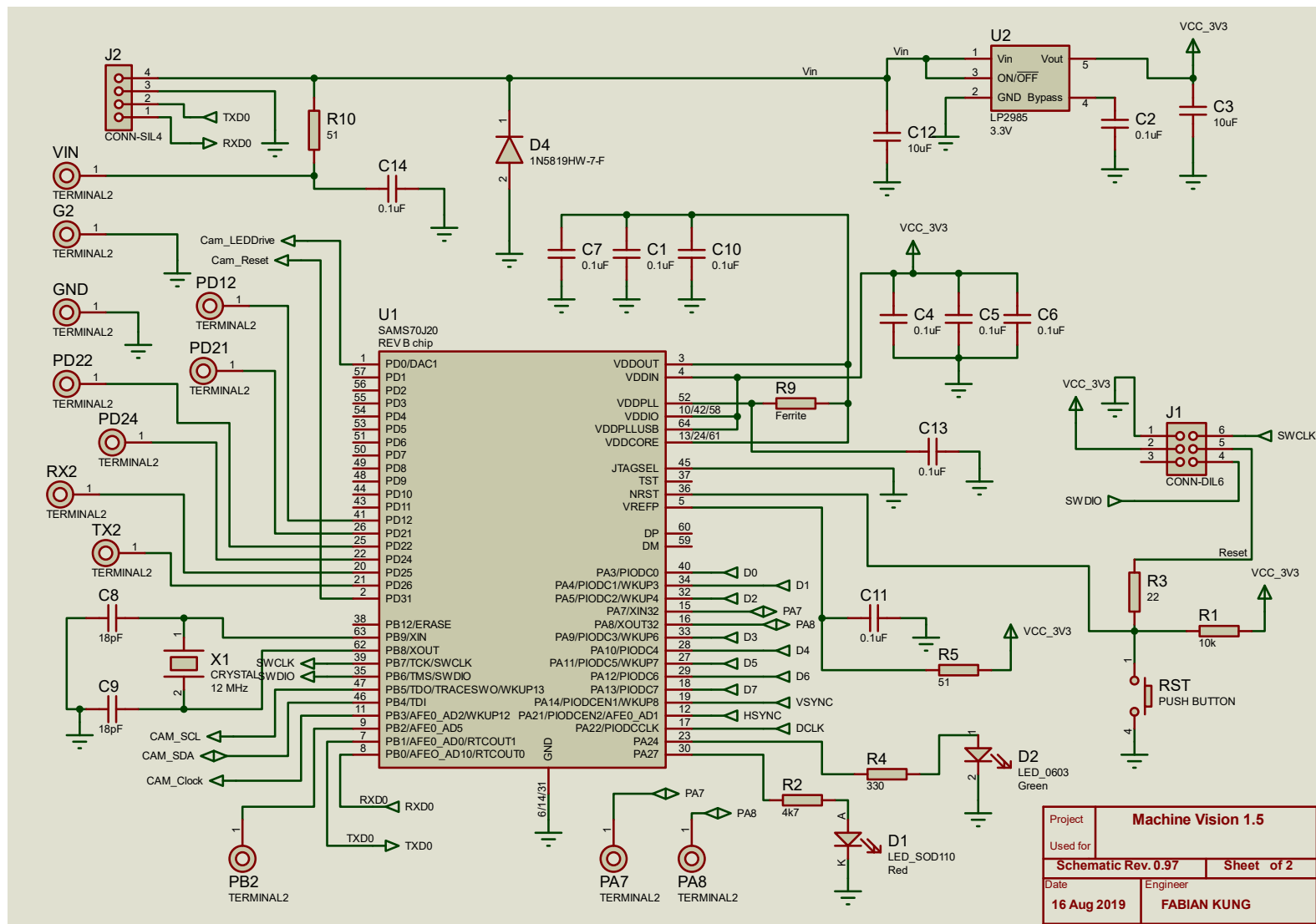

MVM V1.5C Quick Start Guide

Rev 0.90

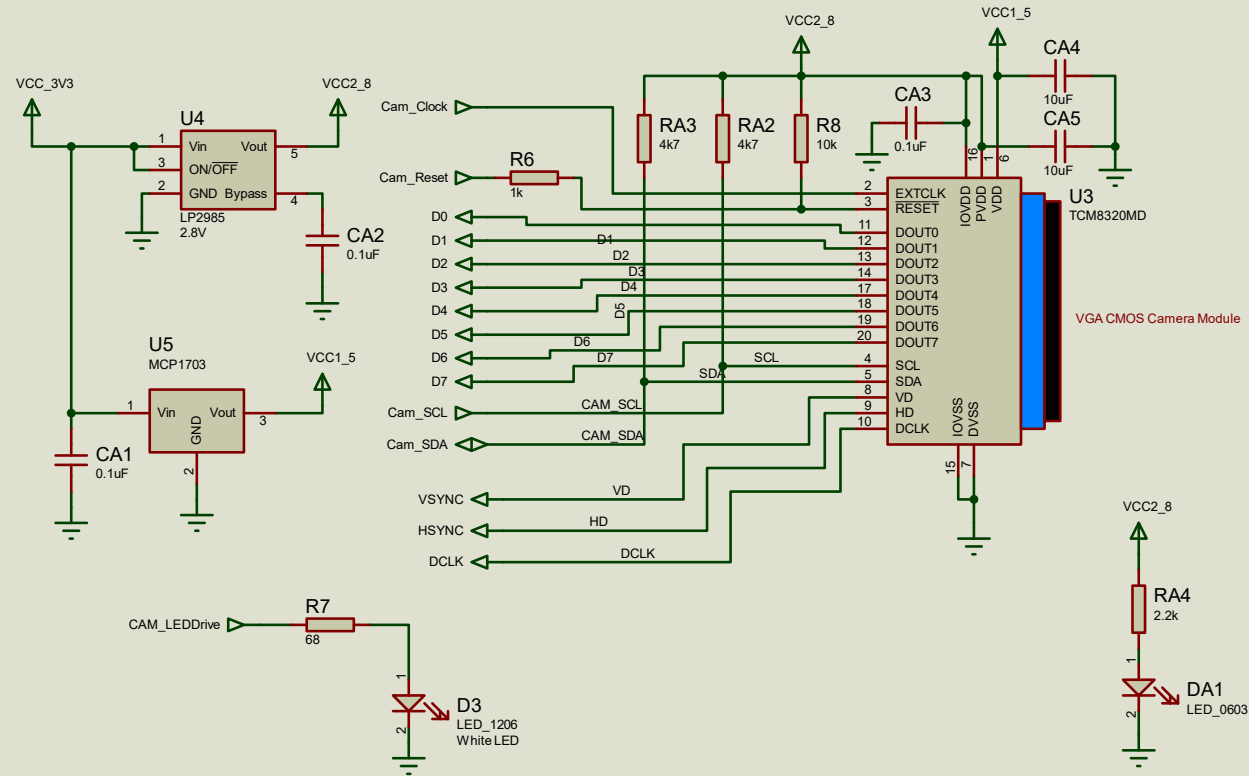
Block Diagram



Schematic 1 – Micro-controller Core

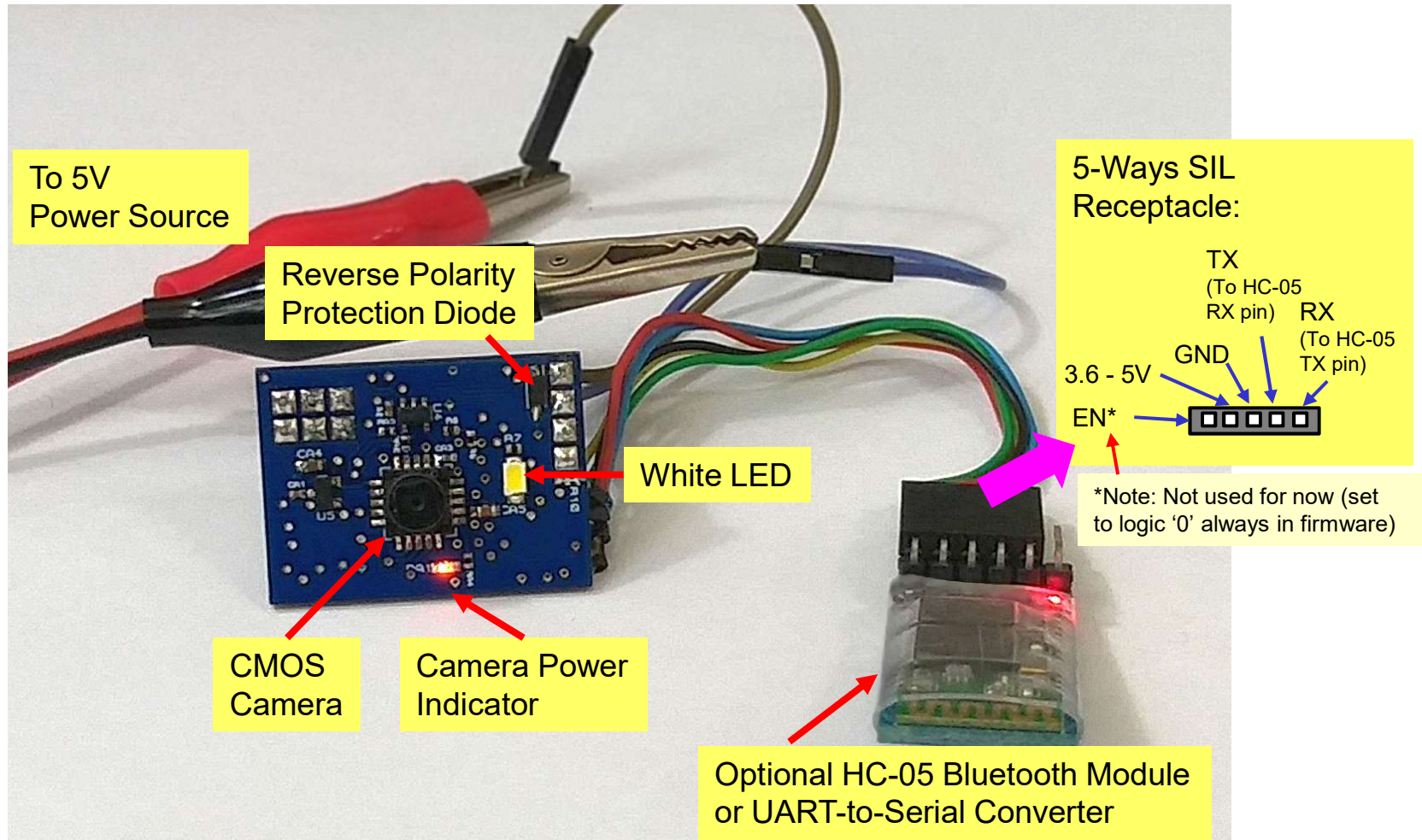


Schematic 2 – Camera Sub-Circuit

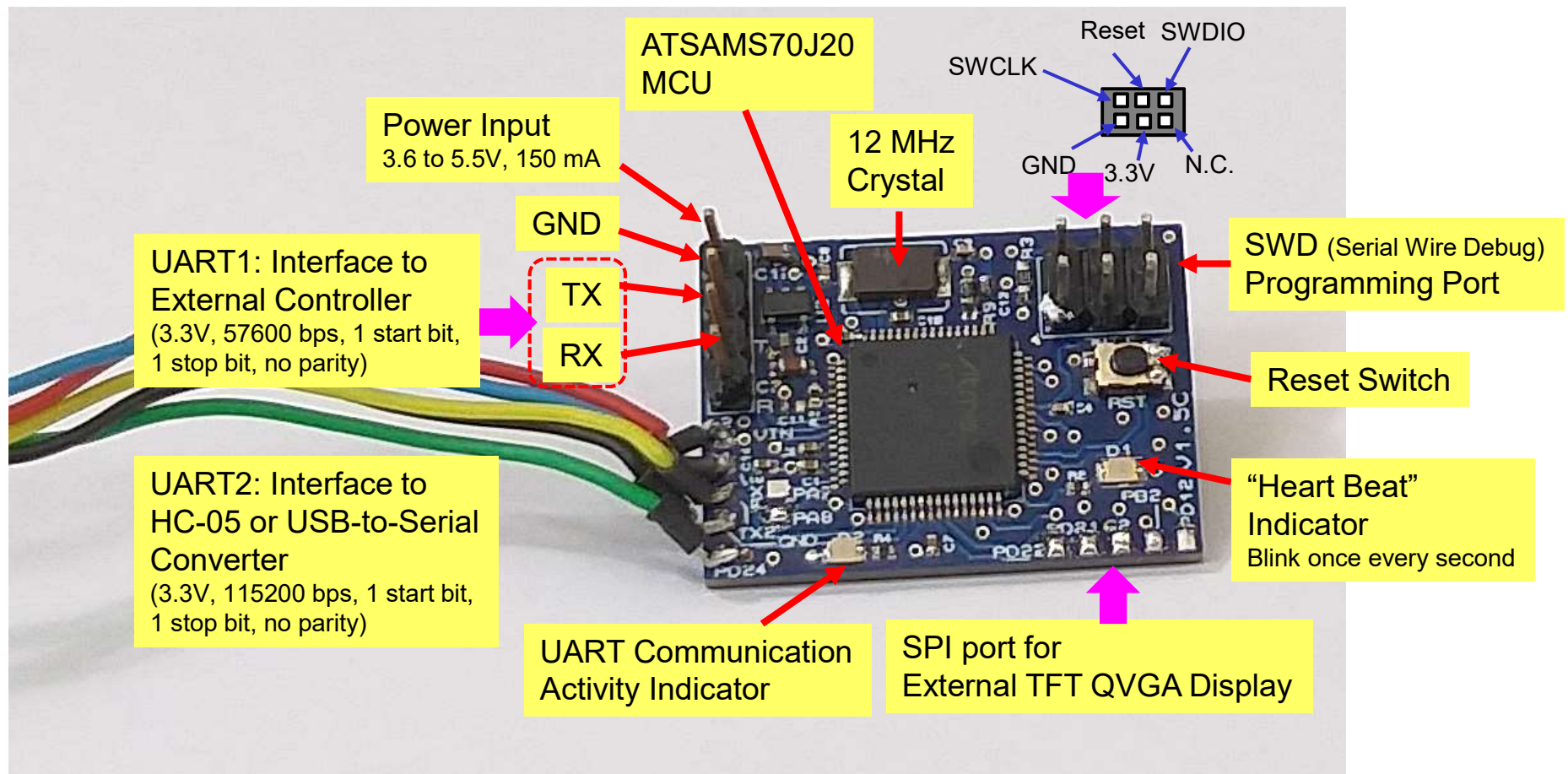


Project	Machine Vision 1.5	
Used for	Schematic Rev. 0.97	
Date	16 Aug 2019	Engineer FABIAN KUNG
	Sheet	of 2

Rear View (MVM V1.5C)



Front View (MVM V1.5C)



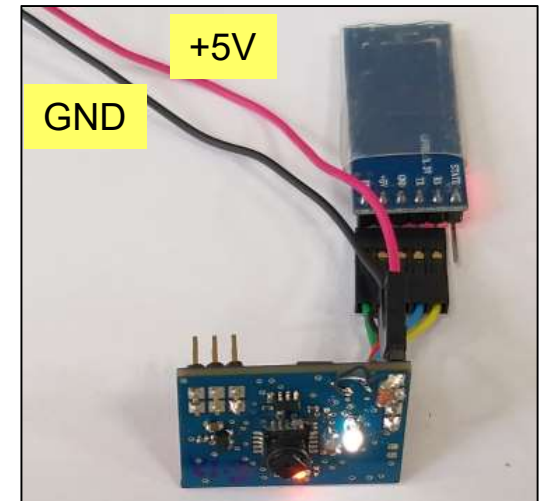
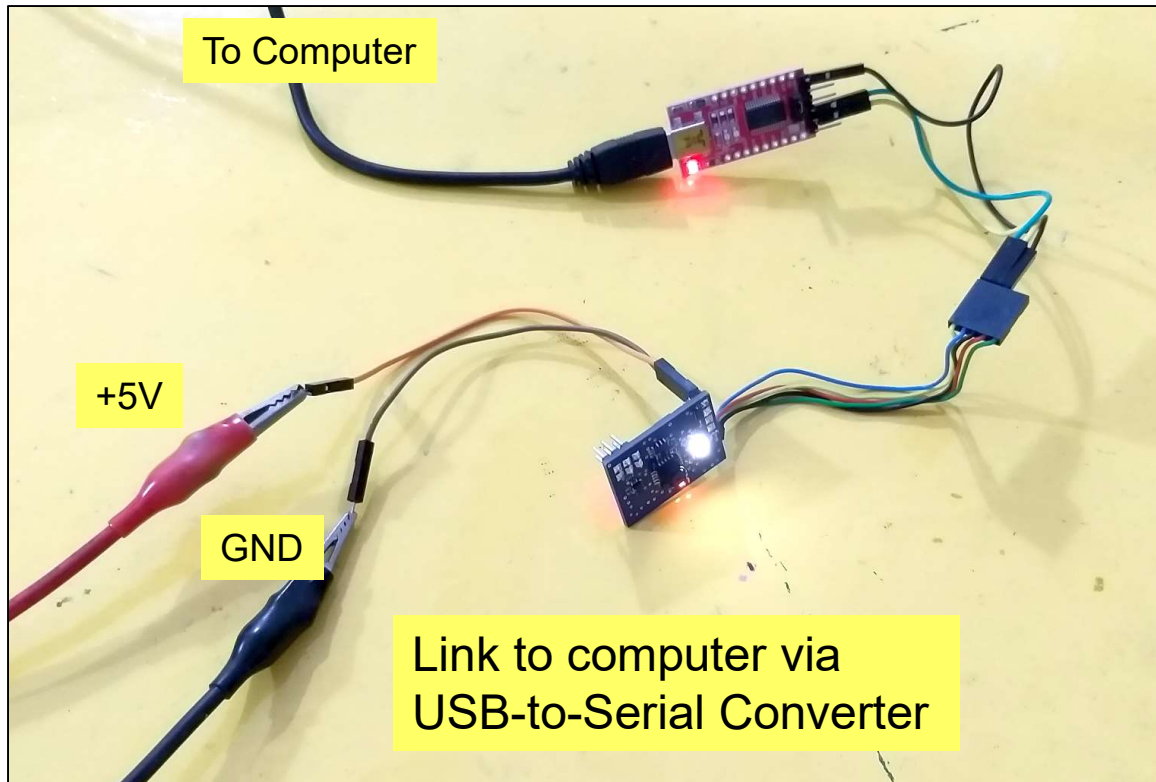
Files

- All relevant files can be obtained from https://github.com/fabiankung/MVM_V1_5C
- Firmware is build using **Atmel Studio 7**.
- PC software is build using **Visual Studio Community 2017**.

Observe the Camera Image via Machine Vision Monitor Software

Step 1 – Power Up the MVM

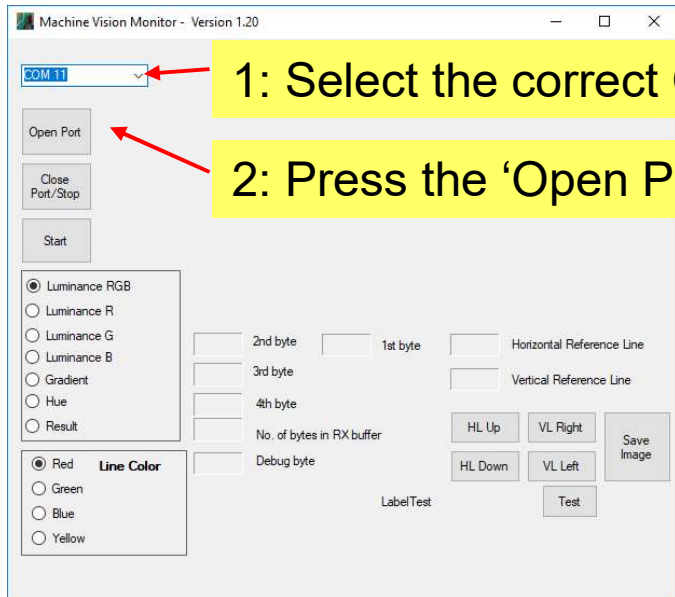
- Here we assume the MVM is connected to HC-05 Bluetooth wireless module or a USB-to-Serial Converter, as shown in the various implementation examples below. Power up the module.



Step 2 – Pair Computer to HC-05

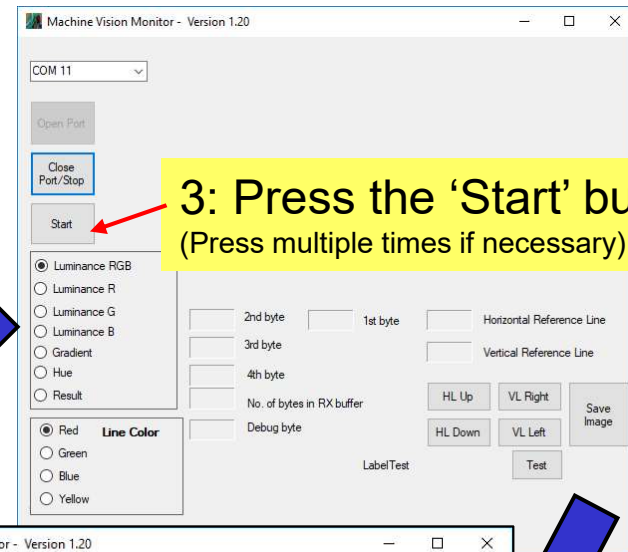
- If need to pair the computer to HC-05.
- Then check virtual COM port number on the computer (for instance by going to the Device Manager).

Step 3 – Run the Machine Vision Monitor Software

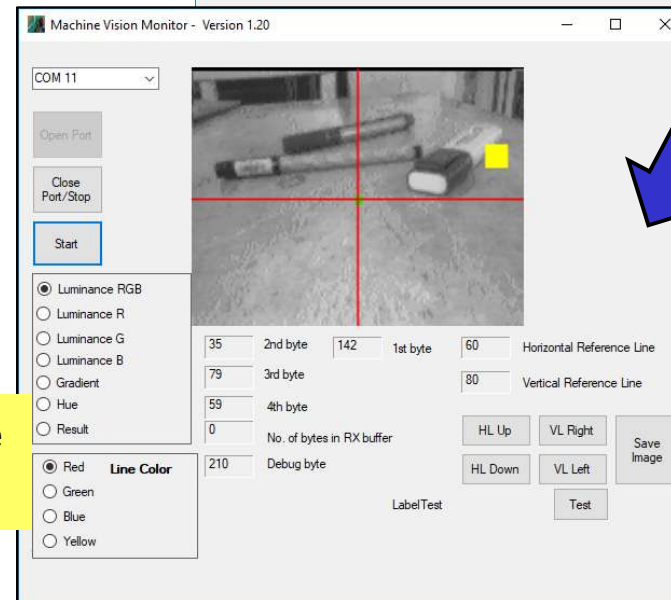
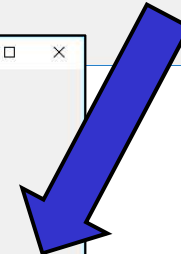


1: Select the correct COM port

2: Press the 'Open Port' button



3: Press the 'Start' button
(Press multiple times if necessary)



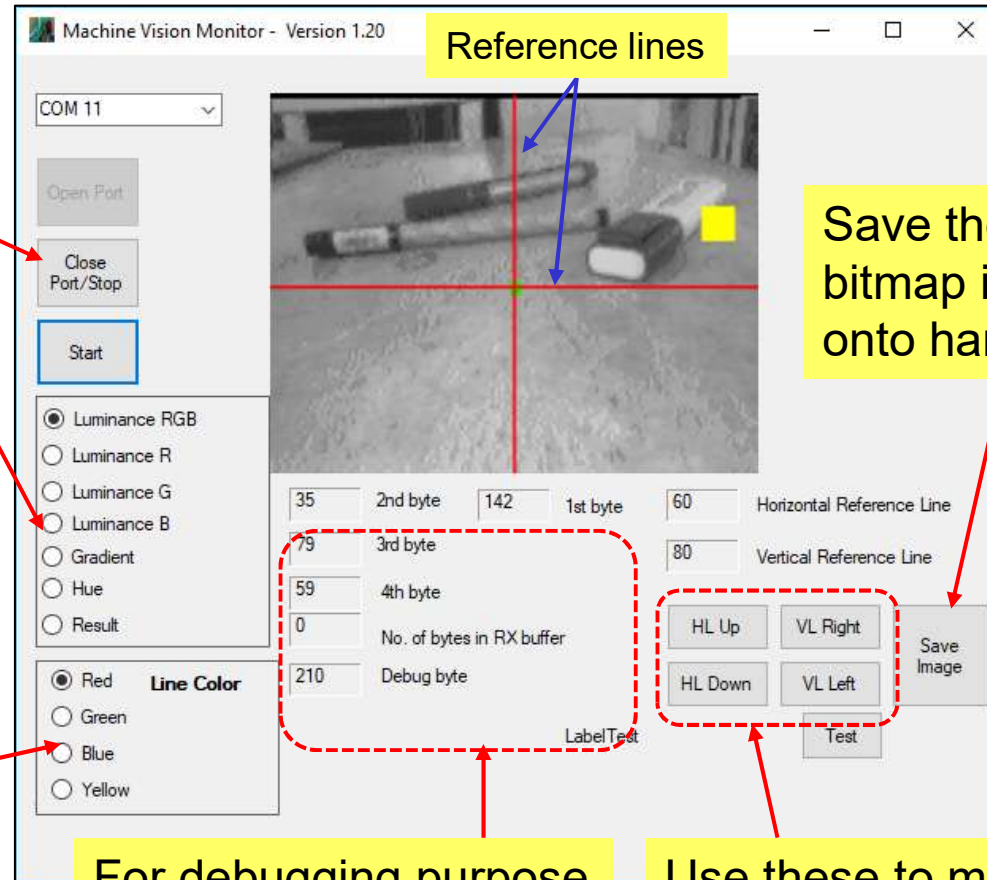
4: Now the MVM will transmit the image data line-by-line to the monitor software

Other Information

Always close the COM port before shutting down the software

Select between various display options. All these are processed in the MVM.

Change reference line color.



Reference lines

Save the current bitmap in display onto hard disk

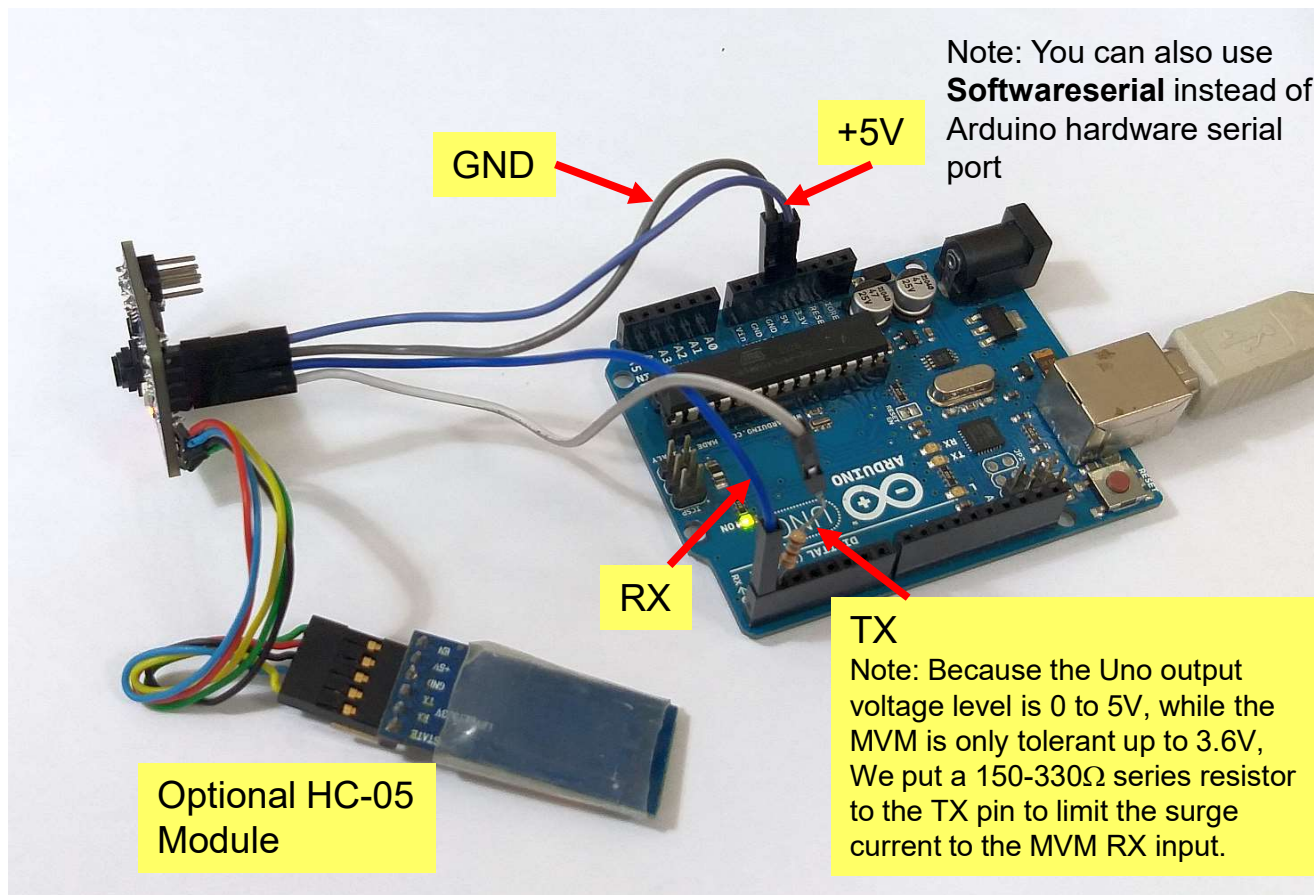
For debugging purpose (see source codes)

Use these to move the reference lines.

Connection to External Controller for Robotic Projects

Connection to External Controllers

- Here we use an Arduino Uno to demonstrate the connection.



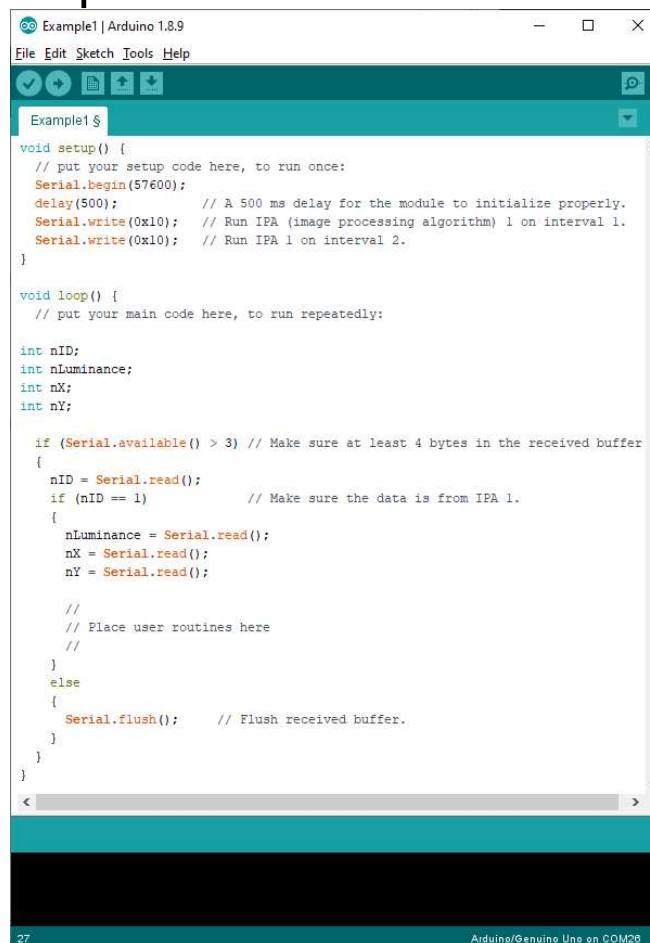
UART1 Communication Protocol

Image Processing Algorithm (IPA)	To Activate	MVM Output
Search for brightest spot in a scene. Image resolution = 160x120	Send hex values to MVM: 0x10 to search for brightest spot	4 bytes: Byte 1 = 1 (Algorithm ID) Byte 2 = Maximum luminance value (1 to 127). Byte 3 = x coordinate of region Byte 4 = y coordinate of region
Obstacle detection on lower half of the image. Image resolution = 160x120	Send hex value to MVM: 0x20	4 bytes: Byte 1 = 2 Byte 2 = 0b00000b ₂ b ₁ b ₀ Byte 3 = 0b00000b ₂ b ₁ b ₀ Byte 4 = 0b00000b ₂ b ₁ b ₀
Color object detection. Image resolution = 160x120	Send hex values to MVM: 0x30 for yellow-green object 0x31 for red object 0x32 for green object 0x33 for blue object	4 bytes: Byte 1 = 3 Byte 2 = Number of pixels matched Byte 3 = x coordinate of region Byte 4 = y coordinate of region

255 will be send for (x,y) if region with matching color is not found

Example 1 – Activate Search for Brightest Spot Algorithm

- Assume the MVM is connected to an Arduino Uno. The left panel shows a simple Arduino Sketch to activate the image processing algorithm to search for brightest spot on both **Interval 1** and **2**, giving effective response time of 50 ms.



```
Example1 | Arduino 1.8.9
File Edit Sketch Tools Help

Example1 $

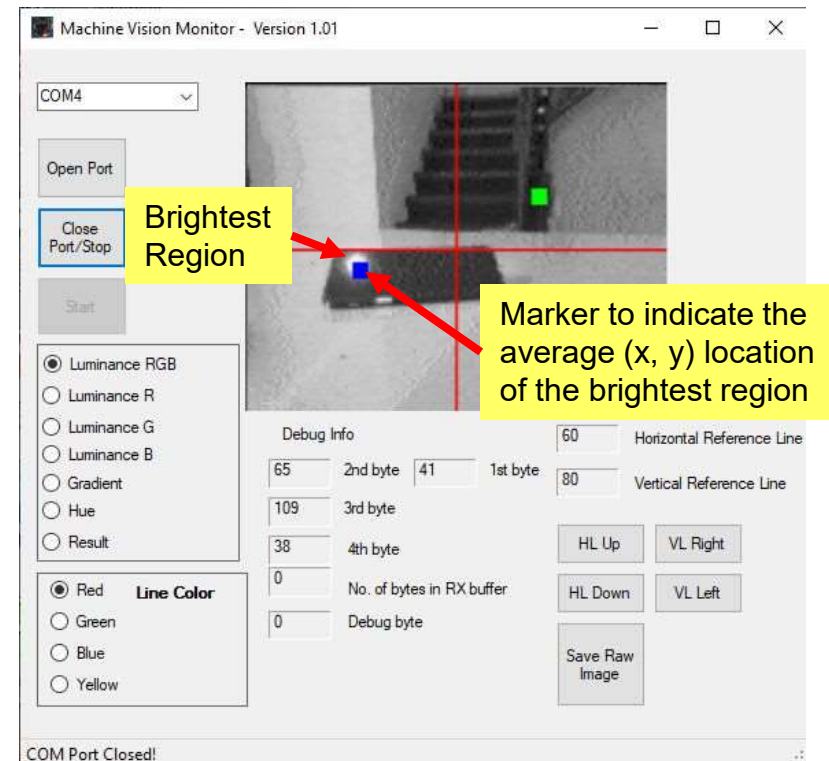
void setup() {
  // put your setup code here, to run once:
  Serial.begin(57600);
  delay(500); // A 500 ms delay for the module to initialize properly.
  Serial.write(0x10); // Run IPA (image processing algorithm) 1 on interval 1.
  Serial.write(0x10); // Run IPA 1 on interval 2.
}

void loop() {
  // put your main code here, to run repeatedly:

  int nID;
  int nLuminance;
  int nX;
  int nY;

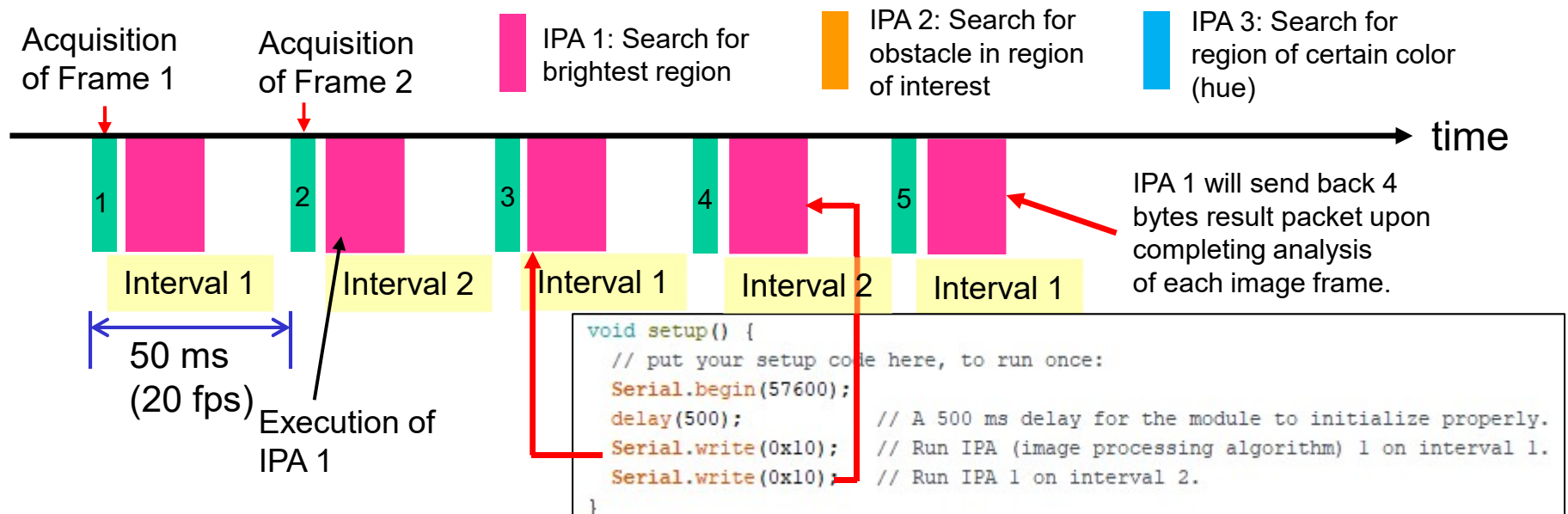
  if (Serial.available() > 3) // Make sure at least 4 bytes in the received buffer
  {
    nID = Serial.read();
    if (nID == 1) // Make sure the data is from IPA 1.
    {
      nLuminance = Serial.read();
      nX = Serial.read();
      nY = Serial.read();

      //
      // Place user routines here
      //
    }
    else
    {
      Serial.flush(); // Flush received buffer.
    }
  }
}
```



Example 1 - More on 'Interval'

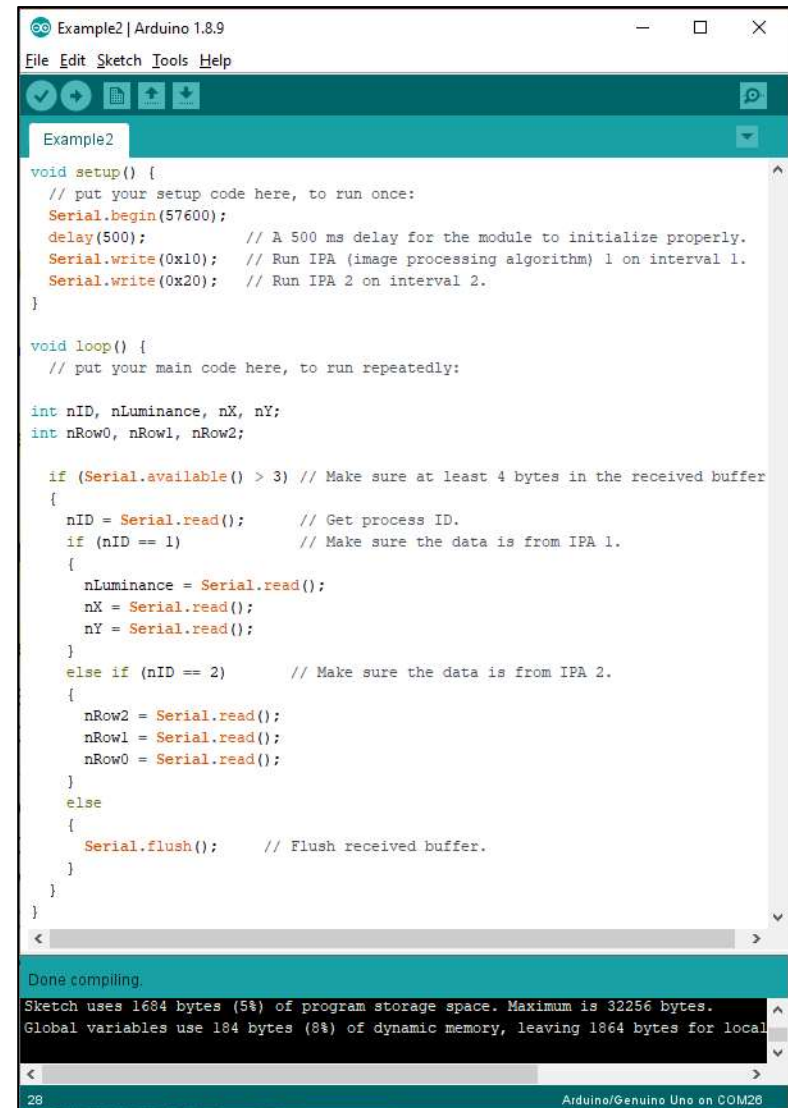
- The firmware of MVM V1.5C assigns odd image frames to *Interval 1* and even image frames to *Interval 2*.
- An image processing algorithm (IPA) can be attached to each interval as shown below and executed after acquisition of a new image frame.



- The C code snippet attaches IPA 1 to both Interval 1 and Interval 2 of the execution flow, thus in this setting IPA 1 runs every 50 ms and any changes in scene is detected within 50 ms.

Example 2 - Activate Both Search for Brightest Region (IPA 1) and Obstacle (IPA 2) Algorithms

- In this example we attach IPA 1 to Interval 1 and IPA 2 to Interval 2.
- Thus a robot using the MVM V1.5C can be programmed to move towards a bright light source while at the same time avoid any obstacle on the floor.



```
Example2 | Arduino 1.8.9
File Edit Sketch Tools Help

Example2

void setup() {
  // put your setup code here, to run once:
  Serial.begin(57600);
  delay(500); // A 500 ms delay for the module to initialize properly.
  Serial.write(0x10); // Run IPA (image processing algorithm) 1 on interval 1.
  Serial.write(0x20); // Run IPA 2 on interval 2.
}

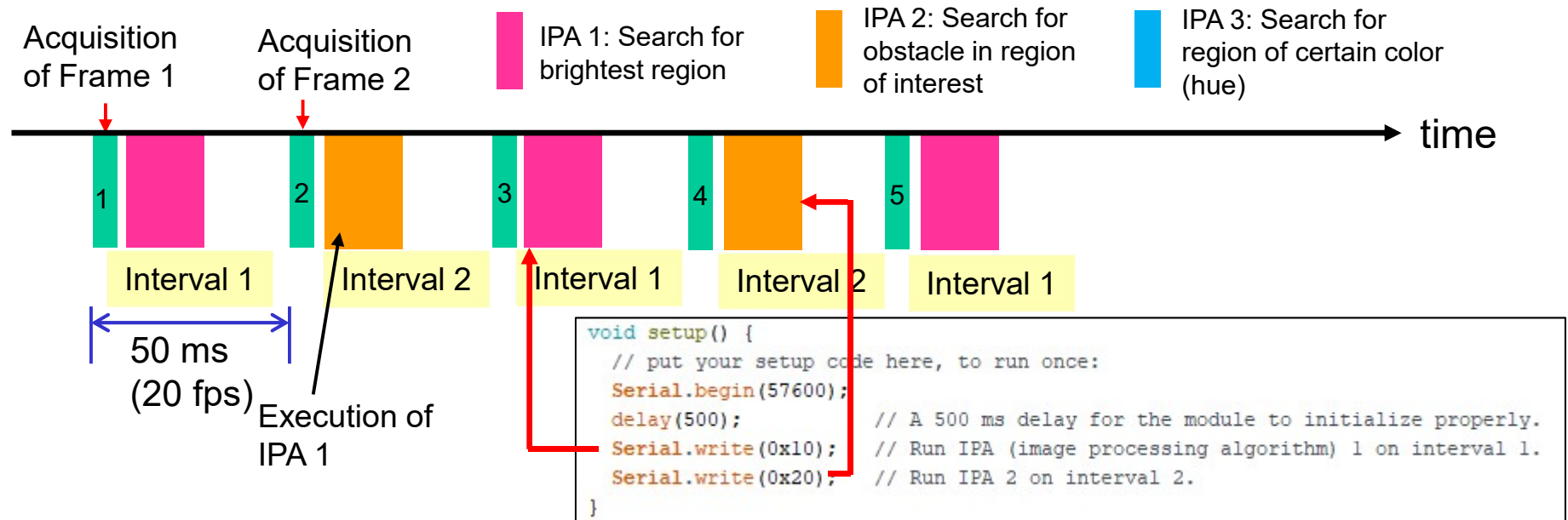
void loop() {
  // put your main code here, to run repeatedly:

  int nID, nLuminance, nX, nY;
  int nRow0, nRow1, nRow2;

  if (Serial.available() > 3) // Make sure at least 4 bytes in the received buffer
  {
    nID = Serial.read(); // Get process ID.
    if (nID == 1) // Make sure the data is from IPA 1.
    {
      nLuminance = Serial.read();
      nX = Serial.read();
      nY = Serial.read();
    }
    else if (nID == 2) // Make sure the data is from IPA 2.
    {
      nRow2 = Serial.read();
      nRow1 = Serial.read();
      nRow0 = Serial.read();
    }
    else
    {
      Serial.flush(); // Flush received buffer.
    }
  }
}

Done compiling
Sketch uses 1684 bytes (5%) of program storage space. Maximum is 32256 bytes.
Global variables use 184 bytes (8%) of dynamic memory, leaving 1864 bytes for local
28 Arduino/Genuino Uno on COM28
```

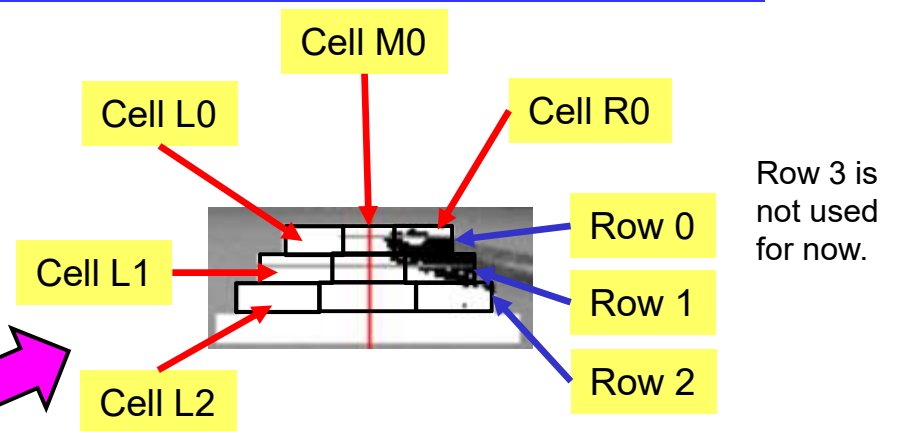
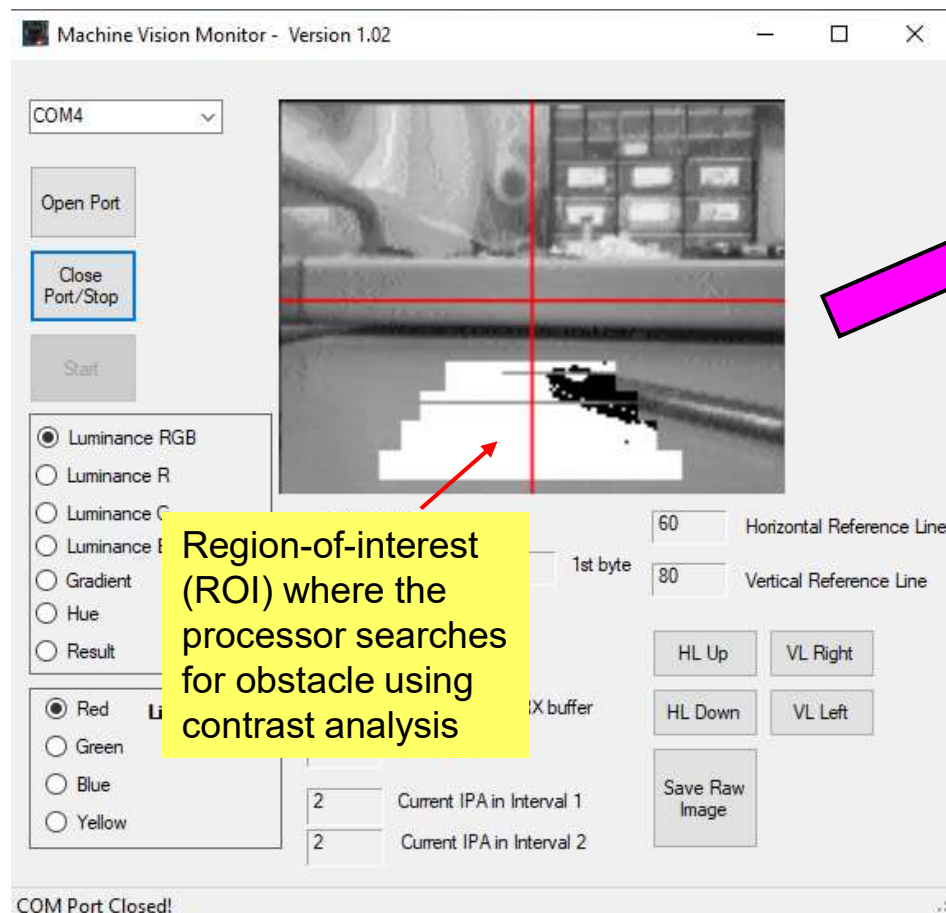
Example 2 – The Assignment of IPAs to Intervals



- Each IPA only executes every 100 ms, thus the response time now slows down to 100 ms, however the up side is we get to run two different algorithms simultaneously.

Interpreting the Results of IPA 2

- When IPA 2 is activated:



Whenever the number of black pixels exceed a pre-determined threshold in a cell, an obstacle is deemed present. Thus, for this example, cells R0, M0 and R1 contains Obstacle and the bits corresponding to these cells will be set to '1'. The following result packet will be transmitted via UART 1 from MVM V1.5C:

Byte 1 = 2 ID

Byte 2 = 0b00000000 Row 2

Byte 3 = 0b00000001 Row 1

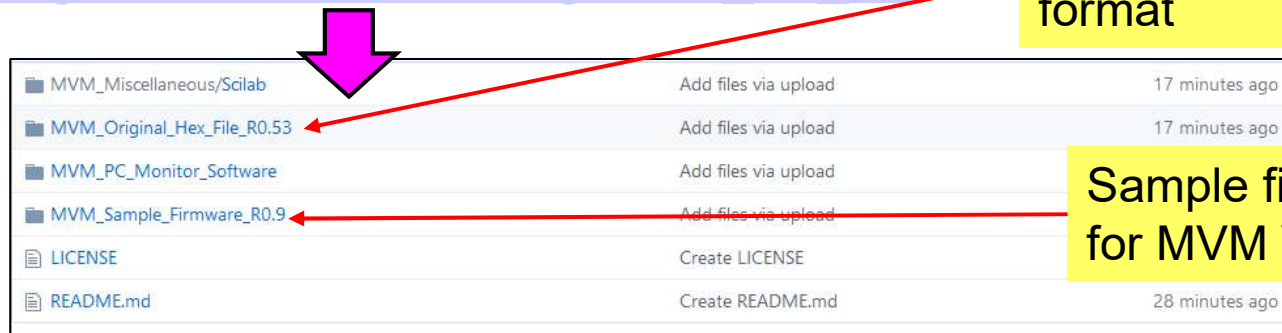
Byte 4 = 0b00000011 Row 0

 L M R

Compiling and Building Your Own Firmware for MVM V1.5C

Introduction

- Clone the sample firmware from https://github.com/fabiankung/MVM_V1_5C



The screenshot shows a file upload interface with a list of items. A large pink arrow points from the URL in the list item above to the 'MVM_Miscellaneous/Scilab' folder. Two red arrows point from yellow text boxes to 'MVM_Original_Hex_File_R0.53' and 'MVM_Sample_Firmware_R0.9' respectively.

MVM_Miscellaneous/Scilab	Add files via upload	17 minutes ago
MVM_Original_Hex_File_R0.53	Add files via upload	17 minutes ago
MVM_PC_Monitor_Software	Add files via upload	
MVM_Sample_Firmware_R0.9	Add files via upload	
LICENSE	Create LICENSE	
README.md	Create README.md	28 minutes ago

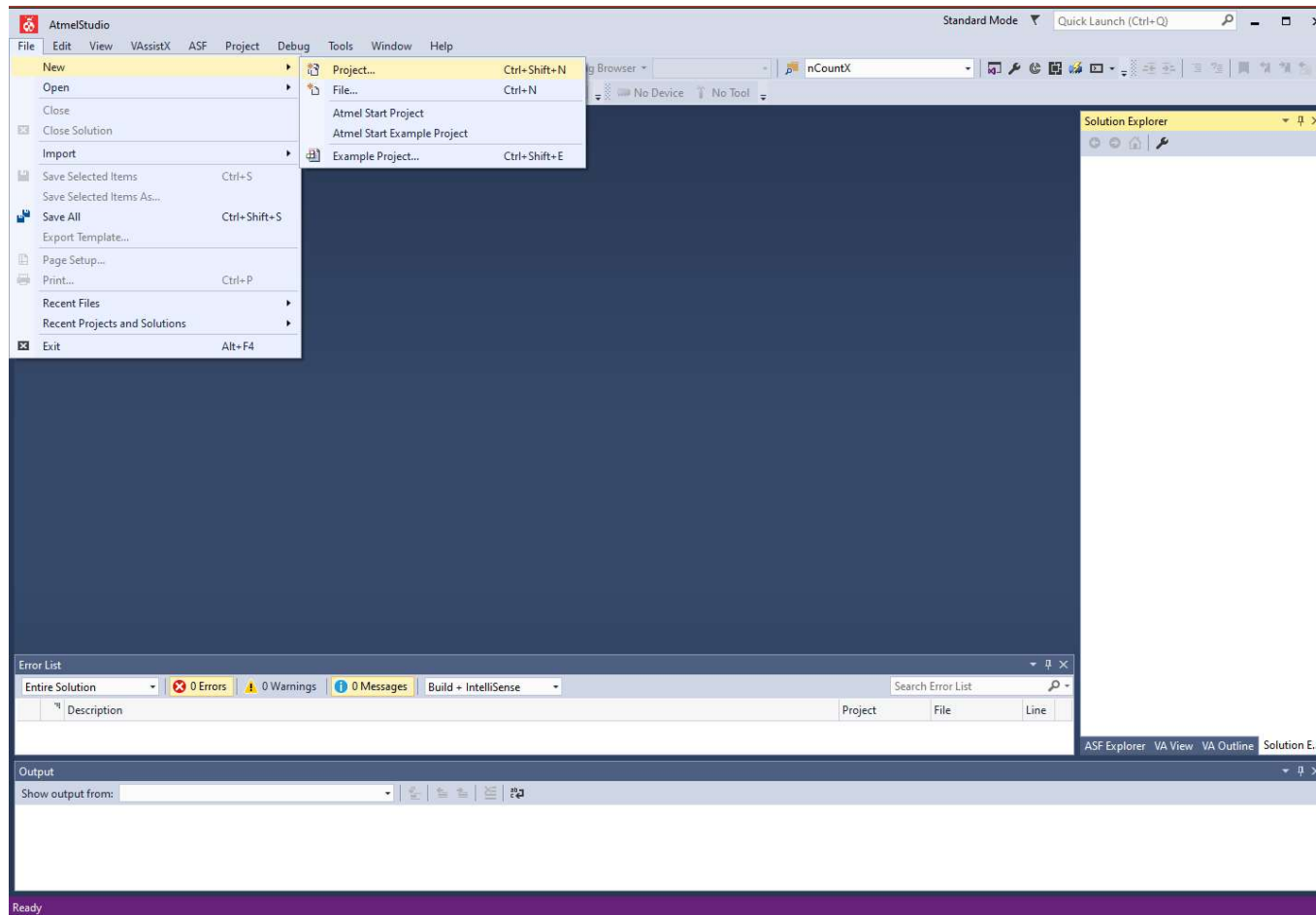
Original firmware in hex format

Sample firmware for MVM V1.5C

- “MVM_Sample_Firmware” contains all the drivers files and IPA 1 routines.

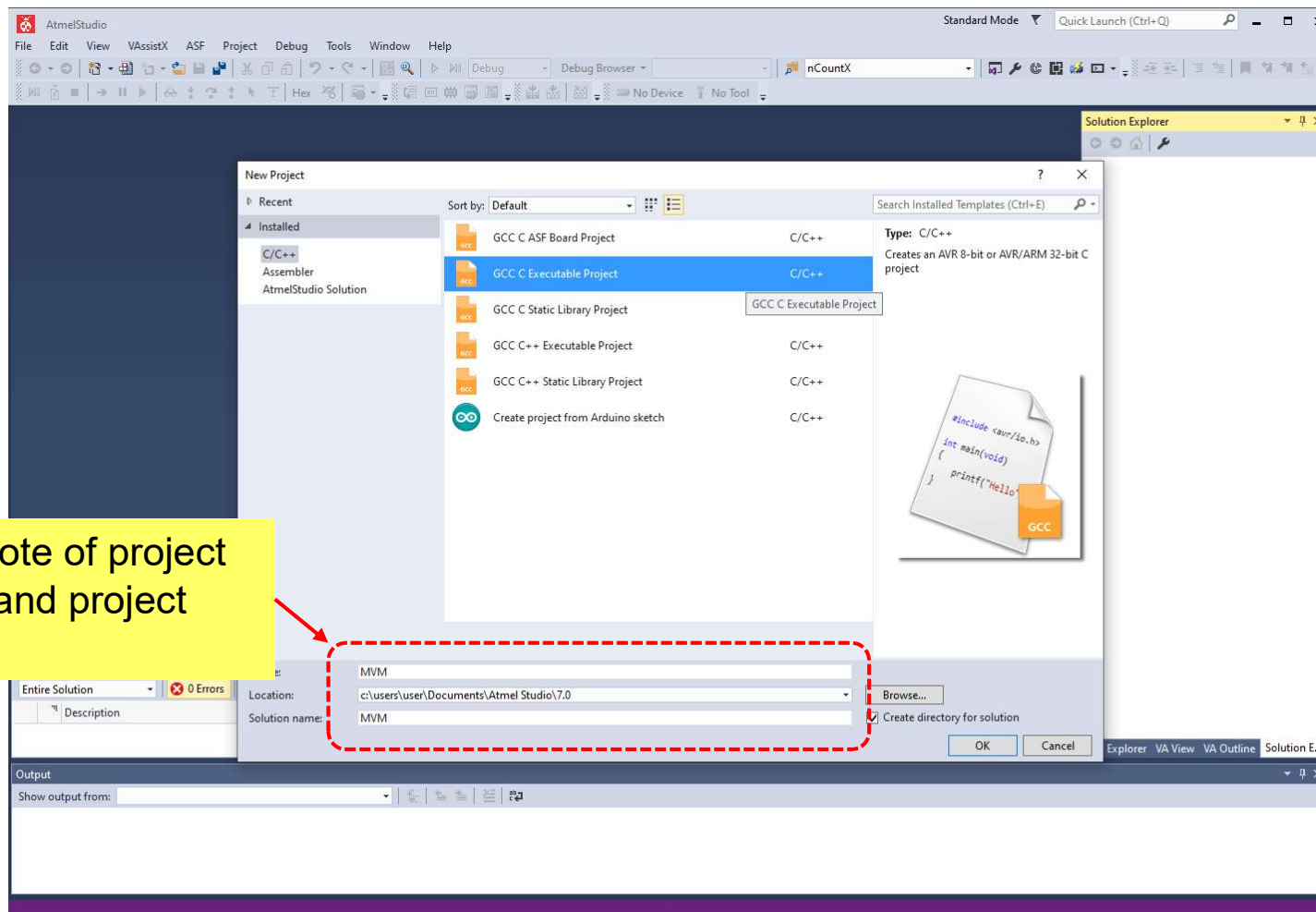
Setting Up An Atmel Studio Project 1

- Start a new project in Atmel Studio 7.



Setting Up An Atmel Studio Project 2

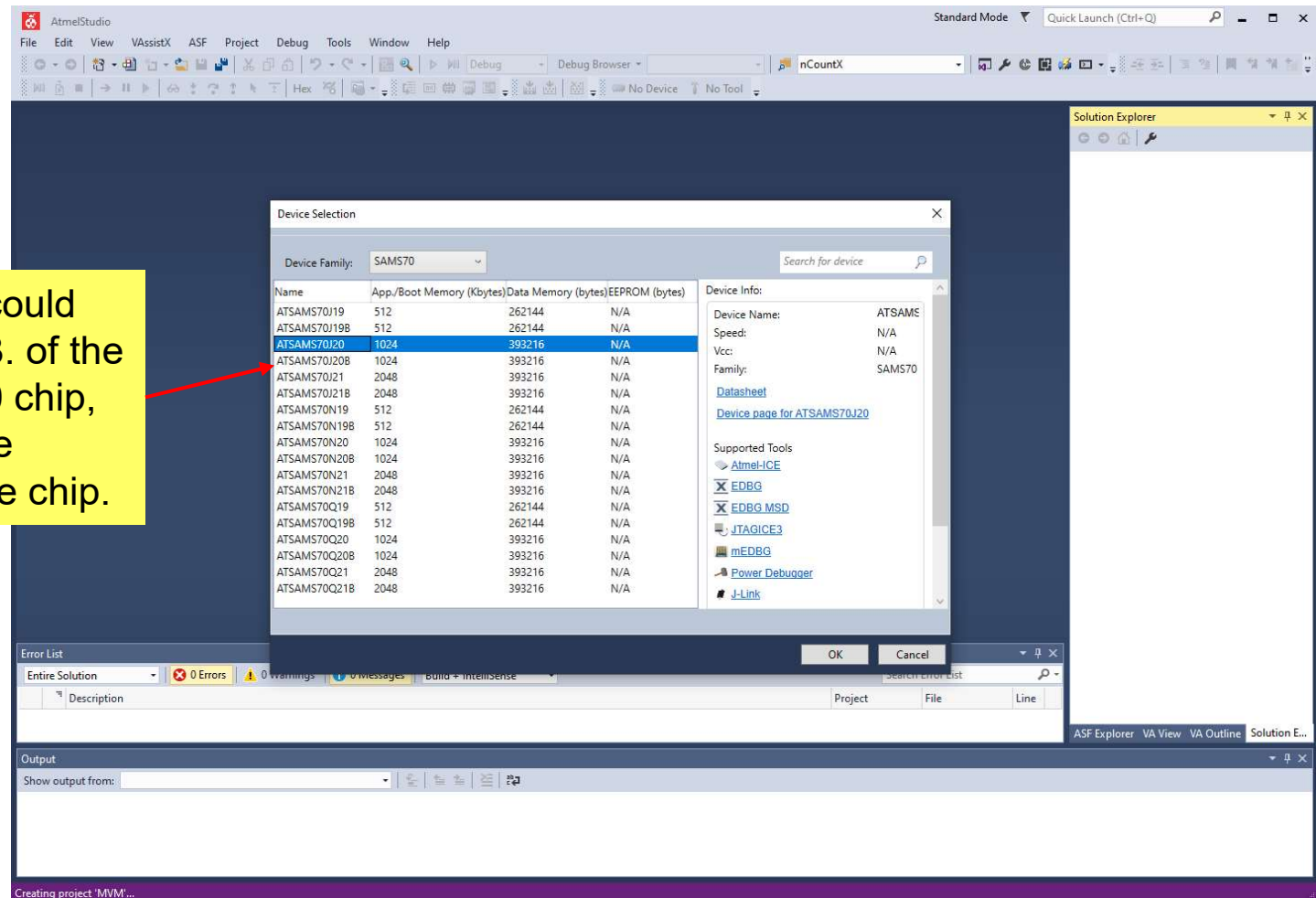
- Create a GCC C executable project.



Setting Up An Atmel Studio Project 3

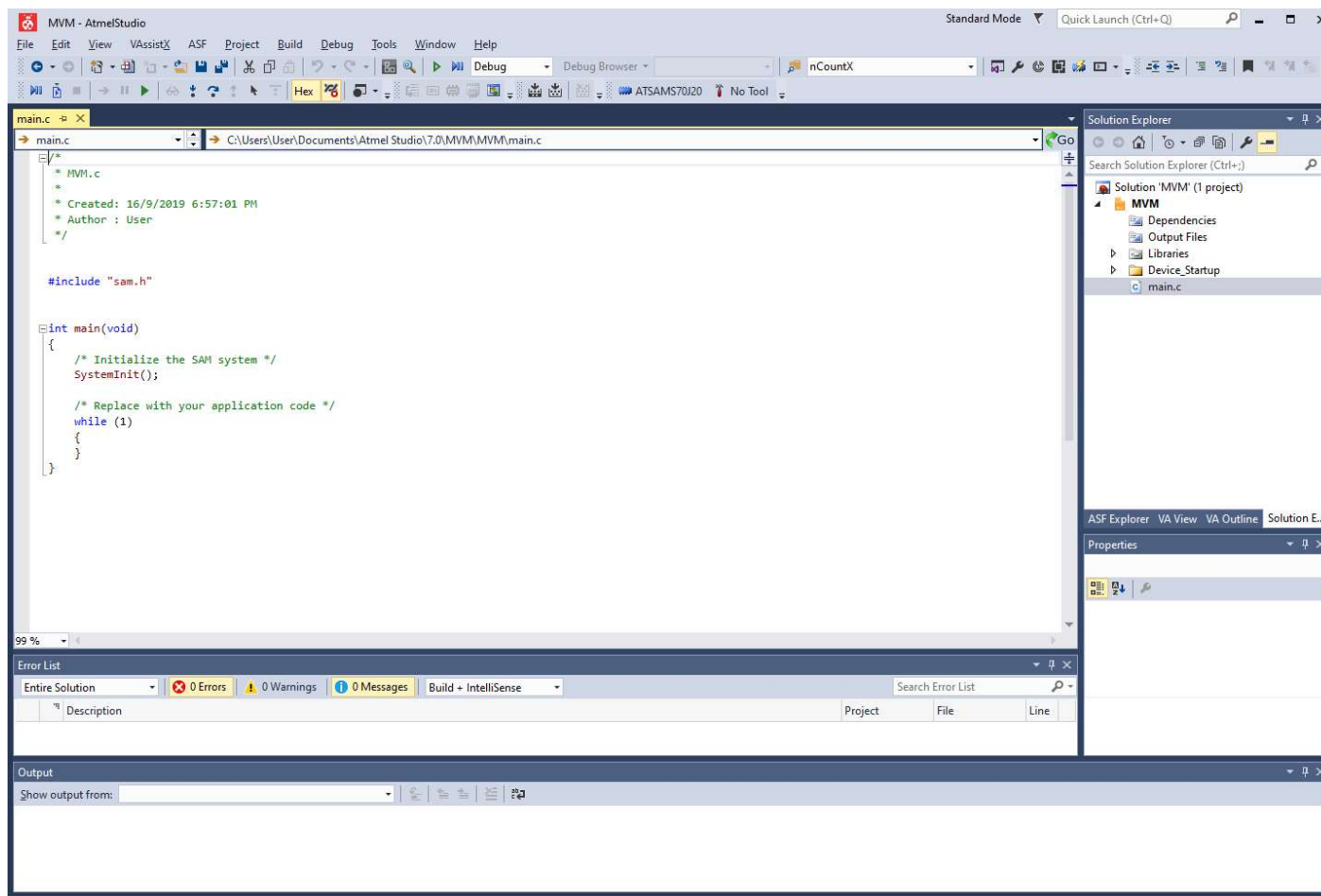
- Select the correct device.

Some boards could be using Rev B. of the ATSAM570J20 chip, so do check the markings on the chip.



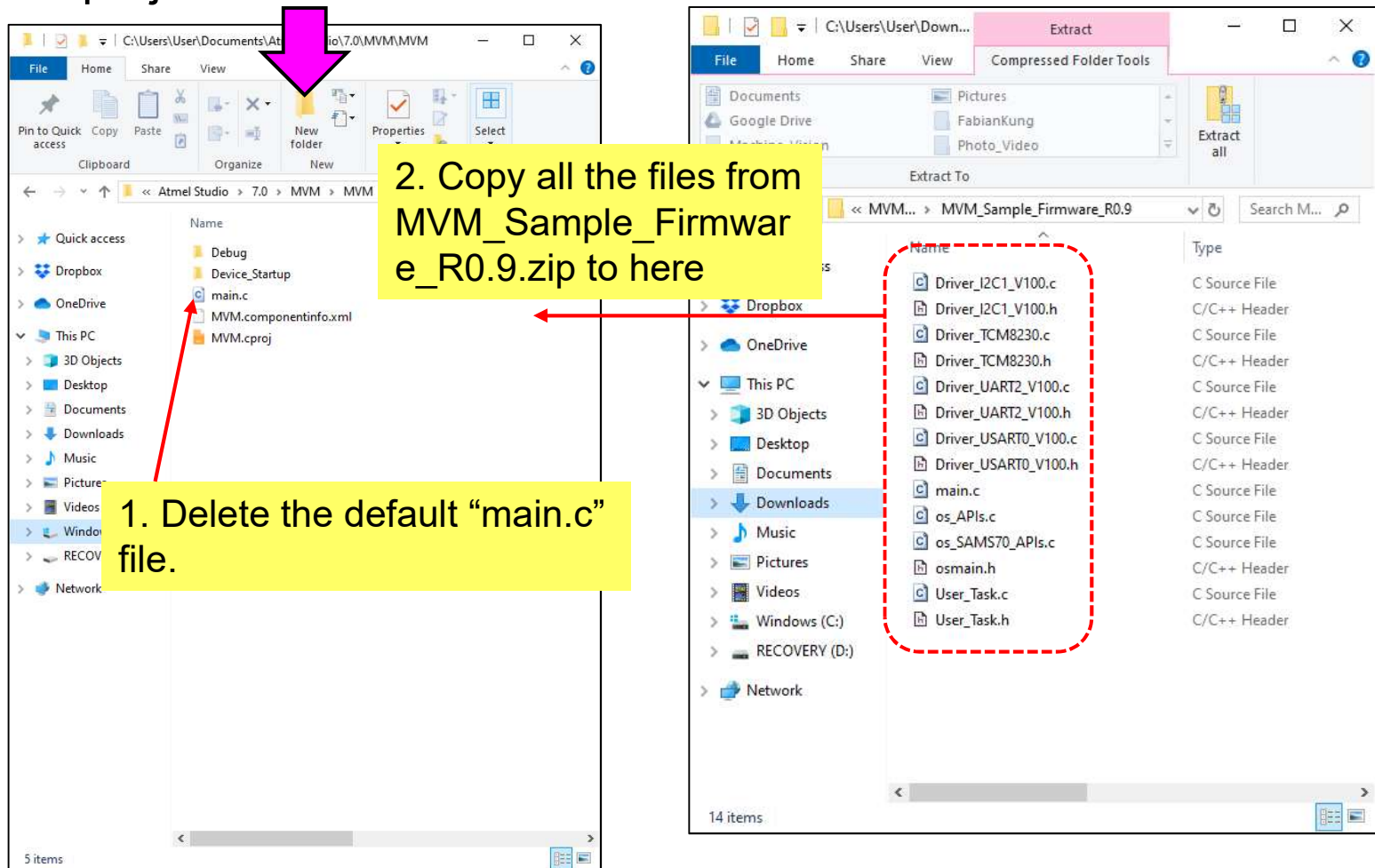
Setting Up An Atmel Studio Project 4

- A project with a default “main.c” file will be created.



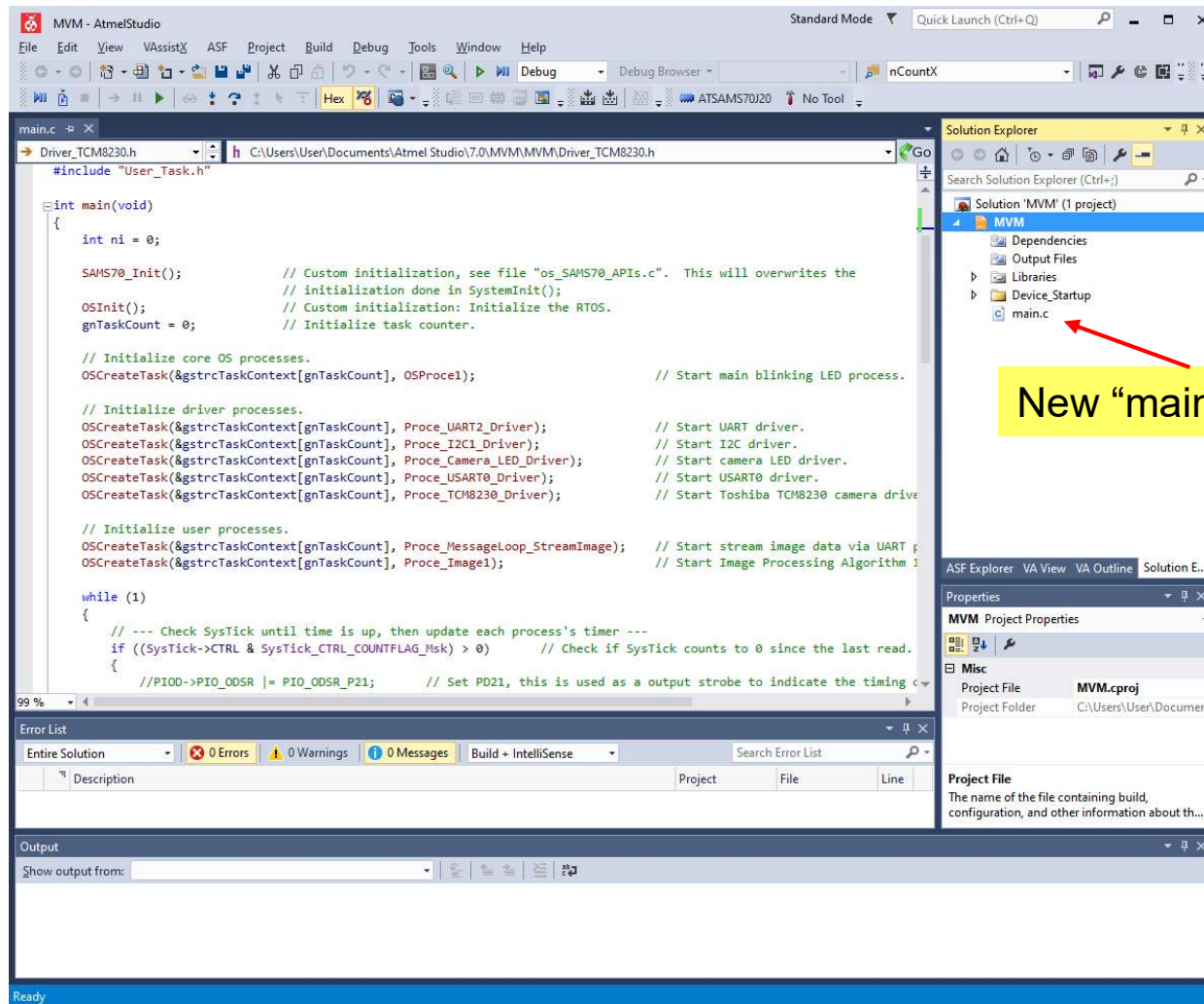
Setting Up An Atmel Studio Project 5

- Now close Atmel Studio 7.
- Go to the project folder.



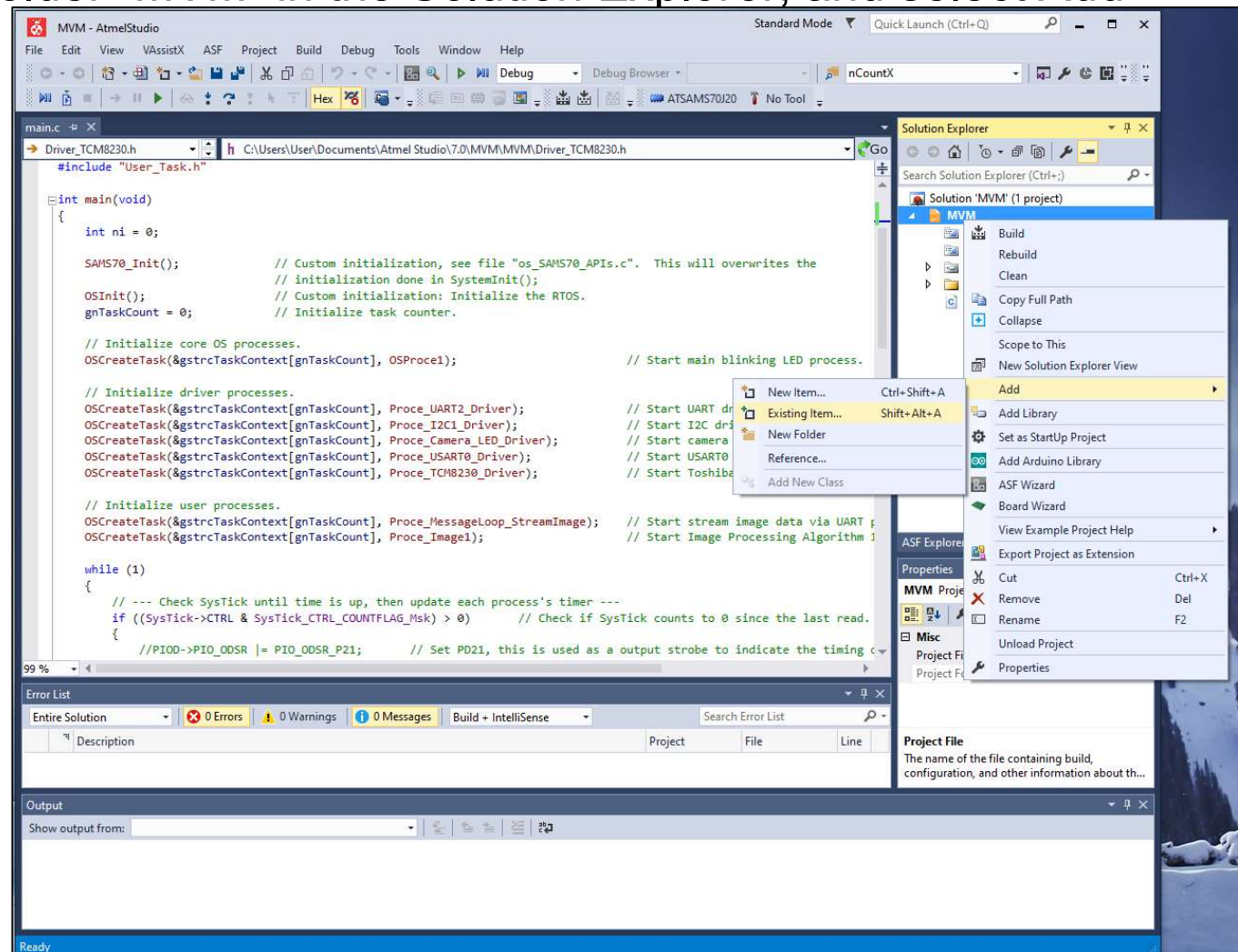
Setting Up An Atmel Studio Project 6

- Now reopen Atmel Studio 7. The new “main.c” file will be reflected window.



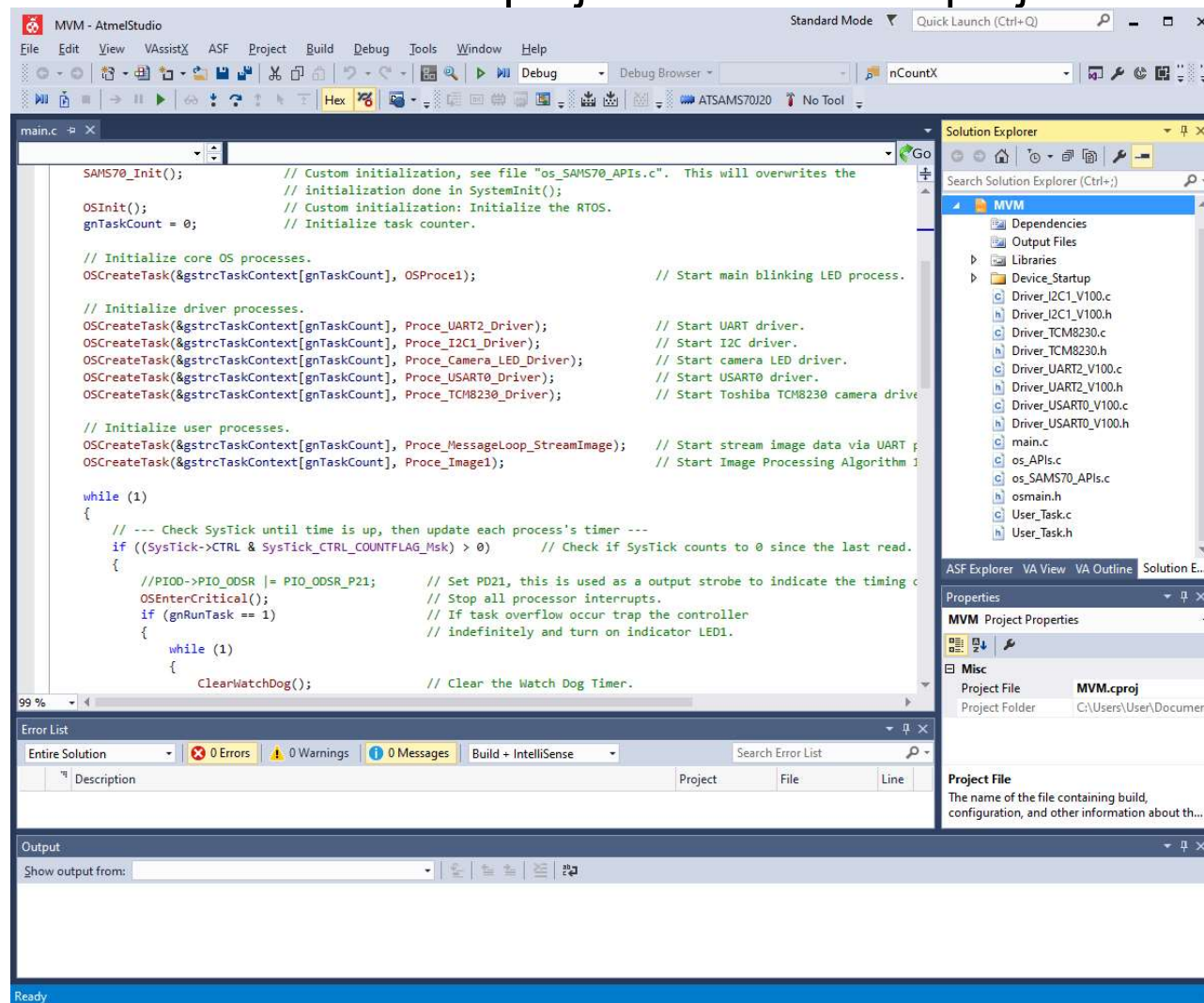
Setting Up An Atmel Studio Project 7

- Right click the folder “MVM” in the Solution Explorer, and select Add Existing Item...



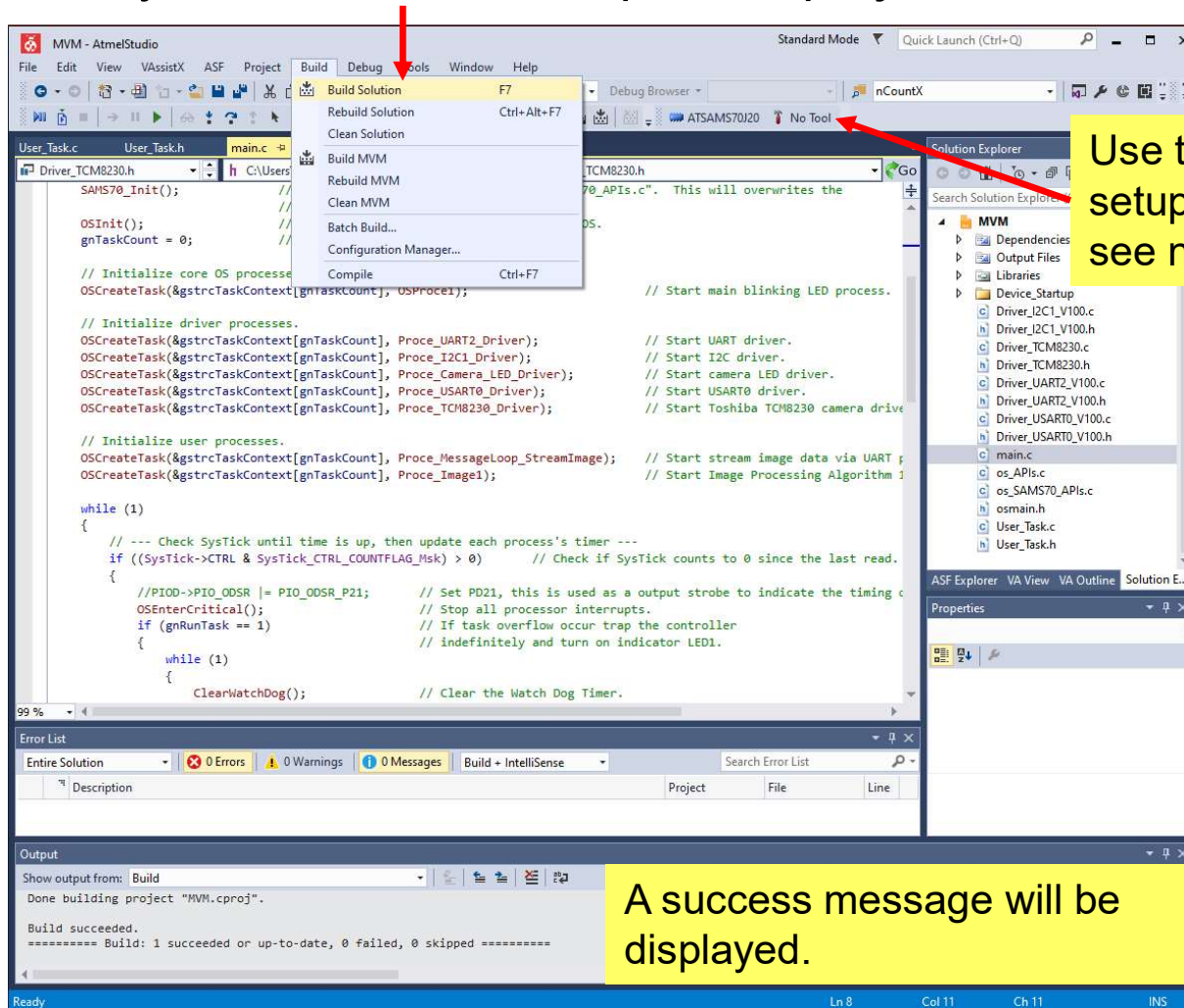
Setting Up An Atmel Studio Project 8

- Add all the *.c and *.h files in the project folder to the project.



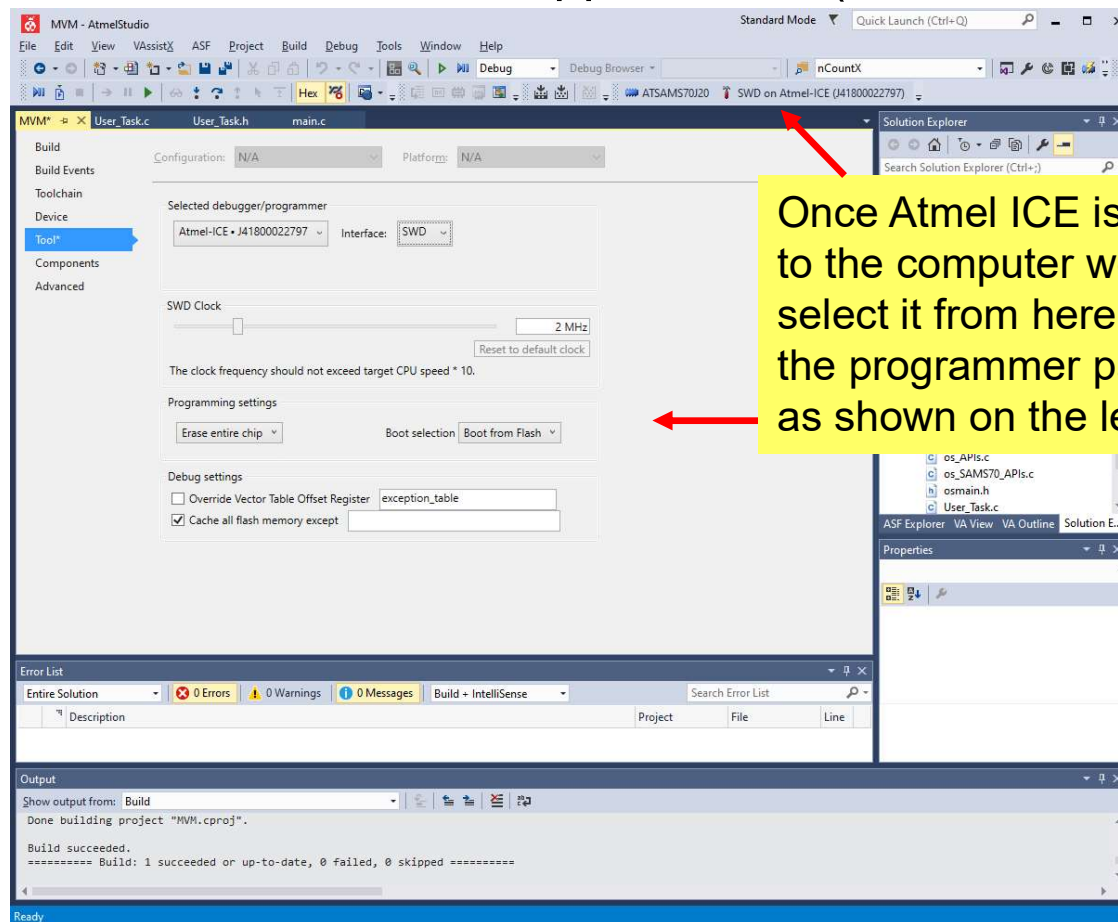
Setting Up An Atmel Studio Project 9

- Now you can build or compile the project.



Setting Up the Programming Tool – Atmel ICE

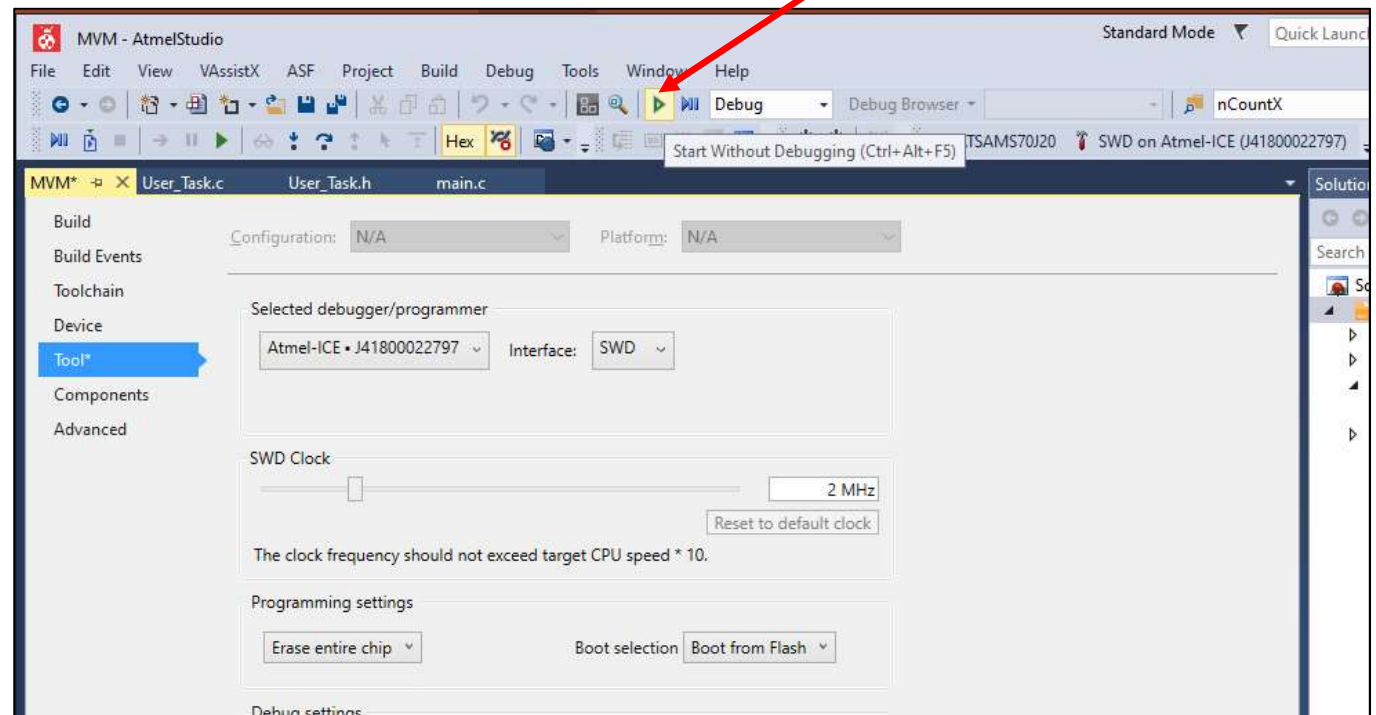
- Now you can load the firmware into the micro-controller with a suitable programmer. Here we are using Atmel ICE, but any programmer compatible with Atmel Studio 7 and support SWD (serial wire debug) mode is fine.



Once Atmel ICE is connected to the computer we can select it from here, and set the programmer parameters as shown on the left.

Flashing the Micro-Controller 1

- Connect the MVM to Atmel ICE. Power up the MVM and click this button to program the flash memory.
- See **Appendix** on the pin assignment on the 2x3 ways receptacle that comes with Atmel ICE.



Flashing the Micro-Controller 2

- Finally you need to setup the TCM (tightly coupled memory) size of Cortex M7 by setting the GPNVM (general purpose non-volatile memory) bits of SAMS70 as shown.

The screenshot shows the AtmelStudio interface with the 'Device Programming' window open. The 'GPNVM Bits' section is highlighted, showing the following configuration:

GPNVM Bit	Value
GPNVMBITS.BOOT_MODE	<input checked="" type="checkbox"/>
GPNVMBITS.TCM_CONFIGURATION	0x01

The 'Program' button is highlighted with a red arrow. A yellow callout box states: "The Heartbeat LED of the MVM V1.5C should start blinking once all the GPNVM bits are programmed."

Another yellow callout box states: "Hit the 'Program' button once the parameters are properly setup."

Coding Your Own Routines

- The source files “**User_Task.c**” and “**User_Task.h**” contains the routines and declarations for **image processing task 1** that search for the brightest region in an image.
- Use this as the basis to add on your own routines. Do remember to use the state machine approach to code your tasks, and keep the total execution time for all tasks within 1 system ticks!
- For more information on scheduler and basic structure of the C codes for ARM Cortex-M see <https://fkeng.blogspot.com/2016/02/atmel-arm-cortex-m4-microcontroller.html>

Appendix – Connecting Atmel ICE to MVM V1.5C

