## **VERTEX COVER**

A DYNAMIC PROGRAMMING APPROACH

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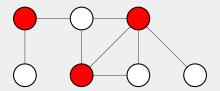
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## INTRODUCTION

#### DEFINITION

#### Formal Definition

A **vertex cover** of an undirected graph G = (V, E) is a subset  $V' \subseteq V$  s. t. if  $(u, v) \in E$ , then  $u \in V'$  or  $v \in V'$  (or both) [CLRS09].



#### A more intuitive definition

A subset of vertices that includes at least one endpoint of every edge.

#### **VERTEX COVER PROBLEM**

#### Which is the problem?

Find a **vertex cover** of minimum size in a given undirected graph. Also known as **minimum vertex cover**.

#### What kind of problem is this?

This problem is the *optimization version* of the NP-complete decision problem of determining whether a graph has a vertex cover of a given size k.

## **APPROACHES**

#### APPROACHES TO SOLVE THE PROBLEM

#### Is it solvable in polynomial time for any undirected graph?

Extremely unlikely to have to have a polynomial time algorithm for any graph [Dem11].

#### What about trees?

We can solve this problem in polynomial time using dynamic programming on trees!

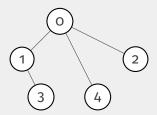
#### RECALL: TREES

#### What is a tree?

A **tree** is an undirected graph in which any two vertices are connected by exactly one path [BW10].

#### Another definition

Connected acyclic undirected graph [BW10].



# DYNAMIC PROGRAMMING APPROACH

#### **ELEMENTS OF DYNAMIC PROGRAMMING: VERTEX COVER**

#### **Optimal Substructure**

A solution for a given tree contains itself optimal solutions to subtrees.

### **Overlapping Subproblems**

Subproblems to subtrees are called multiple times (you'll see how!).

#### BASE CASES

#### Minimum Vertex Cover for o vertices

Clearly, the minimum vertex cover is o.

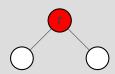
#### Minimum Vertex Cover for 1 vertex

Since there are no edges, the minimum vertex cover is o as well.

#### INTUITION TO APPLY DP

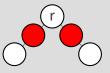
Given an undirected graph G = (V, E). We make two guesses for  $v \in V$ :

#### Root is part of a Minimum Vertex Cover



Then the root is in the cover. We are left with children subtrees as subproblems.

## Root is not part of a Minimum Vertex Cover



Then the children of the root are part of the vertex cover. We are left with the grandchildren subtrees as subproblems.

# CALCULATING THE CARDINALITY OF A MINIMUM VERTEX COVER

A **top-down memoized approach** will suit better this problem, since we must traverse the tree from the root (root can be picked arbitrarily).

An easy way to memoize the subproblems is to **save the cardinality of a minimum vertex cover** in every node (every node has a subtree/subproblem).

# CALCULATING THE CARDINALITY OF A MINIMUM VERTEX COVER

Let G = (V, E) be a tree.

V(v) represents the cardinality of a minimum vertex cover for any  $v \in V$ .

 $c \in V$  and  $g \in V$  represent the children and grandchildren of a given node  $v \in V$ , respectively [Dem11].

#### Recurrence

$$V(v) = \min\{1 + sum(V(c)), |c| + sum(V(g))\}\$$

#### **PSEUDOCODE**

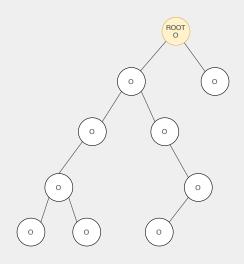
```
1 V(v):
2     if v is null or |v.edges| == 0:
3         return 0
4     if v has not been visited:
5         with_root = 1 + sum(V(c))
6         without_root = |v.edges| + sum(V(g))
7         dp[v] = min(with_root, without_root)
8     return dp[v]
```

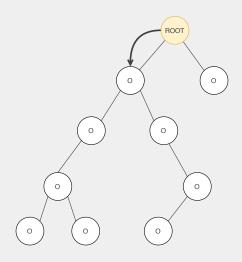
Listing 1: Dynamic programming approach

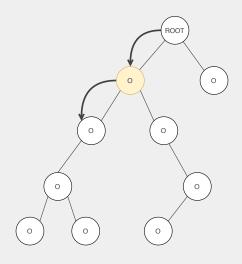
## LOWER LEVEL IMPLEMENTATION (FOR BINARY TREES)

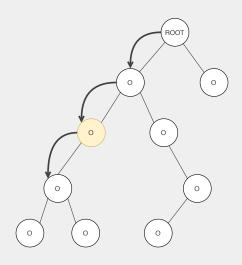
```
1 VC(index):
      if(notExists(index) or (notExists(right(index)
      and notExists(left(index) )):
          return o
      if(tree[index] == 0):
          withRoot = 1 + VC(left(index)) + VC(right(index))
          withoutRoot = 0
7
          if(exists(left(index))):
8
              withoutRoot += 1 + VC(left(left(index))) +
9
              VC(right(left(index)))
10
          if(exists(right(index))):
              withoutRoot += 1 + VC(left(right(index))) +
              VC(right(right(index)))
          tree[index] = minValue(withRoot, withoutRoot)
14
      return tree[index]
15
```

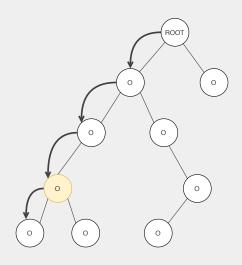
Listing 2: Dynamic programming approach



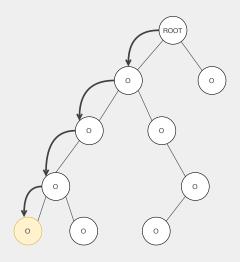


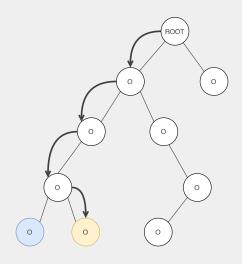


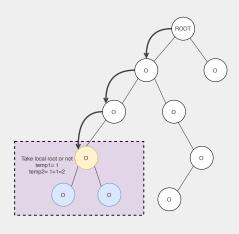


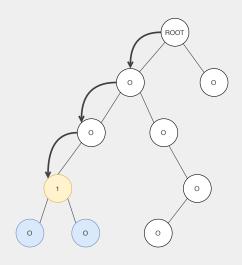


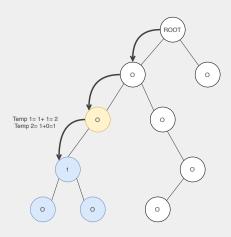
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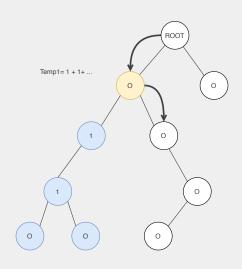


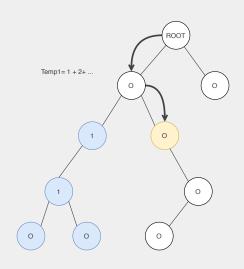


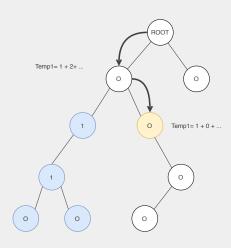


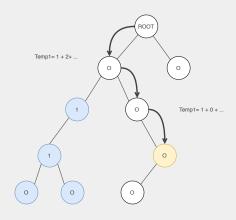


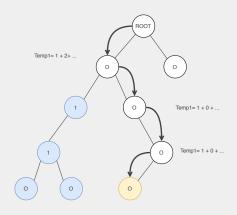


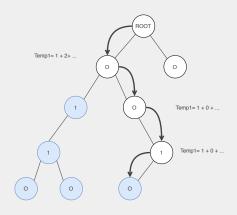


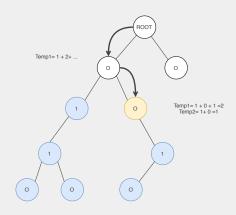


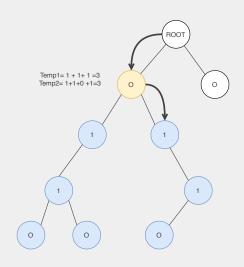


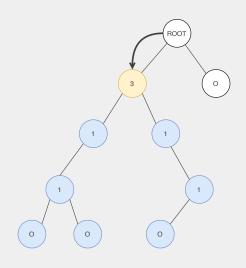


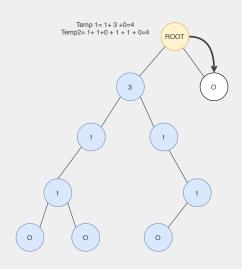


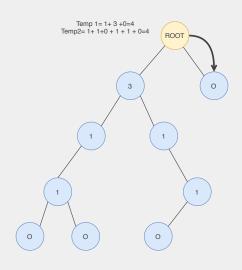


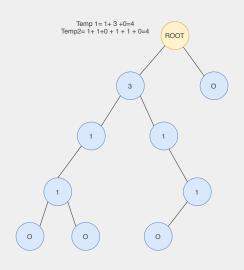


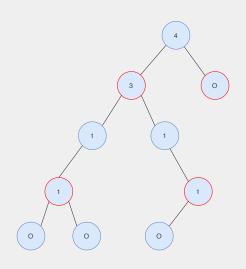












#### **GET VERTEX COVER**

```
int height(Node node){
   if (node=null)
        return -1;
   return 1 + max(height(node.left), height(node.right));
}

int depth(Node root){
   return height(root);
}
```

**Listing 3: Support Functions** 

#### **GET VERTEX COVER**

```
vector<Node> vertexCover(Tree tree){
      vector<Node> result;
      bool oddDepth:
      if(depth%2==0) oddDepth = false;
      else oddDepth = true;
      for(node: tree){
          if(oddDepth){
              if (height(node)%2==0) result.push_back(node);
8
9
          else{
10
              if (height(node)%2!=0) result.push_back(node);
      return result;
14
15 }
```

Listing 4: Dynamic programming approach

#### FOR ANY TREE

```
1 V(v):
2    if v is null or |v.edges| == 0:
3         return 0
4    if v has not been visited:
5         with_root = 1 + sum(V(c))
6         without_root = |v.edges| + sum(V(g))
7         dp[v] = min(with_root, without_root)
8         if root was chosen: paint root
9         else: paint children
10    return dp[v]
```

Listing 5: Dynamic programming approach

#### TIME COMPLEXITY ANALYSIS

#### At first glance...

We have |V| subproblems. Each subproblem takes O(V), since we iterate through the children and the grandchildren of every node.

## But, actually...

We visit every node at most twice (as a child and as a grandchild). So the time taken by this procedure is O(2V) = O(V).

#### **GREEDY APPROACH**

#### Intuition

Keep finding a vertex which covers the maximum numbers of edges [Ban18].

#### Procedure

- 1. Find a vertex with maximum degree.
- 2. Add the vertex to the solution and remove the vertex with all the incident edges from the graph.
- 3. Repeat until all edges are covered.

## **Time Complexity**

 $\mathcal{O}(\log n)$ 

#### **GREEDY PSEUDOCODE**

```
1: function VertexCoverGreedy(G)
2: C \leftarrow \emptyset
3: while W \neq \emptyset do
4: Pick vertex v \in V of maximum degree in G
5: C \leftarrow C \cup \{v\}
6: E \leftarrow E \setminus \{e \cup E : v \cup e\}
7: end while
8: return C
9: end function
```

[ZoLo5]

#### CONCLUSION

- The hardest step in the Dynamic programming approach is not to obtain the optimal substructure, but to count nodes that compose it (for binary trees).
- The Greedy approach is more optimal but it is just an approximation, for that reason choosing to use the Dynamic Programming approach is the best option (when it is possible) to solve the Minimum Vertex Cover Problem.

#### **EXTRA RESOURCES**

Vertex Cover DP implementation:
https://github.com/StephanoWurttele/vertexCover

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