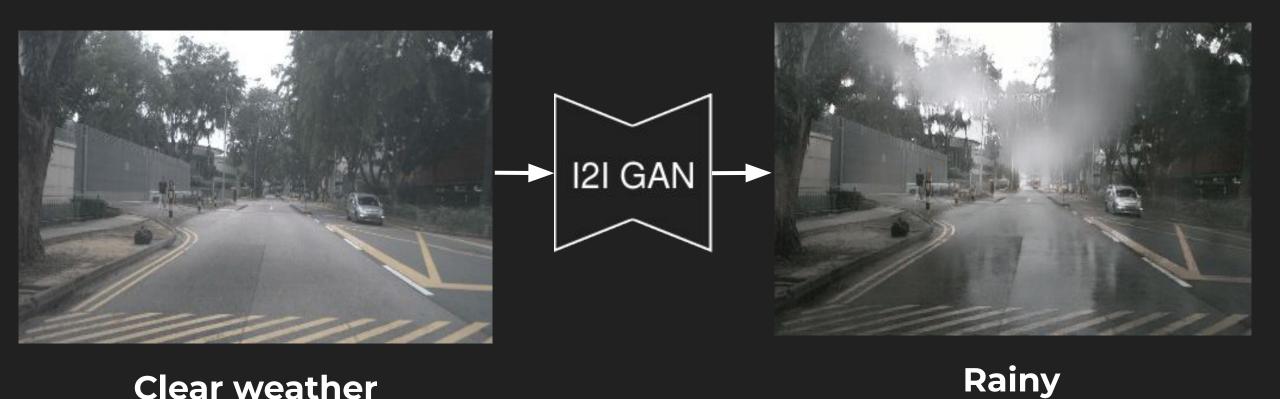
Model-based disentanglement of lens occlusions

Fabio Pizzati^{1, 2}, Pietro Cerri², Raoul de Charette¹





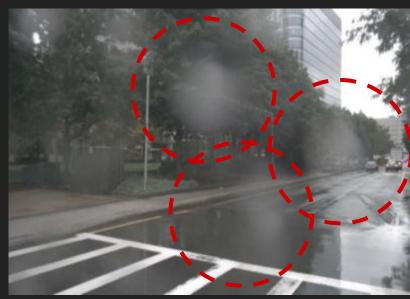
Source **Target** Synthetic Realistic **121 GAN** Adverse weather Clear weather **121 GAN**



Clear weather

Target domain encompasses occlusions (raindrops)







Problem: this is impractical to supervise!

Out-of-focus parameters

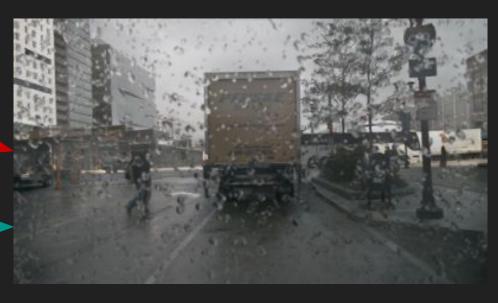


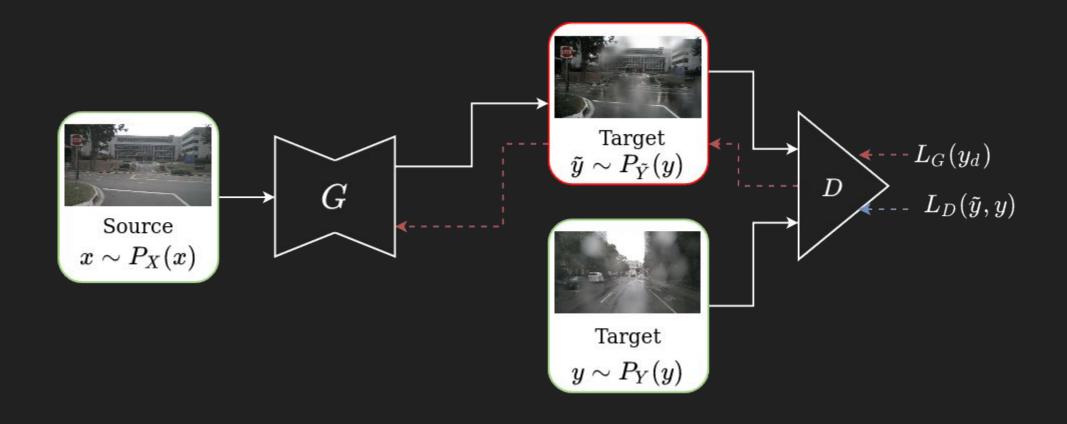
Clear weather

In-focus parameters



Target + occlusions

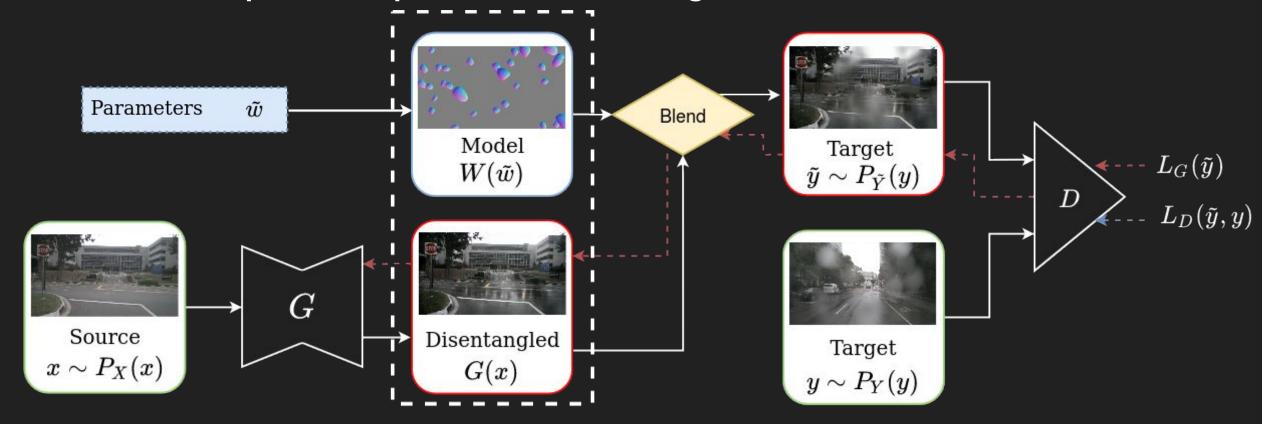




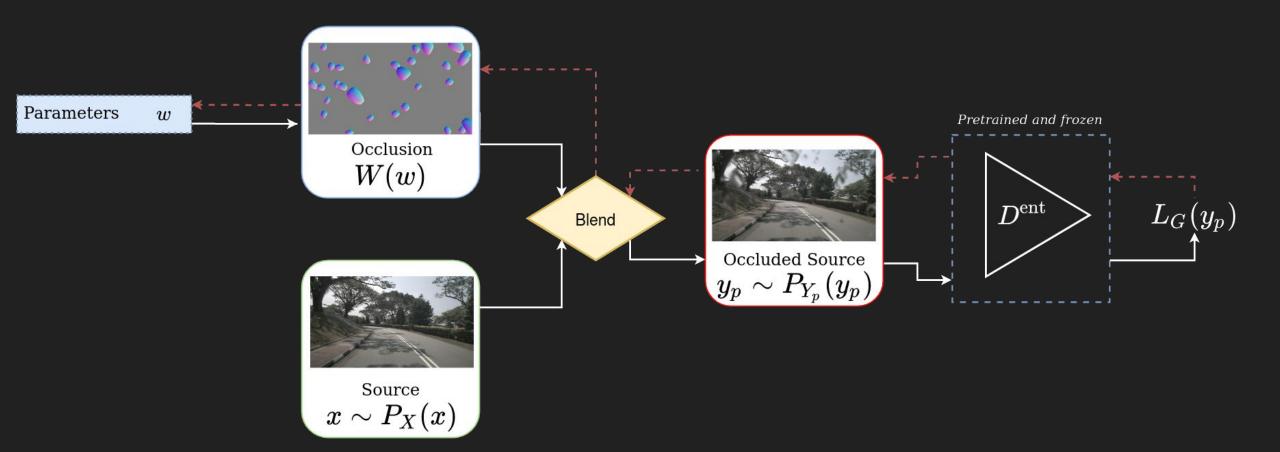
$$\forall x \in X, x \sim P_X(x)$$

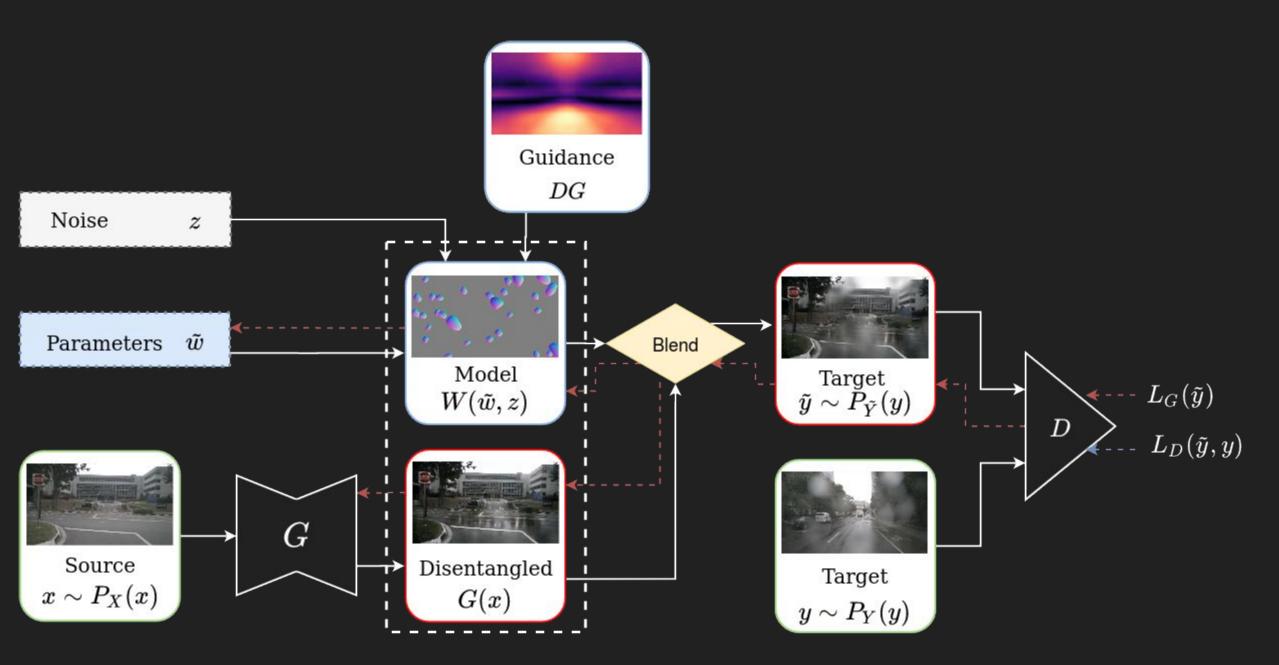
$$\forall y \in Y, y \sim P_Y(y)$$

Unsupervised representation disentanglement

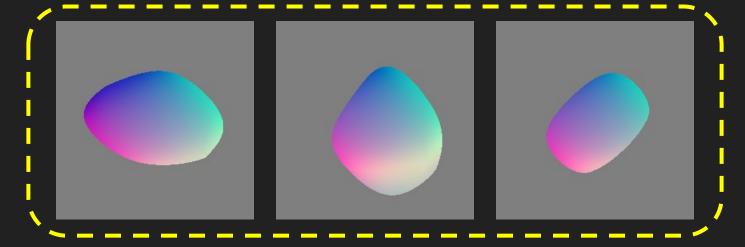


Scene + occlusions Scene Occlusions
$$P_{Y}(y) = P_{Y_S,Y_O}(y_S,y_O) = P_{Y_S}(y_S) P_{Y_O}(y_O)$$

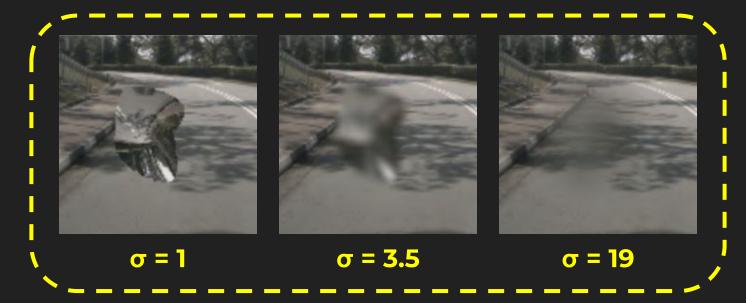




Displacement maps



Defocus blur effects



Dashcam - 1

Disentangled



Target





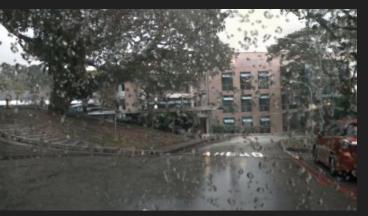
MUNIT [1]







 \tilde{w}



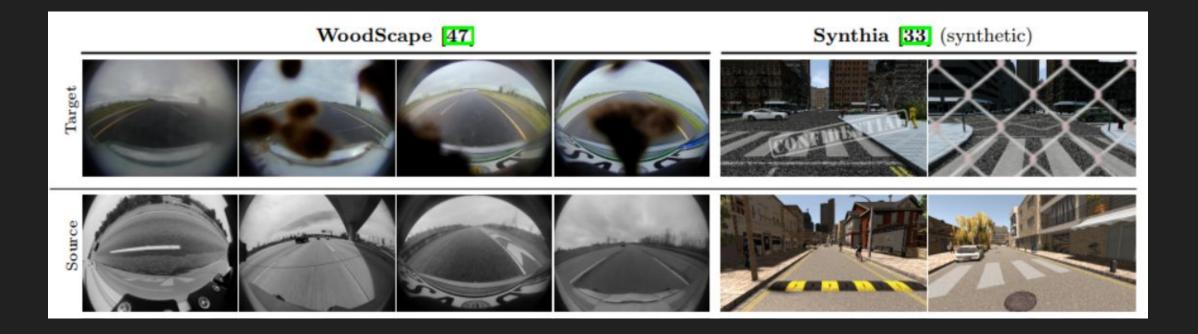
		Method	IS	LPIPS	CIS
		CycleGAN [2]	1.151	0.473	-
Unimodal	4	AttentionGAN [3]	1.406	0.464	-
	l	U-GAT-IT [4]	1.038	0.489	-
Multimodal		DRIT [5]	1.189	0.492	1.120
		MUNIT [1]	1.211	0.495	1.030
		Ours - Target	1.532	0.515	1.148

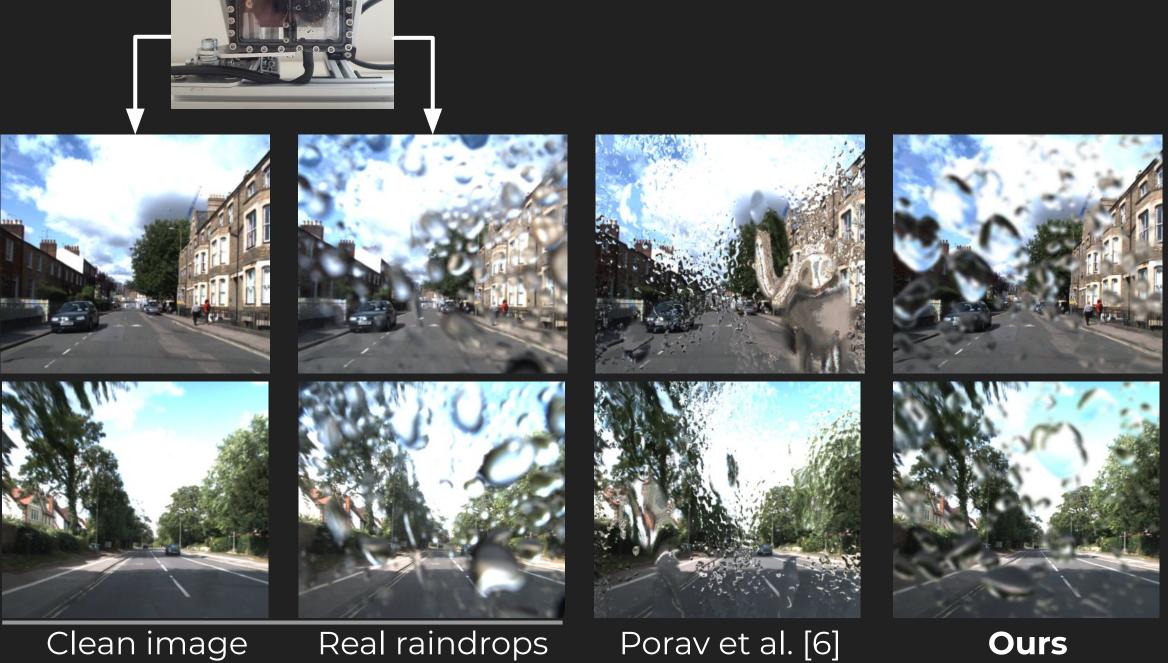
^[1] X Huang et al., ECCV 2018

^[2] JY Zhu et al., ICCV 2017

^[3] H Tang et al., IJCNN 2019

^[4] J Kim et al., ICLR 2020 [5] HY Lee et al., IJCV 2019





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Thanks for your attention!

Questions?

Using disentanglement to improve semantics

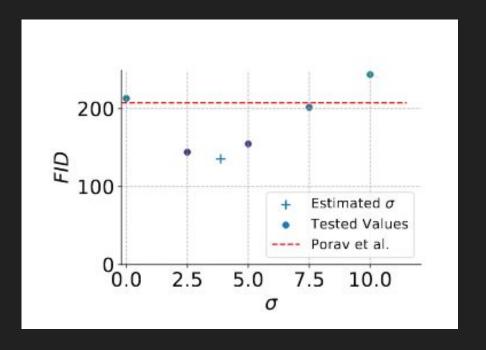
Method	$\mathbf{AP}\uparrow$
Original (from [11])	18.7
Finetuned w/ Halder $et \ al. \ \ \boxed{11}$	25.6
Finetuned w/ Ours target	27.7

Ablation study - drops model complexity

Model	$ $ IS \uparrow	LPIPS ↑	CIS↑
MUNIT (baseline) [1]	1.211	0.495	1.030
Ours - Normal	1.351	0.513	1.125
Ours - Refraction	1.459	0.496	1.123
Ours	1.532	0.515	1.148

Validity of our physical parameter estimation

Method	$\mathbf{FID}\downarrow$	LPIPS↓
Porav et al. [28]	207.34	0.533
Ours target	135.32	0.438



Ablation study - disentanglement guidance

