## Prob 5

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```
[]: from gurobipy import *
     # create a model
     m = Model()
     # create variables
     x1 = m.addVar(vtype=GRB.CONTINUOUS, name="x1", lb=0)
     x2 = m.addVar(vtype=GRB.CONTINUOUS, name="x2", 1b=0)
     x3 = m.addVar(vtype=GRB.CONTINUOUS, name="x3", 1b=0)
     x4 = m.addVar(vtype=GRB.CONTINUOUS, name="x4", 1b=0)
     x5 = m.addVar(vtype=GRB.CONTINUOUS, name="x5", 1b=0)
     x6 = m.addVar(vtype=GRB.CONTINUOUS, name="x6", 1b=0)
     x7 = m.addVar(vtype=GRB.CONTINUOUS, name="x7", lb=0)
     y1 = m.addVar(vtype=GRB.INTEGER, name="y1", 1b=0, ub=1)
     y2 = m.addVar(vtype=GRB.INTEGER, name="y2", 1b=0, ub=1)
     y3 = m.addVar(vtype=GRB.INTEGER, name="y3", lb=0, ub=1)
     y4 = m.addVar(vtype=GRB.INTEGER, name="y4", 1b=0, ub=1)
     y5 = m.addVar(vtype=GRB.INTEGER, name="y5", lb=0, ub=1)
     y6 = m.addVar(vtype=GRB.INTEGER, name="y6", lb=0, ub=1)
     y7 = m.addVar(vtype=GRB.INTEGER, name="y7", lb=0, ub=1)
     # integrate new variables
     m.update()
     # set objective
     m.setObjective(
         33*x1 + 30*x2 + 26*x3 + 24*x4 + 19*x5 + 18*x6 + 17*x7 + 1000*(y1 + y2 + y3_{1})
      \rightarrow + y4 + y5 + y6 + y7),
         GRB.MINIMIZE
     # add constraints
```

```
m.addConstr(x1 >= 400)
m.addConstr(x1 + x2 >= 700)
m.addConstr(x1 + x2 + x3 >= 1200)
m.addConstr(x1 + x2 + x3 + x4 >= 1900)
m.addConstr(x1 + x2 + x3 + x4 + x5 >= 2100)
m.addConstr(x1 + x2 + x3 + x4 + x5 + x6 >= 2500)
m.addConstr(x1 + x2 + x3 + x4 + x5 + x6 + x7 >= 2700)
m.addConstr(x1 <= 400*y1)</pre>
m.addConstr(x2 \ll 700*y2)
m.addConstr(x3 <= 1200*y3)</pre>
m.addConstr(x4 <= 1900*y4)
m.addConstr(x5 \le 2100*y5)
m.addConstr(x6 <= 2500*y6)
m.addConstr(x7 \le 2700*y7)
# optimize
m.optimize()
print("Model status: ", m.status)
# print out decision variables
for v in m.getVars():
    print(v.varName, v.x, "\n")
print("-"*15)
print("Obj Value: ", m.objVal)
```

```
Explored 1 nodes (14 simplex iterations) in 0.01 seconds
Thread count was 4 (of 4 available processors)
Solution count 3: 72200 72600 73400
Optimal solution found (tolerance 1.00e-04)
Best objective 7.220000000000e+04, best bound 7.22000000000e+04, gap 0.0000%
Model status: 2
x1 400.0
x2 300.0
x3 499.9999999999994
x4 700.00000000000001
x5 799.999999999999
x6 0.0
x7 0.0
y1 1.0
y2 1.0
v3 1.0
y4 1.0
y5 1.0
y6 0.0
y7 0.0
Obj Value: 72200.0
```