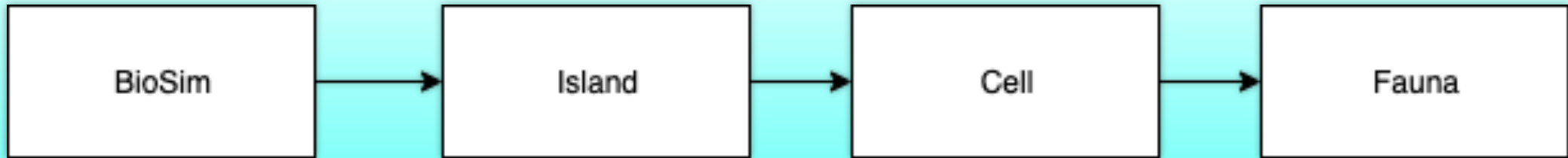


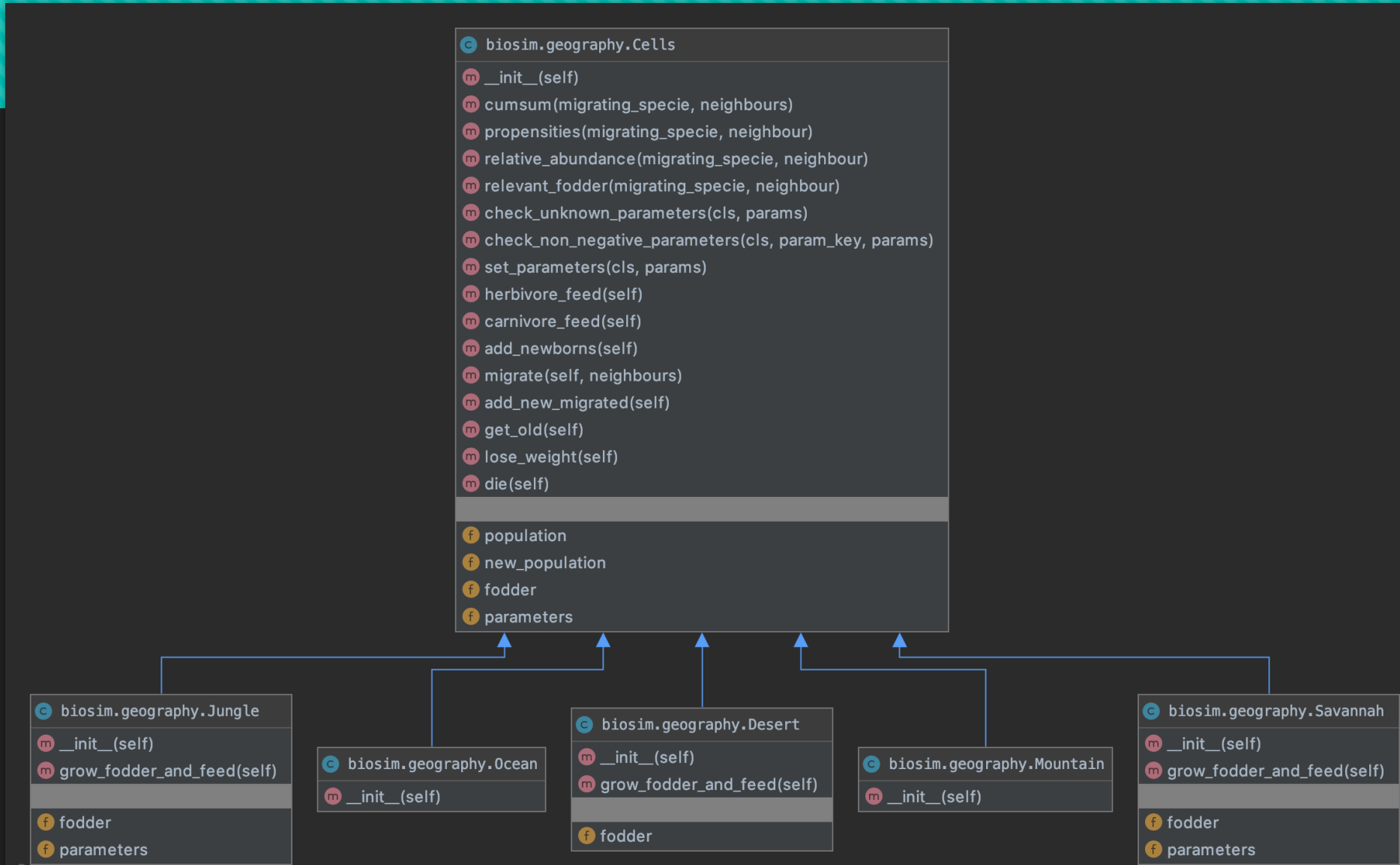
# Modelling the Ecosystem of Rossumøya

By Fábio Rodrigues Pereira and Rabin Senchuri

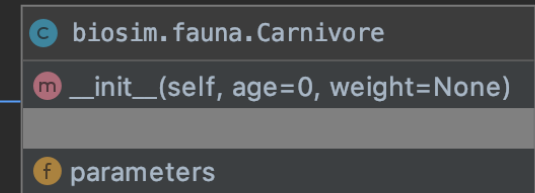
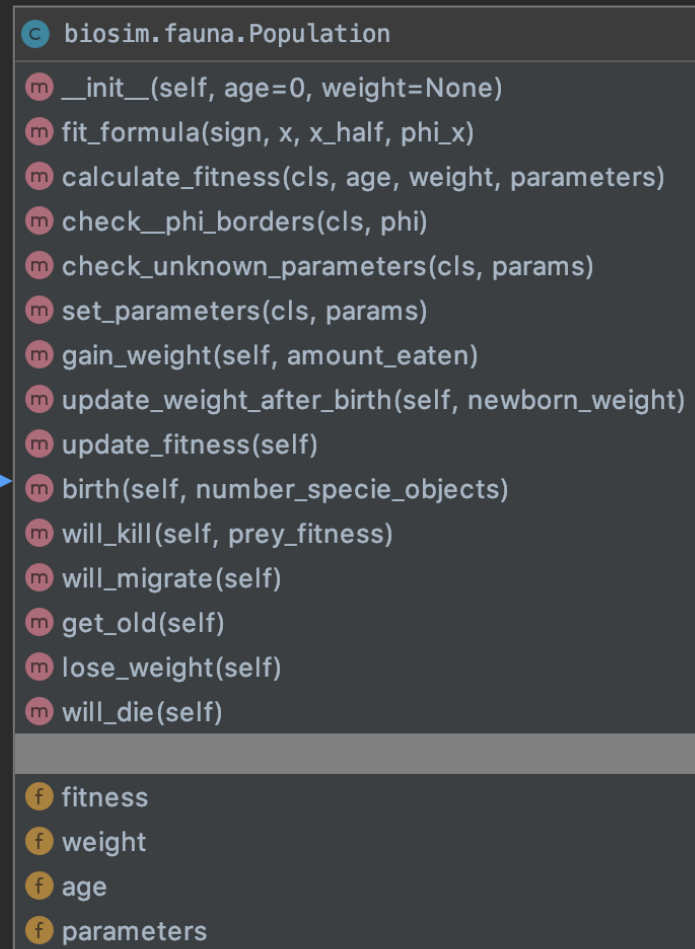
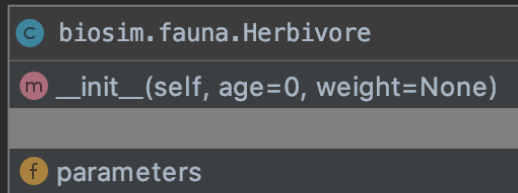
# Classes



# Geography Cell Class



# Fauna Class



# Simulation

```

C biosim.simulation.BioSim
m __init__(self, island_map, ini_pop, seed, ymax_animals=None, cmax_animals=None, img_base=None, img_fmt='png')
P generate_map_array(self)
P num_animals(self)
P year(self)
P num_animals_per_species(self)
P animal_distribution(self)
m set_animal_parameters(self, species, params)
m set_landscape_parameters(self, landscape, params)
m add_population(self, population)
m simulate(self, num_years, vis_years=1, img_years=None)
m save_figures(self)
m create_mp4(self, mov_fmt=DEFAULT_MOVIE_FORMAT)
m setup_graphics(self)
m herbivore_line(self)
m carnivore_line(self)
m static_map(self)
m update_counter_graph(self, pop_count)
m update_herb(self, pop)
m update_carn(self, distribution)
m update_graphics(self)

f img_no
f _carn_img_axis
f img_base
f last_year
f fig
f island
f _carnivore_line
f _mean_ax
f _island_map
f _img_axis
f cmax_animals
f _herbivore_line
f _map
f final_year
f herb_pop
f img_fmt
f _herb_img_axis
f year_num
f carn_pop
f ymax_animals
f map_colors
f map_labels
```

# Island Class

```
c biosim.island.Island
m __init__(self, island_map)
m check_string_instance(argument)
m check_list_instance(argument)
m check_dict_instance(argument)
m list_geo_cells(island_map)
m check_invalid_line_lengths(geos)
m check_invalid_boundary(geos)
m check_invalid_character(cls, geos)
m check_coordinates_exists(cls, coordinates, cells)
m check_habitability(cls, coordinates, cells)
m create_cells(self)
p→ habitable_cells(self)
m set_parameters(self, param_key, params)
m add_population(self, given_pop)
m neighbour_cells(self, loc)
m yearly_cycle(self)
m get_population_numbers(self)

f geos
f cells
f habitable_geos
f fauna_classes
f geo_classes
```

# Minor changes on carnivore\_feed method:

```
236 def carnivore_feed(self):
237     """This method organizes the population of carnivore in order
238     of greatest fitness (those who eat first) to worst. Then,
239     organizes the population of herbivore in order of worst fitness
240     (those who are hunt first) to greatest. Then, per each animal,
241     it is applied the carnivore eating rules, as following:
242
243     Formula and conditions:
244
245     -> Carnivores prey on herbivores on Jungle, Savannah and
246     Desert landscapes, and do not prey on each other;
247     -> A carnivore tries to kill a herbivore per time, beginning
248     with the herbivore with worst fitness, and then to the
249     next herbivore until has eaten an amount 'F' of
250     herbivore weight;
251     -> The probability to kill a herbivore is given by the method
252     'will_kill()';
253     -> The carnivore weight increases by the method
254     'gain_weight()' which also updates its fitness;
255     -> Every herbivore killed is removed from the population
256     by the python's built-in method '.remove()'.
257     """
```

-> We had a merge conflict with the files and it ended up that we pushed an old version of our carnivore\_feed code for submission.

Before on geography.py:

```
258 263 for carnivore in self.population['Carnivore']:
259     self.population['Herbivore'] = carnivore.eat_herb(
260 +         self.population['Herbivore'])
```

And on fauna.py

```
236 def eat_herb(self, herbivores):
237     herbs_survived = []
238     feed = 0
239
240     for herbivore in herbivores[::-1]:
241         if feed < self.parameters["F"] \
242             and self.will_kill(herbivore.fitness):
243             if feed + herbivore.weight > self.parameters["F"]:
244                 herbivore.weight = self.parameters["F"] - feed
245                 self.weight += (
246                     self.parameters["beta"] * herbivore.weight
247 +                 )
248                 weight_eaten = self.parameters["F"]
249
250             else:
251                 self.weight += (
252                     self.parameters["beta"] * herbivore.weight
253                 )
254                 feed += herbivore.weight
255             else:
256                 herbs_survived.append(herbivore)
257
258     return herbs_survived
259
```

After:

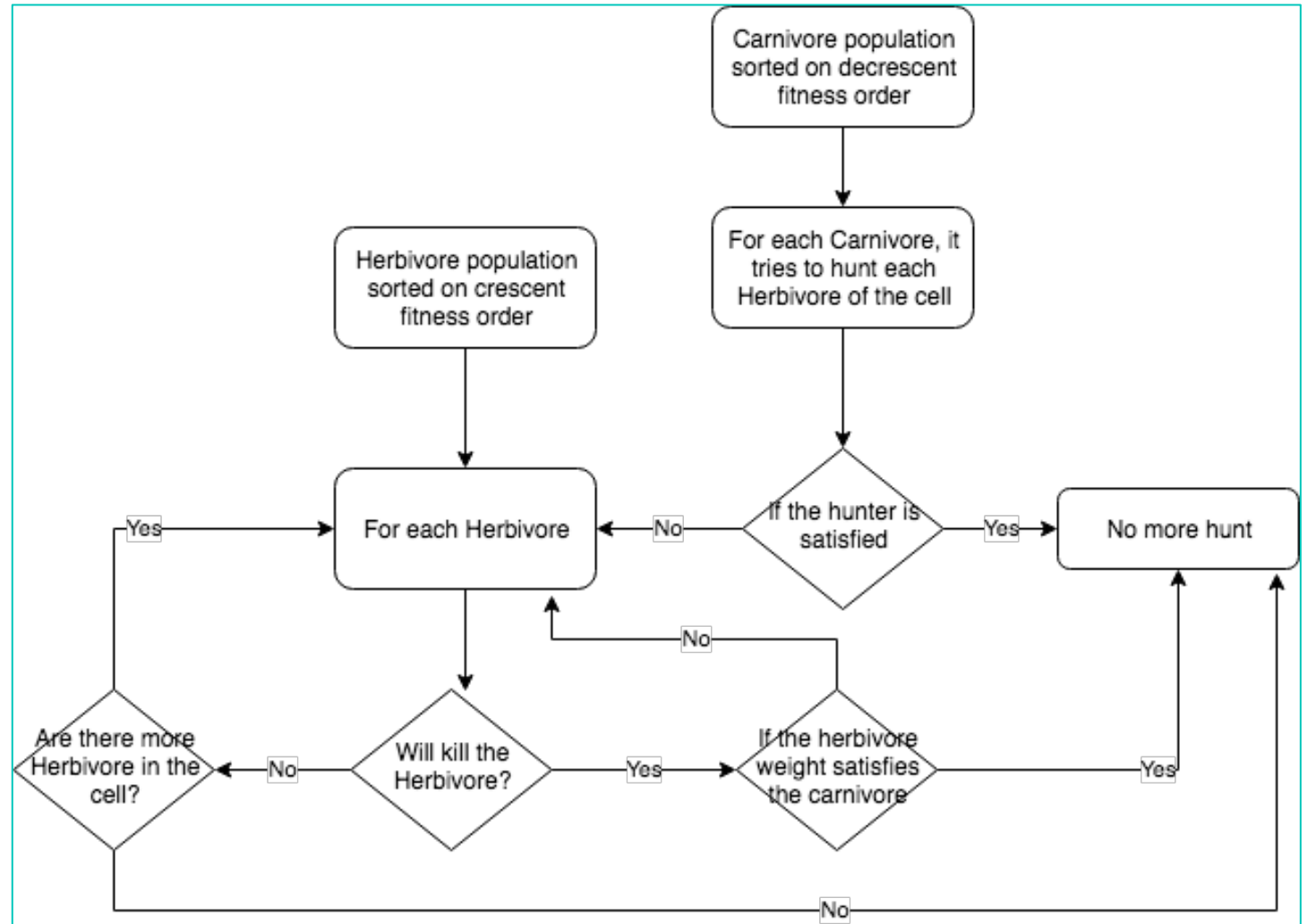
```
258 self.population['Carnivore'].sort(key=lambda h: h.fitness,
259                                   reverse=True)
260
261 self.population['Herbivore'].sort(key=lambda h: h.fitness)
262
263 for carnivore in self.population['Carnivore']:
264     appetite = carnivore.parameters['F']
265     amount_eaten = 0
266
267     for herbivore in self.population['Herbivore']:
268
269         if amount_eaten >= appetite:
270             break
271
272         elif carnivore.will_kill(herbivore.fitness):
273             food_wanted = appetite - amount_eaten
274
275             if herbivore.weight <= food_wanted:
276                 amount_eaten += herbivore.weight
277                 self.population['Herbivore'].remove(herbivore)
278
279             elif herbivore.weight > food_wanted:
280                 amount_eaten += food_wanted
281                 self.population['Herbivore'].remove(herbivore)
282
283     carnivore.gain_weight(amount_eaten)
```

-> The method has been changed after submission, as soon as we got aware. But it is important to say that the previous code is not wrong and has not caused any difference on the simulation's results.



# Flow chart of carnivore eating rules:

```
258 self.population['Carnivore'].sort(key=lambda h: h.fitness,  
259 reverse=True)  
260  
261 self.population['Herbivore'].sort(key=lambda h: h.fitness)  
262  
263 for carnivore in self.population['Carnivore']:  
264     appetite = carnivore.parameters['F']  
265     amount_eaten = 0  
266  
267     for herbivore in self.population['Herbivore']:  
268         if amount_eaten >= appetite:  
269             break  
270  
271         elif carnivore.will_kill(herbivore.fitness):  
272             food_wanted = appetite - amount_eaten  
273  
274             if herbivore.weight <= food_wanted:  
275                 amount_eaten += herbivore.weight  
276                 self.population['Herbivore'].remove(herbivore)  
277  
278             elif herbivore.weight > food_wanted:  
279                 amount_eaten += food_wanted  
280                 self.population['Herbivore'].remove(herbivore)  
281  
282     carnivore.gain_weight(amount_eaten)  
283  
284
```





# Minor changes on migration method:

## BEFORE

```
298  
299     for migrating_specie, animals in self.population.items():  
300         if len(neighbours) > 0 and len(animals) > 0:  
301             for animal in animals:  
302                 cum_prob = self.cumsum(migrating_specie,  
303                                         neighbours)  
304                 if animal.will_migrate():  
305                     n = 0  
306                     while np.random.random() >= cum_prob[n]:  
307                         n += 1  
308                     neighbours[n].new_population[  
309                         migrating_specie].append(animal)  
310                     self.population[migrating_specie].remove(animal)  
311
```



## AFTER

```
322     np.random.shuffle(neighbours)  
323     for migrating_specie, animals in self.population.items():  
324         if len(neighbours) > 0 and len(animals) > 0:  
325             for animal in animals:  
326                 cum_prob = self.cumsum(migrating_specie,  
327                                         neighbours)  
328                 if animal.will_migrate():  
329                     n = 0  
330                     while np.random.random() >= cum_prob[n]:  
331                         n += 1  
332                     n = 0 if n > 3 else n  
333                     neighbours[n].new_population[migrating_specie].\  
334                         append(animal)  
335                     self.population[migrating_specie].remove(animal)  
336
```

## Changes:

1:

```
322     np.random.shuffle(neighbours)
```

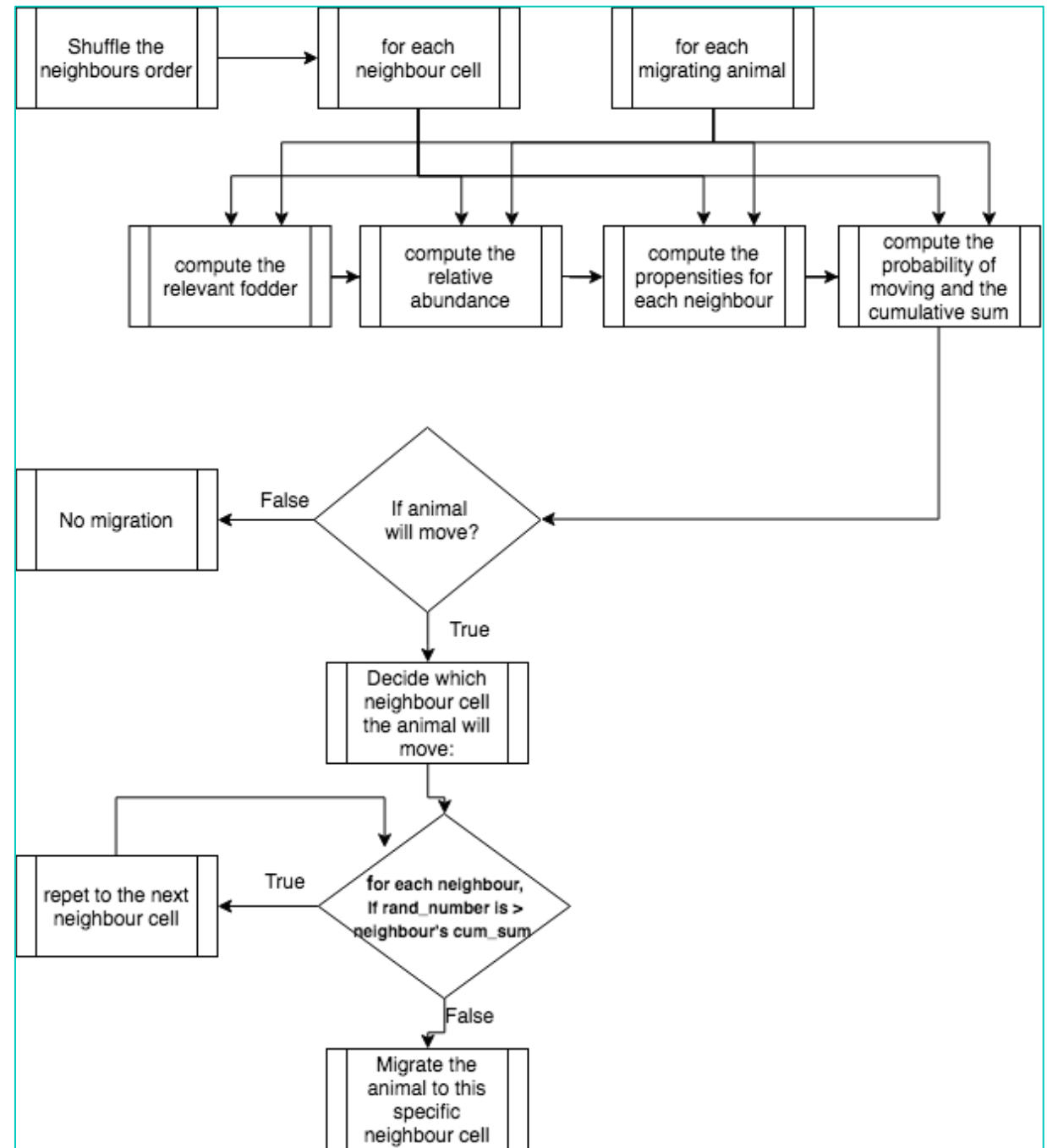
2:

```
332     n = 0 if n > 3 else n
```

# Flow chart of migration method:

```

np.random.shuffle(neighbours)
for migrating_specie, animals in self.population.items():
    if len(neighbours) > 0 and len(animals) > 0:
        for animal in animals:
            cum_prob = self.cumsum(migrating_specie,
                                   neighbours)
            if animal.will_migrate():
                n = 0
                while np.random.random() >= cum_prob[n]:
                    n += 1
                    n = 0 if n > 3 else n
                neighbours[n].new_population[migrating_specie].\
                    append(animal)
                self.population[migrating_specie].remove(animal)
    
```



# Minor changes on yearly\_cycle method:

## BEFORE

```
248 def yearly_cycle(self):
249     """This method calls, in order, the methods that compound
250     the yearly cycle dynamics of the island, such that:
251
252         1. Growing of fodder;
253         2. Animal's feeding;
254         3. Animals's birth;
255         4. Animal's migration;
256         5. Animal's aging;
257         6. Animal's weight loss;
258         7. Animal's death.
259     """
260     for coord, geo_object in self.habitable_cells.items():
261         geo_object.grow_fodder_and_feed()
262         geo_object.add_newborns()
263         geo_object.migrate(self.neighbour_cells(coord))
264         geo_object.add_new_migrated()
265         geo_object.lose_weight()
266         geo_object.get_old()
267         geo_object.die()
```

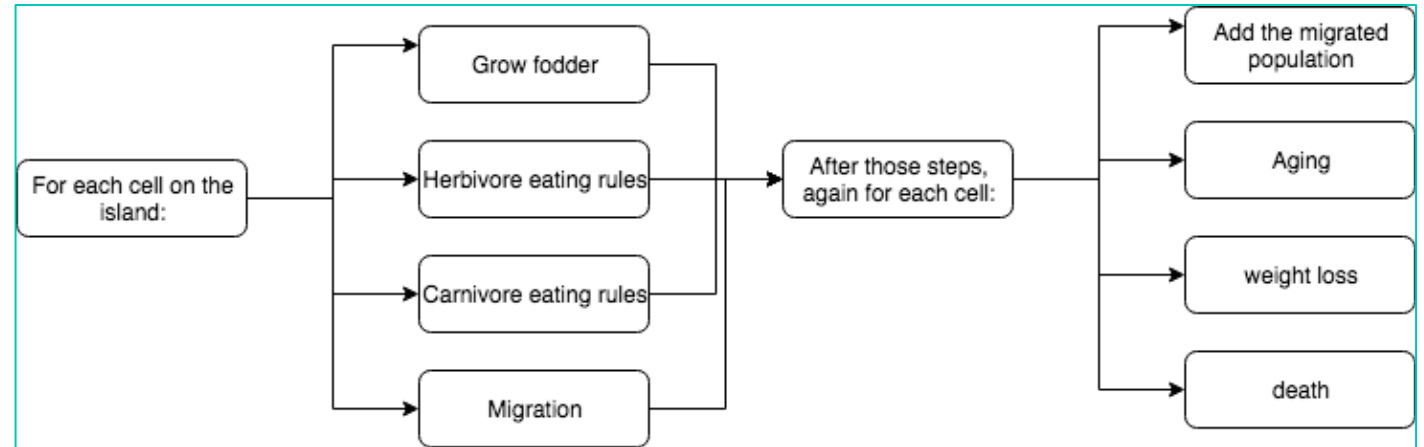


## NOW

```
248 def yearly_cycle(self):
249     """This method calls, in order, the methods that compound
250     the yearly cycle dynamics of the island, such that:
251
252         1. Growing of fodder;
253         2. Animal's feeding;
254         3. Animals's birth;
255         4. Animal's migration;
256         5. Animal's aging;
257         6. Animal's weight loss;
258         7. Animal's death.
259     """
260     for coord, geo_object in self.habitable_cells.items():
261         geo_object.grow_fodder_and_feed()
262         geo_object.add_newborns()
263         geo_object.migrate(self.neighbour_cells(coord))
264
265     for coord, geo_object in self.habitable_cells.items():
266         geo_object.add_new_migrated()
267         geo_object.lose_weight()
268         geo_object.get_old()
269         geo_object.die()
```

# Flow chart of yearly cycle method:

```
260 for coord, geo_object in self.habitable_cells.items():
261     geo_object.grow_fodder_and_feed()
262     geo_object.add_newborns()
263     geo_object.migrate(self.neighbour_cells(coord))
264
265 for coord, geo_object in self.habitable_cells.items():
266     geo_object.add_new_migrated()
267     geo_object.lose_weight()
268     geo_object.get_old()
269     geo_object.die()
```



# Why our code is trustworthy?

▼ **BioSim\_G15\_Fabio-Rodrigues-Pereira\_R**

- ▶ **.pytest\_cache**
- ▼ **biosim** 100% files, 91% lines covered
  - fauna.py 92% lines covered
  - geography.py 84% lines covered
  - island.py 98% lines covered
  - simulation.py 93% lines covered
- ▶ **biosim.egg-info**
- ▶ **data**
- ▶ **doc** 0% files, not covered
- ▶ **examples** 0% files, not covered
- ▶ **pip-wheel-metadata**
- ▶ **tests** 100% files, 96% lines covered
  - pyproject.toml
  - README.md
  - requirements.txt
  - setup.cfg
  - setup.py not covered
  - test.py not covered
  - tox.ini

pytest in test\_biosim\_interface.py x

✓ Tests passed: 23 of 23 tests – 5 s 739 ms

▼ ✓ Test Results 5s 739 ms Testing started at 17.29 ...

pytest in test\_simulation.py x

✓ Tests passed: 3 of 3 tests – 286 ms

▼ ✓ Test Results 286 ms Testing started at 17.31 ...

pytest in test\_island.py x

✓ Tests passed: 11 of 11 tests – 393 ms

▼ ✓ Test Results 393 ms Testing started at 17.29 ...

pytest in test\_geography.py x

✓ Tests passed: 10 of 10 tests – 695 ms

▼ ✓ Test Results 695 ms Testing started at 23.52 ...

pytest in test\_fauna.py x

✓ Tests passed: 16 of 16 tests – 546 ms

▼ ✓ Test Results 546 ms Testing started at 5:31 PM ...

Coverage: pytest in tests x

64% files, 93% lines covered

Element	Statistics, %
▼ .idea	
▼ .pytest_cache	
▼ biosim	100% files, 91% lines covered
▼ biosim.egg-info	
▼ data	
▼ doc	0% files, not covered
▼ examples	0% files, not covered
▼ pip-wheel-metadata	
▼ tests	100% files, 96% lines covered
pyproject.toml	
README.md	
requirements.txt	
setup.cfg	
setup.py	not covered
test.py	not covered
tox.ini	



# Visualization features:

