

Array

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Array in C++

- A set of consecutive memory storing identical data type object,
- `int A[100]; float B[30]; Object C[200];`
- Direct access, given index i , $A[i]$ gives the $i + 1$ st integer stored in array A . Random Access Machine (RAM)
- A , the address where array A begin, an `int` is 4 bytes, we find $A[i]$ at address $A + i$, the value is $*(A + i)$.
- It takes constant time to compute the address, then direct access the memory location.
- We are talking about detail implementation, not the abstract data type.

Array, ADT

- A set of pairs $\langle index, value \rangle$, a *correspondence* or a *mapping*
- The operations
 - Retrieve the value for a given index,
 - store a value to the array at a given index.

```
class GeneralArray {  
public:  
    GeneralArray(int j, RangeList list,  
        float initValue = defaultValue);  
    float Retrieve(index);  
    void Store(index i, float x);  
};
```

- Array can be used to implement other data types,
- *Ordered or linear list* (store those objects that you can define “linear order”). Ordering is an important information for efficient computation.
- examples are
 - Days of the week, (Sunday, Monday, Tuesday, Wednesday, Thursday, Friday, Saturday).
 - Value of card deck (Ace, 2, 3, 4, 5, 6, 7, 8, 9, 10, Jack, Queen, King).
 - Floor of a building (Basement, Lobby, mezzanine, first, second).
 - Or an empty list ().

Ordered List

- Can be written in the form $(a_0, a_1, \dots, a_{n-1})$
- operations performed on list (ADT definitions needs data objects and operations (methods))
 - Find the length n of the list.
 - Read list from left to right (or from right to left).
 - Retrieve the i th element, $0 \leq i < n$.
 - Insert a new element at the position i , $0 \leq i < n$, causing elements numbered $i, i + 1, \dots, n - 1$ to become numbered $i + 1, i + 2, \dots, n$.
 - Delete the element at position i , $0 \leq i < n$, causing elements numbered $i + 1, \dots, n - 1$ to become numbered $i, i + 1, \dots, n - 2$.

Ordered List- Implementation Consideration

- Use an array (C++ array).
 - Find the length, $\Theta(1)$.
 - read the list, $\Theta(n)$.
 - Retrieve the i th element, $\Theta(1)$.
 - Insert a new element, suppose we know where to insert, first move data around then insert.
 - Delete an element, suppose we know what to delete, delete it and move data around.

Polynomial

- A problem requires ordered list.
- Building ADT for the representation and manipulation of polynomials in a single variable.
- Two such polynomials are $a(x) = 3x^2 + 2x - 4$ and $b(x) = x^8 - 10x^5 - 3x^3 + 1$
- There are 3 terms in $a(x)$, $3x^2$, $2x$, and -4 .
- *Coefficients* of the 3 terms are 3, 2, and -4; the *exponents* are 2, 1, 0.
- The *degree* is the largest exponent among the nonzero terms.
- A term can be represented as a pair (coefficient, exponent), such as (3,2), a method that we have chosen to only display the nonzero terms.

Polynomial

- Operations applied to two polynomials.
- Sum of two polynomials, product of two polynomials
- $a(x) = \sum a_i x^i$ and $b(x) = \sum b_i x^i$; then
- $a(x) + b(x) = \sum (a_i + b_i) x^i$,
- $a(x)b(x) = \sum (a_i x^i \cdot \sum (b_j x^j))$
- also subtraction and division

In C++ class

```
class Polynomial {  
public:  
    Polynomial();  
    Polynomial Add(Polynomial poly);  
    Polynomial Mult(Polynomial poly);  
    float Eval(float f);  
};
```

What should the private data look like? (detail implementation!)

Polynomial Representation

- First approach

private:

int *Degree*;

float *coef*[*MaxDegree* + 1];

- *MaxDegree* represents the largest-degree polynomial, $n \leq \text{MaxDegree}$.
- *coef*[*i*] stores a_{n-i} .
- A polynomial a , $a.\text{degree} = n$, $a.\text{coef}[i] = a_{n-i}$, $0 \leq i \leq n$.
- Space *MaxDegree* is allocated, regardless the number of terms (not a function of input size).

Polynomial Representation

- Second Approach, space needed depend on the degree.

private:

```
    int degree;  
    float *coef;
```

- and we need the constructor

```
Polynomial :: Polynomial (int d)  
{  
    degree = d;  
    coef = new float [degree + 1];  
}
```

Polynomial Representation

- A problem with the second approach
- Zero terms also take space,
- $a(n) = n^{1000} + 1$;
- It takes 1001 memory spaces but there are just only two nonzero terms.

Polynomial Representation, The Third Approach

```
class Polynomial; // forward declaration
```

```
class Term {  
friend Polynomial;  
private:  
    float coef;  
    int exp;  
};
```

The private data members of *Polynomial* are private:

```
    Term *termArray;  
    int capacity;  
    int terms;
```

- Third approach fixes the problem with the first and the second approaches.
- Memory required depends on the problem size (number of nonzero terms).
- Addition, *Polynomial* a, b, c ; $c = a + b$;
- if ($a.termArray[i].exp == b.termArray[j].exp$)
- $c.termArray[k].exp = (a.termArray[i].exp + b.termArray[j].exp)$;
- Another example is shown in Figure 2.1. An old implementation using an array.

- Using two arrays, `float * coef` and `int * exp`.
- A polynomial `a`, `a.start` and `a.finish` point to start and finish locations where `a` stored in arrays.
- Figure 2.1.
- A garbage collection problem.
 - compare `new` and `delete` operations for different approaches (C++ and the old array approaches)

Sparse Matrices

Matrix

- mathematical object arises in many physical science problems.
- Study the way to represent matrices so that the operations to be performed on them can be carried out efficiently.
- A matrix: m rows and n columns, an $m \times n$ matrix, there are mn elements,
- $m = n$, square matrix.

$$\begin{bmatrix} -27 & 3 & 4 \\ 6 & 82 & -2 \\ 109 & -64 & 11 \\ 12 & 8 & 9 \\ 48 & 27 & 47 \end{bmatrix} \quad (1)$$

$$\begin{bmatrix} 15 & 0 & 0 & 22 & 0 & -15 \\ 0 & 11 & 3 & 0 & 0 & 0 \\ 0 & 0 & 0 & -6 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 91 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 28 & 0 & 0 & 0 \end{bmatrix} \quad (2)$$

- A matrix can be stored in a C++ 2D array, $a[m][n]$, element $a[i][j]$ can be efficiently access.
- The second matrix contains many zeros, a *sparse* matrix.
- In practice, many matrices are large but sparse, developpe a sparse matrix ADT.

```
class SparseMatrix
{
public:
    SparseMatrix (int  $r$ , int  $c$ , int  $t$ );
    SparseMatrix Transpose();
    SparseMatrix Add(SparseMatrix  $b$ );
    SparseMatrix Multiply(SparseMatrix  $b$ );
};
```

Sparse Matrix Representation

- Try not to store zero terms.
- A nonzero term can be represented by a triple $\langle row, col, value \rangle$.
- use an array of triples to store the non-zero terms.
- To make operations easier, the non-zero terms are stored according
 - sorted according to row index,
 - sorted according to column index in the same row.

```
class SparseMatrix;
```

```
class MatrixTerm {  
friend class SparseMatrix;  
private:  
    int row, col, value;  
};
```

```
and in class SparseMatrix;
```

```
private:  
    int rows, cols, terms, capacity;  
    MatrixTerm *smArray;
```

Left, Sparse Matrix of (b), Right, its transpose

	<i>row</i>	<i>col</i>	<i>value</i>		<i>row</i>	<i>col</i>	<i>value</i>
<i>smArray</i> [0]	0	0	15	<i>smArray</i> [0]	0	0	15
<i>smArray</i> [1]	0	3	22	<i>smArray</i> [1]	0	4	91
<i>smArray</i> [2]	0	5	-15	<i>smArray</i> [2]	1	1	11
<i>smArray</i> [3]	1	1	11	<i>smArray</i> [3]	2	1	3
<i>smArray</i> [4]	1	2	3	<i>smArray</i> [4]	2	5	28
<i>smArray</i> [5]	2	3	-6	<i>smArray</i> [5]	3	0	22
<i>smArray</i> [6]	4	0	91	<i>smArray</i> [6]	3	2	-6
<i>smArray</i> [7]	5	2	28	<i>smArray</i> [7]	5	0	-15

Transposing a Matrix

Change row and column, $A = B^T$, $A[i][j] = B[j][i]$; Direct change row and column in sparse matrix representation, row index is not sorted.

	<i>row</i>	<i>col</i>	<i>value</i>		<i>row</i>	<i>col</i>	<i>value</i>
<i>smArray</i> [0]	0	0	15	<i>smArray</i> [0]	0	0	15
<i>smArray</i> [1]	0	3	22	<i>smArray</i> [1]	3	0	22
<i>smArray</i> [2]	0	5	-15	<i>smArray</i> [2]	5	0	-15
<i>smArray</i> [3]	1	1	11	<i>smArray</i> [3]	1	1	11
<i>smArray</i> [4]	1	2	3	<i>smArray</i> [4]	2	1	3
<i>smArray</i> [5]	2	3	-6	<i>smArray</i> [5]	3	2	-6
<i>smArray</i> [6]	4	0	91	<i>smArray</i> [6]	0	4	91
<i>smArray</i> [7]	5	2	28	<i>smArray</i> [7]	2	5	28

- Try to fix the unsorted problem.
 - observation: row are originally ordered,
 - find all elements in column 0 and store them in row 0, find all elements in column 1, ...
 - to process column i , scan the whole list once,
 - $cols$, $rows$, and $terms$ denote number of columns, number of rows, and number of terms.
 - total time required is $O(terms \cdot cols)$.
 - in the worst case, $terms = cols \cdot rows$, i.e., we have $O(rows \cdot cols^2)$, worse than a straightforward implementation that takes $\Theta(rows \cdot cols)$ time.

FastTranspose

- First determine the number of elements in each column.
- We can then calculate the starting position for each row in the transposed matrix.

	[0]	[1]	[2]	[3]	[4]	[5]
<i>rowSize</i>	2	1	2	2	0	1
<i>rowStart</i>	0	2	3	5	7	7

- Total time $O(cols + terms)$.

Representation of Arrays

- Multidimensional arrays are stored in a 1-D array. (Actually, any data type objects are stored in a 1-D array, i.e., memory.) And recall that we need random access.
- An array declared as $a[u_1][u_2], \dots, [u_n]$, the number of elements $\prod_{i=1}^n u_i$.
- Two way to store array $a[m][n]$, row major and column major. Row major, store array row by row, Column major, column by column.

- 1-D array $a[m]$, a the starting address of array a (address of $a[0]$), denoted α , $a[i]$ stored at $\alpha + i$.
- 2-D array $a[m][n]$, a address of $a[0][0]$, $a[i][j]$ is stored at $\alpha + i \cdot n + j$.
- What if a sparse matrix
 - upper triangle
 - band
- Given a sparse matrix $A[i][j]$, we store only the nonzero terms in a 1D array B , s.t. for a given (i, j) we return $A[i][j]$ by calculating the address we store $A[i][j]$ in B and retrieve it in B .

String Abstract Data Type

- C-string using array, C provides functions to process string of char.
- A string ADT

```
class String
{
public:
    String (char *init, int m);
    int length();
    String Concat (String t);
    String Substr(int, i, int j);
    int Find(String pat);
}
```

String Matching

- Given two strings, s and pat , we usually say that s is the text and pat is the pattern.
- Determine whether pat is in s by using the function $Find$, $Find$ returns -1 if pat is not in s or returns the position in s where pat starts.
- Naive approach, comparing pat with string starting $s[i]$ for every $0 \leq i \leq |s| - |pat|$.
- if matched, return i , otherwise, move to $i + 1$.
- Worst case will be $|s| \cdot |pat|$.
- Can we do better?

Knuth-Morris-Pratt Algorithm

- An $O(|pat| + |s|)$ time algorithm, and it is “optimal”.
- Basic idea, a mismatch also tells us something.
- Calculate information from the pattern, pat , so that when a mismatch occurs, we don't have to start at the next position in s .

- The pattern $pat = abcabcacab$
- The string $s = s_0s_1 \dots s_{m-1}$.
- Suppose that we are determining whether or not there is a match beginning s_i .
- If $s_i \neq a$ then we proceed by comparing s_{i+1} and a .

s	=	-	a	?	?	?	.					
pat	=		a	b	c	a	b	c	a	c	a	b

- If $s_i = a$, we compare b against s_{i+1}
- if $b \neq s_{i+1}$, since that first question mark can be anything but not b ,
- we proceed by comparing a and s_{i+1} .

s	=	-	a	b	?	?	.					
pat	=		a	b	c	a	b	c	a	c	a	b

- Suppose that we have $s_i s_{i+1} = ab$, but $c \neq s_{i+2}$,
- We proceed by comparing a and s_{i+2}
- because we know that s_{i+1} is b , it cannot be a , so we don't have to compare a and s_{i+1} . And s_{i+2} is not c but can be any other, so we compare a and s_{i+2} .

s	=	-	a	b	c	a	?	?				
pat	=		a	b	c	a	b	c	a	c	a	b

- Suppose that we match $abca$ and $s_i s_{i+1} s_{i+2} s_{i+3}$ but b does not match s_{i+4} ,
- Since we know s_{i+3} is a , we can proceed by comparing s_{i+4} and b , the 2nd character in pat .

Failure Function

If $p = p_0p_1 \dots p_{n-1}$ is a pattern, then the failure function, f , is defined as

$$f(j) = \begin{cases} \text{largest } k < j \text{ s.t. } p_0 \dots p_k = p_{j-k} \dots p_j & \text{if such a } k \geq 0 \text{ exist} \\ -1 & \text{otherwise.} \end{cases}$$

$pat = abcabcacab$

j	0	1	2	3	4	5	6	7	8	9
pat	a	b	c	a	b	c	a	c	a	b
f	-1	-1	-1	0	1	2	3	-1	0	1

Matching Algorithm

If a partial match is found s.t. $s_{i-j} \dots s_{i-1} = p_0 \dots p_{j-1}$ and $s_i \neq p_j$ then matching may be resumed by comparing s_i and $p_{f(j-1)+1}$ if $j \neq 0$. If $j = 0$, then we may continue by comparing s_{i+1} and p_0 .

<i>j</i>	0	1	2	3	4	5	6	7	8	9
<i>pat</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>a</i>	<i>c</i>	<i>a</i>	<i>b</i>
<i>f</i>	-1	-1	-1	0	1	2	3	-1	0	1

a b c a b c a b c a b c c b c a b c a b c c
a b c a b c a c
a b c a b c a c
a b c a b c a c
a b c a b c a
a b c a
a

Matching Algorithm

- Time complexity $O(\text{length}(S))$.

- the correctness of the algorithm depends on the failure function can be computed in $O(\text{length}(P))$.
- restate the failure function

$$f(j) = \begin{cases} -1 & \text{if } j = 0 \\ f^m(j-1) + 1 & \text{where } m \text{ is the least integer} \\ & k \text{ for which } p_{f^k(j-1)+1} = p_j \\ -1 & \text{if there is no } k \text{ satisfying the above} \end{cases}$$

- $f^1(j) = f(j)$ and $f^m(j) = f(f^{m-1}(j))$
- Program 2.17 (next page), time complexity $O(\text{length}(P))$

j	0	1	2	3	4	5	6	7	8	9
pat	a	b	c	a	b	c	a	c	a	b
f	-1	-1	-1	0	1	2	3	-1	0	1

- If $j = 6$, $p_j = a$,
- $m = 1$, $f(5) + 1 = 3$, $p_3 = a = p_j$, then $f(6) = 3$

- If $j = 5$, $p_5 = c$,
- $m = 1$, $f(4) + 1 = 2$, $p_2 = c = p_5$, $f(5) = 2$.
-
- If $j = 9$, $p_9 = b$,
- $m = 1$, $f(8) + 1 = 1$, $p_1 = b = p_9$, $f(9) = 1$.
-
- If $j = 7$, $p_7 = c$,
- $m = 1$, $f(6) + 1 = 4$, $p_4 = b \neq p_7$,
- $m = 2$, $f(3) + 1 = 1$, $p_1 = b \neq p_7$,
- $m = 3$, $f(0) + 1 = 0$, $p_0 = a \neq p_7$,
- thus $f(7) = -1$.

```

void String::FailureFunction()
{
    int lengthP=Length();
    f[0]=-1;
    for (int j=1;j<lengthP; j++)
    {
        int i=f[j-1];
        while ((* (str+j) !=* (str+i+1)) && (i>=0))
            i=f[i];
        if (* (str+j)==* (str+i+1))
            f[j]=i+1;
        else f[j]=-1;
    }
}

```