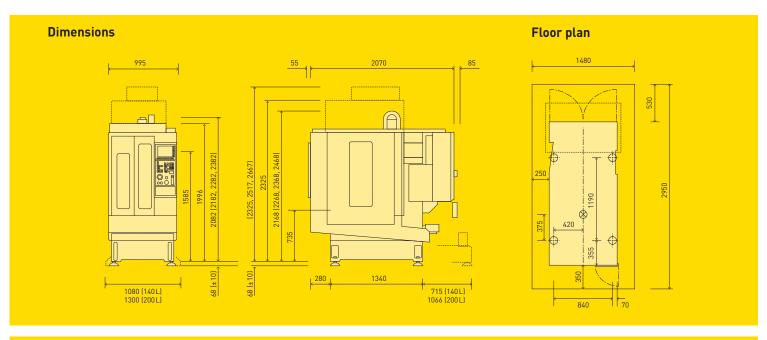
## Three models for every requirement

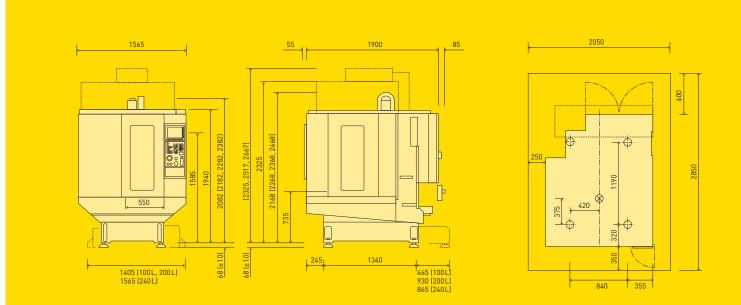
## α-D21SiA5

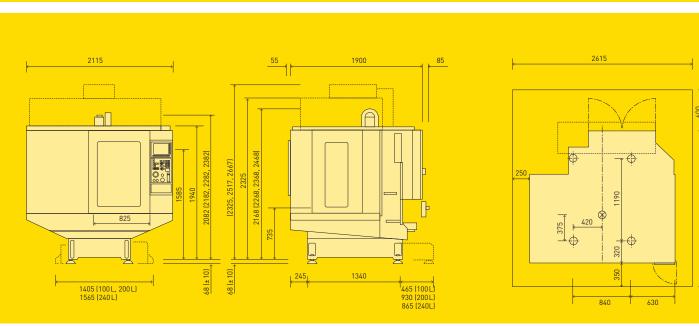




## Technical data

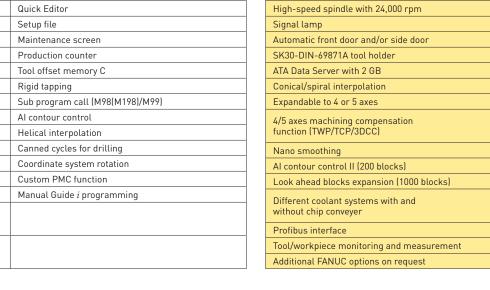


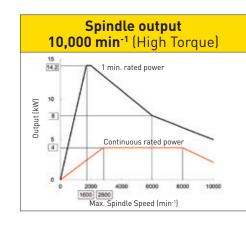


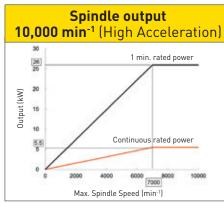


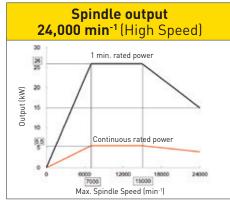
Robodrill $lpha$ -D $i$ A series		<b>α-D21S</b> <i>i</i> <b>A5</b>	$\alpha$ -D21M $i$ A5	α- <b>D21L</b> <i>i</i> <b>A5</b>
Travel X/Y/Z	mm	300 x 300 x 330	500 x 400 x 330	700 x 400 x 330
Max. tool length (0–24,000 min <sup>-1</sup> )	mm	250		
Max. tool diameter	mm	80		
Table size	mm	630 x 330	650 x 400	850 x 410
Max. table load	kg	200	200 300	
Max. tool weight (0–24,000 min <sup>-1</sup> )	kg	3		
Distance from spindle nose to table	mm	250–580 with HC100		
Controller		FANUC 31 <i>i</i> -B5		
Spindle speed (min-1)		10 000/24 000		
Spindle load	10,000 min <sup>-1</sup>	78 Nm, 12.5 kW (1 min), 3.7 kW continuous operation		
	24,000 min <sup>-1</sup>	35 Nm, 26 kW (1 min), 4.5 kW continuous operation		
Rapid traverse in all axes		54 m/min		
Acceleration X/Y/Z		1.5 G		
Number of tools		21		
Tool change time	chip to chip	1.6 s (2 kg/tool)		
Thread cutting	10,000 min <sup>-1</sup>	6,000 min <sup>-1</sup>		
	24,000 min <sup>-1</sup>	8,000 min <sup>-1</sup>		
Programmable cutting feed		30,000 mm/min		
Spindle holder		BT30/SK30 DIN 69871A (optional BBT30)		
Positioning accuracy ISO 230-2		0.006 mm		
Repeatability ISO 230-2		+/- 0.002 mm		
Air pressure consumption		150L/min 0.35-0.55 MPa (3.5-5.5 bar)		
Max. machine weight/with DDR-T	t	1.9/2.1	2.0/2.2	2.1/2.3

Standard equipment		
Dual Check Safety (DCS)	Program simulation	
Manual pulse generator	Quick Editor	
10.4" color LCD screen	Setup file	
Dynamical graphic display	Maintenance screen	
Ethernet	Production counter	
Interface for USB, CF card, RS232C and RJ45	Tool offset memory C	
Alphanumerical operators panel	Rigid tapping	
Variable spindle orientation M19	Sub program call (M98(M198)/M99)	
LED interior lighting	Al contour control	
20 free M-codes	Helical interpolation	
16 free digital inputs/outputs	Canned cycles for drilling	
Multiple language selection	Coordinate system rotation	
Thermal displacement compensation (X-/Y-/Z-axis)	Custom PMC function	
Background editing	Manual Guide <i>i</i> programming	
Additional workpiece coordinate system 48 pairs (G54.1)		









Optional equipment

Center through coolant