

An introduction to PCA

Weekly AI pills

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SSSA, Emerging Digital Technologies, Pisa.

ISTITUTO
DI TECNOLOGIE DELLA
COMUNICAZIONE,
DELL'INFORMAZIONE
E DELLA
PERCEZIONE



Scuola Superiore
Sant'Anna



- The aim of Principal Component Analysis
- Derivation
 1. A Geometrical idea
 2. A statistical Derivation
 3. Singular Value Decomposition
- PCA from Encoder Decoder NN
- Dummy examples



Geometrical Introduction



Geometrical Introduction

Let $X \in \mathbb{R}^{N \times n}$ be a dataset of N **observation** within n **variables**.

$$X = \begin{bmatrix} x_1^T \\ \vdots \\ x_N^T \end{bmatrix} = \begin{bmatrix} x^{(1)} & | & \dots & | & x^{(n)} \end{bmatrix} \quad (1)$$

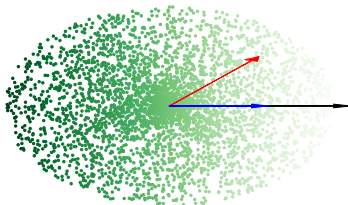
Notations:

- $x_i \in \mathbb{R}^n$ represents a single **observation**, i.e a **sample** in the feature space.
- $x^{(i)} \in \mathbb{R}^N$ represents the single **variable**, i.e a **column** of the dataset.
- The object $\mathbb{1}_n \in \mathbb{R}^n$ is the unitary columnar vector of length n
 $\mathbb{1}_n = [1, \dots, 1]^T$.
- X is centered if $X^T \mathbb{1} = 0$

Geometrical Introduction: Finding a principal direction.

1. Scalar product measures the projection of x_j along the direction w .
2. We are only interested on module.
3. Summation over samples to get the global projection's contribute.
4. Searching for w which maximizes projection.
5. Adding constraint to avoid $w \rightarrow \infty$ solution.

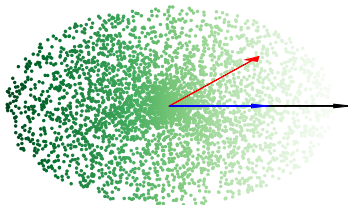
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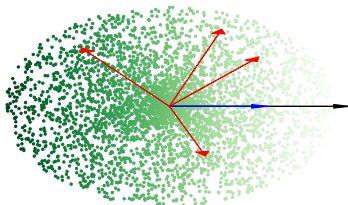
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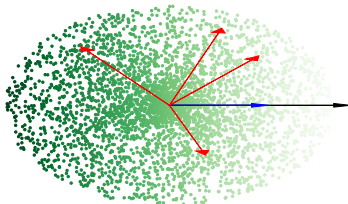
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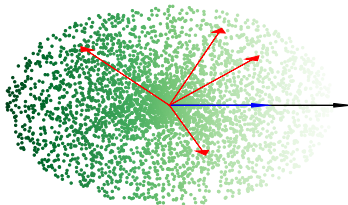
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Geometrical Introduction: Finding other directions

We search for other orthogonal directions which maximize projections.

$$w_1 \in \operatorname{argmax}_{\|w\|_2=1} \sum_{j=1}^N (w \cdot x)^2$$

$$w_2 \in \operatorname{argmax}_{\|w\|_2=1} \sum_{j=1}^N (w \cdot x)^2 \quad \text{and} \quad w_2 \perp w_1$$

$$\vdots$$

$$w_n \in \operatorname{argmax}_{\|w\|_2=1} \sum_{j=1}^N (w \cdot x)^2 \quad \text{and} \quad w_n \perp \{w_1, \dots, w_{n-1}\}$$

Example

Geometrical Introduction: Direction Selection

$$V(w) = \sum_j (w \cdot x_j)^2 \quad \text{momentum along } w$$

If w_1, w_2, w_3 orthogonal that maximizes V in the 3D example, then

1. $V(w_1) = 3181.20$ $\approx 82.5\%$
2. $V(w_2) = 646.25$ $\approx 17.0\%$
3. $V(w_3) = 19.23$ $\approx 0.5\%$

What if we forget the last direction?

Observation

- $x_j = \alpha_{1j}w_1 + \alpha_{2j}w_2 + \alpha_{3j}w_3$ (where $\alpha_{ij} = w_i \cdot x_j$).
- $\tilde{x}_j = \alpha_{1j}w_1 + \alpha_{2j}w_2$.

$$\frac{1}{N} \sum_j \|x_j - \tilde{x}_j\|^2 = \frac{V(w_3)}{N} \approx 4.8 \cdot 10^{-3} \quad (\text{MSE})$$



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Geometrical Introduction: Conclusion

- Given a set of data $X \in \mathbb{R}^{N \times n}$
- We can find w_1, \dots, w_n principal (orthonormal) directions that maximize their momentum.
- $V(w_1) > V(w_2) > \dots > V(w_n)$
- Approximating X with \tilde{X} by taking only the first k directions we are getting an error that is $V(w_{k+1})/N$

What's the catch?

$$\begin{aligned} \max_{w \in \mathbb{R}^n} \quad & \sum_{j=1}^N (w \cdot x_j)^2 \\ \text{s.t.} \quad & w_i \cdot w = 0, \forall i < k \\ & w \cdot w = 1 \end{aligned} \tag{MP}$$



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Classical Derivation



Classical Derivation: Notations

\mathcal{V} random variable, $V = (v_1, \dots, v_N)$ N observations of the variable.

- Expected Value

$$\mathbb{E}[\mathcal{V}] = \frac{1}{N} \sum_{j=1}^N v_j$$

- Variance

$$\text{Var}(\mathcal{V}) = \mathbb{E}[(\mathcal{V} - \mathbb{E}[\mathcal{V}])^2]$$

- Covariance

$$\text{Cov}(\mathcal{U}, \mathcal{V}) = \mathbb{E}[(\mathcal{U} - \mathbb{E}[\mathcal{U}])(\mathcal{V} - \mathbb{E}[\mathcal{V}])]$$

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Under the assumption $\mathbb{E}[\mathcal{U}] = \mathbb{E}[\mathcal{V}] = 0$

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Classical Derivation: An Eigenvalue Problem

$$\max_{\|w\|=1} V(w) = \max_{\|w\|=1} \sum_j (w^T x_j)^2 = \max_{w^T w=1} w^T (X^T X) w \quad (\text{MP})$$

Lagrange Multipliers Technique

Let consider the Lagrangian Function of MP

$$\mathcal{L}(w, \lambda) = V(w) - \lambda(w^T w - 1), \quad \forall w \in \mathbb{R}^n, \lambda \in \mathbb{R}$$

Claim

If w^* is a solution of MP then there exists λ^* such that

$$\nabla \mathcal{L}(w^*, \lambda^*) = 0, \quad \text{i.e.} \quad (X^T X)w^* - \lambda^* w^* = 0 \quad (2)$$

w Principal Direction $\implies w$ Eigenvector of $X^T X$



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Classical Derivation: An Eigenvalue Problem

Why switching to an eigen-pair problem?

$$X^T X$$

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- w_1, \dots, w_n eigenvectors
- $w_i^T X^T X w_i = V(w_i)$ eigenvalues
- $V(w_1) > \dots > V(w_n)$



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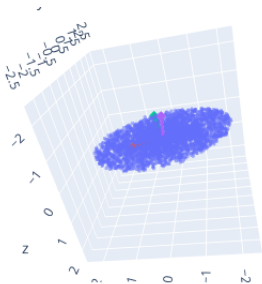
Dimensionality Reduction



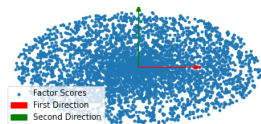
Dimensionality Reduction

The matrix $W = [w_1 | \dots | w_n]$ can be used to reduce the dimensionality

$$F = \begin{bmatrix} f^{(1)} & | & \dots & | & f^{(n)} \end{bmatrix} = X W \quad (\text{factors scores})$$

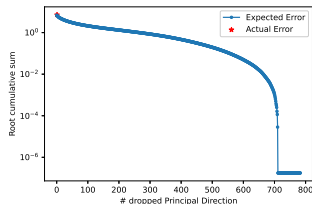
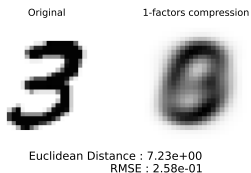


Feature space



Factor scores restricted to the first two principal directions.

Dimensionality Reduction: A concrete example

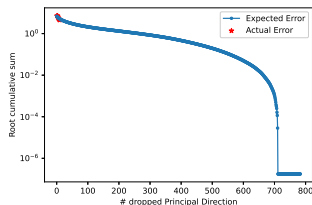
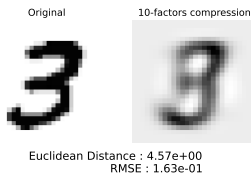


Theoretical Error Estimation

1. $x \in \mathbb{R}^n$ original sample.
2. $f = W^T x \in \mathbb{R}^n$ coordinates in factor-scores space.
3. $\tilde{f} = [f_1, \dots, f_{n-k}] \in \mathbb{R}^{n-k}$ dropping last k coordinates.
4. $\tilde{x} = [w_1 | \dots | w_{n-k}] \tilde{f} \in \mathbb{R}^n$, approximation of x .

$$\|x - \tilde{x}\| \approx \frac{1}{\sqrt{N}} \|X - X_k\| = \frac{1}{\sqrt{N}} \sqrt{V(n-k+1) + \dots + V(n)}$$

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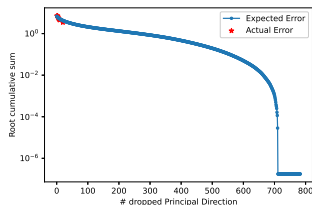
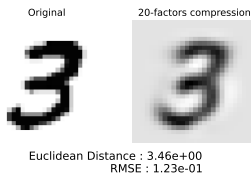


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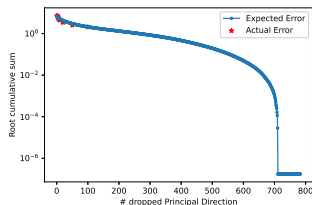
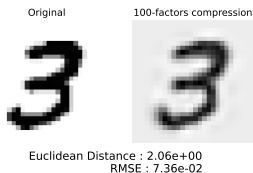


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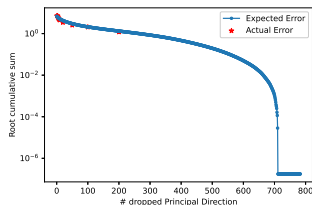
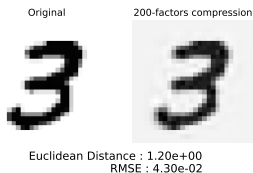


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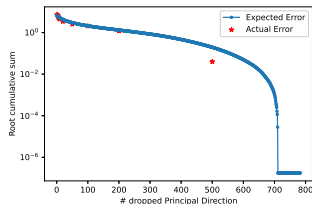
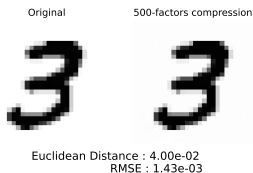


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2. $f = W^T x \in \mathbb{R}^n$ coordinates in factor-scores space.
3. $\tilde{f} = [f_1, \dots, f_{n-k}] \in \mathbb{R}^{n-k}$ dropping last k coordinates.
4. $\tilde{x} = [w_1 | \dots | w_{n-k}] \tilde{f} \in \mathbb{R}^n$, approximation of x .

$$\|x - \tilde{x}\| \approx \frac{1}{\sqrt{N}} \|X - X_k\| = \frac{1}{\sqrt{N}} \sqrt{V(n-k+1) + \dots + V(n)}$$

Dimensionality Reduction: A concrete example

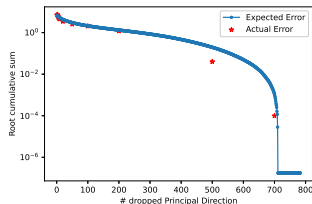
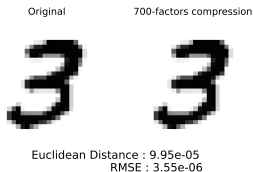


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