Kernel programming

Kernel has access to all resources Kernel programs not subject to any constraints for memory acces or hardware access

⇒ faulty kernel programs can cause system crash

Interaction between kernel and user programs

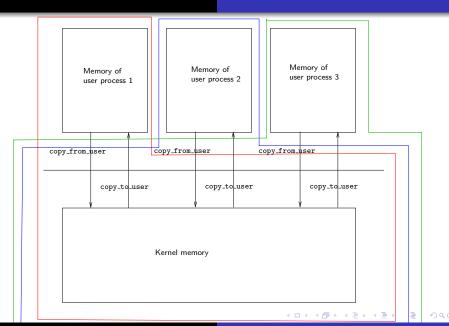
Kernel provides its functions only via special functions, called system calls

standard C-library provides them

Have strict separation of kernel data and data for user programs

 \Rightarrow need explicit copying between user program and kernel

Linux kernel programming



Structure of kernel

```
Simplified structure of kernel:
initialise data structures at boot time;
while (true) {
   while (timer not gone off) {
      assign CPU to suitable process;
      execute process;
   }
   select next suitable process;
}
```

Linux kernel programming

In addition, have interrupts:
kernel asks HW to perform certain action
HW sends interrupt to kernel which performs desired action
interrupts must be processed quickly

⇒ any code called from interrupts must not sleep

Linux kernel modes

Structure of kernel gives rise to two main modes for kernel code:

- process context: kernel code working for user programs by executing a system call
- interrupt context: kernel code handling an interrupt (eg by a device)

have access to user data only in process context

Any code running in process context may be pre-empted at any time by an interrupt

Interrupts have priority levels

Interrupt of lower priority are pre-empted by interrupts of higher priority



Kernel modules

can add code to running kernel
useful for providing device drivers which are required only if
hardware present
modprobe inserts module into running kernel
rmmod removes module from running kernel (if unused)
1smod lists currently running modules

Concurrency issues in the kernel

Correct handling concurrency in the kernel important: Manipulation of data structures which are shared between

- code running in process mode and code running in interrupt mode
- code running in interrupt mode

must happen only within critical regions In multi-processor system even manipulation of data structures shared between code running in process context must happen only within critical sections

Achieving mutual exclusion

Two ways:

- Semaphores: when entering critical section fails, current process is put to sleep until critical region is available
 ⇒ only usable if all critical regions are in process context
- Spinlocks: processor tries repeatedly to enter critical section Usable anywhere
 Disadvantage: Have busy waiting

Programming data transfer between userspace and kernel

Linux maintains a directory called proc as interface between user space and kernel

Files in this directory do not exist on disk

Read-and write-operations on these files translated into kernel operations, together with data transfer between user space and kernel

Useful mechanism for information exchange between kernel and user space

A tour of the Linux kernel

Major parts of the kernel:

- Device drivers: in the subdirectory drivers, sorted according to category
- file systems: in the subdirectory fs
- scheduling and process management: in the subdirectory kernel
- memory management: in the subdirectory mm
- networking code: in the subdirectory net
- architecture specific low-level code (including assembly code):
 in the subdirectory arch
- include-files: in the subdirectory include

