

Week 3 : Noise setting :  $Y = X\theta + w$   
 $\uparrow$   
 Noise

Last week:  $\min \| \theta \|_1$ , such that  $Y = X\theta$   
 Basis pursuit program  $\Downarrow$   
 $\begin{matrix} \uparrow & & \uparrow \\ \mathbb{R}^n & & \mathbb{R}^{n \times d} \end{matrix}$

This week :  $\min \| \theta \|, \quad \text{s.t.} \quad \frac{1}{2n} \| Y - X \theta \|_2^2 \leq b^2$

$$\frac{1}{n} \sum_{i=1}^n (y_i - x_i^T \theta)^2 \leq b^2$$

$$\textcircled{1} \quad \min \| \theta \|_1, \quad \text{s.t.} \quad \frac{1}{2n} \| Y - X \theta \|_2^2 \leq b^2$$

$$\textcircled{2} \quad \min \frac{1}{2n} \|Y - X\theta\|_2^2 \quad \text{s.t.} \quad \|\theta\|_1 \leq R$$

③  $\min_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{2n} \|Y - X\theta\|_2^2 + \lambda_n \|\theta\|_1 \right\}$  Ex.  $\lambda_n = \frac{1}{n}$

Core question:  $\textcircled{1} \overset{?}{\iff} \textcircled{2} \overset{?}{\iff} \textcircled{3}$

We show:  $\textcircled{1} \iff \textcircled{3}$  and  $\textcircled{2} \iff \textcircled{3}$

# Lagrange Method — Convex program.



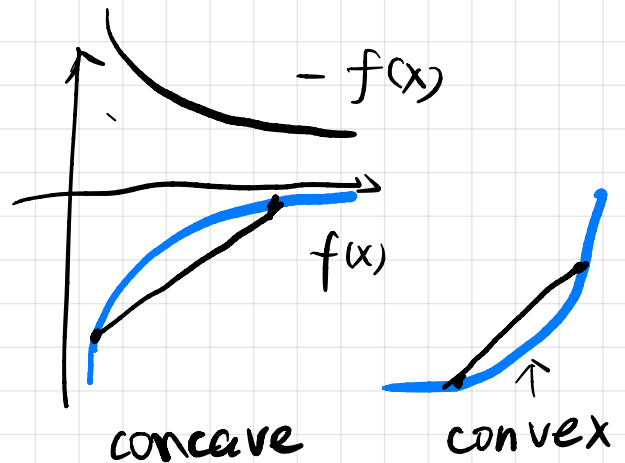
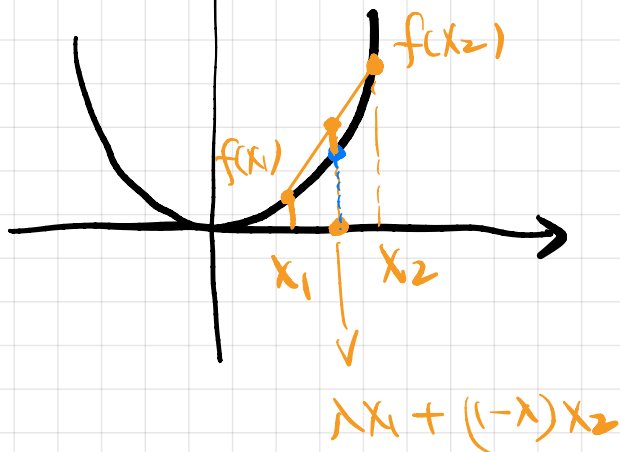
functions are convex

domain : convex set.

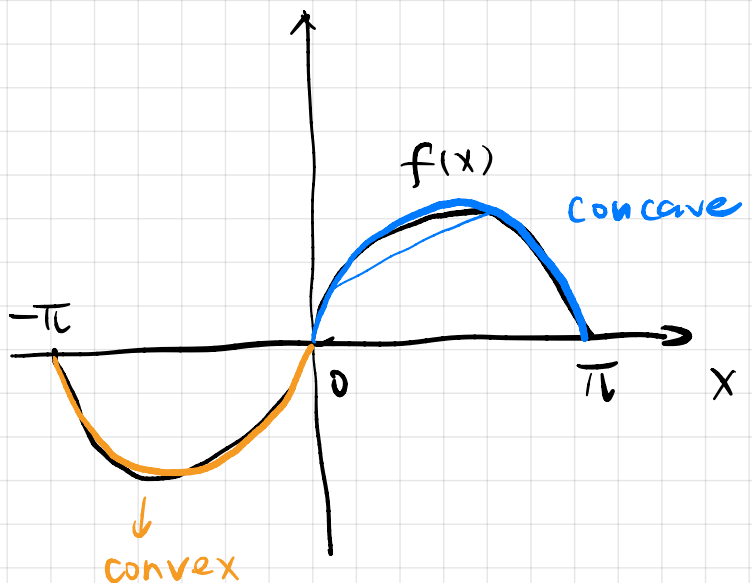
$f: \mathbb{R} \rightarrow \mathbb{R}$  : convex is defined as, for  $\lambda \in (0,1)$

$$f(\lambda x_1 + (1-\lambda)x_2) \leq \lambda f(x_1) + (1-\lambda)f(x_2)$$

Ex:  $f(x) = x^2$



Ex:  $f(x) = \sin x$



$$f: \mathbb{R}^d \rightarrow \mathbb{R}$$

$$f(\lambda x_1 + (1-\lambda)x_2) \leq \lambda f(x_1) + (1-\lambda)f(x_2)$$

$$\nabla \nabla f(x) \succ 0$$

$$\Leftrightarrow \left[ \frac{\partial^2 f(x)}{\partial x_i \partial x_j} \right]_{i,j \in \{1, \dots, d\}} \text{ is semi-positive definite (SPD)}$$

A matrix  $\Lambda \in \mathbb{R}^{d \times d}$  is SPD if for any  $x, y \in \mathbb{R}^d$

$$\underline{x^T \Lambda y \geq 0}$$

Convex optimization:  $\min_x \underline{f_0(x)}$  s.t.  $\begin{cases} f_i(x) \leq 0, i \in [m] \\ h_i(x) = 0, i \in [n] \end{cases}$

$f_i \sim \text{convex}$ ,  $h_i(x) \sim \text{affine}$ :  $\underline{h_i(x) = \sum_{j=1}^d a_{ij} x_j}$

Lagrangian function:

$$\mathcal{L}(x, \lambda, v) := \underline{f_0(x)} + \lambda^T f(x) + v^T h(x)$$

$$\mathcal{L}(x, \lambda, v) := \underbrace{f_0(x)}_{\leq 0} + \lambda^T \underbrace{f(x)}_{\leq 0} + v^T \underbrace{h(x)}_{=0}$$

$$\underline{g(\lambda, v) = \min_x \mathcal{L}(x, \lambda, v)}$$

$$\underline{d^* = \max_{\lambda \geq 0, v} g(\lambda, v)}$$

Question:

$$\boxed{\max_{\lambda \geq 0, v} \min_x \mathcal{L}(x, \lambda, v)} \quad \stackrel{||}{=} \quad d^* \quad \stackrel{?}{=} \quad \min_{\substack{f_0(x) \\ \text{(primal)}}} \text{ s.t. } \begin{cases} h(x) = 0 \\ f(x) \leq 0 \end{cases} \quad \stackrel{||}{=} \quad p^*$$

3.1  
Theorem: If a feasible solution for (primal) exists,  
then  $d^* = p^*$ .

$$\begin{aligned} \text{(dual)} \quad \max_{\lambda \geq 0, v} \min_x \mathcal{L}(x, \lambda, v) \\ = f_0(x) + \lambda^T f(x) + v^T h(x) \end{aligned}$$

(dual)  $\max_{\lambda > 0, v} \min_x \mathcal{L}(x, \lambda, v)$

$$= f_0(x) + \lambda^T f(x) + v^T h(x)$$

(Theorem 3.2) If  $\mathcal{L}$  is convex w.r.t.  $x$   
and  $\mathcal{L}$  is concave w.r.t.  $y$

and feasible set is not zero. then (dual) is  
equivalent to

$$\min_x \max_{\lambda > 0, v} \mathcal{L}(x, \lambda, v)$$


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①  $\min \|\theta\|_1 \quad \text{s.t.} \quad \frac{1}{2n} \|Y - X\theta\|_2^2 \leq b^2$

②  $\min \frac{1}{2n} \|Y - X\theta\|_2^2 \quad \text{s.t.} \quad \|\theta\|_1 \leq R$

③  $\min_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{2n} \|Y - X\theta\|_2^2 + \lambda_n \|\theta\|_1 \right\} \quad \text{Ex. } \lambda_n = \frac{1}{n}$

$$\textcircled{1} \quad \min \|\theta\|_1 \quad \text{s.t.} \quad \frac{1}{2n} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2 \leq b^2 \quad (\text{primal})$$

$$\mathcal{L}(\theta, \lambda) = \|\theta\|_1 + \lambda \left( \frac{1}{2n} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2 - b^2 \right)$$

$$(\text{dual}): \max_{\lambda > 0} \min_{\theta \in \mathbb{R}^d} \mathcal{L}(\theta, \lambda)$$

Theorem 3.1 : (primal)  $\Leftrightarrow$  (dual)

$$\text{Theorem 3.2 : } (\text{dual}) \Leftrightarrow \min_{\theta \in \mathbb{R}^d} \max_{\lambda > 0} \mathcal{L}(\theta, \lambda)$$

$$\Leftrightarrow \min_{\theta \in \mathbb{R}^d} \max_{\lambda > 0} \|\theta\|_1 + \lambda \cdot \underbrace{\frac{1}{2n} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2}_{\text{MSE}} - \lambda b^2$$

$$\Leftrightarrow \min_{\theta \in \mathbb{R}^d} \|\theta\|_1 + \underbrace{\lambda^* \cdot \frac{1}{2n} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2}_{\text{MSE}} - \underbrace{\lambda^* b^2}_{\text{constant}}$$

$\lambda^*$   
 $\parallel$   
constant

$$\Leftrightarrow \min_{\theta \in \mathbb{R}^d} \underbrace{\frac{1}{\lambda^*} \|\theta\|_1}_{\text{punishment}} + \underbrace{\frac{1}{2n} \|\mathbf{Y} - \mathbf{X}\theta\|_2^2}_{\text{MSE}}$$

$$\tilde{\phi}(y) = \min_{x \in \mathcal{X}} \phi(x, y) = \phi(x^*, y) \quad y^* = \arg \max_{y \in \mathcal{Y}} \phi(x^*, y)$$