RG2 Center of mass

Mass properties of RG2 at 0° mounting

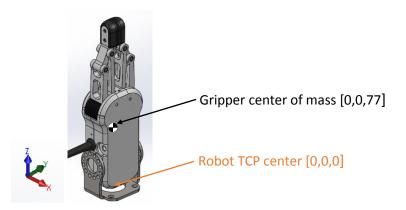
Mass = 0.65 Kg

Center of mass:

X = 0 mm

Y = 0 mm

Z = 77 mm



Mass properties of RG2 at 30° mounting

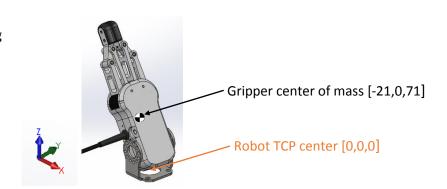
Mass = 0.65 Kg

Center of mass:

X = -21 mm

Y = 0 mm

Z = 71 mm



Mass properties of RG2 at 60° mounting

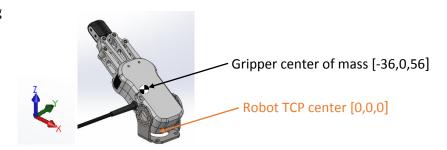
Mass = 0.65 Kg

Center of mass:

X = -36 mm

Y = 0 mm

Z = 56 mm



Mass properties of RG2 at 90° mounting

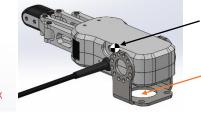
Mass = 0.65 Kg

Center of mass:

X = -41 mm

Y = 0 mm

Z = 36 mm



Gripper center of mass [-41,0,36]

Robot TCP center [0,0,0]