

SenseBERT: Driving Some Sense into BERT

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Abstract

The ability to learn from large unlabeled corpora has allowed neural language models to advance the frontier in natural language understanding. However, existing self-supervision techniques operate at the word *form* level, which serves as a surrogate for the underlying semantic content. This paper proposes a method to employ weak-supervision directly at the word *sense* level. Our model, named SenseBERT, is pre-trained to predict not only the masked words but also their WordNet supersenses. Accordingly, we attain a lexical-semantic level language model, without the use of human annotation. SenseBERT achieves significantly improved lexical understanding, as we demonstrate by experimenting on SemEval Word Sense Disambiguation, and by attaining a state of the art result on the ‘Word in Context’ task.

1 Introduction

Neural language models have recently undergone a qualitative leap forward, pushing the state of the art on various NLP tasks. Together with advances in network architecture (Vaswani et al., 2017), the use of self-supervision has proven to be central to these achievements, as it allows the network to learn from massive amounts of unannotated text.

The self-supervision strategy employed in BERT (Devlin et al., 2019) involves masking some of the words in an input sentence, and then training the model to predict them given their context. Other proposed approaches for self-supervised objectives, including unidirectional (Radford et al., 2019), permutational (Yang et al., 2019), or word insertion-based (Chan et al., 2019) methods, operate similarly, over words. However, since a given word form can possess multiple meanings (e.g., the word ‘bass’ can refer to a fish, a guitar, a type of singer, etc.), the word itself is merely a surrogate of its

actual meaning in a given context, referred to as its *sense*. Indeed, the word-form level is viewed as a surface level which often introduces challenging ambiguity (Navigli, 2009).

In this paper, we bring forth a novel methodology for applying weak-supervision directly on the level of a word’s meaning. By infusing word-sense information into BERT’s pre-training signal, we explicitly expose the model to lexical semantics when learning from a large unannotated corpus. We call the resultant sense-informed model *SenseBERT*. Specifically, we add a masked-word sense prediction task as an auxiliary task in BERT’s pre-training. Thereby, jointly with the standard word-form level language model, we train a *semantic-level language model* that predicts the missing word’s meaning. Our method does not require sense-annotated data; self-supervised learning from unannotated text is facilitated by using WordNet (Miller, 1998), an expert constructed inventory of word senses, as weak supervision.

We focus on a coarse-grained variant of a word’s sense, referred to as its WordNet *supersense*, in order to mitigate an identified brittleness of fine-grained word-sense systems, caused by arbitrary sense granularity, blurriness, and general subjectiveness (Kilgarriff, 1997; Schneider, 2014). WordNet lexicographers organize all word senses into 45 supersense categories, 26 of which are for nouns, 15 for verbs, 3 for adjectives and 1 for adverbs (see full supersense table in the supplementary materials). Disambiguating a word’s supersense has been widely studied as a fundamental lexical categorization task (Ciaramita and Johnson, 2003; Basile, 2012; Schneider and Smith, 2015).

We employ the masked word’s allowed supersenses list from WordNet as a set of possible labels for the sense prediction task. The labeling of words with a single supersense (e.g., ‘sword’ has only the supersense noun.artifact) is straightforward: We

train the network to predict this supersense given the masked word’s context. As for words with multiple supersenses (*e.g.*, ‘bass’ can be: noun.food, noun.animal, noun.artifact, noun.person, *etc.*), we train the model to predict any of these senses, leading to a simple yet effective soft-labeling scheme.

We show that SenseBERT_{BASE} outcores both BERT_{BASE} and BERT_{LARGE} by a large margin on a supersense variant of the SemEval Word Sense Disambiguation (WSD) data set standardized in [Raganato et al. \(2017\)](#). Notably, SenseBERT receives competitive results on this task without fine-tuning, *i.e.*, when training a linear classifier over the pretrained embeddings, which serves as a testament for its self-acquisition of lexical semantics. Furthermore, we show that SenseBERT_{BASE} surpasses BERT_{LARGE} in the Word in Context (WiC) task ([Pilehvar and Camacho-Collados, 2019](#)) from the SuperGLUE benchmark ([Wang et al., 2019](#)), which directly depends on word-supersense awareness. A single SenseBERT_{LARGE} model achieves state of the art performance on WiC with a score of 72.14, improving the score of BERT_{LARGE} by 2.5 points.

2 Related Work

Neural network based word embeddings first appeared as a static mapping (non-contextualized), where every word is represented by a constant pretrained embedding ([Mikolov et al., 2013](#); [Pennington et al., 2014](#)). Such embeddings were shown to contain some amount of word-sense information ([Iacobacci et al., 2016](#); [Yuan et al., 2016](#); [Arora et al., 2018](#); [Le et al., 2018](#)). Additionally, sense embeddings computed for each word sense in the word-sense inventory (*e.g.* WordNet) have been employed, relying on hypernymy relations ([Rothe and Schütze, 2015](#)) or the gloss for each sense ([Chen et al., 2014](#)). These approaches rely on static word embeddings and require a large amount of annotated data per word sense.

The introduction of contextualized word embeddings ([Peters et al., 2018](#)), for which a given word’s embedding is context-dependent rather than pre-computed, has brought forth a promising prospect for sense-aware word embeddings. Indeed, visualizations in [Reif et al. \(2019\)](#) show that sense sensitive clusters form in BERT’s word embedding space. Nevertheless, we identify a clear gap in this ability. We show that a vanilla BERT model trained with the current word-level self-supervision,

burdened with the implicit task of disambiguating word meanings, often fails to grasp lexical semantics, exhibiting high supersense misclassification rates. Our suggested weakly-supervised word-sense signal allows SenseBERT to significantly bridge this gap.

Moreover, SenseBERT exhibits an improvement in lexical semantics ability (reflected by the Word in Context task score) even when compared to models with WordNet infused linguistic knowledge. Specifically we compare to [Peters et al. \(2019\)](#) who re-contextualize word embeddings via a word-to-entity attention mechanism (where entities are WordNet lemmas and synsets), and to [Loureiro and Jorge \(2019\)](#) which construct sense embeddings from BERT’s word embeddings and use the WordNet graph to enhance coverage (see quantitative comparison in table 3).

3 Incorporating Word-Supersense Information in Pre-training

In this section, we present our proposed method for integrating word sense-information within SenseBERT’s pre-training. We start by describing the vanilla BERT architecture in subsection 3.1. We conceptually divide it into an internal transformer encoder and an external mapping W which translates the observed vocabulary space into and out of the transformer encoder space [see illustration in figure 1(a)].

In the subsequent subsections, we frame our contribution to the vanilla BERT architecture as an addition of a parallel external mapping to the words supersenses space, denoted S [see illustration in figure 1(b)]. Specifically, in section 3.2 we describe the loss function used for learning S in parallel to W , effectively implementing word-form and word-sense multi-task learning in the pre-training stage. Then, in section 3.3 we describe our methodology for adding supersense information in S to the initial Transformer embedding, in parallel to word-level information added by W . In section 3.4 we address the issue of supersense prediction for out-of-vocabulary words, and in section 3.5 we describe our modification of BERT’s masking strategy, prioritizing single-supersensed words which carry a clearer semantic signal.

3.1 Background

The input to BERT is a sequence of words $\{x^{(j)} \in \{0, 1\}^{D_w}\}_{j=1}^N$ where 15% of the words are re-

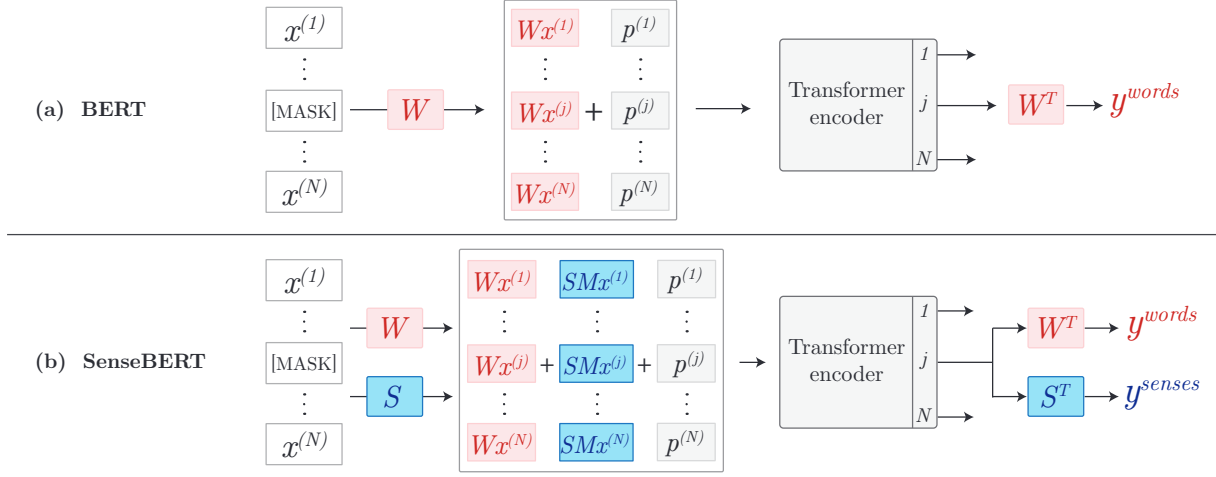


Figure 1: SenseBERT includes a masked-word supersense prediction task, pre-trained jointly with BERT’s original masked-word prediction task (Devlin et al., 2019) (see section 3.2). As in the original BERT, the mapping from the Transformer dimension to the external dimension is the same both at input and at output (W for words and S for supersenses), where M denotes a fixed mapping between word-forms and their allowed WordNet supersenses (see section 3.3). The vectors $p^{(j)}$ denote positional embeddings. For clarity, we omit a reference to a sentence-level Next Sentence Prediction task trained jointly with the above.

placed by a [MASK] token (see treatment of sub-word tokenization in section 3.4). Here N is the input sentence length, D_W is the word vocabulary size, and $x^{(j)}$ is a 1-hot vector corresponding to the j^{th} input word. For every masked word, the output of the pretraining task is a word-score vector $y^{\text{words}} \in \mathbb{R}^{D_W}$ containing the per-word score. BERT’s architecture can be decomposed to (1) an internal Transformer encoder architecture (Vaswani et al., 2017) wrapped by (2) an external mapping to the word vocabulary space, denoted by W .¹

The Transformer encoder operates over a sequence of word embeddings $v_{\text{input}}^{(j)} \in \mathbb{R}^d$, where d is the Transformer encoder’s hidden dimension. These are passed through multiple attention-based Transformer layers, producing a new sequence of contextualized embeddings at each layer. The Transformer encoder output is the final sequence of contextualized word embeddings $v_{\text{output}}^{(j)} \in \mathbb{R}^d$.

The external mapping $W \in \mathbb{R}^{d \times D_W}$ is effectively a translation between the external word vocabulary dimension and the internal Transformer dimension. Original words in the input sentence are translated into the Transformer block by applying this mapping (and adding positional encoding vectors $p^{(j)} \in \mathbb{R}^d$):

$$v_{\text{input}}^{(j)} = Wx^{(j)} + p^{(j)} \quad (1)$$

¹For clarity, we omit a description of the Next Sentence Prediction task which we employ as in Devlin et al. (2019).

The word-score vector for a masked word at position j is extracted from the Transformer encoder output by applying the transpose: $y^{\text{words}} = W^T v_{\text{output}}^{(j)}$ [see illustration in figure 1(a)]. The use of the same matrix W as the mapping in and out of the transformer encoder space is referred to as *weight tying* (Inan et al., 2017; Press and Wolf, 2017).

Given a masked word in position j , BERT’s original masked-word prediction pre-training task is to have the softmax of the word-score vector $y^{\text{words}} = W^T v_{\text{output}}^{(j)}$ get as close as possible to a 1-hot vector corresponding to the masked word. This is done by minimizing the cross-entropy loss between the softmax of the word-score vector and a 1-hot vector corresponding to the masked word:

$$\mathcal{L}_{\text{LM}} = -\log p(w|\text{context}), \quad (2)$$

where w is the masked word, the context is composed of the rest of the input sequence, and the probability is computed by:

$$p(w|\text{context}) = \frac{\exp(y_w^{\text{words}})}{\sum_{w'} \exp(y_{w'}^{\text{words}})}, \quad (3)$$

where y_w^{words} denotes the w^{th} entry of the word-score vector.

3.2 Weakly-Supervised Supersense Prediction Task

Jointly with the above procedure for training the word-level language model of SenseBERT, we train the model to predict the supersense of every masked word, thereby training a semantic-level language model. This is done by adding a parallel external mapping to the words supersenses space, denoted $S \in \mathbb{R}^{d \times D_S}$ [see illustration in figure 1(b)], where $D_S = 45$ is the size of supersenses vocabulary. Ideally, the objective is to have the softmax of the sense-score vector $y^{\text{senses}} \in \mathbb{R}^{D_S} := S^\top v_{\text{output}}^{(j)}$ get as close as possible to a 1-hot vector corresponding to the word’s supersense in the given context.

For each word w in our vocabulary, we employ the WordNet word-sense inventory for constructing $A(w)$, the set of its “allowed” supersenses. Specifically, we apply a WordNet Lemmatizer on w , extract the different synsets that are mapped to the lemmatized word in WordNet, and define $A(w)$ as the union of supersenses coupled to each of these synsets. As exceptions, we set $A(w) = \emptyset$ for the following: (i) short words (up to 3 characters), since they are often treated as abbreviations, (ii) stop words, as WordNet does not contain their main synset (e.g. ‘he’ is either the element helium or the hebrew language according to WordNet), and (iii) tokens that represent part-of-word (see section 3.4 for further discussion on these tokens).

Given the above construction, we employ a combination of two loss terms for the supersense-level language model. The following *allowed-senses term* maximizes the probability that the predicted sense is in the set of allowed supersenses of the masked word w :

$$\begin{aligned} \mathcal{L}_{\text{SLM}}^{\text{allowed}} &= -\log p(s \in A(w) | \text{context}) \\ &= -\log \sum_{s \in A(w)} p(s | \text{context}), \end{aligned} \quad (4)$$

where the probability for a supersense s is given by:

$$p(s | \text{context}) = \frac{\exp(y_s^{\text{senses}})}{\sum_{s'} \exp(y_{s'}^{\text{senses}})}. \quad (5)$$

The soft-labeling scheme given above, which treats all the allowed supersenses of the masked word equally, introduces noise to the supersense labels. We expect that encountering many contexts in a sufficiently large corpus will reinforce the correct labels whereas the signal of incorrect labels will diminish. To illustrate this, consider the following examples for the food context:

1. “This **bass** is delicious”
(supersenses: noun.food, noun.artifact, *etc.*)
2. “This **chocolate** is delicious”
(supersenses: noun.food, noun.attribute, *etc.*)
3. “This **pickle** is delicious”
(supersenses: noun.food, noun.state, *etc.*)

Masking the marked word in each of the examples results in three identical input sequences, each with a different sets of labels. The ground truth label, noun.food, appears in all cases, so that its probability in contexts indicating food is increased whereas the signals supporting other labels cancel out.

While $\mathcal{L}_{\text{SLM}}^{\text{allowed}}$ pushes the network in the right direction, minimizing this loss could result in the network becoming overconfident in predicting a strict subset of the allowed senses for a given word, i.e., a collapse of the prediction distribution. This is especially acute in the early stages of the training procedure, when the network could converge to the noisy signal of the soft-labeling scheme.

To mitigate this issue, the following *regularization term* is added to the loss, which encourages a uniform prediction distribution over the allowed supersenses:

$$\mathcal{L}_{\text{SLM}}^{\text{reg}} = - \sum_{s \in A(w)} \frac{1}{|A(w)|} \log p(s | \text{context}), \quad (6)$$

i.e., a cross-entropy loss with a uniform distribution over the allowed supersenses.

Overall, jointly with the regular word level language model trained with the loss in eq. 2, we train the semantic level language model with a combined loss of the form:

$$\mathcal{L}_{\text{SLM}} = \mathcal{L}_{\text{SLM}}^{\text{allowed}} + \mathcal{L}_{\text{SLM}}^{\text{reg}}. \quad (7)$$

3.3 Supersense Aware Input Embeddings

Though in principle two different matrices could have been used for converting in and out of the Tranformer encoder, the BERT architecture employs the same mapping W . This approach, referred to as weight tying, was shown to yield theoretical and practical benefits (Inan et al., 2017; Press and Wolf, 2017). Intuitively, constructing the Transformer encoder’s input embeddings from the same mapping with which the scores are computed improves their quality as it makes the input more sensitive to the training signal.

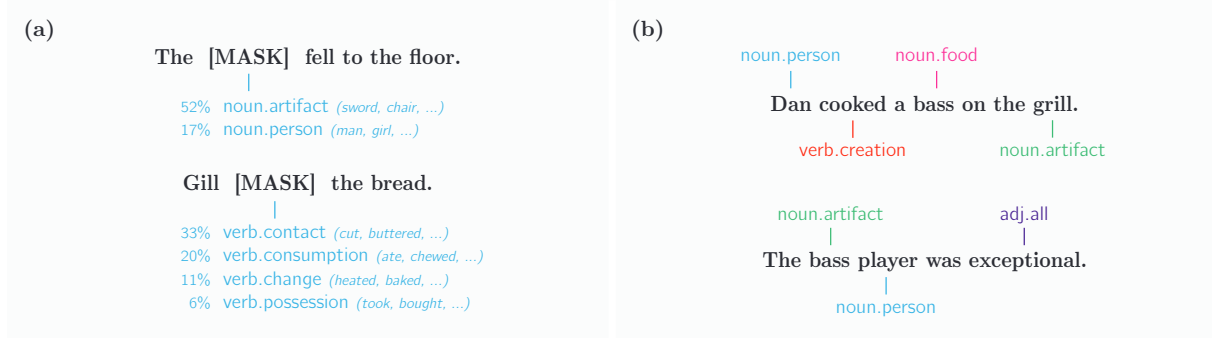


Figure 3: **(a)** A demonstration of supersense probabilities assigned to a masked position within context, as given by SenseBERT’s word-supersense level semantic language model (capped at 5%). Example words corresponding to each supersense are presented in parentheses. **(b)** Examples of SenseBERT’s prediction on raw text, when the unmasked input sentence is given to the model. This beyond word-form abstraction ability facilitates a more natural elicitation of semantic content at pre-training.

vocabulary and employ a whole-word-masking strategy. Accordingly, all of the tokens of a tokenized OOV word are masked together. In this case, we train the supersense prediction task to predict the WordNet supersenses of this word from the *average* of the output embeddings at the location of the masked sub-words tokens.

3.5 Single-Supersensed Word Masking

Words that have a single supersense are good anchors for obtaining an unambiguous semantic signal. These words teach the model to accurately map contexts to supersenses, such that it is then able to make correct context-based predictions even when a masked word has several supersenses. We therefore favor such words in the masking strategy, choosing 50% of the single-supersensed words in each input sequence to be masked. We stop if 40% of the overall 15% masking budget is filled with single-supersensed words (this rarely happens), and in any case we randomize the choice of the remaining words to complete this budget. As in the original BERT, 1 out of 10 words chosen for masking is shown to the model as itself rather than replaced with [MASK].

4 Semantic Language Model Visualization

A SenseBERT pretrained as described in section 3 (with training hyperparameters as in Devlin et al. (2019)), has an immediate non-trivial bi-product. The pre-trained mapping to the supersenses space, denoted S , acts as an additional head predicting a word’s supersense given context [see figure 1(b)]. We thereby effectively attain a semantic-level lan-

| SenseBERT _{BASE} | SemEval-SS Fine-tuned |
|---------------------------|-----------------------|
| 30K no OOV | 81.9 |
| 30K average OOV | 82.7 |
| 60K no OOV | 83 |

Table 1: Testing variants for predicting supersenses of rare words during SenseBERT’s pretraining, as described in section 5.1. Results are reported on the SemEval-SS task (see section 5.2). 30K/60K stand for vocabulary size, and no/average OOV stand for not predicting senses for OOV words or predicting senses from the average of the sub-word token embeddings, respectively.

guage model that predicts the missing word’s meaning jointly with the standard word-form level language model.

We illustrate the resultant mapping in figure 2, showing a UMAP dimensionality reduction (McInnes et al., 2018) of the rows of S , which corresponds to the different supersenses. A clear clustering according to the supersense part-of-speech is apparent in figure 2(a). We further identify finer-grained semantic clusters, as shown for example in figure 2(b) and given in more detail in the supplementary materials.

SenseBERT’s semantic language model allows predicting a distribution over supersenses rather than over words in a masked position. Figure 3(a) shows the supersense probabilities assigned by SenseBERT in several contexts, demonstrating the model’s ability to assign semantically meaningful categories to the masked position.

Finally, we demonstrate that SenseBERT enjoys

| | | BERT | SenseBERT |
|-------------------|---|----------------------|-------------------|
| (a) SemEval-SS | The team used a <u>battery</u> of the newly developed “gene probes” | <i>noun.artifact</i> | <i>noun.group</i> |
| | Ten shirt-sleeved ringers stand in a circle, one <u>foot</u> ahead of the other in a prize-fighter's stance | <i>noun.quantity</i> | <i>noun.body</i> |
| (b) WiC | Sent. A: The <u>kick</u> must be synchronized with the arm movements. | <i>Same</i> | <i>Different</i> |
| | Sent. B: A sidecar is a smooth drink but it has a powerful <u>kick</u> . | | |
| | Sent. A: <u>Plant</u> bugs in the dissident's apartment. | <i>Different</i> | <i>Same</i> |
| | Sent. B: <u>Plant</u> a spy in Moscow. | | |

Figure 4: Example entries of (a) the SemEval-SS task, where a model is to predict the supersense of the marked word, and (b) the Word in Context (WiC) task where a model must determine whether the underlined word is used in the same/different supersense within sentences A and B. In all displayed examples, taken from the corresponding development sets, SenseBERT predicted the correct label while BERT failed to do so. A quantitative comparison between models is presented in table 2.

an ability to view raw text at a lexical semantic level. Figure 3(b) shows example sentences and their supersense prediction by the pretrained model. Where a vanilla BERT would see only the words of the sentence “Dan cooked a bass on the grill”, SenseBERT would also have access to the supersense abstraction: “[Person] [created] [food] on the [artifact]”. This sense-level perspective can help the model extract more knowledge from every training example, and to generalize semantically similar notions which do not share the same phrasing.

5 Lexical Semantics Experiments

In this section, we present quantitative evaluations of SenseBERT, pre-trained as described in section 3. We test the model’s performance on a supersense-based variant of the SemEval WSD test sets standardized in Raganato et al. (2017), and on the Word in Context (WiC) task (Pilehvar and Camacho-Collados, 2019) (included in the recently introduced SuperGLUE benchmark (Wang et al., 2019)), both directly relying on the network’s ability to perform lexical semantic categorization.

5.1 Comparing Rare Words Supersense Prediction Methods

We first report a comparison of the two methods described in section 3.4 for predicting the supersenses of rare words which do not appear in BERT’s original vocabulary. The first 60K vocabulary method enriches the vocabulary and the second average embedding method predicts a supersense from the average embeddings of the sub-word tokens com-

prising an OOV word. During fine-tuning, when encountering an OOV word we predict the supersenses from the rightmost sub-word token in the 60K vocabulary method and from the average of the sub-word tokens in the average embedding method.

As shown in table 1, both methods perform comparably on the SemEval supersense disambiguation task (see following subsection), yielding an improvement over the baseline of learning supersense information only for whole words in BERT’s original 30K-token vocabulary. We continue with the 60K-token vocabulary for the rest of the experiments, but note the average embedding option as a viable competitor for predicting word-level semantics.

5.2 SemEval-SS: Supersense Disambiguation

We test SenseBERT on a Word Supersense Disambiguation task, a coarse grained variant of the common WSD task. We use SemCor (Miller et al., 1993) as our training dataset (226, 036 annotated examples), and the SenseEval (Edmonds and Cotton, 2001; Snyder and Palmer, 2004) / SemEval (Pradhan et al., 2007; Navigli et al., 2013; Moro and Navigli, 2015) suite for evaluation (overall 7253 annotated examples), following Raganato et al. (2017). For each word in both training and test sets, we change its fine-grained sense label to its corresponding WordNet supersense, and therefore train the network to predict a given word’s supersense. We name this Supersense disambiguation task SemEval-SS. See figure 4(a) for an example

| | SemEval-SS Frozen | SemEval-SS Fine-tuned | Word in Context |
|----------------------------|-------------------|-----------------------|-----------------|
| BERT _{BASE} | 65.1 | 79.2 | — |
| BERT _{LARGE} | 67.3 | 81.1 | 69.6 |
| SenseBERT _{BASE} | 75.6 | 83.0 | 70.3 |
| SenseBERT _{LARGE} | 79.5 | 83.7 | 72.1 |

Table 2: Results on a supsense variant of the SemEval WSD test set standardized in Raganato et al. (2017), which we denote SemEval-SS, and on the Word in Context (WiC) dataset (Pilehvar and Camacho-Collados, 2019) included in the recently introduced SuperGLUE benchmark (Wang et al., 2019). These tasks require a high level of lexical semantic understanding, as can be seen in the examples in figure 4. For both tasks, SenseBERT demonstrates a clear improvement over BERT in the regular fine-tuning setup, where network weights are modified during training on the task. Notably, SenseBERT_{LARGE} achieves state of the art performance on the WiC task. In the SemEval-SS Frozen setting, we train a linear classifier over pretrained embeddings, without changing the network weights. The results show that SenseBERT introduces a dramatic improvement in this setting, implying that its word-sense aware pre-training (section 3) yields embeddings that carries lexical semantic information which is easily extractable for the benefits of downstream tasks. Results for BERT on the SemEval-SS task are attained by employing the published pre-trained BERT models, and the BERT_{LARGE} result on WiC is taken from the baseline scores published on the SuperGLUE benchmark (Wang et al., 2019) (no result has been published for BERT_{BASE}).

| | Word in Context |
|-------------------------------------|-----------------|
| ELMo [†] | 57.7 |
| BERT sense embeddings ^{††} | 67.7 |
| BERT _{LARGE} [‡] | 69.6 |
| RoBERTa ^{‡‡} | 69.9 |
| KnowBERT-W+W [◊] | 70.9 |
| SenseBERT | 72.1 |

Table 3: Test set results for the WiC dataset.

[†]Pilehvar and Camacho-Collados (2019)

^{††}Loureiro and Jorge (2019)

[‡]Wang et al. (2019)

^{‡‡}Liu et al. (2019)

[◊]Peters et al. (2019)

from this modified data set.

We show results on the SemEval-SS task for two different training schemes. In the first, we trained a linear classifier over the ‘frozen’ output embeddings of the examined model – we do not change the the trained SenseBERT’s parameters in this scheme. This Frozen setting is a test for the amount of basic lexical semantics readily present in the pre-trained model, easily extricable by further downstream tasks (reminiscent of the semantic probes employed in Hewitt and Manning (2019); Reif et al. (2019)).

In the second training scheme we fine-tuned the examined model on the task, allowing its parameters to change during training (see full training details in the supplementary materials). Results attained by employing this training method reflect

the model’s potential to acquire word-supersense information given its pre-training.

Table 2 shows a comparison between vanilla BERT and SenseBERT on the supsense disambiguation task. Our semantic level pre-training signal clearly yields embeddings with enhanced word-meaning awareness, relative to embeddings trained with BERT’s vanilla word-level signal. SenseBERT_{BASE} improves the score of BERT_{BASE} in the Frozen setting by over 10 points and SenseBERT_{LARGE} improves that of BERT_{LARGE} by over 12 points, demonstrating competitive results even without fine-tuning. In the setting of model fine-tuning, we see a clear demonstration of the model’s ability to learn word-level semantics, as SenseBERT_{BASE} surpasses the score of BERT_{LARGE} by 2 points.

5.3 Word in Context (WiC) Task

We test our model on the recently introduced WiC binary classification task. Each instance in WiC has a target word w for which two contexts are provided, each invoking a specific meaning of w . The task is to determine whether the occurrences of w in the two contexts share the same meaning or not, clearly requiring an ability to identify the word’s semantic category. The WiC task is defined over supersenses (Pilehvar and Camacho-Collados, 2019) – the negative examples include a word used in two different supersenses and the positive ones include a word used in the same supersense. See figure 4(b) for an example from this data set.

| | Score | CoLA | SST-2 | MRPC | STS-B | QQP | MNLI | QNLI | RTE |
|-----------------------------|-------|------|-------|-----------|-----------|-----------|------|------|------|
| BERT _{BASE} (OURS) | 77.5 | 50.1 | 92.6 | 88.7/84.3 | 85.7/84.6 | 71.0/88.9 | 83.6 | 89.4 | 67.9 |
| SenseBERT _{BASE} | 77.9 | 54.6 | 92.2 | 89.2/85.2 | 83.5/82.3 | 70.3/88.8 | 83.6 | 90.6 | 67.5 |

Table 4: Results on the GLUE benchmark test set.

Results on the WiC task comparing SenseBERT to vanilla BERT are shown in table 2. SenseBERT_{BASE} surpasses a larger vanilla model, BERT_{LARGE}. As shown in table 3, a single SenseBERT_{LARGE} model achieves the state of the art score in this task, demonstrating unprecedented lexical semantic awareness.

5.4 GLUE

The General Language Understanding Evaluation (GLUE; Wang et al. (2018)) benchmark is a popular testbed for language understanding models. It consists of 9 different NLP tasks, covering different linguistic phenomena. We evaluate our model on GLUE, in order to verify that SenseBERT gains its lexical semantic knowledge without compromising performance on other downstream tasks. Due to slight differences in the data used for pretraining BERT and SenseBERT (BookCorpus is not publicly available), we trained a BERT_{BASE} model with the same data used for our models. BERT_{BASE} and SenseBERT_{BASE} were both finetuned using the exact same procedures and hyperparameters. The results are presented in table 4. Indeed, SenseBERT performs on par with BERT, achieving an overall score of 77.9, compared to 77.5 achieved by BERT_{BASE}.

6 Conclusion

We introduce lexical semantic information into a neural language model’s pre-training objective. This results in a boosted word-level semantic awareness of the resultant model, named SenseBERT, which considerably outperforms a vanilla BERT on a SemEval based Supersense Disambiguation task and achieves state of the art results on the Word in Context task. This improvement was obtained without human annotation, but rather by harnessing an external linguistic knowledge source. Our work indicates that semantic signals extending beyond the lexical level can be similarly introduced at the pre-training stage, allowing the network to elicit further insight without human supervision.

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A Supersenses and Their Representation in SenseBERT

We present in table 5 a comprehensive list of WordNet supersenses, as they appear in the WordNet documentation. In fig. 5 we present a Dendrogram of an Agglomerative hierarchical clustering over the supersense embedding vectors learned by SenseBERT in pre-training. The clustering shows a clear separation between Noun senses and Verb senses. Furthermore, we can observe that semantically related supersenses are clustered together (i.e., noun.animal and noun.plant).

B Training Details

As hyperparameters for the fine-tuning, we used $max_seq_length = 128$, chose learning rates from $\{5e-6, 1e-5, 2e-5, 3e-5, 5e-5\}$, batch sizes from $\{16, 32\}$, and fine-tuned up to 10 epochs for all the datasets.

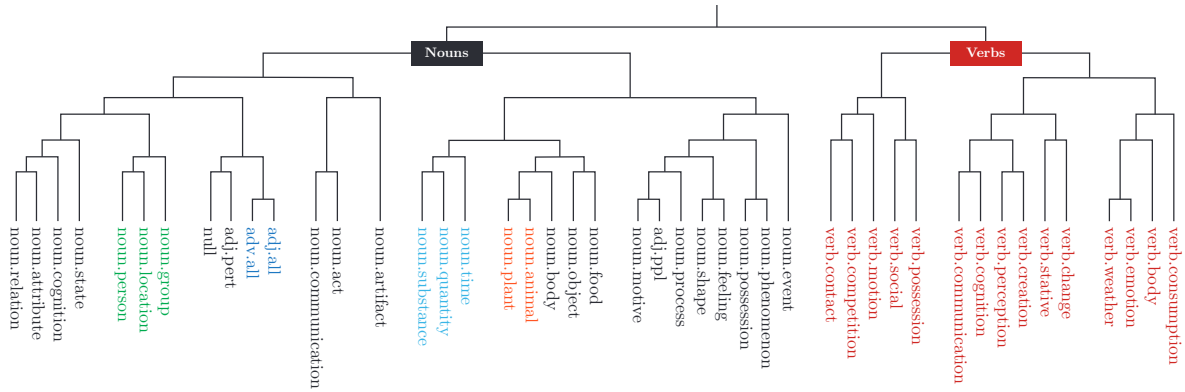


Figure 5: Dendrogram visualization of an Agglomerative hierarchical clustering over the supersense vectors (rows of the classifier S) learned by SenseBERT.

| Name | Content | Name | Content |
|--------------------|--|--------------------|--|
| adj.all | All adjective clusters | noun.quantity | Nouns denoting quantities and units of measure |
| adj.pert | Relational adjectives (pertainyms) | noun.relation | Nouns denoting relations between people or things or ideas |
| adv.all | All adverbs | noun.shape | Nouns denoting two and three dimensional shapes |
| noun.Tops | Unique beginner for nouns | noun.state | Nouns denoting stable states of affairs |
| noun.act | Nouns denoting acts or actions | noun.substance | Nouns denoting substances |
| noun.animal | Nouns denoting animals | noun.time | Nouns denoting time and temporal relations |
| noun.artifact | Nouns denoting man-made objects | verb.body | Verbs of grooming, dressing and bodily care |
| noun.attribute | Nouns denoting attributes of people and objects | verb.change | Verbs of size, temperature change, intensifying, etc. |
| noun.body | Nouns denoting body parts | verb.cognition | Verbs of thinking, judging, analyzing, doubting |
| noun.cognition | Nouns denoting cognitive processes and contents | verb.communication | Verbs of telling, asking, ordering, singing |
| noun.communication | Nouns denoting communicative processes and contents | verb.competition | Verbs of fighting, athletic activities |
| noun.event | Nouns denoting natural events | verb.consumption | Verbs of eating and drinking |
| noun.feeling | Nouns denoting feelings and emotions | verb.contact | Verbs of touching, hitting, tying, digging |
| noun.food | Nouns denoting foods and drinks | verb.creation | Verbs of sewing, baking, painting, performing |
| noun.group | Nouns denoting groupings of people or objects | verb.emotion | Verbs of feeling |
| noun.location | Nouns denoting spatial position | verb.motion | Verbs of walking, flying, swimming |
| noun.motive | Nouns denoting goals | verb.perception | Verbs of seeing, hearing, feeling |
| noun.object | Nouns denoting natural objects (not man-made) | verb.possession | Verbs of buying, selling, owning |
| noun.person | Nouns denoting people | verb.social | Verbs of political and social activities and events |
| noun.phenomenon | Nouns denoting natural phenomena | verb.stative | Verbs of being, having, spatial relations |
| noun.plant | Nouns denoting plants | verb.weather | Verbs of raining, snowing, thawing, thundering |
| noun.possession | Nouns denoting possession and transfer of possession | adj.ppl | Participial adjectives |
| noun.process | Nouns denoting natural processes | | |

Table 5: A list of supersense categories from WordNet lexicographer.