

Training convolutional neural networks by simulated/quantum annealing

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We consider the possibility of training convolutional neural networks (CNN) by simulated or quantum annealing. This is realized by mapping the mean square error (MSE) loss function of each individual network's layer to a set of spin glasses Hamiltonians. Finding the ground state of the spin glass system is then equivalent to minimizing the layer loss function.

1 Linear layer

Let start by considering a network composed by a single linear layer:

$$s_i(q) = \sum_{j=0}^{N-1} \omega_{ij} q_j - \theta_i, \quad (1)$$

where q_i , ($i = 0, \dots, N-1$) are the network input neurons, s_i , ($i = 0, \dots, M-1$) the network output neurons, ω_{ij} the synaptic weights, θ_i the biases and $f(x)$ the activation function.

Training the layer means finding the configuration $\{\omega_{ij}, \theta_i\}$ that minimize a loss function over a training dataset. We are interested in the Mean Squared Error (MSE) loss function which is given by:

$$\text{MSE}_i = \frac{1}{Q} \sum_{a=0}^{Q-1} \left(s_i(q^a) - \xi_i^a \right)^2, \quad i = 0 \dots M-1, \quad (2)$$

where q^a is the a -th training sample and ξ^a the corresponding expected output. Setting the biases to zero ($\theta_i = 0$) for simplicity, we can insert Eq. (1) into Eq. (2) and expand the square as follow

$$\begin{aligned} \text{MSE}_i &= \frac{1}{Q} \sum_{a=0}^{Q-1} \left[\left(\sum_{j=0}^{N-1} \omega_{ij} q_j^a \right)^2 - 2 \left(\sum_{j=0}^{N-1} \omega_{ij} q_j^a \right) \xi_i^a + (\xi_i^a)^2 \right] = \\ &= \left[\sum_{j,l} \left(\frac{1}{Q} \sum_a q_j^a q_l^a \right) \omega_{ij} \omega_{il} + \sum_j \left(-\frac{2}{Q} \sum_a \xi_i^a q_j^a \right) \omega_{ij} + \frac{1}{Q} \sum_a (\xi_i^a)^2 \right]. \end{aligned} \quad (3)$$

By identifying

$$\begin{aligned} J_{jl} &\equiv \frac{1}{Q} \sum_{a=0}^{Q-1} q_j^a q_l^a, & h_j^i &\equiv -\frac{2}{Q} \sum_{a=0}^{Q-1} \xi_i^a q_j^a, \\ E_0^i &\equiv \frac{1}{Q} \sum_{a=0}^{Q-1} (\xi_i^a)^2, & S_j^i &\equiv \omega_{ij}, \end{aligned} \quad (4)$$

the loss function has been mapped to a system of equations that resemble spin glass Hamiltonians:

$$\text{MSE}_i \equiv H_i(\vec{S}) = \sum_{j,l=0}^{N-1} J_{jl} S_j^i S_l^i + \sum_{j=0}^{N-1} h_j^i S_j^i + E_0^i. \quad (5)$$

However, the weights S_j^i are here continuous variables instead of spin variables ($\sigma_j^i = \pm 1$).

To convert them to spin variables we can choose a range around the current weight values S_j^{0i} , i.e. $S_j^i \in [S_j^{0i} - L, S_j^{0i} + L]$ and map these spans to the interval $[0, 1]$ ¹

$$\begin{aligned} S_j^i \in [S_j^{0i} - L, S_j^{0i} + L] &\longrightarrow S_j'^i = \frac{S_j^i + L - S_j^{0i}}{2L} \in [0, 1], \\ S_j^i &= L(2S_j'^i - 1) + S_j^{0i}. \end{aligned} \quad (6)$$

By casting these normalized weights to an n -bit representation

$$S_j'^i = \frac{1}{N_b} \sum_{\alpha=0}^{n-1} 2^\alpha \frac{\sigma_{j\alpha}^i + 1}{2}, \quad \sigma_{j\alpha}^i = \pm 1, \quad N_b = 2^n - 1, \quad (7)$$

we can rewrite the Hamiltonian (5) in terms of spin variables $\sigma_{j\alpha}^i$. In this representation, the Hamiltonian's interaction J_{jl} and magnetic field h_j^i become

$$\begin{aligned} J_{jl} &\rightarrow J_{jl}'^{\alpha\beta} = \frac{L^2}{N_b^2} J_{jl} 2^\alpha 2^\beta, \\ h_j^i &\rightarrow h_j'^{i\alpha} = \frac{L}{N_b} \left(h_j^i + 2 \sum_l J_{jl} S_l^{0i} \right) 2^\alpha. \end{aligned} \quad (8)$$

Note that we do not need to compute the expression of the zero energy $E_0'^i$ because it does not affect the system ground state configuration.

Finally, combining the input neuron's index $j = 0 \dots N - 1$ with the corresponding bit index $\alpha = 0 \dots n - 1$ into a single index $\mu = 0 \dots N_L - 1$ with $N_L = Nn$, we obtain the system of spin glasses Hamiltonians

$$\text{MSE}_i \equiv H_i(\vec{\sigma}) = \sum_{\mu,\nu=0}^{N_L-1} J_{\mu\nu}' \sigma_\mu^i \sigma_\nu^i + \sum_{\mu=0}^{N_L-1} h_\mu'^i \sigma_\mu^i + E_0'^i, \quad i = 0 \dots M - 1. \quad (9)$$

¹This is better than choosing a global range $S_j^i \in [-L, L]$ because it allows us to set different range sizes L at different training epochs (similarly to varying the learning rate in backpropagation).

1.1 Biases

To keep things simple, we have set the biases θ_i to zero (and we will keep them so for the rest of this document). However, we want to point out that the above derivation is valid also in the presence of biases which can be interpreted as additional spin variables.

When expanding the MSE loss function, the biases contribution is

$$\text{MSE}_i(\theta) = \frac{1}{Q} \sum_a \left(\theta_i - 2 \sum_{j=0}^{N-1} \omega_{ij} \sigma_j^a + 2 \xi_i^a \right) \theta_i. \quad (10)$$

By defining

$$S_N^i = \theta_i, \quad J_{NN} = 1, \quad J_{Nj} = -\frac{1}{Q} \sum_a \sigma_j^a, \quad h_N^i = \frac{2}{Q} \sum_a \xi_i^a, \quad (11)$$

The total MSE loss function translates to the Hamiltonian

$$\text{MSE}_i \equiv H_i(\vec{S}) = \sum_{jl=0}^N J_{jl} S_j^i S_l^i + \sum_{j=0}^N h_j^i S_j^i + E_0^i, \quad (12)$$

where the sums run now over $N + 1$ weight variables instead of the N in Eq. (5).

2 Convolutional layer

The same approach outlined above for a linear layer can be carried out for convolutional layers as well. Let us consider a 2 dimensional convolution with C_1 input channels C_2 output channels and kernel c_{kl}^{pr} of size K :

$$s_{ij}^r = \sum_{p=0}^{C_1-1} \sum_{kl=0}^{K-1} c_{kl}^{rp} q_{i-\frac{K}{2}+k, j-\frac{K}{2}+l}^p, \quad r = 0, \dots, C_2 - 1, \quad (13)$$

where q_{ij}^p is the input layer and s_{ij}^r the output layer, and $i \in [\frac{K}{2}, N - \frac{K}{2}]$, $j \in [\frac{K}{2}, M - \frac{K}{2}]$. The MSE loss function is

$$\text{MSE}_r = \frac{1}{Q} \sum_{a=0}^{Q-1} \sum_{i=\frac{K}{2}}^{N-\frac{K}{2}} \sum_{j=\frac{K}{2}}^{M-\frac{K}{2}} \left(s_{ij}^r(q^a) - \xi_{ij}^{ra} \right)^2, \quad r = 0 \dots C_2 - 1, \quad (14)$$

where we have introduced a sum over the i, j input sites because the convolutional kernel does not depend on them. Expanding the loss function and defining

$$\begin{aligned} J_{kl, mn}^{pp'} &\equiv \frac{1}{Q} \sum_a \sum_{ij} q_{i-\frac{K}{2}+k, j-\frac{K}{2}+l}^{pa} q_{i-\frac{K}{2}+m, j-\frac{K}{2}+n}^{p'a}, & p, p' \in [0, C_1 - 1], \\ h_{kl}^{rp} &\equiv -\frac{2}{Q} \sum_a \sum_{ij} q_{i-\frac{K}{2}+k, j-\frac{K}{2}+l}^{pa} \xi_{ij}^{ra}, & r \in [0, C_2 - 1], p \in [0, C_1 - 1], \\ E_0^r &\equiv \frac{1}{Q} \sum_a \sum_{ij} (\xi_{ij}^{ra})^2, & r \in [0, C_2 - 1], \end{aligned} \quad (15)$$

the loss function is mapped to the set of Hamiltonians

$$\text{MSE}_r \equiv H_r(c) = \sum_{pkl} \sum_{p'mn} J_{kl,mn}^{pp'} c_{kl}^{rp} c_{mn}^{rp'} + \sum_{pkl} h_{kl}^{rp} c_{kl}^{rp} + E_0^r. \quad (16)$$

As before, we can convert the continuous kernel variables c_{kl}^{rp} to spin variables:

$$H_r(\sigma) = \sum_{pkl\alpha} \sum_{p'mn\beta} J'_{kl\alpha,mn\beta} \sigma_{kl\alpha}^{rp} \sigma_{mn\beta}^{rp'} + \sum_{pkl\alpha} h'_{kl\alpha} \sigma_{kl\alpha}^{rp} + E_0'^r, \quad (17)$$

where

$$\begin{aligned} J'_{kl\alpha,mn\beta} &= \frac{L^2}{N_b^2} J_{kl,mn}^{pp'} 2^\alpha 2^\beta, \\ h'_{kl\alpha} &= \frac{L}{N_b} \left(h_{kl}^{rp} + 2 \sum_{p'mn} J_{kl,mn}^{pp'} c_{mn}^{rp'} \right) 2^\alpha. \end{aligned} \quad (18)$$

Finally by combining the kernel indices $k, l \in [0, K-1]$, the input channel index $p \in [0, C_1-1]$ and the bit index $\alpha \in [0, n-1]$ into a single index $\mu \in [0, N_C-1]$ with $N_C = K^2 C_1 n$ we obtain the system of spin glass Hamiltonians

$$\text{MSE}_r \equiv H_r(\vec{\sigma}) = \sum_{\mu\nu=0}^{N_C-1} J'_{\mu\nu} \sigma_\mu^r \sigma_\nu^r + \sum_{\mu=0}^{N_C-1} h'_\mu \sigma_\mu^r + E_0'^r, \quad r = 0 \dots C_2 - 1. \quad (19)$$

3 Activation function

Including an activation function in the above approach can be easily done at least for a piecewise linear function. Consider for example the LeakyReLU activation function:

$$f(x) = \gamma(x)x, \quad \gamma(x) = \begin{cases} 1, & x \geq 0 \\ \alpha, & x < 0 \end{cases}.$$

By inserting it in Eq. (1), the activated layer output becomes

$$f(s_i(q^a)) = \sum_{j=0}^{N-1} \gamma_i^a \omega_{ij} q_j^a, \quad \gamma_i^a = \gamma(s_i(q^a)). \quad (20)$$

Expanding the MSE (2) with the activated neurons, the spin glass Hamiltonian parameters (Eq. (4)) become

$$\begin{aligned} J_{jl}^i &\equiv \frac{1}{Q} \sum_{a=0}^{Q-1} (\gamma_i^a)^2 q_j^a q_l^a, & h_j^i &\equiv -\frac{2}{Q} \sum_{a=0}^{Q-1} \gamma_i^a \xi_i^a q_j^a, \\ E_0^i &\equiv \frac{1}{Q} \sum_{a=0}^{Q-1} (\xi_i^a)^2, & S_j^i &\equiv \omega_{ij}. \end{aligned} \quad (21)$$

This allows us to carry on the simulated annealing by updating the Hamiltonian parameters as the spin configuration evolves.

4 Multilayer networks

The equivalence outlined above between MSE loss functions and spin glass Hamiltonians can be used directly to train single layer networks for which inputs and outputs are given by the elements of the training dataset.

But when considering multilayer networks, the ideal inputs and outputs of the internal hidden layers are unknown.

We assume then that it is possible to proceed in steps where at each step the dataset samples are propagated forward and backward through the network generating the input/output configurations for each layer, the layers Hamiltonians are minimized for the given configuration and the procedure is repeated until eventually the system converges to an optimal solution.

Note that in this approach, backward propagation requires to compute the true inverse of the network. Since the layers are in general not bijective, we have to resort to use the Moore-Penrose pseudoinverse. Furthermore, the inversion of convolutional layers requires to express the convolution in Fourier space where it acts as a matrix multiplication and the pseudoinverse can be computed.

To be more specific, the procedure we use to train multilayer networks is outlined by the following steps:

1. Initialize the network weights randomly
2. Given the training set $\{q^a, \xi^a\}$, propagate the output sample ξ^a backward through the (pseudo)inverse network.
3. For each layer in the network:
 - Propagate the training input samples q^a forward through the network up to the layer in question
 - Transform the layer to the equivalent system of spin glasses Hamiltonians.
 - Find the spin configuration that minimize the Hamiltonian
 - Convert back the spin configuration and update the layer's weights
4. Once all layers weights have been updated, recalculate the network (pseudo)inverse.
5. Repeat from step 2 until the system's energy reaches a minimum.

As an example, consider a 2 layers network composed of an output linear layer s_i with weights ω_{ij}^1 and an input linear layer h_j with weights ω_{jk}^0 activated by a leakyReLU function. The MSE is

$$\text{MSE}_i = \frac{1}{Q} \sum_{a=0}^{Q-1} (T_i^a)^2 = \frac{1}{Q} \sum_{a=0}^{Q-1} \left(\sum_j \omega_{ij}^1 \gamma_i^{1a} h_j^a - \xi_i^a \right)^2, \quad (22)$$

where we have introduced the quantity T_i^a :

$$T_i^a = f(s_i(f(h(q^a))) - \xi_i^a = \left(\sum_j \omega_{ij}^1 \gamma_i^{1a} \sum_k \omega_{jk}^0 \gamma_j^{0a} q_k^a \right) - \xi_i^a. \quad (23)$$

By applying the pseudo-inverse of the output layer $(\omega_{ij}^1)^{-1}$, one gets

$$T_j^a = \sum_i (\omega^1)_{ji}^{-1} \frac{T_i^a}{\gamma_i^{1a}} = \sum_k \omega_{jk}^0 \gamma_j^{0a} q_k^a - \xi_j'^a, \quad (24)$$

where

$$\xi_j'^a = \sum_i (\omega^1)_{ji}^{-1} \frac{\xi_i^a}{\gamma_i^{1a}}.$$

One can then use T_j^a to minimize the MSE_j for the input layer weights ω_{jk}^0 . Then, use this weight configuration to calculate the input layer output

$$h_j^a = \sum_k \omega_{jk}^0 \gamma_j^{0a} q_k^a,$$

and use it to minimize the MSE_i for the output layer weights ω_{ij}^1 .²

Note that when minimizing the weight configuration ω_{jk}^0 of the input layer, Eq. (24) shows that the input samples q_k^a are affected only by the activation factors γ_j^{0a} relative to the input layer. On the other hand, in the gradient descent approach, the gradient component relative to the input layer weight $\omega_{j'k'}^0$ contains contributions from both layers activation factors:

$$\frac{\partial \text{MSE}_i}{\partial \omega_{j'k'}^0} = \frac{2}{Q} \sum_a \left(\sum_j \omega_{ij}^1 \gamma_i^{1a} \sum_k \omega_{jk}^0 \gamma_j^{0a} q_k^a - \xi_i^a \right) \omega_{ij'}^1 \gamma_i^{1a} \gamma_{j'}^{0a} q_{k'}^a. \quad (25)$$

In order to keep a similar contribution in the spin glass approach, one can re-express Eq. (23) as

$$T_i^a = \sum_j T_{ij}^a, \quad (26)$$

where

$$T_{ij}^a = \omega_{ij}^1 \gamma_i^{1a} \sum_k \omega_{jk}^0 \gamma_j^{0a} q_k^a - \omega_{ij}^1 \gamma_i^{1a} \sum_{i'} (\omega^1)_{ji'}^{-1} \frac{\xi_{i'}^a}{\gamma_{i'}^{1a}}. \quad (27)$$

When minimizing the input layer weight configuration, one can then use the expression

$$T_j^a = \sum_i T_{ij}^a = \sum_k \omega_{jk}^0 \beta_j^{1a} \gamma_j^{0a} q_k^a - \xi_j''^a, \quad (28)$$

where

$$\beta_j^{1a} = \sum_i \omega_{ij}^1 \gamma_i^{1a}, \quad \xi_j''^a = \beta_j^{1a} \sum_{i'} (\omega^1)_{ji'}^{-1} \frac{\xi_{i'}^a}{\gamma_{i'}^{1a}}. \quad (29)$$

While now the input samples are affected by the activation factors from both layers, the approach does not seem to produce better results than the previous one.

²Note that this derivation is based on the assumption that $\sum_i (\omega^1)_{ji}^{-1} \omega_{ij}^1 = \delta_{jj'}$, which is not generally true for non-invertible matrices. However, tests shows that the procedure works well independently of the shape of the weight matrices.

5 Tests and results

In order to assess the performance of the approach described above, we compare it to standard backpropagation in training some simple network architectures for classification³.

To minimize the spin glass Hamiltonians, we use simulated annealing and quantum annealing (when possible).

Simulated annealing is based on the Metropolis-Hastings algorithm where the system temperature is slowly lowered during the iteration. In the Metropolis algorithm, to find the spin configuration that minimizes the Hamiltonian (9), each spin σ_μ is flipped if it decreases the system energy, i.e. if

$$dE_\mu^i = H_i(\sigma'_\mu) - H_i(\sigma_\mu) = (\sigma'_\mu - \sigma_\mu) \left(2 \sum_{\nu \neq \mu} J_{\mu\nu}^i \sigma_\nu + h_\mu^i \right) < 0, \quad (30)$$

or if a random number $r \in [0, 1]$ is smaller than the acceptance probability

$$P_a = E^{-\beta dE_\mu^i}, \quad (31)$$

where $\beta \propto \frac{1}{T}$ is the inverse temperature.

Quantum annealing is performed on the D-wave quantum annealing machines.

The code of the tests is available here.

5.1 Single linear layer

Let's start by considering a network consisting of a single linear layer:

$$\boxed{\begin{array}{c} \text{Input} \\ (1, 32, 32) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Flatten} \\ (1024) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Linear} \\ (1024 \times 10) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Output} \\ (10) \end{array}}. \quad (32)$$

When performing simulated annealing, we use a 8bit representation to convert the synaptic weights to spin variables so that the network is mapped to a system of 10 spin glasses each containing 8192 spins.

We train this network using a subset of the MNIST dataset consisting on 1000 samples.

In Fig. 1(a), we compare the mean accuracy over 20 epochs of training by backpropagation and simulated annealing (the model is too large to be trained by quantum annealing). The result shows that the two methods reach the same level of accuracy.

Since this network does not fit on the current D-wave architectures, we consider a smaller version in order to observe how quantum annealing performs. By inserting a pooling layer after the input we can reduce the number of weights in the Linear layer:

$$\boxed{\begin{array}{c} \text{Input} \\ (1, 32, 32) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Spectralpool} \\ (1, 4, 2) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Flatten} \\ (8) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Linear} \\ (8 \times 10) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Output} \\ (10) \end{array}}. \quad (33)$$

³For classification tasks, Cross Entropy loss function is usually preferred over MSE. However, for such simple datasets and architectures, the use of MSE loss function does not seem to negatively affect the training performance.

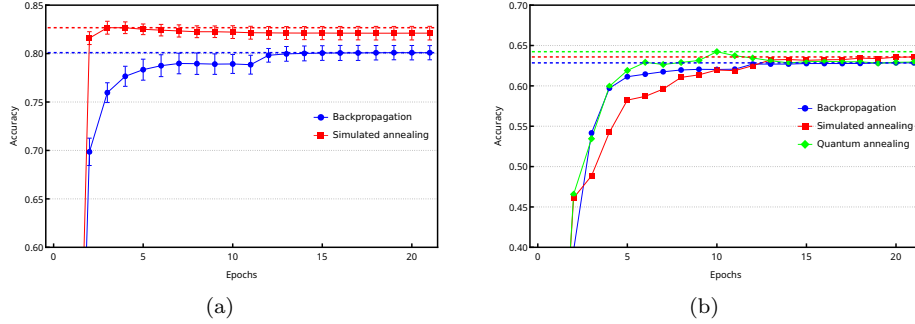


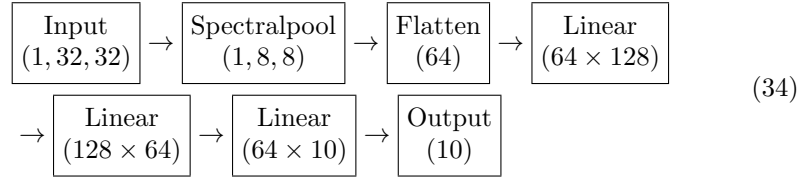
Figure 1: a) Comparison of accuracies obtained by training the 1-layer model (32) by backpropagation (blue) and by simulated annealing (red). b) Comparison of accuracies obtained by training the 1-layer model (33) by backpropagation (blue), simulated annealing (red) and quantum annealing (green).

By using a 4bit representation for the synaptic weights, the network is then mapped to system of 10 spin glasses each consisting of 32 spin variables.

Fig. 1(b) compares the accuracies over 20 epochs of training by backpropagation, simulated annealing and quantum annealing on 10000 samples of the MNIST dataset. The result shows that the three methods reach the same level of accuracy. It appears that no evident advantage arises by using quantum annealing (at least for such a simple system).

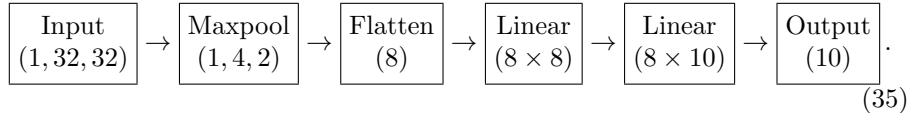
5.2 Multiple linear layers

We consider here a multilayer network consisting of 3 linear layers:



The network is trained on a subset of the MNIST dataset of 1000 samples for 20 epochs. The accuracies for backpropagation and simulated annealing are plotted in Fig. 2(a).

In order to test the performance of quantum annealing for multiple layers, again we consider a simplified architecture consisting of only 2 linear layer:



The results are shown in Fig. 2(b).

5.3 Convolutional layer

For testing how the training approach performs with convolutional layers, we consider a single layer and a three layers architecture. The single layer network

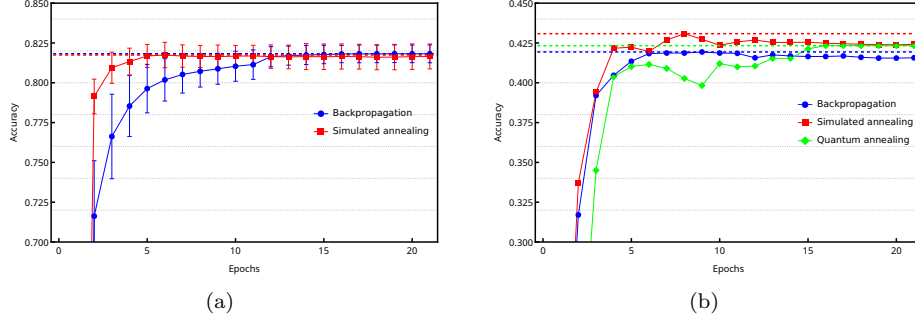
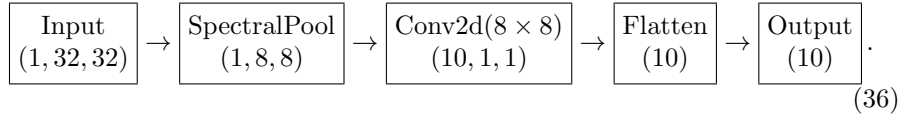


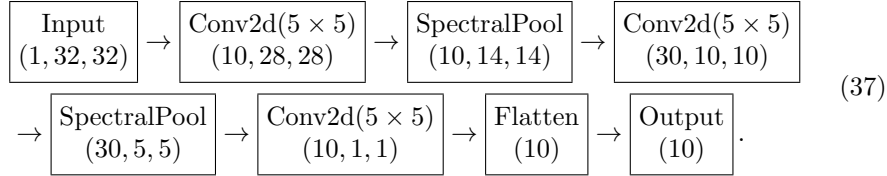
Figure 2: a) Comparison of accuracies obtained by training the 5-layers model (34) by backpropagation (blue) and simulated annealing (red). b) Comparison of accuracies obtained by training the 2-layers network (35) by backpropagation (blue), simulated annealing (red) and quantum annealing (green).

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Again, we use a 8bit representation for the synaptic weights which translates to a system of 10 spin glasses each containing 512 spins and the network is trained on a subset of the MNIST dataset consisting on 1000 samples.

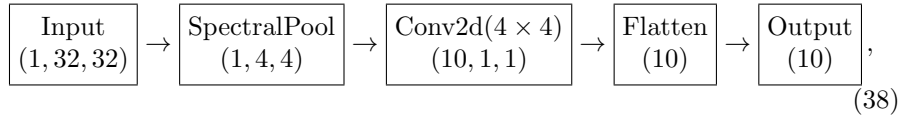
The three layer network is defined as



Note that in this case, we apply an amplification of the signal in the inverse network before each convolutional layer. This improves the performance of the simulated annealing procedure.

In Fig. 3, we compare the accuracies obtained by training the two networks by backpropagation and simulated annealing. As for the linear layer cases, the simulated annealing approach seems to perform well and give results comparable to the ones obtained by standard backpropagation.

As before, in order to test the quantum annealing approach, we use smaller networks. For the single convolutional layer case we consider the network:



so that, by using a 4bit representation for the convolutional kernel, we end up with a system of 10 spin glasses each containing 64 spin variables.

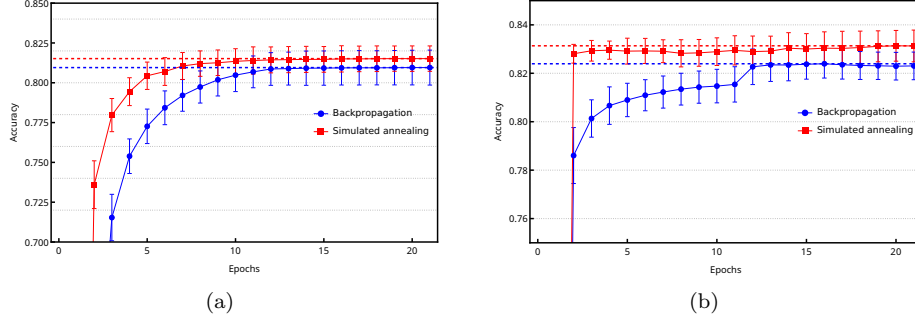


Figure 3: a) Comparison of accuracies obtained by training the 1 convolutional layer model (36) by backpropagation (blue) and by simulated annealing (red). b) Comparison of accuracies obtained by training the 3 convolutional layers model (37) by backpropagation (blue) and simulated annealing (red).

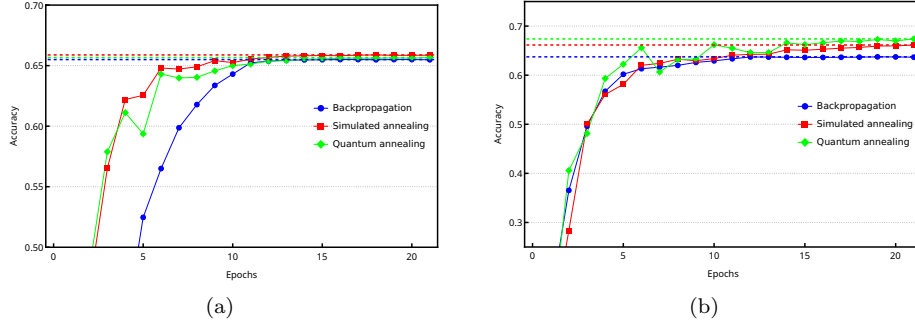


Figure 4: Comparison of accuracies obtained training by backpropagation (blue), simulated annealing (red) and quantum annealing (green) the 1 convolutional layer model (38) (a) and the 2 convolutional layers model (39) (b).

For the multi layers case, we consider the 2 layers architecture:

$$\begin{array}{c}
 \boxed{\begin{array}{c} \text{Input} \\ (1, 32, 32) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{SpectralPool} \\ (1, 4, 4) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Conv2d}(3 \times 3) \\ (4, 2, 2) \end{array}} \\
 \rightarrow \boxed{\begin{array}{c} \text{Conv2d}(2 \times 2) \\ (10, 1, 1) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Flatten} \\ (10) \end{array}} \rightarrow \boxed{\begin{array}{c} \text{Output} \\ (10) \end{array}}, \quad (39)
 \end{array}$$

where the first layer is mapped to a system of 4 spin glasses of 32 spin variables and the second layer is mapped to a system of 10 spin glasses of 64 spin variables. Results are shown in Fig. 4.

5.4 Activation function

As discussed in Sec. 3, an activation function like LeakyReLU can be easily incorporated in the spin glass model by including the activation factors γ_i^a in the Hamiltonian parameters J_{ji}^i and h_j^i , Eq. (21).

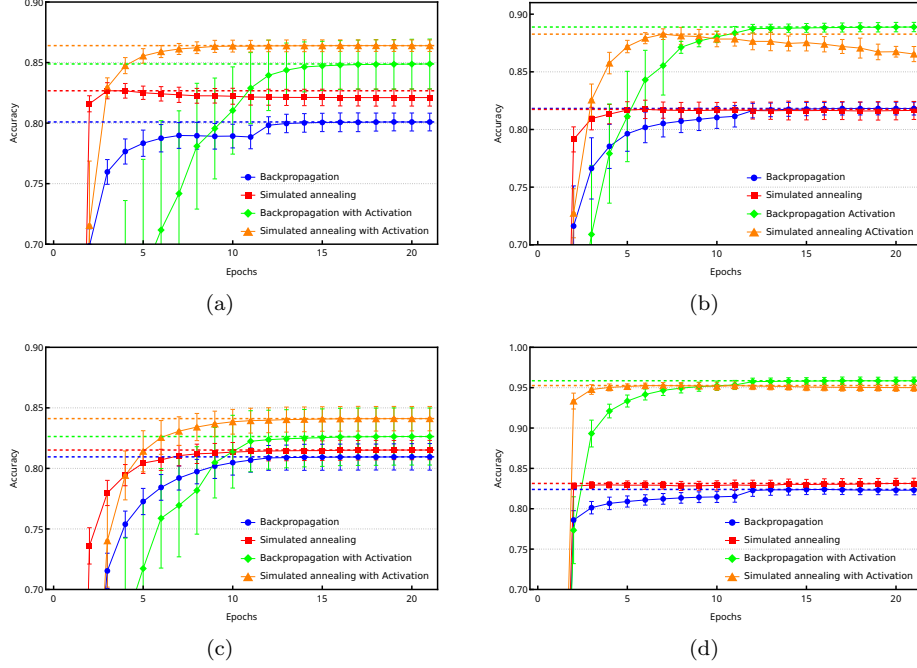
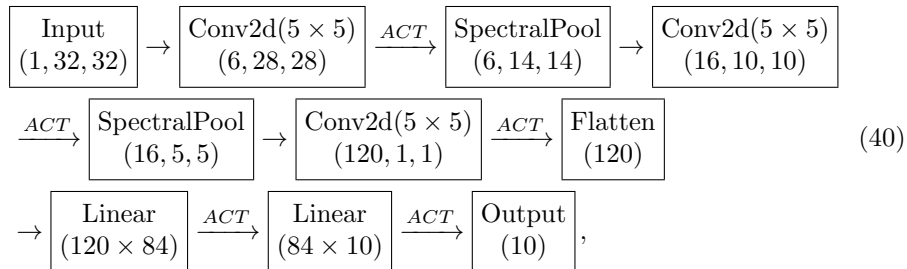


Figure 5: Comparison of the effect of introducing a LeakyReLU ($\alpha = 0.001$) activation function (after each linear and convolutional layer) when training by backpropagation and simulated annealing the 1 linear layer network (32) (a), the 3 linear layers network (34) (b), the 1 convolutional layer network (36) (c) and the 3 convolutional layer network (37).

In Fig. 5 we shows the effect of introducing a LeakyReLU activation function with negative slope $\alpha = 0.001$ after each layer for some of the network tested so far.

5.5 CNN

After having verified that the annealing training procedure works in a number of scenarios, let us test it on a full convolutional network architecture. Specifically, we consider the following Lenet-like architecture



where ACT indicates a LeakyReLU activation function with negative slope $\alpha = 0.001$.

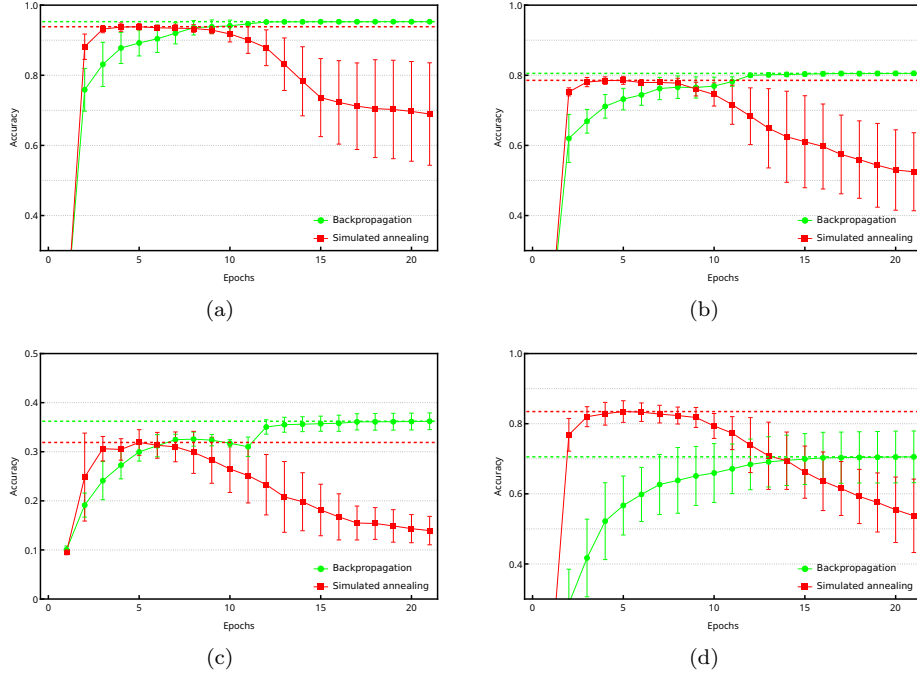


Figure 6: Comparison of accuracies obtained by training by backpropagation and simulated annealing the CNN (40). (a) MNIST dataset, 1000 samples, (b) FashionMNIST dataset, 1000 samples, (c) CIFAR10 dataset, 1000 samples, (d) MNIST dataset, 100 samples.

In Fig. 6, we compare the performance of the simulated annealing approach with standard backpropagation when training the network over 1000 samples of the MNIST (a), FashionMNIST (b) and CIFAR10 (c) datasets and over 100 samples of the MNIST dataset.

It emerges that the simulated annealing experiences instabilities after a few epochs that prevent the method to converge to the optimal configuration. We need to investigate and try to eliminate the source of such instabilities in order for the method to be competitive with backpropagation.

Interestingly, the spin glass approach seems to outperform backpropagation when considering small datasets. It could be a useful alternative when the availability of training data is scarce.

Further considerations: while backpropagation algorithms are well optimized and parallelized, we didn't focus on the optimization of the spin glass approach. Consequently, the training procedure is slower and requires more memory (especially when considering activated layers and large datasets). More work could be done to optimize the approach.

It would be interesting to test the performance of quantum annealing on larger networks, starting with the CNN (40). Unfortunately, the quantum annealing machines do not support such large architecture.