
poliastro Documentation

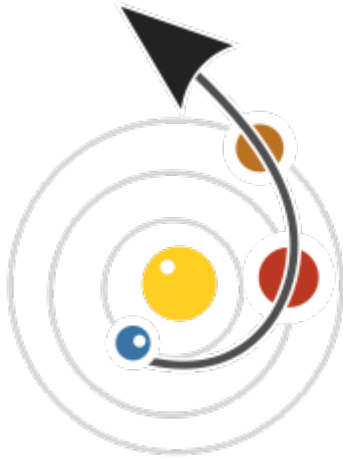
Release 0.7.dev0

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Nov 14, 2017

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poliastro

Astrodynamics in Python

poliastro is an open source (MIT) collection of Python functions useful in Astrodynamics and Orbital Mechanics, focusing on interplanetary applications. It provides a simple and intuitive API and handles physical quantities with units. Some of its awesome features are:

- Analytical and numerical orbit propagation
- Conversion between position and velocity vectors and classical orbital elements
- Coordinate frame transformations
- Hohmann and bielliptic maneuvers computation
- Trajectory plotting
- Initial orbit determination (Lambert problem)
- Planetary ephemerides (using SPICE kernels via Astropy)
- Computation of Near-Earth Objects (NEOs)

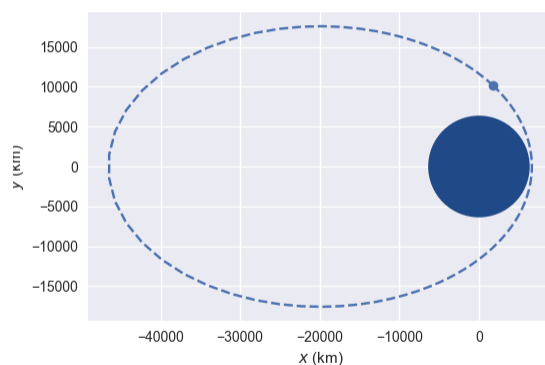
And more to come!

poliastro is developed by an open, international community. Release announcements and general discussion take place on our mailing list and chat.

The [source code](#), [issue tracker](#) and [wiki](#) are hosted on GitHub, and all contributions and feedback are more than welcome. You can test poliastro in your browser using binder, a cloud Jupyter notebook server: poliastro works on recent versions of Python and is released under the MIT license, hence allowing commercial use of the library.

```
from poliastro.examples import molniya
from poliastro.plotting import plot

plot(molniya)
```



CHAPTER 1

Success stories

“My team and I used Poliastro for our final project in our Summer App Space program. This module helped us in plotting asteroids by using the data provided to us. It was very challenging finding a module that can take orbits from the orbital elements, plot planets, and multiple ones. This module helped us because we were able to understand the code as most of us were beginners and make some changes the way we wanted our project to turn out. We made small changes such as taking out the axis and creating a function that will create animations. I am happy we used Poliastro because it helped us directs us in a direction where we were satisfied of our final product.”

—Nayeli Ju (2017)

“We are a group of students at University of Illinois at Urbana-Champaign, United States. We are currently working on a student AIAA/AAS satellite competition to design a satellite perform some science missions on asteroid (469219) 2016 HO3. We are using your poliastro python package in designing and visualizing the trajectory from GEO into asteroid’s orbit. Thank you for your work on poliastro, especially the APIs that are very clear and informational, which helps us significantly.”

—Yufeng Luo (University of Illinois at Urbana-Champaign, United States, 2017)

“We, at the Institute of Space and Planetary Astrophysics (ISPA, University of Karachi), are using Poliastro as part of Space Flight Dynamics Text Book development program. The idea is to develop a book suitable for undergrad students which will not only cover theoretical background but will also focus on some computational tools. We chose Poliastro as one of the packages because it was very well written and provided results with good accuracy. It is especially useful in covering some key topics like the Lambert’s problem. We support the use of Poliastro and open source software because they are easily accessible to students (without any charges, unlike some other tools). A great plus point for Poliastro is that it is Python based and Python is now becoming a very important tool in areas related to Space Sciences and Technologies.”

—Prof. Jawed iqbal, Syed Faisal ur Rahman (ISPA, University of Karachi, 2016)

2.1 About poliaastro

2.1.1 Overview

poliaastro is an open source collection of Python subroutines for solving problems in Astrodynamics and Orbital Mechanics.

poliaastro combines cutting edge technologies like Python JIT compiling (using numba) with young, well developed astronomy packages (like astropy and jplephem) to provide a user friendly API for solving Astrodynamics problems. It is therefore a experiment to mix the best Python open source practices with my love for Orbital Mechanics.

Since I have only solved easy academic problems I cannot assess the suitability of the library for professional environments, though I am aware that at least a company that uses it.

2.1.2 History

I started poliaastro as a wrapper of some MATLAB and Fortran algorithms that I needed for a University project: having good performance was a must, so pure Python was not an option. As a three language project, it was only known to work in my computer, and I had to fight against oct2py and f2py for long hours.

Later on, I enhanced poliaastro plotting capabilities to serve me in further University tasks. I removed the MATLAB (Octave) code and kept only the Fortran algorithms. Finally, when numba was mature enough, I implemented everything in pure Python and poliaastro 0.3 was born.

2.1.3 Related software

These are some projects which share similarities with poliaastro or which served as inspiration:

- **astropy**: According to its website, “The Astropy Project is a community effort to develop a single core package for Astronomy in Python and foster interoperability between Python astronomy packages”. Not only it provides

important core features for poliastro like time and physical units handling, but also sets a high bar for code quality and documentation standards. A truly inspiring project.

- **Skyfield**: Another Astronomy Python package focused on computing observations of planetary bodies and Earth satellites written by Brandon Rhodes. It is the successor of pyephem, also written by him, but skyfield is a pure Python package and provides a much cleaner API.
- **Plyades**: A pioneering astrodynamics library written in Python by Helgee Eichhorn. Its clean and user friendly API inspired me to completely refactor poliastro 0.2 so it could be much easier to use. It has been stalled for a while, but at the moment of writing these lines its author is pushing new commits.
- **orbital**: Yet another orbital mechanics Python library written by Frazer McLean. It is very similar to poliastro (orbital plotting module was inspired in mine) but its internal structure is way smarter. It is more focused in plotting and it even provides 3D plots and animations.
- **orekit-python-wrapper**: According to its website, “The Orekit python wrapper enables to use Orekit within a normal python environment”, using JCC. Orekit is a well-established, mature open source library for Astrodynamics written in Java strongly supported by several space agencies. The Python wrapper is developed by the Swedish Space Corporation.
- **beyond**: A young flight dynamics library written in Python with a focus on developing “a simple API for space observations”. Some parts overlap with poliastro, but it also introduces many interesting features, and the examples look promising. Worth checking!
- **Spiceypy**: This Python library wraps the SPICE Toolkit, a huge software collection developed by NASA which offers advanced astrodynamics functionality. Among all the wrappers available on the Internet, at the time of writing this is the most advanced and well-maintained one, although there are others.

2.1.4 Future ideas

These are some things that I would love to implement in poliastro to expand its capabilities:

- 3D plotting of orbits
- Continuous thrust maneuvers
- Tisserand graphs
- Porkchop plots

2.1.5 Note of the original author

I am Juan Luis Cano Rodríguez (two names and two surnames, it’s the Spanish way!), an Aerospace Engineer with a passion for Astrodynamics and the Open Source world. Before poliastro started to be a truly community project, I started it when I was an Erasmus student at Politecnico di Milano, an important technical university in Italy which deeply influenced my life and ambitions and gave name to the library itself. It is and always will be my tiny tribute to a country that will always be in my heart and to people that never ceased to inspire me. *Grazie mille!*

2.2 Getting started

2.2.1 Requirements

poliastro requires the following Python packages:

- NumPy, for basic numerical routines

- Astropy, for physical units and time handling
- numba (optional), for accelerating the code
- jplephem, for the planetary ephemerides using SPICE kernels
- matplotlib, for orbit plotting
- scipy, for root finding and numerical propagation
- pytest, for running the tests from the package

poliastro is usually tested on Linux, Windows and OS X on Python 3.5 and 3.6 against latest NumPy.

2.2.2 Installation

The easiest and fastest way to get the package up and running is to install poliastro using [conda](#):

```
$ conda install poliastro --channel conda-forge
```

Note: We encourage users to use conda and the [conda-forge](#) packages for convenience, especially when developing on Windows.

If the installation fails for any reason, please open an issue in the [issue tracker](#).

Alternative installation methods

If you don't want to use conda you can [install poliastro from PyPI](#) using pip:

```
$ pip install numpy # Run this one first!
$ pip install poliastro
```

Finally, you can also install the latest development version of poliastro [directly from GitHub](#):

```
$ pip install https://github.com/poliastro/poliastro/archive/master.zip
```

This is useful if there is some feature that you want to try, but we did not release it yet as a stable version. Although you might find some unpolished details, these development installations should work without problems. If you find any, please open an issue in the [issue tracker](#).

Warning: It is recommended that you **never ever use sudo** with distutils, pip, setuptools and friends in Linux because you might seriously break your system [1][2][3][4]. Options are [per user directories](#), [virtualenv](#) or [local installations](#).

2.2.3 Testing

If installed correctly, the tests can be run using pytest:

```
$ python -c "import poliastro.testing; poliastro.testing.test()"
Running unit tests for poliastro
[...]
OK
$
```

If for some reason any test fails, please report it in the [issue tracker](#).

2.3 User guide

2.3.1 Defining the orbit: `Orbit` objects

The core of poliastro are the `Orbit` objects inside the `poliastro.twobody` module. They store all the required information to define an orbit:

- The body acting as the central body of the orbit, for example the Earth.
- The position and velocity vectors or the orbital elements.
- The time at which the orbit is defined.

First of all, we have to import the relevant modules and classes:

```
# If using the Jupyter notebook, use %matplotlib inline
%matplotlib inline

import numpy as np
import matplotlib.pyplot as plt
from astropy import units as u

from poliastro.bodies import Earth, Mars, Sun
from poliastro.twobody import Orbit

plt.style.use("seaborn") # Recommended
```

From position and velocity

There are several methods available to create `Orbit` objects. For example, if we have the position and velocity vectors we can use `from_vectors()`:

```
# Data from Curtis, example 4.3
r = [-6045, -3490, 2500] * u.km
v = [-3.457, 6.618, 2.533] * u.km / u.s

ss = Orbit.from_vectors(Earth, r, v)
```

And that's it! Notice a couple of things:

- Defining vectorial physical quantities using Astropy units is very easy. The list is automatically converted to a `astropy.units.Quantity`, which is actually a subclass of NumPy arrays.
- If we display the orbit we just created, we get a string with the radius of pericenter, radius of apocenter, inclination and attractor:

```
>>> ss
7283 x 10293 km x 153.2 deg orbit around Earth ()
```

- If no time is specified, then a default value is assigned:

```
>>> ss.epoch
<Time object: scale='utc' format='jyear_str' value=J2000.000>
```

```
>>> ss.epoch.iso
'2000-01-01 12:00:00.000'
```

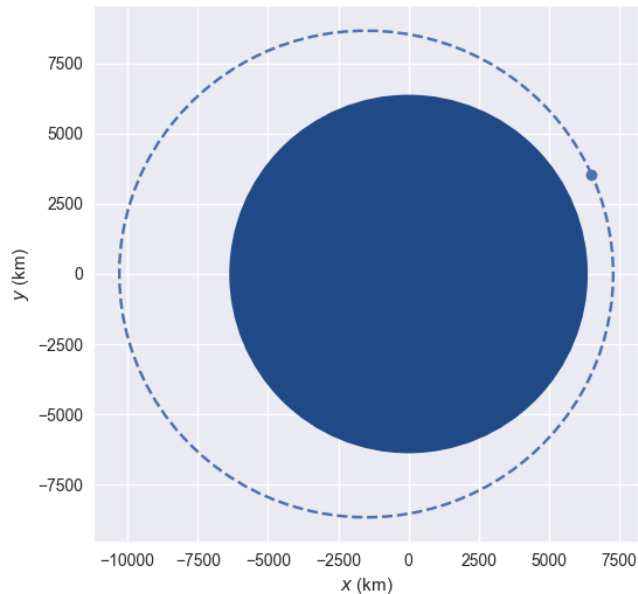
If we're working on interactive mode (for example, using the wonderful IPython notebook) we can immediately plot the current state:

```
from poliastro.plotting import plot
plot(ss)
```

This plot is made in the so called *perifocal frame*, which means:

- we're visualizing the plane of the orbit itself,
- the x axis points to the pericenter, and
- the y axis is turned 90° in the direction of the orbit.

The dotted line represents the *osculating orbit*: the instantaneous Keplerian orbit at that point. This is relevant in the context of perturbations, when the object shall deviate from its Keplerian orbit.



Warning: Be aware that, outside the Jupyter notebook (i.e. a normal Python interpreter or program) you might need to call `plt.show()` after the plotting commands or `plt.ion()` before them or they won't show. Check out the [Matplotlib FAQ](#) for more information.

From classical orbital elements

We can also define a *Orbit* using a set of six parameters called orbital elements. Although there are several of these element sets, each one with its advantages and drawbacks, right now poliastro supports the *classical orbital elements*:

- Semimajor axis (a) .
- Eccentricity (e) .
- Inclination (i) .
- Right ascension of the ascending node (Ω) .
- Argument of pericenter (ω) .
- True anomaly (ν) .

In this case, we'd use the method `from_classical()`:

```
# Data for Mars at J2000 from JPL HORIZONS
a = 1.523679 * u.AU
ecc = 0.093315 * u.one
inc = 1.85 * u.deg
raan = 49.562 * u.deg
argp = 286.537 * u.deg
nu = 23.33 * u.deg

ss = Orbit.from_classical(Sun, a, ecc, inc, raan, argp, nu)
```

Notice that whether we create a `Orbit` from $\backslash(r)$ and $\backslash(v)$ or from elements we can access many mathematical properties individually using the `state` property of `Orbit` objects:

```
>>> ss.state.period.to(u.day)
<Quantity 686.9713888628166 d>
>>> ss.state.v
<Quantity [ 1.16420211, 26.29603612, 0.52229379] km / s>
```

To see a complete list of properties, check out the `poliastro.twobody.orbit.Orbit` class on the API reference.

2.3.2 Moving forward in time: propagation

Now that we have defined an orbit, we might be interested in computing how is it going to evolve in the future. In the context of orbital mechanics, this process is known as **propagation**, and can be performed with the `propagate` method of `Orbit` objects:

```
>>> from poliastro.examples import iss
>>> iss
6772 x 6790 km x 51.6 deg orbit around Earth ()
>>> iss.epoch
<Time object: scale='utc' format='iso' value=2013-03-18 12:00:00.000>
>>> iss.nu.to(u.deg)
<Quantity 46.595804677061956 deg>
>>> iss.n.to(u.deg / u.min)
<Quantity 3.887010576192155 deg / min>
```

Using the `propagate()` method we can now retrieve the position of the ISS after some time:

```
>>> iss_30m = iss.propagate(30 * u.min)
>>> iss_30m.epoch # Notice we advanced the epoch!
<Time object: scale='utc' format='iso' value=2013-03-18 12:30:00.000>
>>> iss_30m.nu.to(u.deg)
<Quantity 163.1409357544868 deg>
```

For more advanced propagation options, check out the `poliastro.twobody.propagation` module.

2.3.3 Changing the orbit: Maneuver objects

poliastro helps us define several in-plane and general out-of-plane maneuvers with the `Maneuver` class inside the `poliastro.maneuver` module.

Each `Maneuver` consists on a list of impulses $\backslash(\Delta v_i)$ (changes in velocity) each one applied at a certain instant $\backslash(t_i)$. The simplest maneuver is a single change of velocity without delay: you can recreate it either using the `impulse()` method or instantiating it directly.

```
from poliastro.maneuver import Maneuver

dv = [5, 0, 0] * u.m / u.s

man = Maneuver.impulse(dv)
man = Maneuver((0 * u.s, dv)) # Equivalent
```

There are other useful methods you can use to compute common in-plane maneuvers, notably `hohmann()` and `bielliptic()` for Hohmann and bielliptic transfers respectively. Both return the corresponding `Maneuver` object, which in turn you can use to calculate the total cost in terms of velocity change ($\sum \|\Delta v_i\|$) and the transfer time:

```
>>> ss_i = Orbit.circular(Earth, alt=700 * u.km)
>>> ss_i
7078 x 7078 km x 0.0 deg orbit around Earth ()
>>> hoh = Maneuver.hohmann(ss_i, 36000 * u.km)
>>> hoh.get_total_cost()
<Quantity 3.6173981270031357 km / s>
>>> hoh.get_total_time()
<Quantity 15729.741535747102 s>
```

You can also retrieve the individual vectorial impulses:

```
>>> hoh.impulses[0]
(<Quantity 0 s>, <Quantity [ 0.          , 2.19739818, 0.          ] km / s>)
>>> hoh[0] # Equivalent
(<Quantity 0 s>, <Quantity [ 0.          , 2.19739818, 0.          ] km / s>)
>>> tuple(val.decompose([u.km, u.s]) for val in hoh[1])
(<Quantity 15729.741535747102 s>, <Quantity [ 0.          , 1.41999995, 0.          ] km /
→ s>)
```

To actually retrieve the resulting `Orbit` after performing a maneuver, use the method `apply_maneuver()`:

```
>>> ss_f = ss_i.apply_maneuver(hoh)
>>> ss_f
36000 x 36000 km x 0.0 deg orbit around Earth ()
```

2.3.4 More advanced plotting: `OrbitPlotter` objects

We previously saw the `poliastro.plotting.plot()` function to easily plot orbits. Now we'd like to plot several orbits in one graph (for example, the maneuver we computed in the previous section). For this purpose, we have `OrbitPlotter` objects in the `plotting` module.

These objects hold the perifocal plane of the first `Orbit` we plot in them, projecting any further trajectories on this plane. This allows to easily visualize in two dimensions:

```
from poliastro.plotting import OrbitPlotter

op = OrbitPlotter()
ss_a, ss_f = ss_i.apply_maneuver(hoh, intermediate=True)
op.plot(ss_i, label="Initial orbit")
op.plot(ss_a, label="Transfer orbit")
op.plot(ss_f, label="Final orbit")
```

Which produces this beautiful plot:

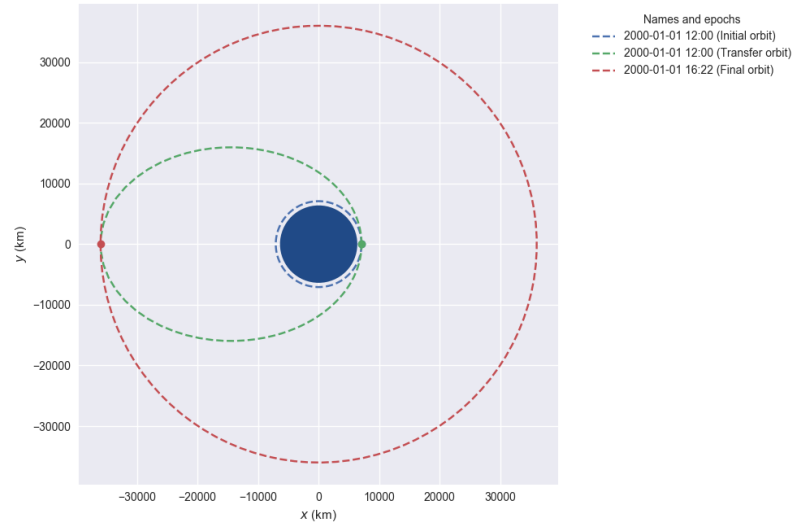


Fig. 2.1: Plot of a Hohmann transfer.

2.3.5 Where are the planets? Computing ephemerides

New in version 0.3.0.

Thanks to Astropy and jplephem, poliastro can now read Satellite Planet Kernel (SPK) files, part of NASA's SPICE toolkit. This means that we can query the position and velocity of the planets of the Solar System.

The function `poliastro.ephem.get_body_ephem()` will return position and velocity vectors using low precision ephemerides available in Astropy and an `astropy.time.Time`:

```
from astropy import time
epoch = time.Time("2015-05-09 10:43") # UTC by default
```

And finally, retrieve the planet orbit:

```
>>> from poliastro import ephem
>>> Orbit.from_body_ephem(Earth, epoch)
1 x 1 AU x 23.4 deg orbit around Sun ()
```

This does not require any external download. If on the other hand we want to use higher precision ephemerides, we can tell Astropy to do so:

```
>>> from astropy.coordinates import solar_system_ephemeris
>>> solar_system_ephemeris.set("jpl")
Downloading http://naif.jpl.nasa.gov/pub/naif/generic_kernels/spk/planets/de430.bsp
|=====>-----| 23M/119M (19.54%) ETA 59s22ss23
```

This in turn will download the ephemerides files from NASA and use them for future computations. For more information, check out [Astropy documentation on ephemerides](#).

Note: The position and velocity vectors are given with respect to the Solar System Barycenter in the **International Celestial Reference Frame (ICRF)**, which means approximately equatorial coordinates.

2.3.6 Traveling through space: solving the Lambert problem

The determination of an orbit given two position vectors and the time of flight is known in celestial mechanics as **Lambert's problem**, also known as two point boundary value problem. This contrasts with Kepler's problem or propagation, which is rather an initial value problem.

The package `poliastro.ioc` allows us to solve Lambert's problem, provided the main attractor's gravitational constant, the two position vectors and the time of flight. As you can imagine, being able to compute the positions of the planets as we saw in the previous section is the perfect complement to this feature!

For instance, this is a simplified version of the example [Going to Mars with Python using poliastro](#), where the orbit of the Mars Science Laboratory mission (rover Curiosity) is determined:

```
date_launch = time.Time('2011-11-26 15:02', scale='utc')
date_arrival = time.Time('2012-08-06 05:17', scale='utc')
tof = date_arrival - date_launch

ss0 = Orbit.from_body_ephem(Earth, date_launch)
ssf = Orbit.from_body_ephem(Mars, date_arrival)

from poliastro.ioc import ioc
(v0, v), = ioc.lambert(Sun.k, ss0.r, ssf.r, tof)
```

And these are the results:

```
>>> v0
<Quantity [-29.29150998, 14.53326521,  5.41691336] km / s>
>>> v
<Quantity [ 17.6154992 , -10.99830723, -4.20796062] km / s>
```

2.3.7 Working with NEOs

NEOs (Near Earth Objects) are asteroids and comets whose orbits are near to earth (obvious, isn't it?). More correctly, their perihelion (closest approach to the Sun) is less than 1.3 astronomical units ($200 * 10^6$ km). Currently, they are being an important subject of study for scientists around the world, due to their status as the relatively unchanged remains from the solar system formation process.

Because of that, a new module related to NEOs has been added to `poliastro` as part of [SOCIS 2017 project](#).

For the moment, it is possible to search NEOs by name (also using wildcards), and get their orbits straight from NASA APIs, using `orbit_from_name()`. For example, we can get [Apophis asteroid \(99942 Apophis\)](#) orbit with one command, and plot it:

```
from poliastro.neos import news

apophis_orbit = news.orbit_from_name('apophis') # Also '99942' or '99942 apophis'
↳ works
earth_orbit = Orbit.from_body_ephem(Earth)

op = OrbitPlotter()
op.plot(earth_orbit, label='Earth')
op.plot(apophis_orbit, label='Apophis')
```

Per Python ad astra ;)

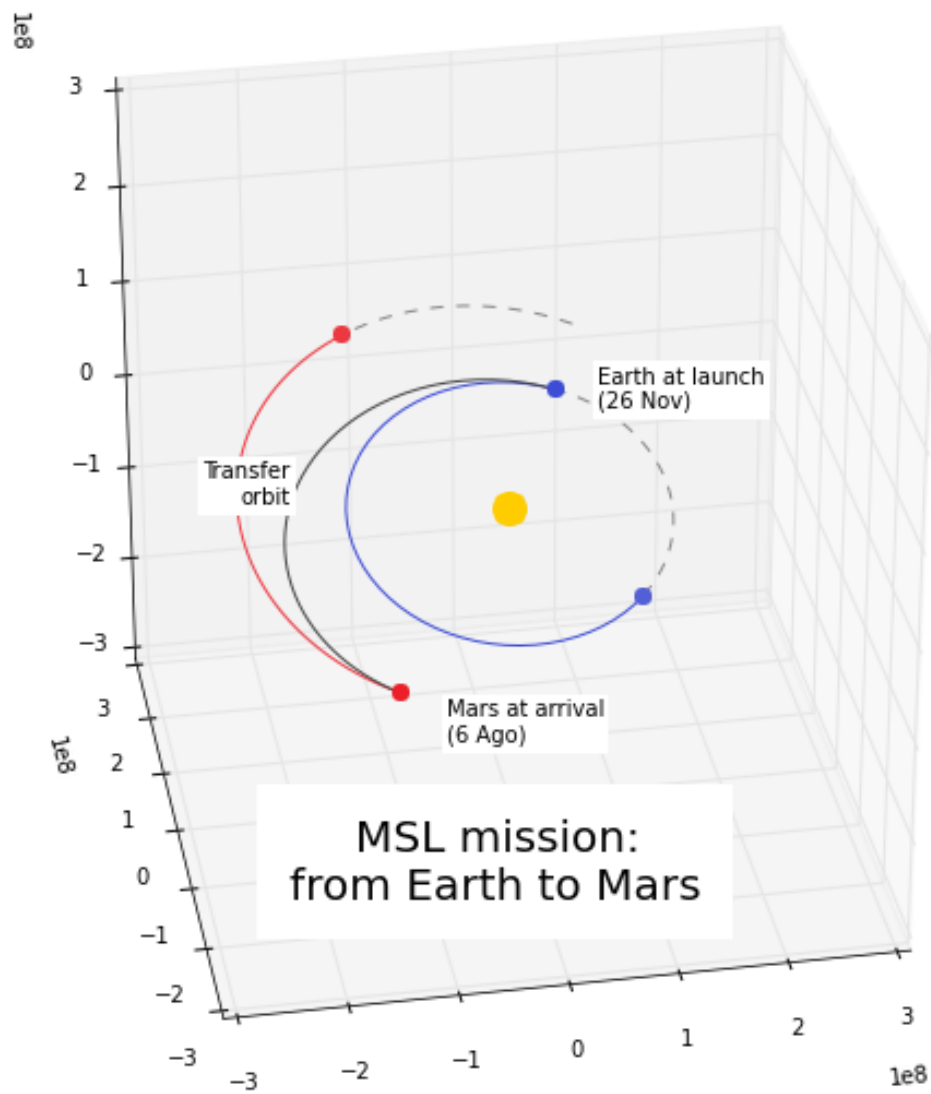


Fig. 2.2: Mars Science Laboratory orbit.

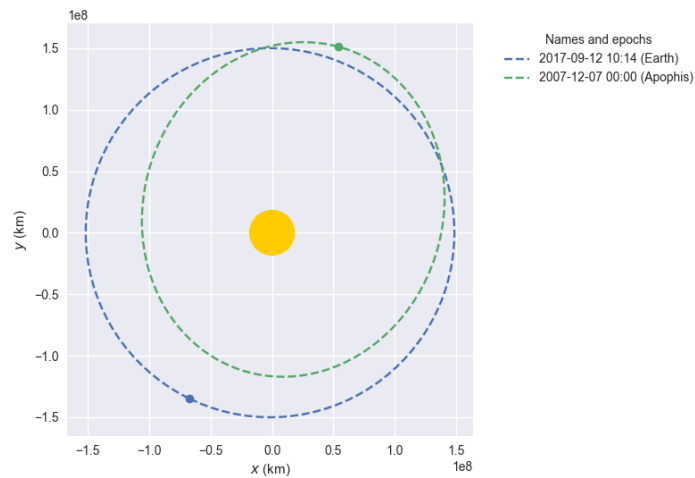


Fig. 2.3: Apophis asteroid orbit compared to Earth orbit.

2.4 Jupyter notebooks

2.4.1 Catch that asteroid!

```
In [1]: %matplotlib inline
import matplotlib.pyplot as plt

from astropy import units as u
from astropy.time import Time
from astropy.coordinates import solar_system_ephemeris
solar_system_ephemeris.set("jpl")

from poliastro.bodies import *
from poliastro.twobody import Orbit
from poliastro.plotting import OrbitPlotter, plot

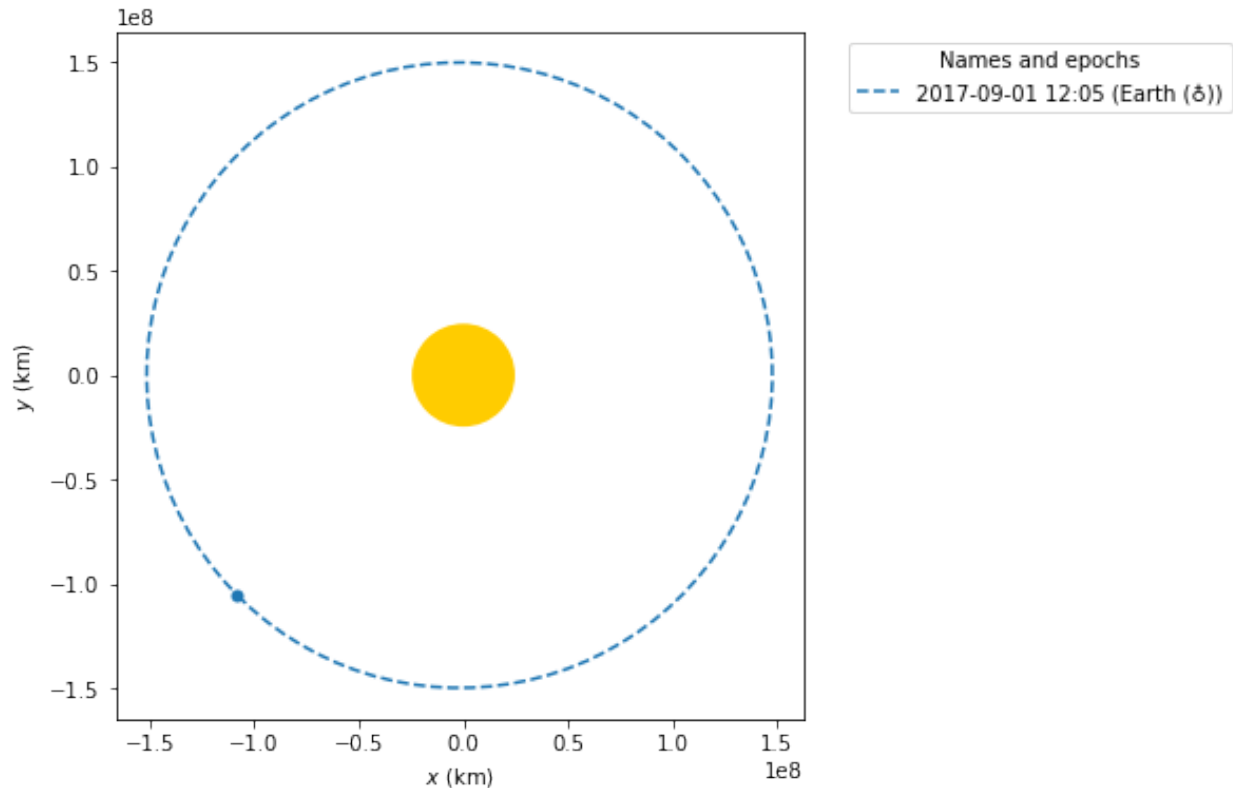
EPOCH = Time("2017-09-01 12:05:50", scale="tdb")

In [2]: earth = Orbit.from_body_ephem(Earth, EPOCH)
earth

Out[2]: 1 x 1 AU x 23.4 deg orbit around Sun ()

In [3]: plot(earth, label=Earth)

Out[3]: [<matplotlib.lines.Line2D at 0x7fad05cb76d8>,
<matplotlib.lines.Line2D at 0x7fad05cb70b8>]
```



```
In [4]: from poliastro.neos import neows
In [5]: florence = neows.orbit_from_name("Florence")
         florence
```

```
Out[5]: 1 x 3 AU x 22.2 deg orbit around Sun ()
```

Two problems: the epoch is not the one we desire, and the inclination is with respect to the ecliptic!

```
In [6]: florence.epoch
Out[6]: <Time object: scale='tdb' format='jd' value=2458000.5>
In [7]: florence.epoch.iso
Out[7]: '2017-09-04 00:00:00.000'
In [8]: florence.inc
```

22.15078 ° We first propagate:

```
In [9]: florence = florence.propagate(EPOCH)
         florence.epoch.tdb.iso
Out[9]: '2017-09-01 12:05:50.000'
```

And now we have to convert to another reference frame, using <http://docs.astropy.org/en/stable/coordinates/>.

```
In [10]: from astropy.coordinates import (
          ICRS, GCRS,
          CartesianRepresentation, CartesianDifferential
        )
         from poliastro.frames import HeliocentricEclipticJ2000
```

The NASA servers give the orbital elements of the asteroids in an Heliocentric Ecliptic frame. Fortunately, it is already defined in Astropy:

```
In [11]: florence_heclip = HeliocentricEclipticJ2000(
        x=florence.r[0], y=florence.r[1], z=florence.r[2],
        d_x=florence.v[0], d_y=florence.v[1], d_z=florence.v[2],
        representation=CartesianRepresentation,
        differential_cls=CartesianDifferential,
        obstime=EPOCH
    )
    florence_heclip

Out[11]: <HeliocentricEclipticJ2000 Coordinate (obstime=2017-09-01 12:05): (x, y, z) in km
        ( 1.45904366e+08, -58569290.31320047, 2270778.95771309)
        (d_x, d_y, d_z) in km / s
        ( 7.40819577, 31.11060241, 12.80050223)>
```

Now we just have to convert to ICRS, which is the “standard” reference in which poliastro works:

```
In [12]: florence_icrs_trans = florence_heclip.transform_to(ICRS)
        florence_icrs_trans.representation = CartesianRepresentation
        florence_icrs_trans

Out[12]: <ICRS Coordinate: (x, y, z) in km
        ( 1.46271269e+08, -53880006.88710973, -20906928.0521954)
        (v_x, v_y, v_z) in km / s
        ( 7.39978737, 23.46064313, 24.1234135)>

In [13]: florence_icrs = Orbit.from_vectors(
        Sun,
        r=[florence_icrs_trans.x, florence_icrs_trans.y, florence_icrs_trans.z] * u.km,
        v=[florence_icrs_trans.v_x, florence_icrs_trans.v_y, florence_icrs_trans.v_z] * (u.km /
        epoch=florence.epoch
    )
    florence_icrs

Out[13]: 1 x 3 AU x 44.6 deg orbit around Sun ()

In [14]: florence_icrs.rv()

Out[14]: (<Quantity [ 1.46271269e+08, -5.38800069e+07, -2.09069281e+07] km>,
        <Quantity [ 7.39978737, 23.46064313, 24.1234135 ] km / s>)
```

Let us compute the distance between Florence and the Earth:

```
In [15]: from poliastro.util import norm

In [16]: norm(florence_icrs.r - earth.r) - Earth.R

7060313.3 km This value is consistent with what ESA says! 7 060 160 km

In [17]: from IPython.display import HTML

        HTML(
            """<blockquote class="twitter-tweet" data-lang="en"><p lang="es" dir="ltr">La <a href="http:
            <script async src="//platform.twitter.com/widgets.js" charset="utf-8"></script>"""
        )

Out[17]: <IPython.core.display.HTML object>
```

And now we can plot!

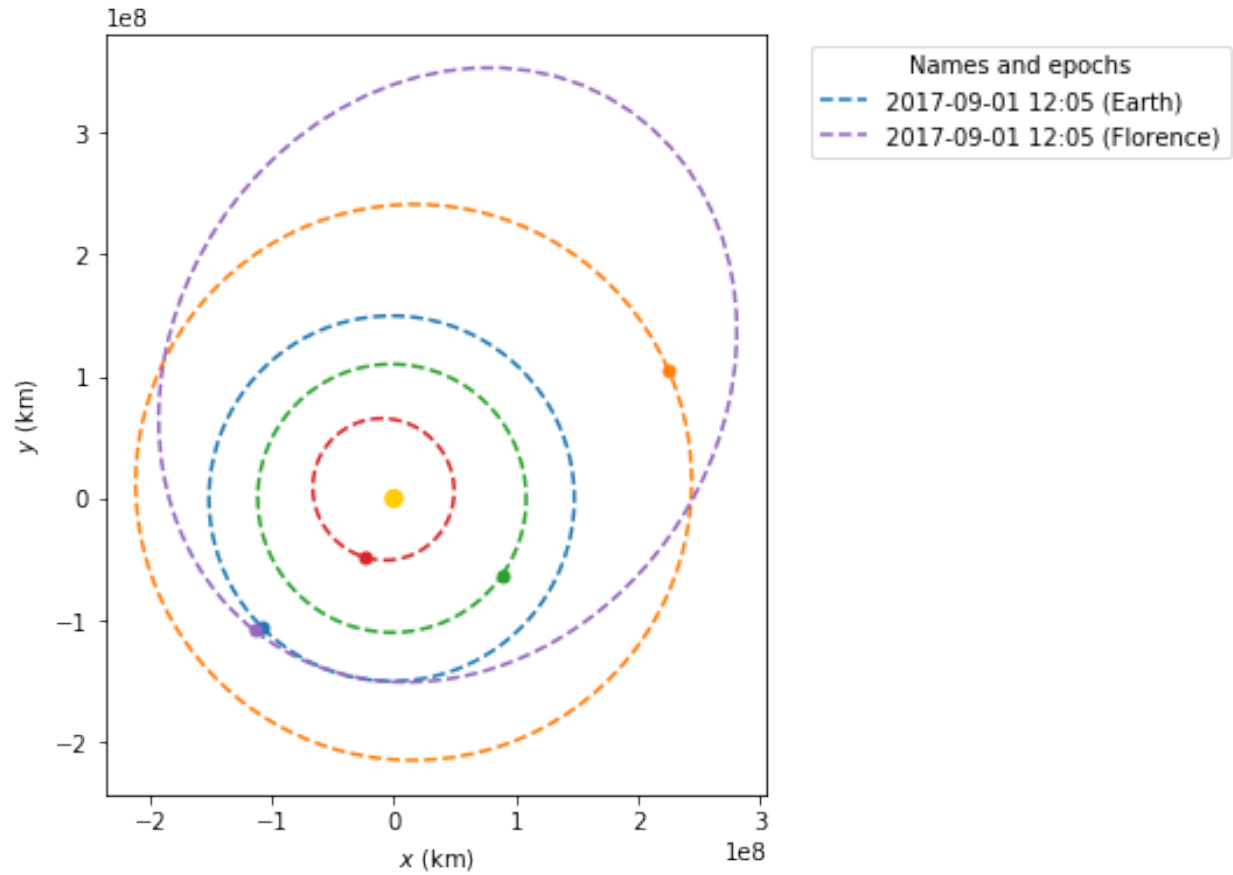
```
In [18]: frame = OrbitPlotter()

        frame.plot(earth, label="Earth")

        frame.plot(Orbit.from_body_ephem(Mars, EPOCH))
        frame.plot(Orbit.from_body_ephem(Venus, EPOCH))
        frame.plot(Orbit.from_body_ephem(Mercury, EPOCH))
```

```
frame.plot(florence_icsr, label="Florence")
```

Out [18]: [<matplotlib.lines.Line2D at 0x7f3e2bf66320>,
<matplotlib.lines.Line2D at 0x7f3e2bf66518>]



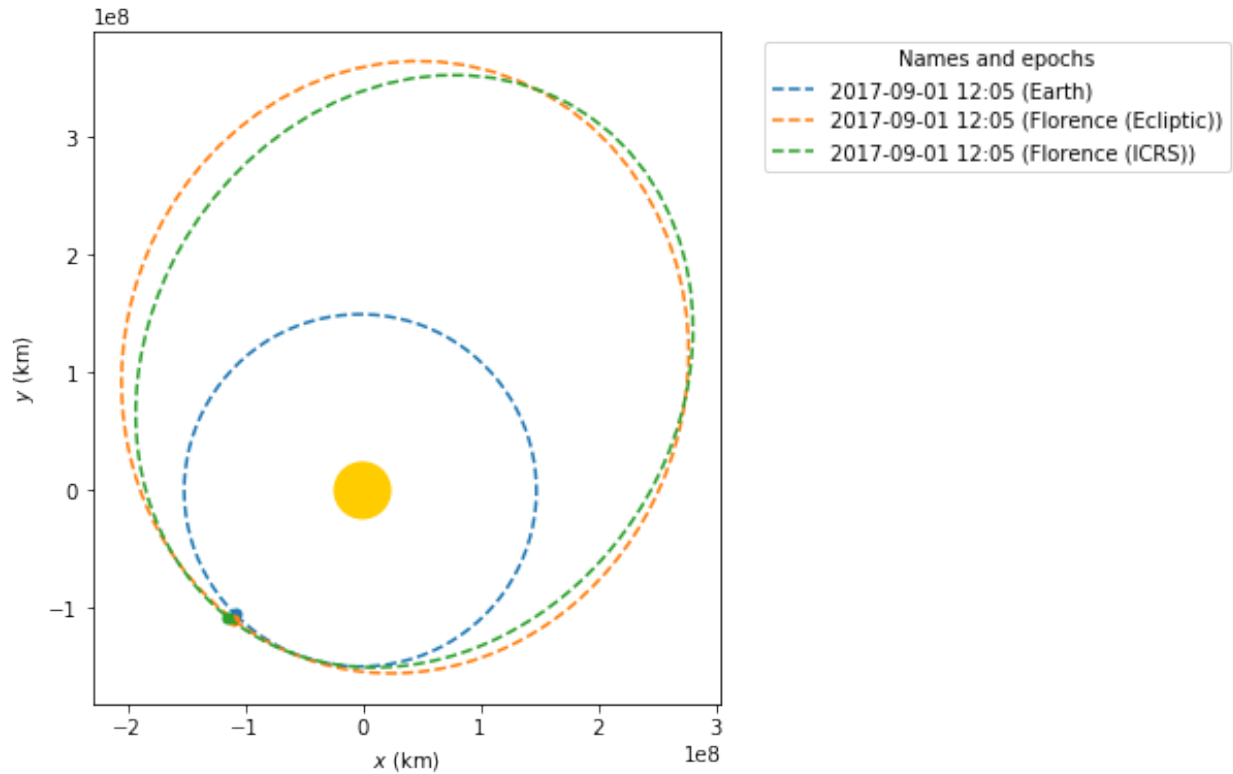
The difference between doing it well and doing it wrong is clearly visible:

```
In [19]: frame = OrbitPlotter()

frame.plot(earth, label="Earth")

frame.plot(florence, label="Florence (Ecliptic)")
frame.plot(florence_icsr, label="Florence (ICRS)")
```

Out [19]: [<matplotlib.lines.Line2D at 0x7f3e2be71048>,
<matplotlib.lines.Line2D at 0x7f3e2be71240>]



And now let's do something more complicated: express our orbit with respect to the Earth! For that, we will use GCRS, with care of setting the correct observation time:

```
In [20]: florence_gcrs_trans = florence_heclip.transform_to(GCRS(obstime=EPOCH))
         florence_gcrs_trans.representation = CartesianRepresentation
         florence_gcrs_trans
```

```
Out[20]: <GCRS Coordinate (obstime=2017-09-01 12:05, obsgeoloc=( 0.,  0.,  0.) m, obsgeovel=( 0.,  0.,  0.) m/s,
         ( 4966319.35958239, -5018473.35356456,  297867.61376881)
         (v_x, v_y, v_z) in km / s
         (-2.76873111, -1.96008601,  13.10279932)>
```

```
In [21]: florence_hyper = Orbit.from_vectors(
         Earth,
         r=[florence_gcrs_trans.x, florence_gcrs_trans.y, florence_gcrs_trans.z] * u.km,
         v=[florence_gcrs_trans.v_x, florence_gcrs_trans.v_y, florence_gcrs_trans.v_z] * (u.km / s),
         epoch=EPOCH
         )
         florence_hyper
```

```
Out[21]: 7066691 x -7071046 km x 104.3 deg orbit around Earth ()
```

Notice that the ephemerides of the Moon is also given in ICRS, and therefore yields a weird hyperbolic orbit!

```
In [22]: moon = Orbit.from_body_ephem(Moon, EPOCH)
         moon
```

```
Out[22]: 151218466 x -151219347 km x 23.3 deg orbit around Earth ()
```

```
In [23]: moon.a
```

```
-440.42131 km
```

```
In [24]: moon.ecc
```

343350.57 So we have to convert again.

```
In [25]: moon_icrs = ICRS(
        x=moon.r[0], y=moon.r[1], z=moon.r[2],
        v_x=moon.v[0], v_y=moon.v[1], v_z=moon.v[2],
        representation=CartesianRepresentation,
        differential_cls=CartesianDifferential
    )
    moon_icrs
```

```
Out[25]: <ICRS Coordinate: (x, y, z) in km
        ( 1.41399531e+08, -49228391.42507221, -21337616.62766309)
        (v_x, v_y, v_z) in km / s
        ( 11.10890252, 25.6785744, 11.0567569)>
```

```
In [26]: moon_gcrs = moon_icrs.transform_to(GCRS(obstime=EPOCH))
    moon_gcrs.representation = CartesianRepresentation
    moon_gcrs
```

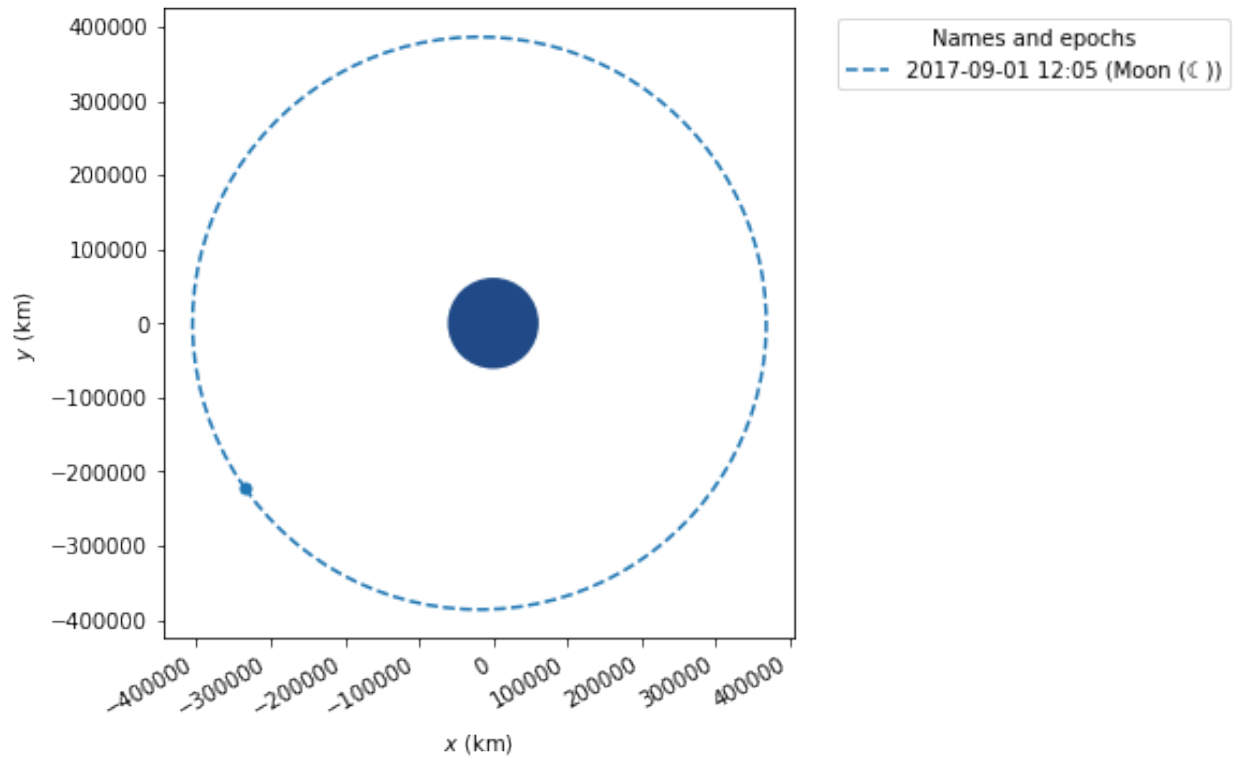
```
Out[26]: <GCRS Coordinate (obstime=2017-09-01 12:05, obsgeoloc=( 0., 0., 0.) m, obsgeovel=( 0., 0., 0.) m/s)
        ( 94189.90120828, -367278.24304992, -133087.21297573)
        (v_x, v_y, v_z) in km / s
        ( 0.94073662, 0.25786326, 0.03569047)>
```

```
In [27]: moon = Orbit.from_vectors(
        Earth,
        [moon_gcrs.x, moon_gcrs.y, moon_gcrs.z] * u.km,
        [moon_gcrs.v_x, moon_gcrs.v_y, moon_gcrs.v_z] * (u.km / u.s),
        epoch=EPOCH
    )
    moon
```

```
Out[27]: 367937 x 405209 km x 19.4 deg orbit around Earth ()
```

And finally, we plot the Moon:

```
In [28]: plot(moon, label=Moon)
    plt.gcf().autofmt_xdate()
```

And now for the final plot:

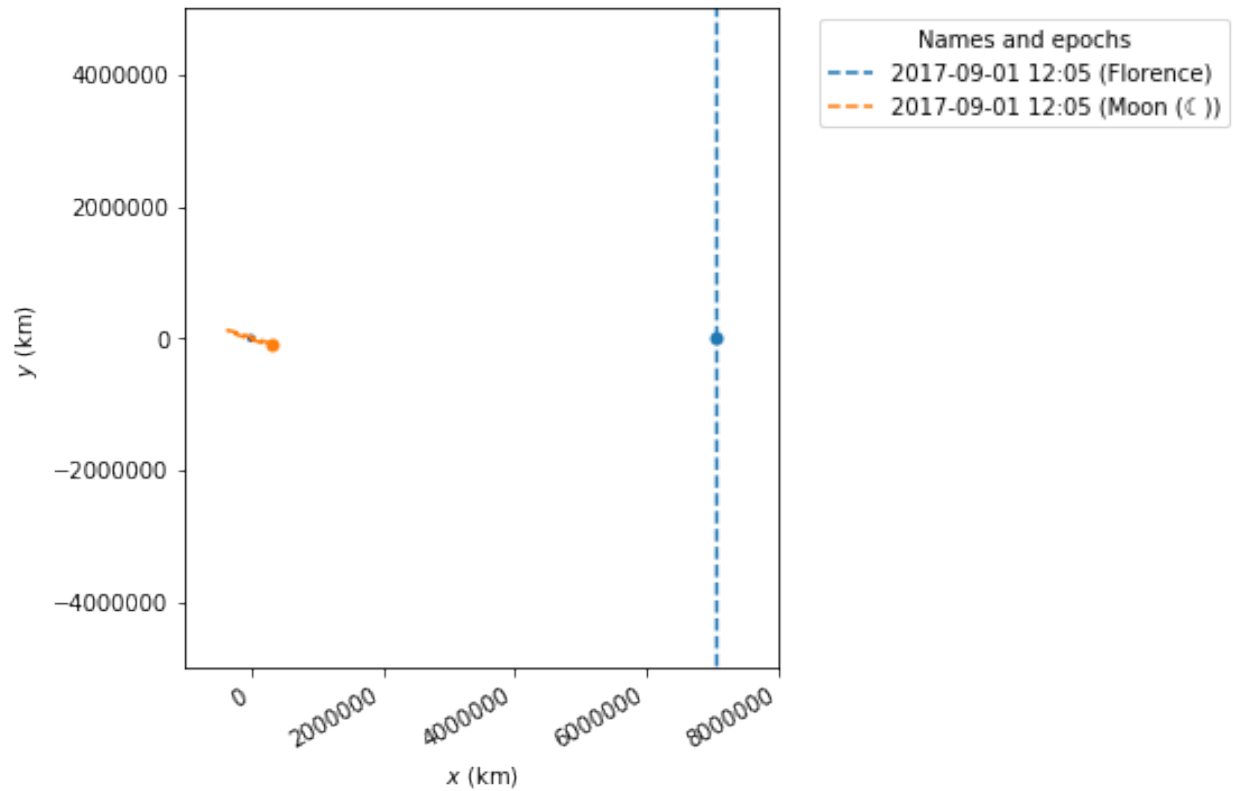
```
In [29]: frame = OrbitPlotter()

         # This first plot sets the frame
         frame.plot(florence_hyper, label="Florence")

         # And then we add the Moon
         frame.plot(moon, label="Moon")

         plt.xlim(-1000000, 8000000)
         plt.ylim(-5000000, 5000000)

         plt.gcf().autofmt_xdate()
```



Per Python ad astra!

2.4.2 Comparing Hohmann and bielliptic transfers

```
In [1]: %matplotlib inline
import numpy as np
import matplotlib.pyplot as plt

from mpl_toolkits.axes_grid1.inset_locator import zoomed_inset_axes
from mpl_toolkits.axes_grid1.inset_locator import mark_inset

from astropy import units as u

from poliastro.bodies import Earth
from poliastro.twobody import Orbit
from poliastro.maneuver import Maneuver

In [2]: ZOOM = True

R = np.linspace(2, 75, num=100)
Rstar = [15.58, 40, 60, 100, 200, np.inf]

hohmann_data = np.zeros_like(R)
bielliptic_data = np.zeros((len(R), len(Rstar)))

ss_i = Orbit.circular(Earth, 1.8 * u.km)
r_i = ss_i.a
v_i = np.sqrt(ss_i.v.dot(ss_i.v))
for ii, r in enumerate(R):
```

```

    r_f = r * r_i
    man = Maneuver.hohmann(ss_i, r_f)
    hohmann_data[ii] = (man.get_total_cost() / v_i).decompose().value
    for jj, rstar in enumerate(Rstar):
        r_b = rstar * r_i
        man = Maneuver.bielliptic(ss_i, r_b, r_f)
        bielliptic_data[ii, jj] = (man.get_total_cost() / v_i).decompose().value

    idx_max = np.argmax(hohmann_data)

    ylimits = (0.35, 0.6)

/home/juanlu/Development/astropy/astropy/units/quantity.py:641: RuntimeWarning: invalid value encountered
  *arrays, **kwargs)

In [3]: fig, ax = plt.subplots(figsize=(8, 6))

    l, = ax.plot(R, hohmann_data, lw=2)
    for jj in range(len(Rstar)):
        ax.plot(R, bielliptic_data[:, jj], color=l.get_color())
    ax.vlines([11.94, R[idx_max]], *ylimits, color='0.6')

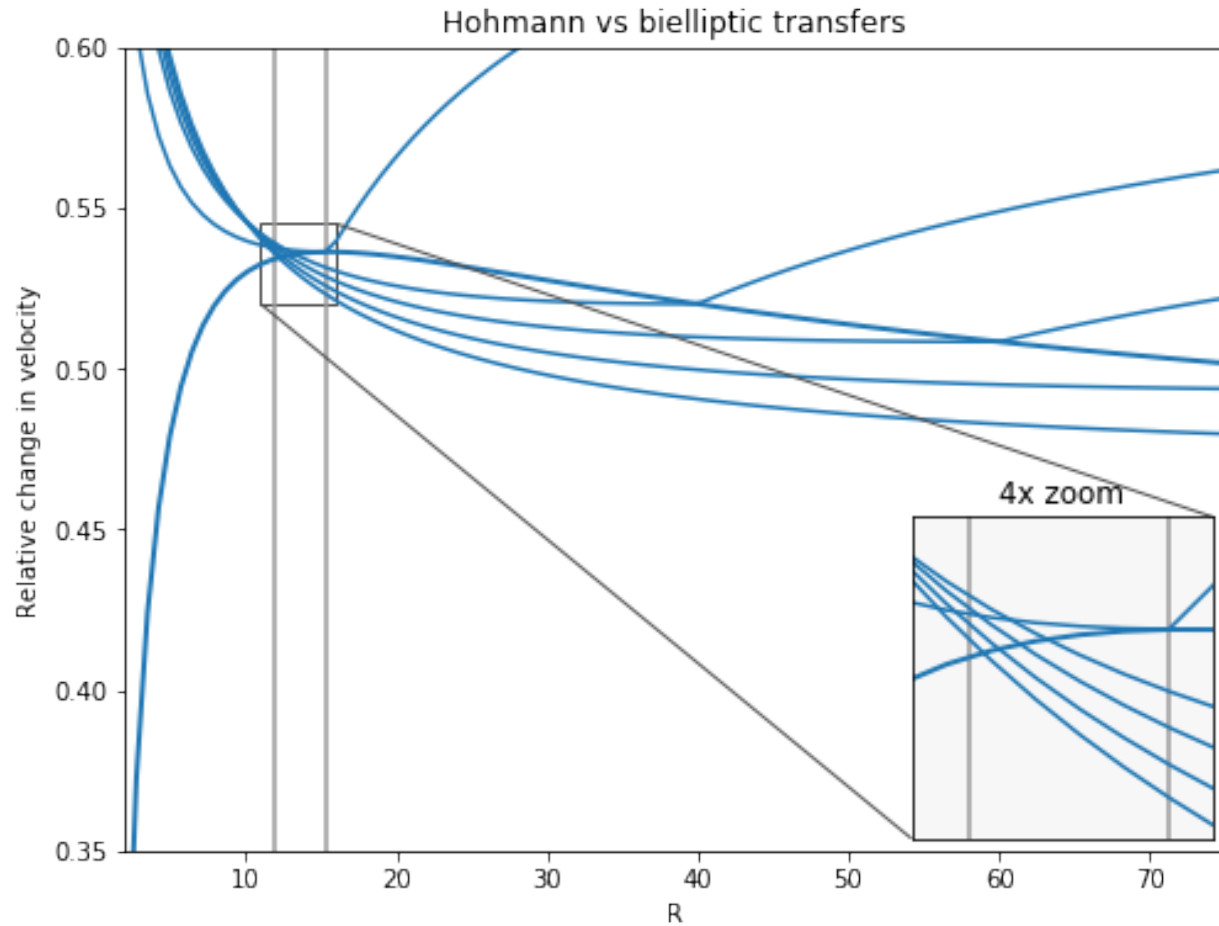
    if ZOOM:
        ax_zoom = zoomed_inset_axes(ax, 4, loc=4, axes_kwargs={'facecolor': '0.97'})
        ax_zoom.plot(R, hohmann_data, lw=2)
        for jj in range(len(Rstar)):
            ax_zoom.plot(R, bielliptic_data[:, jj], color=l.get_color())
        ax_zoom.vlines([11.94, R[idx_max]], *ylimits, color='0.6')

        ax_zoom.set_xlim(11.0, 16.0)
        ax_zoom.set_ylim(0.52, 0.545)
        ax_zoom.set_xticks([])
        ax_zoom.set_yticks([])
        ax_zoom.grid(False)
        ax_zoom.set_title("4x zoom")
        mark_inset(ax, ax_zoom, loc1=1, loc2=3, fc="none", ec='0.3')

    ax.set_xlabel("R")
    ax.set_ylabel("Relative change in velocity")
    ax.set_ylim(*ylimits)
    ax.set_xlim(2, 75)
    ax.set_title("Hohmann vs bielliptic transfers")

    fig.savefig("hohmann-bielliptic-transfers.png")

```



2.4.3 New Horizons launch and trajectory

Main data source: Guo & Farquhar “New Horizons Mission Design” <http://www.boulder.swri.edu/pkb/ssr/ssr-mission-design.pdf>

```
In [1]: %matplotlib inline
import matplotlib
import matplotlib.pyplot as plt

from astropy import time
from astropy import units as u

from poliastro.bodies import Sun, Earth, Jupiter
from poliastro.twobody import Orbit
from poliastro.plotting import plot, OrbitPlotter
from poliastro import iod
from poliastro.util import norm
```

Parking orbit

Quoting from “New Horizons Mission Design”:

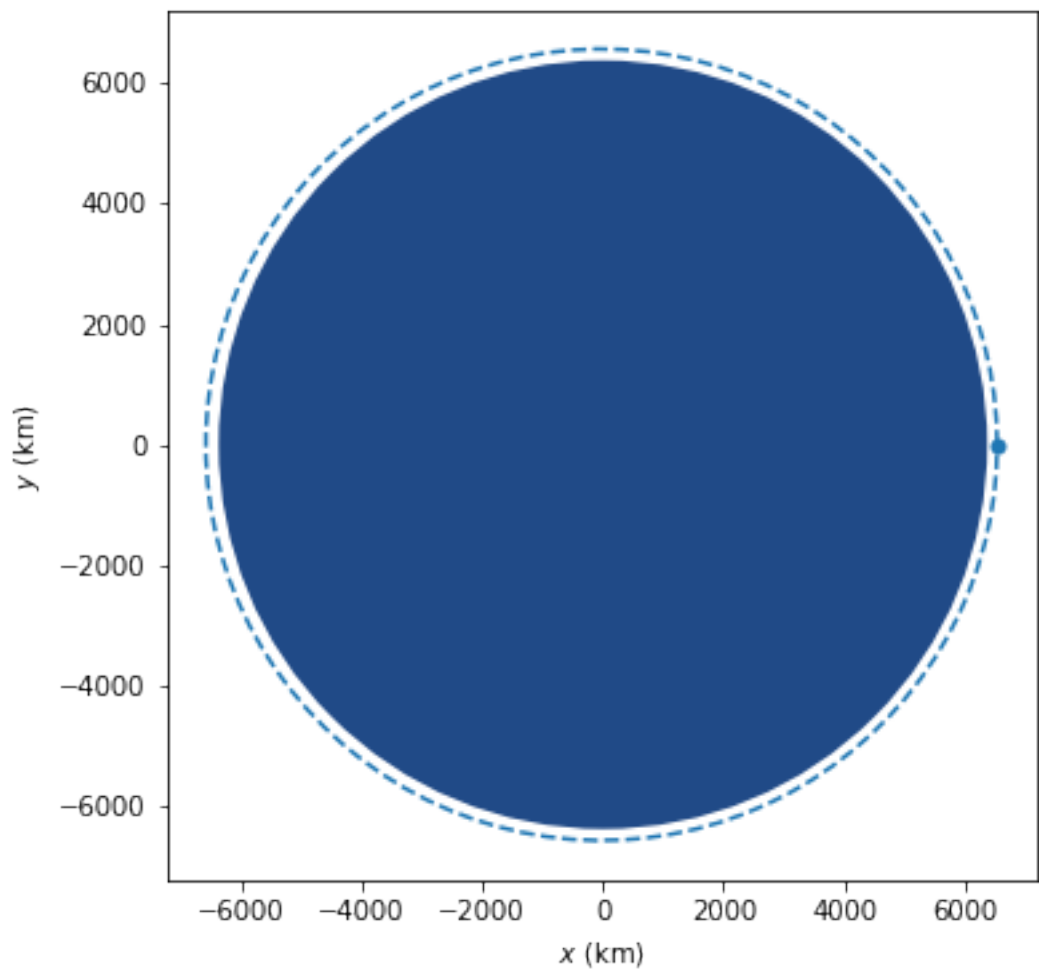
It was first inserted into an elliptical Earth parking orbit of **perigee altitude 165 km** and **apogee altitude 215 km**. [Emphasis mine]

```
In [2]: r_p = Earth.R + 165 * u.km
        r_a = Earth.R + 215 * u.km

        a_parking = (r_p + r_a) / 2
        ecc_parking = 1 - r_p / a_parking

        parking = Orbit.from_classical(Earth, a_parking, ecc_parking,
                                       0 * u.deg, 0 * u.deg, 0 * u.deg, 0 * u.deg, # We don't mind
                                       time.Time("2006-01-19", scale='utc'))

        plot(parking)
        parking.v
```



$[0, 7.8198936, 0] \frac{\text{km}}{\text{s}}$

Hyperbolic exit

Hyperbolic excess velocity:

$$v_{\infty}^2 = \frac{\mu}{-a} = 2\varepsilon = C_3$$

Relation between orbital velocity v , local escape velocity v_e and hyperbolic excess velocity v_∞ :

$$v^2 = v_e^2 + v_\infty^2$$

Option a): Insert C_3 from report, check v_e at parking perigee

```
In [3]: C_3_A = 157.6561 * u.km**2 / u.s**2 # Designed

a_exit = -(Earth.k / C_3_A).to(u.km)
ecc_exit = 1 - r_p / a_exit

exit = Orbit.from_classical(Earth, a_exit, ecc_exit,
                           0 * u.deg, 0 * u.deg, 0 * u.deg, 0 * u.deg, # We don't mind
                           time.Time("2006-01-19", scale='utc'))

norm(exit.v).to(u.km / u.s)
```

16.718069 $\frac{\text{km}}{\text{s}}$ Quoting “New Horizons Mission Design”:

After a short coast in the parking orbit, the spacecraft was then injected into the desired heliocentric orbit by the Centaur second stage and Star 48B third stage. At the Star 48B burnout, the New Horizons spacecraft reached the highest Earth departure speed, **estimated at 16.2 km/s**, becoming the fastest spacecraft ever launched from Earth. [Emphasis mine]

```
In [4]: v_estimated = 16.2 * u.km / u.s

print("Relative error of {:.2f} %".format((norm(exit.v) - v_estimated) / v_estimated * 100))
```

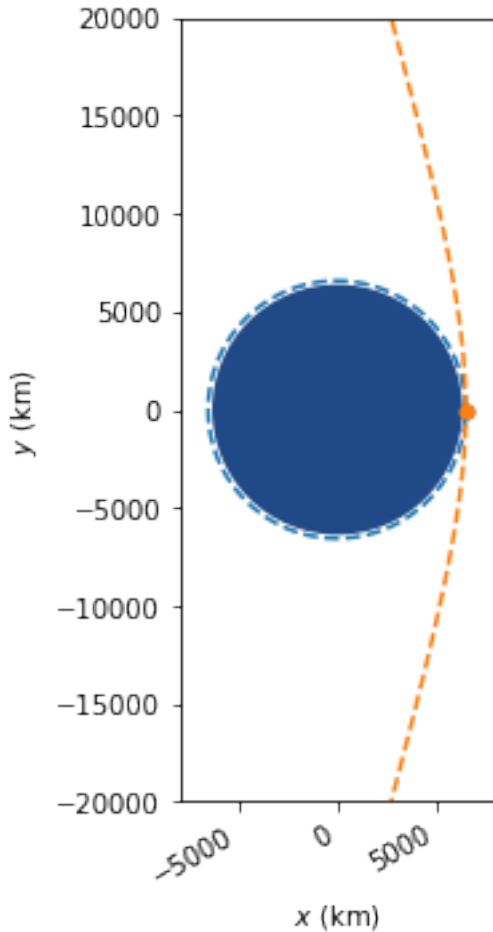
Relative error of 3.20 %

So it stays within the same order of magnitude. Which is reasonable, because real life burns are not instantaneous.

```
In [5]: op = OrbitPlotter()

op.plot(parking)
op.plot(exit)

plt.xlim(-8000, 8000)
plt.ylim(-20000, 20000)
plt.gcf().autofmt_xdate()
```



Option b): Compute v_∞ using the Jupyter flyby

According to Wikipedia, the closest approach occurred at 05:43:40 UTC. We can use this data to compute the solution of the Lambert problem between the Earth and Jupiter.

```
In [6]: nh_date = time.Time("2006-01-19 19:00", scale='utc')
        nh_flyby_date = time.Time("2007-02-28 05:43:40", scale='utc')
        nh_tof = nh_flyby_date - nh_date

        nh_earth = Orbit.from_body_ephem(Earth, nh_date)
        nh_r_0, v_earth = nh_earth.rv()

        nh_jup = Orbit.from_body_ephem(Jupiter, nh_flyby_date)
        nh_r_f, v_jup = nh_jup.rv()

        (nh_v_0, nh_v_f), = iod.lambert(Sun.k, nh_r_0, nh_r_f, nh_tof)
```

The hyperbolic excess velocity is measured with respect to the Earth:

```
In [7]: C_3_lambert = (norm(nh_v_0 - v_earth)).to(u.km / u.s)**2
        C_3_lambert

158.45628  $\frac{\text{km}^2}{\text{s}^2}$ 

In [8]: print("Relative error of {:.2f} %".format((C_3_lambert - C_3_A) / C_3_A * 100))
```

Relative error of 0.51 %

Which again, stays within the same order of magnitude of the figure given to the Guo & Farquhar report.

From Earth to Jupiter

```
In [9]: from poliastro.plotting import BODY_COLORS

nh = Orbit.from_vectors(Sun, nh_r_0.to(u.km), nh_v_0.to(u.km / u.s), nh_date)

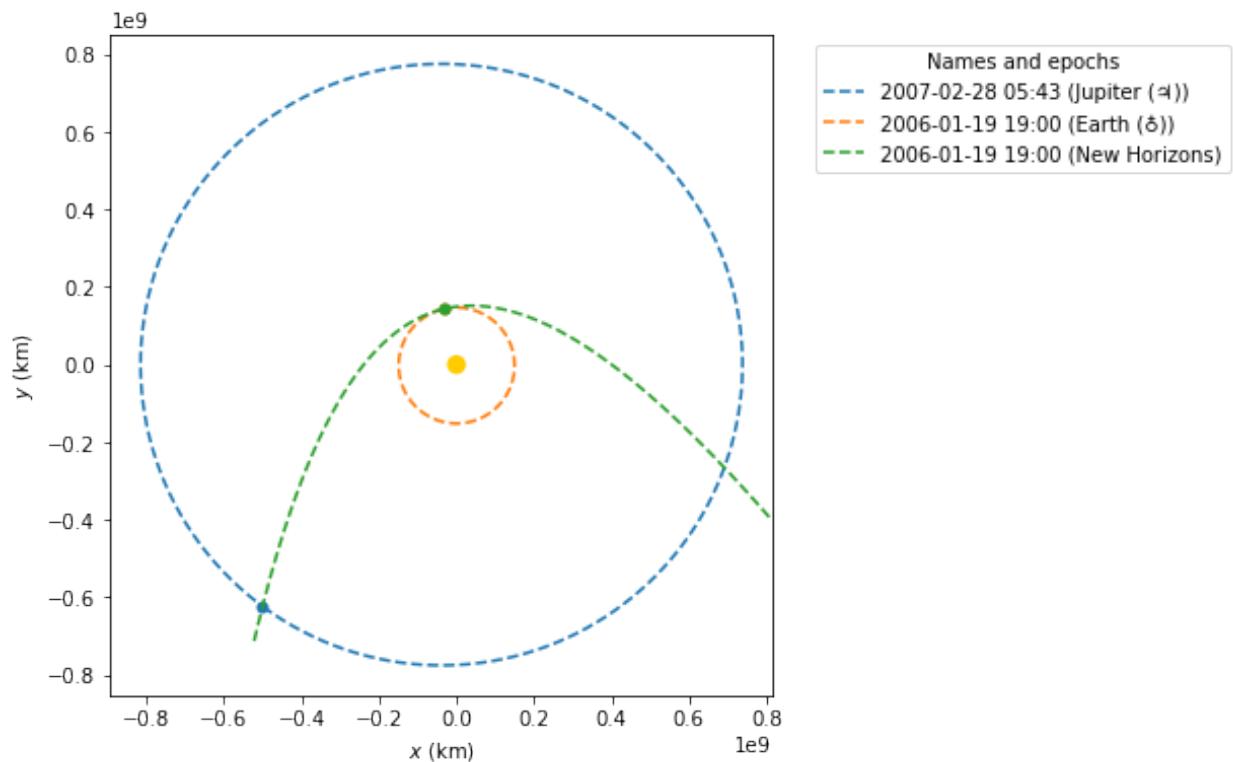
op = OrbitPlotter(num_points=1000)

op.plot(nh_jup, label=Jupiter)

plt.gca().set_autoscale_on(False)

op.plot(nh_earth, label=Earth)
op.plot(nh, label="New Horizons")

Out[9]: [<matplotlib.lines.Line2D at 0x16562f13198>,
        <matplotlib.lines.Line2D at 0x16562f07e80>]
```



2.4.4 Going to Mars with Python using poliastro

This is an example on how to use [poliastro](#), a little library I've been working on to use in my Astrodynamics lessons. It features conversion between **classical orbital elements** and position vectors, propagation of **Keplerian orbits**, initial orbit determination using the solution of the **Lambert's problem** and **orbit plotting**.

In this example we're going to draw the trajectory of the mission [Mars Science Laboratory \(MSL\)](#), which carried the rover Curiosity to the surface of Mars in a period of something less than 9 months.

Note: This is a very simplistic analysis which doesn't take into account many important factors of the mission, but can serve as an starting point for more serious computations (and as a side effect produces a beautiful plot at the end).

First of all, we import the necessary modules. Apart from poliastro we will make use of astropy to deal with physical units and time definitions and jplephem to compute the positions and velocities of the planets.

```
In [1]: %matplotlib notebook
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

import astropy.units as u
from astropy import time

from poliastro import iod
from poliastro.bodies import Sun
from poliastro.twobody import Orbit
```

We need a binary file from NASA called *SPICE kernel* to compute the position and velocities of the planets. Astropy downloads it for us:

```
In [2]: from astropy.coordinates import solar_system_ephemeris
from poliastro.ephem import get_body_ephem

solar_system_ephemeris.set("jpl")

Out[2]: <ScienceState solar_system_ephemeris: 'jpl'>
```

The initial data was gathered from Wikipedia: the date of the launch was on **November 26, 2011 at 15:02 UTC** and landing was on **August 6, 2012 at 05:17 UTC**. We compute then the time of flight, which is exactly what it sounds. It is a crucial parameter of the mission.

```
In [3]: # Initial data
N = 50

date_launch = time.Time('2011-11-26 15:02', scale='utc')
date_arrival = time.Time('2012-08-06 05:17', scale='utc')
tof = (date_arrival - date_launch)

tof.to(u.h)
```

6086.2503 h With the date of launch and the date of landing we can compute the **Julian days**. The Julian day is an integer assigned to a date, and it's useful for not having to deal with leap years, changes of calendar and other messy stuff. It is measured from around 4713 BC so it is a pretty big number, as we'll see:

```
In [4]: # Calculate vector of times from launch and arrival Julian days
dt = (date_arrival - date_launch) / N

# Idea from http://docs.astropy.org/en/stable/time/#getting-started
times_vector = date_launch + dt * np.arange(N + 1)
```

Once we have the vector of times we can use `get_body_ephem` to compute the array of positions and velocities of the Earth and Mars.

```
In [5]: rr_earth, vv_earth = get_body_ephem("earth", times_vector)
In [6]: rr_earth[:, 0]
[64600643, 1.2142487 × 108, 52640047] km
In [7]: vv_earth[:, 0]
[−2352414.3, 1032013.3, 447276.92]  $\frac{\text{km}}{\text{d}}$ 
In [8]: rr_mars, vv_mars = get_body_ephem("mars", times_vector)
```

```
In [9]: rr_mars[:, 0]
[-1.2314963 × 108, 1.9075251 × 108, 90809654] km

In [10]: vv_mars[:, 0]
[-1730626.7, -811069.96, -325255.38]  $\frac{\text{km}}{\text{d}}$ 
```

To compute the transfer orbit, we have the useful function `lambert`: according to a theorem with the same name, *the transfer orbit between two points in space only depends on those two points and the time it takes to go from one to the other*. We have the starting and final position and we have the time of flight: there we go!

```
In [11]: # Compute the transfer orbit!
r0 = rr_earth[:, 0]
rf = rr_mars[:, -1]

(va, vb), = iod.lambert(Sun.k, r0, rf, tof)

ss0_trans = Orbit.from_vectors(Sun, r0, va, date_launch)
ssf_trans = Orbit.from_vectors(Sun, rf, vb, date_arrival)
```

The rest of the code is boilerplate we need for a beautiful plot: we retrieve all the intermediate positions of the transfer orbit, and compute some more vectors outside of the mission time frame to decorate the plot.

This code sucks. Pull requests welcome!

```
In [12]: # Extract whole orbit of Earth, Mars and transfer (for plotting)
rr_trans = np.zeros_like(rr_earth)
rr_trans[:, 0] = r0
for ii in range(1, len(times_vector)):
    tof = (times_vector[ii] - times_vector[0]).to(u.day)
    rr_trans[:, ii] = ss0_trans.propagate(tof).r

In [13]: # Now compute the trail, better backwards
date_final = date_arrival - 1 * u.year
dt2 = (date_final - date_launch) / N

times_rest_vector = date_launch + dt2 * np.arange(N + 1)
rr_earth_rest, _ = get_body_ephem("earth", times_rest_vector)
rr_mars_rest, _ = get_body_ephem("mars", times_rest_vector)
```

The positions are in the International Standard Reference Frame, which has the Equator as the fundamental plane

And finally, we can plot the figure! There is no more magic here, just passing the position vectors to matplotlib `plot` function and adding some style to the plot.

```
In [14]: # Plot figure
# To add arrows:
# https://github.com/matplotlib/matplotlib/blob/v2.0.0/lib/matplotlib/streamplot.py#L172-L175

fig = plt.figure(figsize=(5, 5))
ax = fig.add_subplot(111, projection='3d')

def plot_body(ax, r, color, size, border=False, **kwargs):
    """Plots body in axes object.

    """
    return ax.plot(*r[:, None], marker='o', color=color, ms=size, mew=int(border), **kwargs)
```

```

# I like color
color_earth0 = '#3d4cd5'
color_earthf = '#525fd5'
color_mars0 = '#ec3941'
color_marsf = '#ec1f28'
color_sun = '#ffcc00'
color_orbit = '#888888'
color_trans = '#444444'

# Plotting orbits is easy!
ax.plot(*rr_earth.to(u.km).value, c=color_earth0)
ax.plot(*rr_mars.to(u.km).value, c=color_mars0)

ax.plot(*rr_trans.to(u.km).value, c=color_trans)

ax.plot(*rr_earth_rest.to(u.km).value, ls='--', c=color_orbit)
ax.plot(*rr_mars_rest.to(u.km).value, ls='--', c=color_orbit)

# But plotting planets feels even magical!
plot_body(ax, np.zeros(3), color_sun, 16)

plot_body(ax, r0.to(u.km).value, color_earth0, 8)
plot_body(ax, rr_earth[:, -1].to(u.km).value, color_earthf, 8)

plot_body(ax, rr_mars[:, 0].to(u.km).value, color_mars0, 8)
plot_body(ax, rf.to(u.km).value, color_marsf, 8)

# Add some text
#ax.text(-0.75e8, -3.5e8, -1.5e8, "MSL mission:\nfrom Earth to Mars", size=20, ha='center',
ax.text(r0[0].to(u.km).value * 1.4, r0[1].to(u.km).value * 0.4, r0[2].to(u.km).value * 1.25,
        "Earth at launch\n(26 Nov)", ha="left", va="bottom", #, backgroundColor='#ffffff')
ax.text(rf[0].to(u.km).value * 0.7, rf[1].to(u.km).value * 1.1, rf[2].to(u.km).value,
        "Mars at arrival\n(6 Ago)", ha="left", va="top", #, backgroundColor='#ffffff')
ax.text(-1.9e8, 8e7, 0, "Transfer\norbit", ha="right", va="center", #, backgroundColor='#fff

# Tune axes
ax.set_xlim(-3e8, 3e8)
ax.set_ylim(-3e8, 3e8)
ax.set_zlim(-3e8, 3e8)

# And finally!
ax.view_init(30, 260)
ax.set_title("MSL mission:\nfrom Earth to Mars")
fig.savefig("trans_30_260.png", bbox_inches='tight')

```

<IPython.core.display.Javascript object>

<IPython.core.display.HTML object>

And now, let's do it interactively!

```

In [15]: def go_to_mars(offset=0., tof_=6000.):
# Initial data
N = 50

date_launch = time.Time('2011-11-26 15:02', scale='utc') + offset * u.day
#date_arrival = time.Time('2012-08-06 05:17', scale='utc')
tof = tof_ * u.h

# Calculate vector of times from launch and arrival

```

```
date_arrival = date_launch + tof
dt = (date_arrival - date_launch) / N

# Idea from http://docs.astropy.org/en/stable/time/#getting-started
times_vector = date_launch + dt * np.arange(N + 1)

rr_earth, vv_earth = get_body_ephem("earth", times_vector)
rr_mars, vv_mars = get_body_ephem("mars", times_vector)

# Compute the transfer orbit!
r0 = rr_earth[:, 0]
rf = rr_mars[:, -1]

(va, vb), = iod.lambert(Sun.k, r0, rf, tof)

ss0_trans = Orbit.from_vectors(Sun, r0, va, date_launch)
ssf_trans = Orbit.from_vectors(Sun, rf, vb, date_arrival)

# Extract whole orbit of Earth, Mars and transfer (for plotting)
rr_trans = np.zeros_like(rr_earth)
rr_trans[:, 0] = r0
for ii in range(1, len(times_vector)):
    tof = (times_vector[ii] - times_vector[0]).to(u.day)
    rr_trans[:, ii] = ss0_trans.propagate(tof).r

# Better compute backwards
date_final = date_arrival - 1 * u.year
dt2 = (date_final - date_launch) / N

times_rest_vector = date_launch + dt2 * np.arange(N + 1)
rr_earth_rest, _ = get_body_ephem("earth", times_rest_vector)
rr_mars_rest, _ = get_body_ephem("mars", times_rest_vector)

# Plot figure
fig = plt.gcf()
ax = plt.gca()
ax.cla()

def plot_body(ax, r, color, size, border=False, **kwargs):
    """Plots body in axes object.

    """
    return ax.plot(*r[:, None], marker='o', color=color, ms=size, mew=int(border), **kwargs)

# I like color
color_earth0 = '#3d4cd5'
color_earthf = '#525fd5'
color_mars0 = '#ec3941'
color_marsf = '#ec1f28'
color_sun = '#ffcc00'
color_orbit = '#888888'
color_trans = '#444444'

# Plotting orbits is easy!
ax.plot(*rr_earth.to(u.km).value, color=color_earth0)
ax.plot(*rr_mars.to(u.km).value, color=color_mars0)

ax.plot(*rr_trans.to(u.km).value, color=color_trans)
ax.plot(*rr_earth_rest.to(u.km).value, ls='--', color=color_orbit)
```

```

ax.plot(*rr_mars_rest.to(u.km).value, ls='--', color=color_orbit)

# But plotting planets feels even magical!
plot_body(ax, np.zeros(3), color_sun, 16)

plot_body(ax, r0.to(u.km).value, color_earth0, 8)
plot_body(ax, rr_earth[:, -1].to(u.km).value, color_earthf, 8)

plot_body(ax, rr_mars[:, 0].to(u.km).value, color_mars0, 8)
plot_body(ax, rf.to(u.km).value, color_marsf, 8)

# Add some text
#ax.text(-0.75e8, -3.5e8, -1.5e8, "MSL mission:\nfrom Earth to Mars", size=20, ha='center')
ax.text(r0[0].to(u.km).value * 1.4, r0[1].to(u.km).value * 0.4, r0[2].to(u.km).value * 1.4,
        "Earth at launch\n({0:%b %d})".format(date_launch.datetime),
        ha="left", va="bottom", backgroundcolor='#ffffff')
ax.text(rf[0].to(u.km).value * 0.7, rf[1].to(u.km).value * 1.1, rf[2].to(u.km).value,
        "Mars at arrival\n({0:%b %d})".format(date_arrival.datetime),
        ha="left", va="top", backgroundcolor='#ffffff')
ax.text(-1.9e8, 8e7, 0, "Transfer\norbit", ha="right", va="center", backgroundcolor='#ffffff')

# Tune axes
ax.set_xlim(-3e8, 3e8)
ax.set_ylim(-3e8, 3e8)
ax.set_zlim(-3e8, 3e8)
ax.view_init(30, 260)

In [16]: fig = plt.figure(figsize=(5, 5))
        ax = fig.add_subplot(111, projection='3d')

        go_to_mars();

<IPython.core.display.Javascript object>
<IPython.core.display.HTML object>

In [17]: from ipywidgets import interact

        interact(go_to_mars, offset=(-100., 300.), tof_=(100., 12000.));

Widget Javascript not detected. It may not be installed or enabled properly.

Not bad! Hope you found it interesting. In case you didn't but are still reading, here is some music that you may
enjoy:

In [18]: from IPython.display import YouTubeVideo
        YouTubeVideo('zSgiXGELjbc')

```



2.4.5 Going to Jupiter with Python using Jupyter and poliastro

```
In [1]: %matplotlib inline
import numpy as np
import matplotlib.pyplot as plt

import astropy.units as u
from astropy.time import Time
from astropy.coordinates import solar_system_ephemeris

from poliastro.bodies import Sun, Earth, Jupiter
from poliastro.twobody import Orbit
from poliastro.maneuver import Maneuver
from poliastro.iod import izzo
from poliastro.plotting import plot, OrbitPlotter
from poliastro.util import norm

solar_system_ephemeris.set("jpl")

Out[1]: <ScienceState solar_system_ephemeris: 'jpl'>

In [2]: ## Initial data
# Links and sources: https://github.com/poliastro/poliastro/wiki/EuroPython:-Per-Python-ad-A
date_launch = Time("2011-08-05 16:25", scale='utc')
C_3 = 31.1 * u.km**2 / u.s**2
```

```

date_flyby = Time("2013-10-09 19:21", scale='utc')
date_arrival = Time("2016-07-05 03:18", scale='utc')

In [3]: # Initial state of the Earth
ss_e0 = Orbit.from_body_ephem(Earth, date_launch)
r_e0, v_e0 = ss_e0.rv()

In [4]: r_e0
[1.0246553 × 108, -1.023135 × 108, -44353346] km

In [5]: v_e0
[1847708.5, 1594323.4, 691089.12]  $\frac{\text{km}}{\text{d}}$ 

In [6]: # State of the Earth the day of the flyby
ss_efly = Orbit.from_body_ephem(Earth, date_flyby)
r_efly, v_efly = ss_efly.rv()

In [7]: # Assume that the insertion velocity is tangential to that of the Earth
dv = C_3**0.5 * v_e0 / norm(v_e0)
man = Maneuver.impulse(dv)

In [8]: # Inner Cruise 1
ic1 = ss_e0.apply_maneuver(man)
ic1.rv()

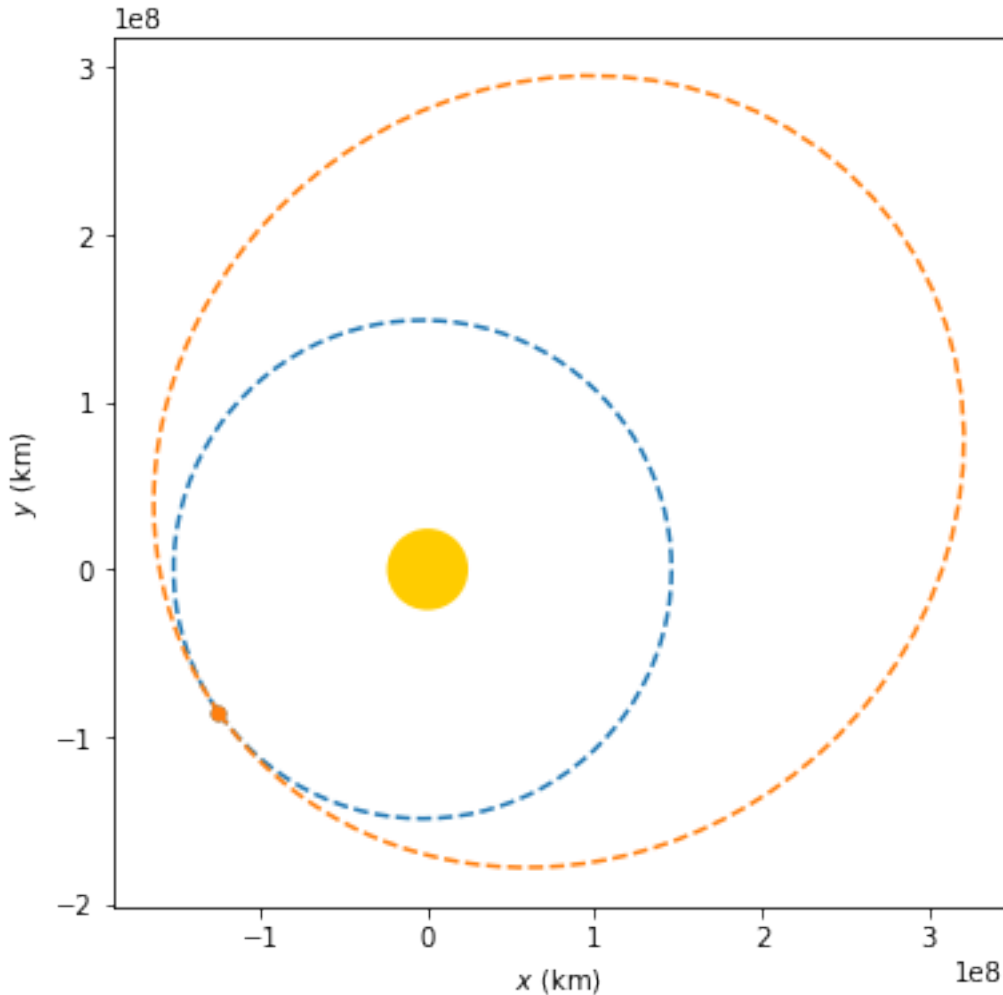
Out[8]: (<Quantity [ 1.02465527e+08, -1.02313505e+08, -4.43533465e+07] km>,
<Quantity [ 2198705.82621214, 1897186.74383867, 822370.88977492] km / d>)

In [9]: ic1.period.to(u.year)
2.1515474 yr

In [10]: op = OrbitPlotter()

op.plot(ss_e0)
op.plot(ic1)

Out[10]: [<matplotlib.lines.Line2D at 0x22d5f6f7390>,
<matplotlib.lines.Line2D at 0x22d5f6f7fd0>]
```



```
In [11]: # We propagate until the aphelion
ss_aph = ic1.propagate(ic1.period / 2)
ss_aph.epoch

Out[11]: <Time object: scale='utc' format='iso' value=2012-09-01 14:38:54.507>

In [12]: # Let's compute the Lambert solution to do the flyby of the Earth
time_of_flight = date_flyby - ss_aph.epoch
time_of_flight

Out[12]: <TimeDelta object: scale='tai' format='jd' value=403.19589691198047>

In [13]: (v_aph, v_fly), = izzo.lambert(Sun.k, ss_aph.r, ss_efly.r, time_of_flight)

In [14]: # Check the delta-V
norm(v_aph - ss_aph.v) # Too high!
1.079866  $\frac{\text{km}}{\text{s}}$ 

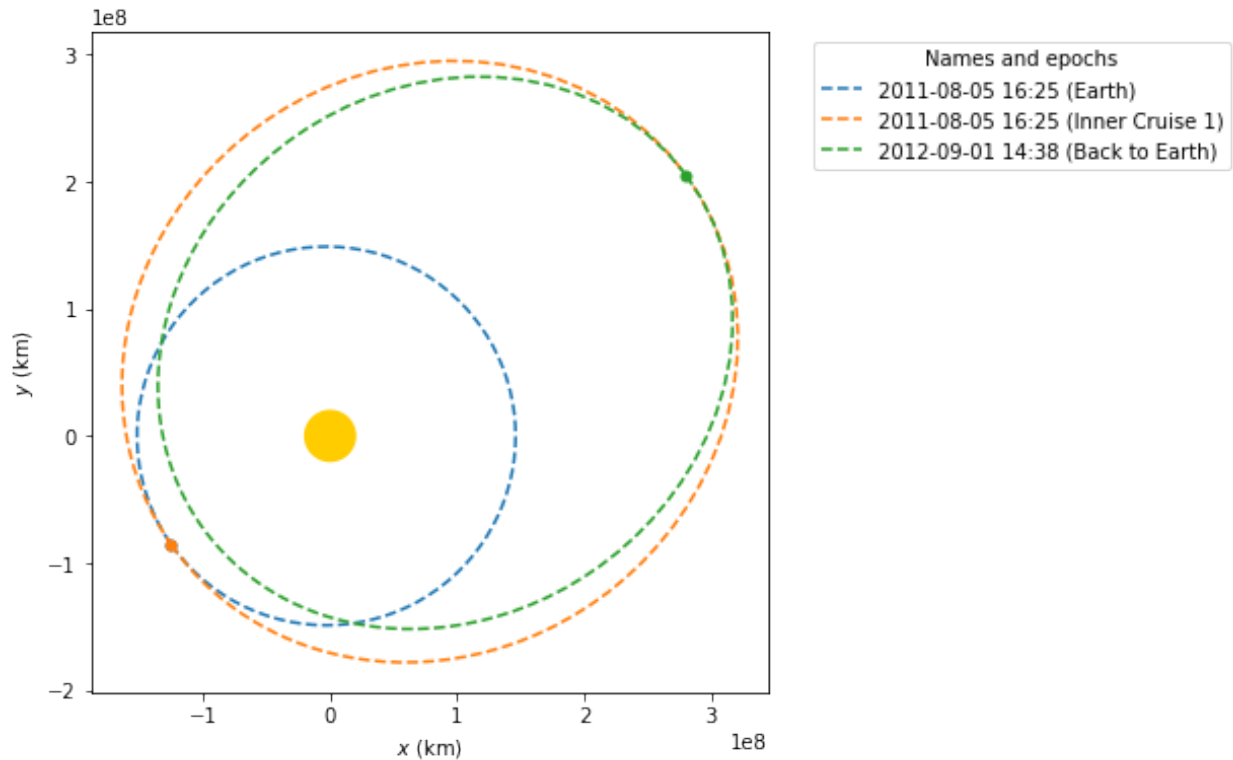
In [15]: ss_aph_post = Orbit.from_vectors(Sun, ss_aph.r, v_aph, epoch=ss_aph.epoch)
ss_junofly = Orbit.from_vectors(Sun, r_efly, v_fly, epoch=date_flyby)

In [16]: op = OrbitPlotter()

op.plot(ss_e0, label="Earth")
op.plot(ic1, label="Inner Cruise 1")
```



```
#op.plot(ss_efly)
op.plot(ss_aph_post, label="Back to Earth")
Out[16]: [<matplotlib.lines.Line2D at 0x22d612d8630>,
<matplotlib.lines.Line2D at 0x22d612d8c18>]
```



```
In [17]: # And now, go to Jupiter!
ss_j = Orbit.from_body_ephem(Jupiter, date_arrival)
r_j, v_j = ss_j.rv()

In [18]: (v_flypre, v_oip), = izzo.lambert(Sun.k, r_efly, r_j, date_arrival - date_flyby)

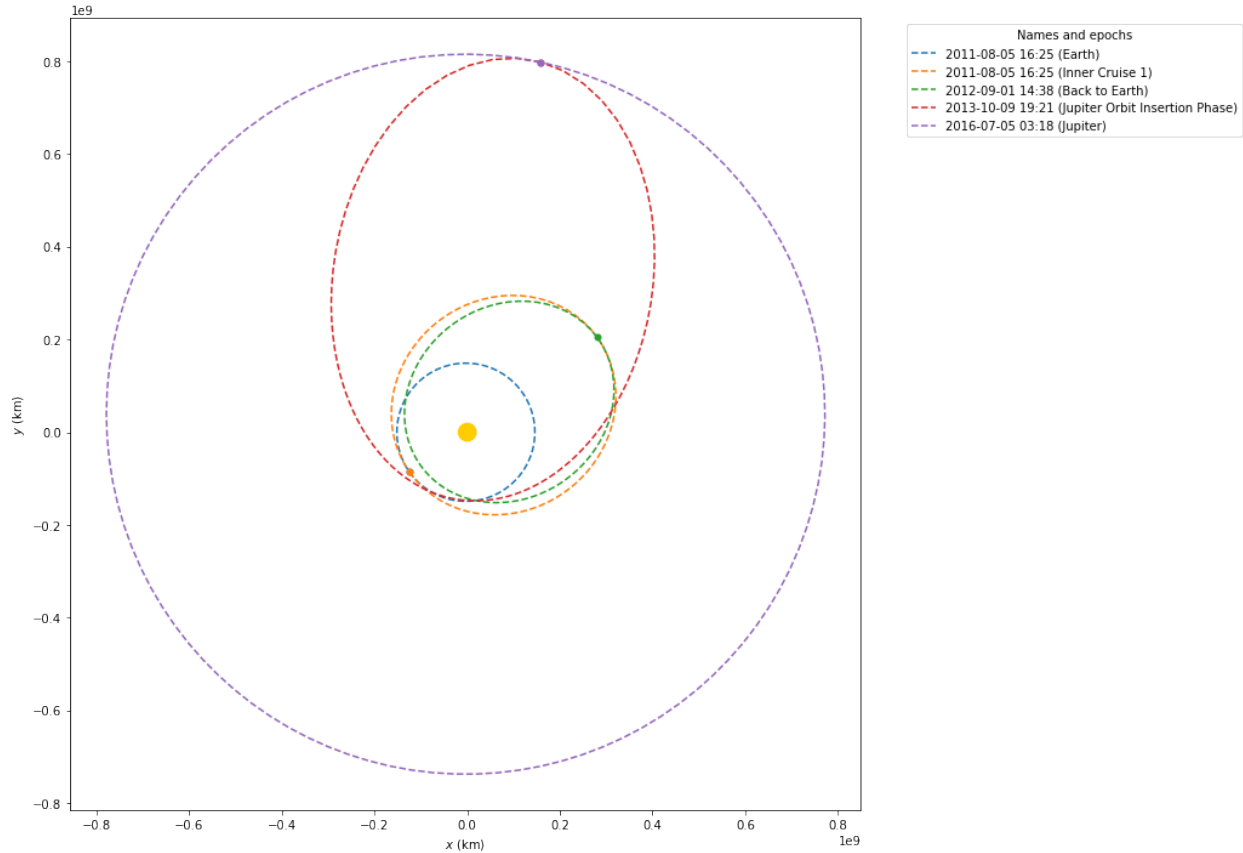
In [19]: ss_oip = Orbit.from_vectors(Sun, r_j, v_oip, epoch=date_flyby)

In [20]: fig, ax = plt.subplots(figsize=(9, 12))

op = OrbitPlotter(ax)

op.plot(ss_e0, label="Earth")
op.plot(ic1, label="Inner Cruise 1")
#op.plot(ss_efly)
op.plot(ss_aph_post, label="Back to Earth")
op.plot(ss_oip, label="Jupiter Orbit Insertion Phase")
op.plot(ss_j, label="Jupiter")

fig.savefig("jupiter.png")
```



2.4.6 Cowell's formulation

For cases where we only study the gravitational forces, solving the Kepler's equation is enough to propagate the orbit forward in time. However, when we want to take perturbations that deviate from Keplerian forces into account, we need a more complex method to solve our initial value problem: one of them is **Cowell's formulation**.

In this formulation we write the two body differential equation separating the Keplerian and the perturbation accelerations:

$$\ddot{\mathbf{r}} = -\frac{\mu}{|\mathbf{r}|^3} \mathbf{r} + \mathcal{D}_d$$

For an in-depth exploration of this topic, still to be integrated in poliastro, check out <https://github.com/Juanlu001/pfc-uc3m>

First example

Let's setup a very simple example with constant acceleration to visualize the effects on the orbit.

```
In [1]: %matplotlib inline
import numpy as np
from astropy import units as u

from matplotlib import ticker
```

```

from matplotlib import pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

from scipy.integrate import ode

from poliastro.bodies import Earth
from poliastro.twobody import Orbit
from poliastro.examples import iss

from poliastro.twobody.propagation import func_twobody

from poliastro.util import norm

from ipywidgets.widgets import interact, fixed

In [2]: def state_to_vector(ss):
        r, v = ss.rv()
        x, y, z = r.to(u.km).value
        vx, vy, vz = v.to(u.km / u.s).value
        return np.array([x, y, z, vx, vy, vz])

In [3]: u0 = state_to_vector(iss)
        u0

Out[3]: array([ 8.59072560e+02, -4.13720368e+03,  5.29556871e+03,
                7.37289205e+00,  2.08223573e+00,  4.39999794e-01])

In [4]: t = np.linspace(0, 10 * iss.period, 500).to(u.s).value
        t[:10]

Out[4]: array([  0.          ,  111.36211826,  222.72423652,  334.08635478,
                445.44847304,  556.8105913 ,  668.17270956,  779.53482782,
                890.89694608, 1002.25906434])

In [5]: dt = t[1] - t[0]
        dt

Out[5]: 111.36211825977986

In [6]: k = Earth.k.to(u.km**3 / u.s**2).value

To provide an acceleration depending on an extra parameter, we can use closures like this one:

In [7]: def constant_accel_factory(accel):
        def constant_accel(t0, u, k):
            v = u[3:]
            norm_v = (v[0]**2 + v[1]**2 + v[2]**2)**.5
            return accel * v / norm_v

        return constant_accel

        constant_accel_factory(accel=1e-5)(t[0], u0, k)

Out[7]: array([ 9.60774274e-06,  2.71339728e-06,  5.73371317e-07])

```

```
In [8]: help(func_twobody)
```

Help on function func_twobody in module poliastro.twobody.propagation:

```
func_twobody(t0, u_, k, ad)
    Differential equation for the initial value two body problem.
```

This function follows Cowell's formulation.

Parameters

```
-----
t0 : float
    Time.
u_ : ~numpy.ndarray
    Six component state vector [x, y, z, vx, vy, vz] (km, km/s).
k : float
    Standard gravitational parameter.
ad : function(t0, u, k)
    Non Keplerian acceleration (km/s2).
```

Now we setup the integrator manually using `scipy.integrate.ode`. We cannot provide the Jacobian since we don't know the form of the acceleration in advance.

```
In [9]: res = np.zeros((t.size, 6))
        res[0] = u0
        ii = 1

        accel = 1e-5

        rr = ode(func_twobody).set_integrator('dop853') # All parameters by default
        rr.set_initial_value(u0, t[0])
        rr.set_f_params(k, constant_accel_factory(accel))

        while rr.successful() and rr.t + dt < t[-1]:
            rr.integrate(rr.t + dt)
            res[ii] = rr.y
            ii += 1

        res[:5]

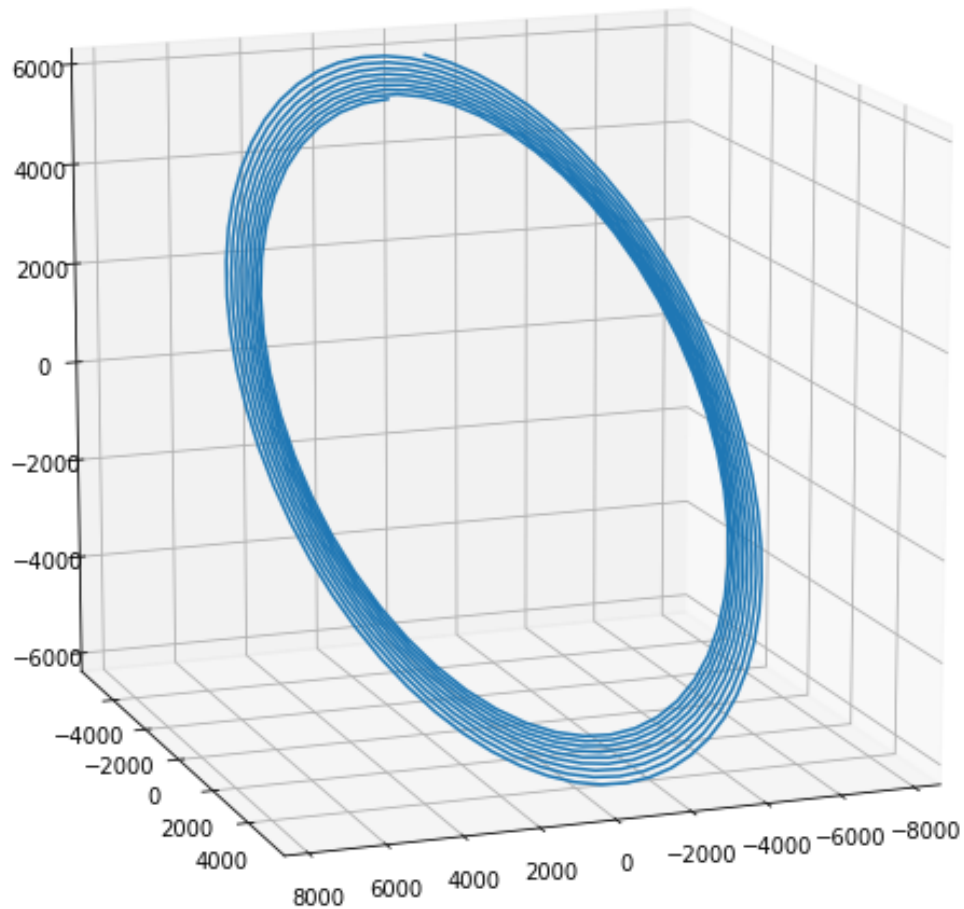
Out[9]: array([[ 8.59072560e+02, -4.13720368e+03,  5.29556871e+03,
                  7.37289205e+00,  2.08223573e+00,  4.39999794e-01],
                [ 1.67120051e+03, -3.87307888e+03,  5.30240756e+03,
                  7.19314492e+00,  2.65498748e+00, -3.17310887e-01],
                [ 2.45692273e+03, -3.54744387e+03,  5.22509021e+03,
                  6.89930296e+00,  3.18546088e+00, -1.06938976e+00],
                [ 3.20378169e+03, -3.16548222e+03,  5.06486727e+03,
                  6.49612475e+00,  3.66524400e+00, -1.80427142e+00],
                [ 3.89994802e+03, -2.73326986e+03,  4.82430776e+03,
                  5.99011730e+00,  4.08674433e+00, -2.51027603e+00]])
```

And we plot the results:

```
In [10]: fig = plt.figure(figsize=(10, 10))
         ax = fig.add_subplot(111, projection='3d')

         ax.plot(*res[:, :3].T)

         ax.view_init(14, 70)
```



Interactivity

This is the last time we used `scipy.integrate.ode` directly. Instead, we can now import a convenient function from poliastro:

```
In [11]: from poliastro.twobody.propagation import cowell

In [12]: def plot_iss(thrust=0.1, mass=2000.):
    r0, v0 = iss.rv()
    k = iss.attractor.k
    t = np.linspace(0, 10 * iss.period, 500).to(u.s).value
    u0 = state_to_vector(iss)

    res = np.zeros((t.size, 6))
    res[0] = u0
```

```
accel = thrust / mass

# Perform the whole integration
r0 = r0.to(u.km).value
v0 = v0.to(u.km / u.s).value
k = k.to(u.km**3 / u.s**2).value
ad = constant_accel_factory(accel)
r, v = r0, v0
for ii in range(1, len(t)):
    r, v = cowell(k, r, v, t[ii] - t[ii - 1], ad=ad)
    x, y, z = r
    vx, vy, vz = v
    res[ii] = [x, y, z, vx, vy, vz]

fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')

ax.set_xlim(-20e3, 20e3)
ax.set_ylim(-20e3, 20e3)
ax.set_zlim(-20e3, 20e3)

ax.view_init(14, 70)

return ax.plot(*res[:, :3].T)
```

```
In [13]: interact(plot_iss, thrust=(0.0, 0.2, 0.001), mass=fixed(2000.))
```

A Jupyter Widget

```
Out[13]: <function __main__.plot_iss>
```

Error checking

```
In [14]: rtol = 1e-13
         full_periods = 2
```

```
In [15]: u0 = state_to_vector(iss)
         tf = ((2 * full_periods + 1) * iss.period / 2).to(u.s).value

         u0, tf
```

```
Out[15]: (array([ 8.59072560e+02, -4.13720368e+03,  5.29556871e+03,
                  7.37289205e+00,  2.08223573e+00,  4.39999794e-01]),
         13892.424252907538)
```

```
In [16]: iss_f_kep = iss.propagate(tf * u.s, rtol=1e-18)
```

```
In [17]: r0, v0 = iss.rv()
         r, v = cowell(k, r0.to(u.km).value, v0.to(u.km / u.s).value, tf, rtol=rtol)
```

```
         iss_f_num = Orbit.from_vectors(Earth, r * u.km, v * u.km / u.s, iss.epoch + tf * u.s)
```

```
In [18]: iss_f_num.r, iss_f_kep.r
```

```
Out[18]: (<Quantity [ -835.92108005, 4151.60692532,-5303.60427969] km>,
         <Quantity [ -835.92108005, 4151.60692532,-5303.60427969] km>)
```

```
In [19]: assert np.allclose(iss_f_num.r, iss_f_kep.r, rtol=rtol, atol=1e-08 * u.km)
         assert np.allclose(iss_f_num.v, iss_f_kep.v, rtol=rtol, atol=1e-08 * u.km / u.s)
```

```
In [20]: #assert np.allclose(iss_f_num.a, iss_f_kep.a, rtol=rtol, atol=1e-08 * u.km)
         #assert np.allclose(iss_f_num.ecc, iss_f_kep.ecc, rtol=rtol)
         #assert np.allclose(iss_f_num.inc, iss_f_kep.inc, rtol=rtol, atol=1e-08 * u.rad)
```

```
#assert np.allclose(iss_f_num.raan, iss_f_kep.raan, rtol=rtol, atol=1e-08 * u.rad)
#assert np.allclose(iss_f_num.argp, iss_f_kep.argp, rtol=rtol, atol=1e-08 * u.rad)
#assert np.allclose(iss_f_num.nu, iss_f_kep.nu, rtol=rtol, atol=1e-08 * u.rad)
```

Too bad I cannot access the internal state of the solver. I will have to do it in a blackbox way.

```
In [21]: u0 = state_to_vector(iss)
         full_periods = 4

         tof_vector = np.linspace(0, ((2 * full_periods + 1) * iss.period / 2).to(u.s).value, num=100)
         rtol_vector = np.logspace(-3, -12, num=30)

         res_array = np.zeros((rtol_vector.size, tof_vector.size))
         for jj, tof in enumerate(tof_vector):
             rf, vf = iss.propagate(tof * u.s, rtol=1e-12).rv()
             for ii, rtol in enumerate(rtol_vector):
                 rr = ode(func_twobody).set_integrator('dop853', rtol=rtol, nsteps=1000)
                 rr.set_initial_value(u0, 0.0)
                 rr.set_f_params(k, constant_accel_factory(0.0)) # Zero acceleration

                 rr.integrate(rr.t + tof)

                 if rr.successful():
                     uf = rr.y

                     r, v = uf[:3] * u.km, uf[3:] * u.km / u.s

                     res = max(norm((r - rf) / rf), norm((v - vf) / vf))
                 else:
                     res = np.nan

                 res_array[ii, jj] = res

/home/juanlu/.miniconda36/envs/poliastro36/lib/python3.6/site-packages/scipy/integrate/_ode.py:1035:
self.messages.get(idid, 'Unexpected idid=%s' % idid))

In [22]: fig, ax = plt.subplots(figsize=(16, 6))

         xx, yy = np.meshgrid(tof_vector, rtol_vector)

         cs = ax.contourf(xx, yy, res_array, levels=np.logspace(-12, -1, num=12),
                          locator=ticker.LogLocator(), cmap=plt.cm.Spectral_r)
         fig.colorbar(cs)

         for nn in range(full_periods + 1):
             lf = ax.axvline(nn * iss.period.to(u.s).value, color='k', ls='-')
             lh = ax.axvline((2 * nn + 1) * iss.period.to(u.s).value / 2, color='k', ls='--')

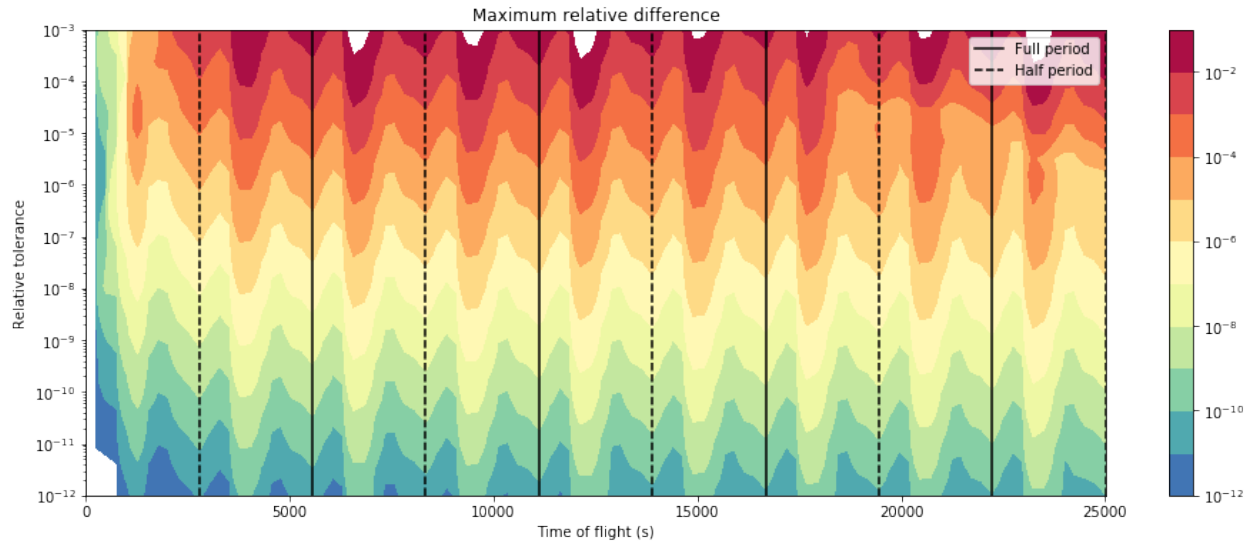
         ax.set_yscale('log')

         ax.set_xlabel("Time of flight (s)")
         ax.set_ylabel("Relative tolerance")

         ax.set_title("Maximum relative difference")

         ax.legend((lf, lh), ("Full period", "Half period"))

Out[22]: <matplotlib.legend.Legend at 0x7f9ad3788e80>
```



Numerical validation

According to [Edelbaum, 1961], a coplanar, semimajor axis change with tangent thrust is defined by:

$$\frac{da}{a_0} = 2 \frac{F}{mV_0} dt, \quad \frac{\Delta V}{V_0} = \frac{1}{2} \frac{\Delta a}{a_0}$$

So let's create a new circular orbit and perform the necessary checks, assuming constant mass and thrust (i.e. constant acceleration):

```
In [24]: ss = Orbit.circular(Earth, 500 * u.km)
         tof = 20 * ss.period

         ad = constant_accel_factory(1e-7)

         r0, v0 = ss.rv()
         r, v = cowell(k, r0.to(u.km).value, v0.to(u.km / u.s).value,
                       tof.to(u.s).value, ad=ad)

         ss_final = Orbit.from_vectors(Earth, r * u.km, v * u.km / u.s, ss.epoch + rr.t * u.s)

In [25]: da_a0 = (ss_final.a - ss.a) / ss.a
         da_a0
2.9896209 × 10-6  $\frac{\text{km}}{\text{m}}$ 

In [26]: dv_v0 = abs(norm(ss_final.v) - norm(ss.v)) / norm(ss.v)
         2 * dv_v0
0.0029960537

In [27]: np.allclose(da_a0, 2 * dv_v0, rtol=1e-2)
Out[27]: True

In [28]: dv = abs(norm(ss_final.v) - norm(ss.v))
         dv
0.011403892  $\frac{\text{km}}{\text{s}}$ 

In [29]: accel_dt = accel * u.km / u.s**2 * (t[-1] - t[0]) * u.s
         accel_dt
```


0.55569697 $\frac{\text{km}}{\text{s}}$

```
In [30]: np.allclose(dv, accel_dt, rtol=1e-2, atol=1e-8 * u.km / u.s)
```

```
Out[30]: False
```

This means **we successfully validated the model against an extremely simple orbit transfer with approximate analytical solution**. Notice that the final eccentricity, as originally noticed by Edelbaum, is nonzero:

```
In [31]: ss_final.ecc
```

6.6621428×10^{-6}

References

- [Edelbaum, 1961] “Propulsion requirements for controllable satellites”

2.4.7 Revisiting Lambert’s problem in Python

```
In [1]: %matplotlib notebook
import numpy as np
import matplotlib.pyplot as plt
from cycler import cycler

from poliastro.iod import izzo

plt.rc('text', usetex=True)
```

Part 1: Reproducing the original figure

```
In [2]: x = np.linspace(-1, 2, num=1000)
M_list = 0, 1, 2, 3
ll_list = 1, 0.9, 0.7, 0, -0.7, -0.9, -1

In [3]: fig, ax = plt.subplots(figsize=(8, 6))
ax.set_prop_cycle(cyclar('linestyle', ['- ', '--']) *
                  (cyclar('color', ['black']) * len(ll_list)))

for M in M_list:
    for ll in ll_list:
        T_x0 = np.zeros_like(x)
        for ii in range(len(x)):
            y = izzo._compute_y(x[ii], ll)
            T_x0[ii] = izzo._tof_equation(x[ii], y, 0.0, ll, M)
        if M == 0 and ll == 1:
            T_x0[x > 0] = np.nan
        elif M > 0:
            # Mask meaningless solutions
            T_x0[x > 1] = np.nan
        l, = ax.plot(x, T_x0)

ax.set_ylim(0, 10)

ax.set_xticks((-1, 0, 1, 2))
ax.set_yticks((0, np.pi, 2 * np.pi, 3 * np.pi))
ax.set_yticklabels(('0$', '\pi$', '2 \pi$', '3 \pi$'))

ax.vlines(1, 0, 10)
ax.text(0.65, 4.0, "elliptic")
```

```
ax.text(1.16, 4.0, "hyperbolic")

ax.text(0.05, 1.5, "$M = 0$", bbox=dict(facecolor='white'))
ax.text(0.05, 5, "$M = 1$", bbox=dict(facecolor='white'))
ax.text(0.05, 8, "$M = 2$", bbox=dict(facecolor='white'))

ax.annotate("$\\lambda = 1$", xy=(-0.3, 1), xytext=(-0.75, 0.25), arrowprops=dict(arrowstyle=
ax.annotate("$\\lambda = -1$", xy=(0.3, 2.5), xytext=(0.65, 2.75), arrowprops=dict(arrowstyle=

ax.grid()
ax.set_xlabel("$x$")
ax.set_ylabel("$T$")

<IPython.core.display.Javascript object>
<IPython.core.display.HTML object>
```

Part 2: Locating T_{min}

```
In [4]: for M in M_list:
        for ll in ll_list:
            x_T_min, T_min = izzo._compute_T_min(ll, M, 10, 1e-8)
            ax.plot(x_T_min, T_min, 'kx', mew=2)
```

Part 3: Try out solution

```
In [5]: T_ref = 1
        ll_ref = 0

        (x_ref, _), = izzo._find_xy(ll_ref, T_ref, 0, 10, 1e-8)
        x_ref

Out[5]: 0.43344673453504257

In [6]: ax.plot(x_ref, T_ref, 'o', mew=2, mec='red', mfc='none')

Out[6]: [<matplotlib.lines.Line2D at 0x7fb45a5d2da0>]
```

Part 4: Run some examples

```
In [7]: from astropy import units as u

        from poliastro.bodies import Earth
```

Single revolution

```
In [8]: k = Earth.k
        r0 = [15945.34, 0.0, 0.0] * u.km
        r = [12214.83399, 10249.46731, 0.0] * u.km
        tof = 76.0 * u.min

        expected_va = [2.058925, 2.915956, 0.0] * u.km / u.s
        expected_vb = [-3.451569, 0.910301, 0.0] * u.km / u.s

        (v0, v), = izzo.lambert(k, r0, r, tof)
        v
```

```
[−3.4515665, 0.91031354, 0]  $\frac{\text{km}}{\text{s}}$ 
```

```
In [9]: k = Earth.k
        r0 = [5000.0, 10000.0, 2100.0] * u.km
        r = [−14600.0, 2500.0, 7000.0] * u.km
        tof = 1.0 * u.h

        expected_va = [−5.9925, 1.9254, 3.2456] * u.km / u.s
        expected_vb = [−3.3125, −4.1966, −0.38529] * u.km / u.s

        (v0, v), = izzo.lambert(k, r0, r, tof)
        v

[−3.3124585, −4.196619, −0.38528906]  $\frac{\text{km}}{\text{s}}$ 
```

Multiple revolutions

```
In [10]: k = Earth.k
         r0 = [22592.145603, −1599.915239, −19783.950506] * u.km
         r = [1922.067697, 4054.157051, −8925.727465] * u.km
         tof = 10 * u.h

         expected_va = [2.000652697, 0.387688615, −2.666947760] * u.km / u.s
         expected_vb = [−3.79246619, −1.77707641, 6.856814395] * u.km / u.s

         expected_va_l = [0.50335770, 0.61869408, −1.57176904] * u.km / u.s
         expected_vb_l = [−4.18334626, −1.13262727, 6.13307091] * u.km / u.s

         expected_va_r = [−2.45759553, 1.16945801, 0.43161258] * u.km / u.s
         expected_vb_r = [−5.53841370, 0.01822220, 5.49641054] * u.km / u.s

In [11]: (v0, v), = izzo.lambert(k, r0, r, tof, M=0)
        v

[−3.7924662, −1.7770764, 6.8568144]  $\frac{\text{km}}{\text{s}}$ 
In [12]: (_, v_l), (_, v_r) = izzo.lambert(k, r0, r, tof, M=1)
In [13]: v_l

[−4.1833463, −1.1326273, 6.1330709]  $\frac{\text{km}}{\text{s}}$ 
In [14]: v_r

[−5.5384132, 0.018222134, 5.4964102]  $\frac{\text{km}}{\text{s}}$ 
```

2.4.8 Studying Hohmann transfers

```
In [1]: %matplotlib inline
        import numpy as np

        import matplotlib.pyplot as plt

        from astropy import units as u

        from poliastro.util import norm

        from poliastro.bodies import Earth
        from poliastro.twobody import Orbit
        from poliastro.maneuver import Maneuver
```

```

In [2]: Earth.k
3.9860044 × 1014  $\frac{\text{m}^3}{\text{s}^2}$ 

In [3]: ss_i = Orbit.circular(Earth, alt=800 * u.km)
        ss_i

Out[3]: 7178 x 7178 km x 0.0 deg orbit around Earth ()

In [4]: r_i = ss_i.a.to(u.km)
        r_i

7178.1366 km

In [5]: v_i_vec = ss_i.v.to(u.km / u.s)
        v_i = norm(v_i_vec)
        v_i

7.4518315  $\frac{\text{km}}{\text{s}}$ 

In [6]: N = 1000
        dv_a_vector = np.zeros(N) * u.km / u.s
        dv_b_vector = dv_a_vector.copy()
        r_f_vector = r_i * np.linspace(1, 100, num=N)
        for ii, r_f in enumerate(r_f_vector):
            man = Maneuver.hohmann(ss_i, r_f)
            (_, dv_a), (_, dv_b) = man.impulses
            dv_a_vector[ii] = norm(dv_a)
            dv_b_vector[ii] = norm(dv_b)

In [8]: fig, ax = plt.subplots(figsize=(7, 7))

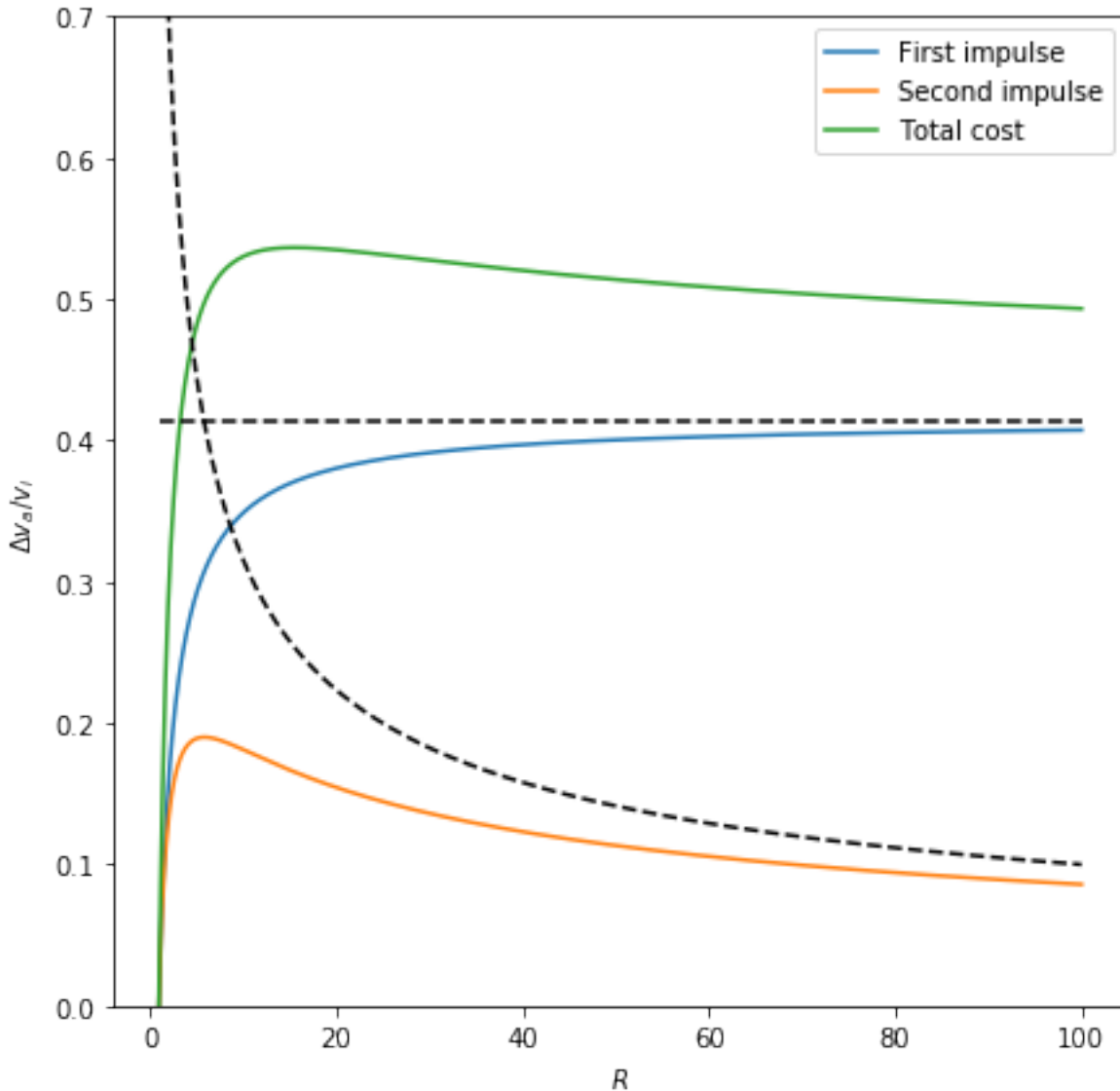
        ax.plot((r_f_vector / r_i).value, (dv_a_vector / v_i).value, label="First impulse")
        ax.plot((r_f_vector / r_i).value, (dv_b_vector / v_i).value, label="Second impulse")
        ax.plot((r_f_vector / r_i).value, ((dv_a_vector + dv_b_vector) / v_i).value, label="Total cost")

        ax.plot((r_f_vector / r_i).value, np.full(N, np.sqrt(2) - 1), 'k--')
        ax.plot((r_f_vector / r_i).value, (1 / np.sqrt(r_f_vector / r_i)).value, 'k--')

        ax.set_ylim(0, 0.7)
        ax.set_xlabel("$R$")
        ax.set_ylabel("$\Delta v_a / v_i$")

        plt.legend()
        fig.savefig("hohmann.png")

```



2.4.9 Using NEOS package

With the new poliastro version (0.7.0), a new package is included: [NEOs package](#).

The docstrings of this package states the following:

Functions related to NEOs and different NASA APIs. All of them are coded as part of SOCIS 2017 proposal.

So, first of all, an important question:

What are NEOs?

NEO stands for near-Earth object. The Center for NEO Studies ([CNEOS](#)) defines NEOs as comets and asteroids that have been nudged by the gravitational attraction of nearby planets into orbits that allow them to enter the Earth's neighborhood.

And what does “near” exactly mean? In terms of orbital elements, asteroids and comets can be considered NEOs if their perihelion (orbit point which is nearest to the Sun) is less than $1.3 \text{ au} = 1.945 * 10^8 \text{ km}$ from the Sun.

```
In [1]: %matplotlib inline

        from astropy import time
        from poliastro.twobody.orbit import Orbit
        from poliastro.bodies import Earth
        from poliastro.plotting import OrbitPlotter
```

NeoWS module

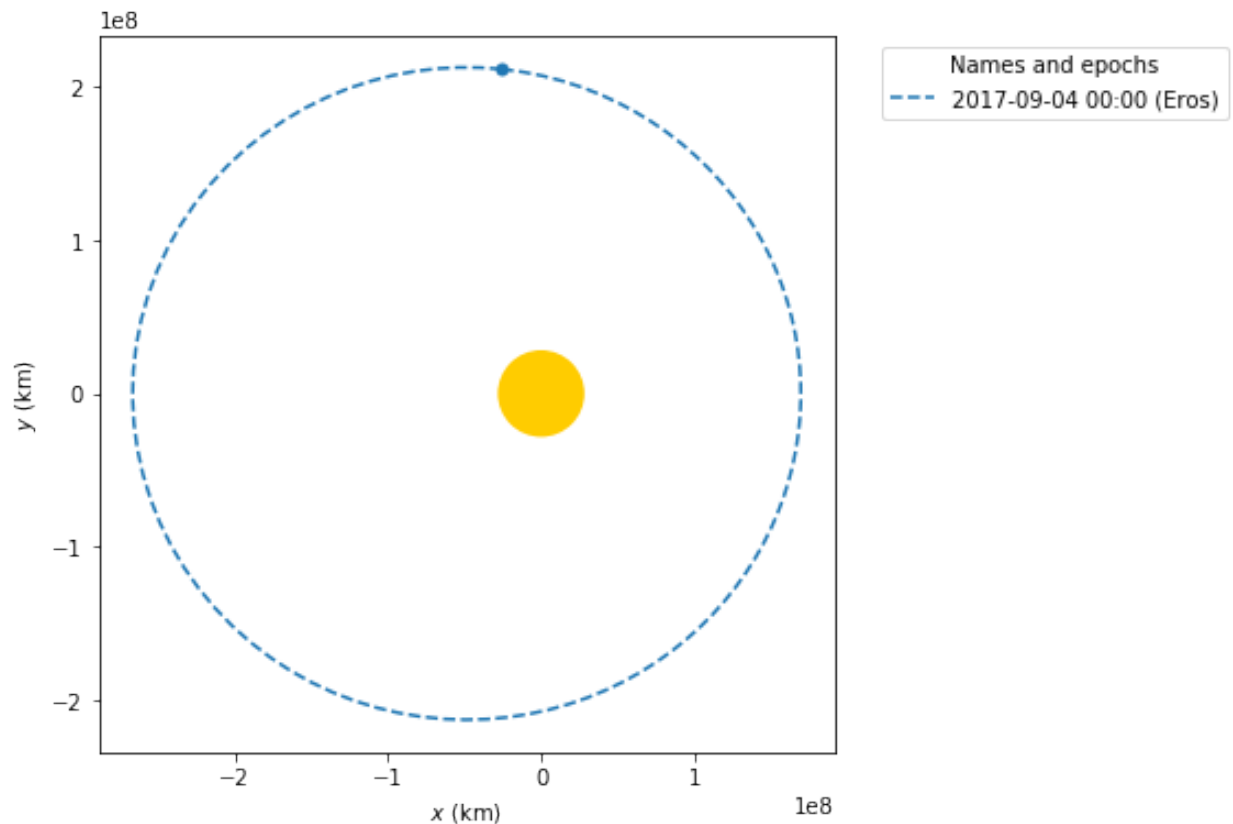
This module make requests to [NASA NEO Webservice](#), so you’ll need an internet connection to run the next examples.

The simplest neows function is `orbit_from_name()`, which return an `Orbit` object given a name:

```
In [2]: from poliastro.neos import neows
In [3]: eros = neows.orbit_from_name('Eros')

        frame = OrbitPlotter()
        frame.plot(eros, label='Eros')

Out[3]: [<matplotlib.lines.Line2D at 0x7fe2970f80f0>,
         <matplotlib.lines.Line2D at 0x7fe2970f89e8>]
```



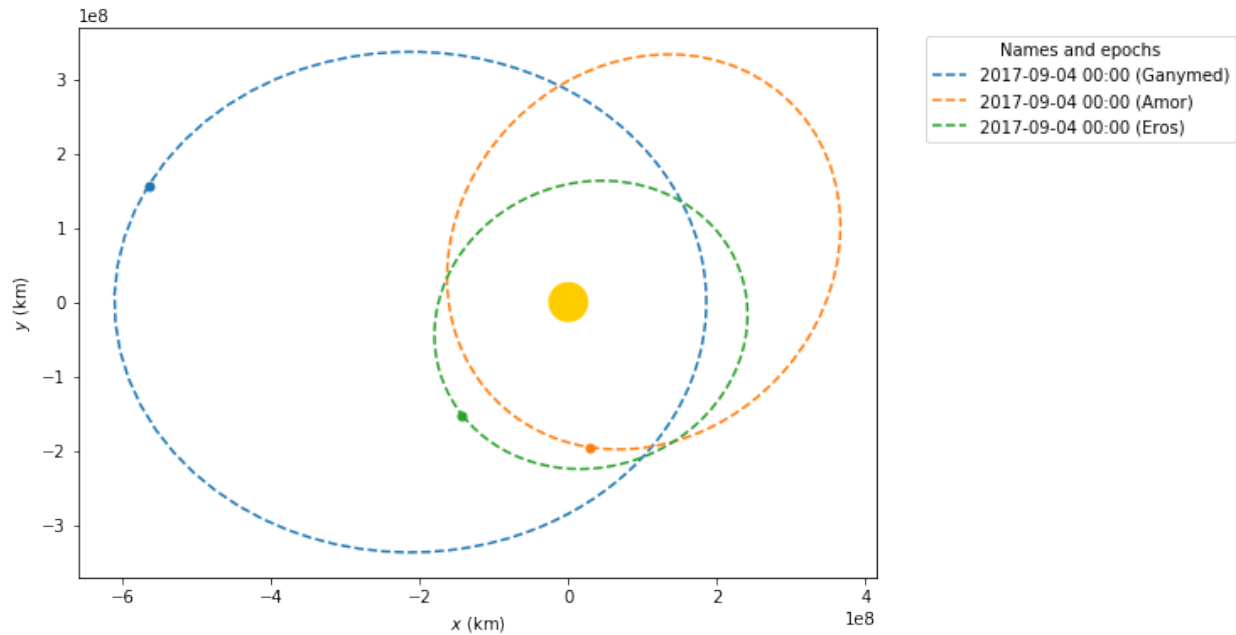
You can also search by IAU number or SPK-ID (there is a faster `neows.orbit_from_spk_id()` function in that case, although):

```
In [4]: ganymed = neows.orbit_from_name('1036') # Ganymed IAU number
        amor = neows.orbit_from_name('2001221') # Amor SPK-ID
```

```
eros = neows.orbit_from_spk_id('2000433') # Eros SPK-ID

frame = OrbitPlotter()
frame.plot(ganymed, label='Ganymed')
frame.plot(amor, label='Amor')
frame.plot(eros, label='Eros')
```

```
Out[4]: [<matplotlib.lines.Line2D at 0x7fe296e03be0>,
         <matplotlib.lines.Line2D at 0x7fe296e03dd8>]
```



Since `neows` relies on [Small-Body Database browser](#) to get the SPK-ID given a body name, you can use the wildcards from that browser: `*` and `?`.

Keep it in mind that `orbit_from_name()` can only return one Orbit, so if several objects are found with that name, it will raise an error with the different bodies.

```
In [5]: neows.orbit_from_name('*alley')
```

```
-----
ValueError                                Traceback (most recent call last)
```

```
<ipython-input-5-8e1358d8245f> in <module>()
```

```
----> 1 neows.orbit_from_name('*alley')
```

```
~/Development/poliastro/poliastro-library/src/poliastro/neos/neows.py in orbit_from_name(name, api_key)
```

```
126
```

```
127     """
```

```
--> 128     spk_id = spk_id_from_name(name)
```

```
129     if spk_id is not None:
```

```
130         return orbit_from_spk_id(spk_id, api_key)
```

```
~/Development/poliastro/poliastro-library/src/poliastro/neos/neows.py in spk_id_from_name(name)
```

```
101     for body in object_list[:obj_num]:
```

```
102         bodies += body.string + '\n'
```

```
--> 103         raise ValueError(str(len(object_list)) + ' different bodies found:\n' + bodies)
```

```
104     else:
```

```
105         raise ValueError('Object could not be found. You can visit: ' +  
  
ValueError: 6 different bodies found:  
903 Nealley (1918 EM)  
2688 Halley (1982 HG1)  
14182 Alley (1998 WG12)
```

Note that epoch is provided by the Web Service itself, so if you need orbit on another epoch, you have to propagate it:

```
In [6]: eros.epoch.iso  
Out[6]: '2017-09-04 00:00'  
  
In [7]: epoch = time.Time(2458000.0, scale='tdb', format='jd')  
        eros_november = eros.propagate(epoch)  
        eros_november.epoch.iso  
Out[7]: '2017-09-03 12:00'
```

Given that we are using NASA APIs, there is a maximum number of requests. If you want to make many requests, it is recommended getting a [NASA API key](#). You can use your API key adding the `api_key` parameter to the function:

```
In [8]: neows.orbit_from_name('Toutatis', api_key='DEMO_KEY')  
Out[8]: 1 x 4 AU x 0.4 deg orbit around Sun ()
```

DASTCOM5 module

This module can also be used to get NEOs orbit, in the same way that `neows`, but it have some advantages (and some disadvantages).

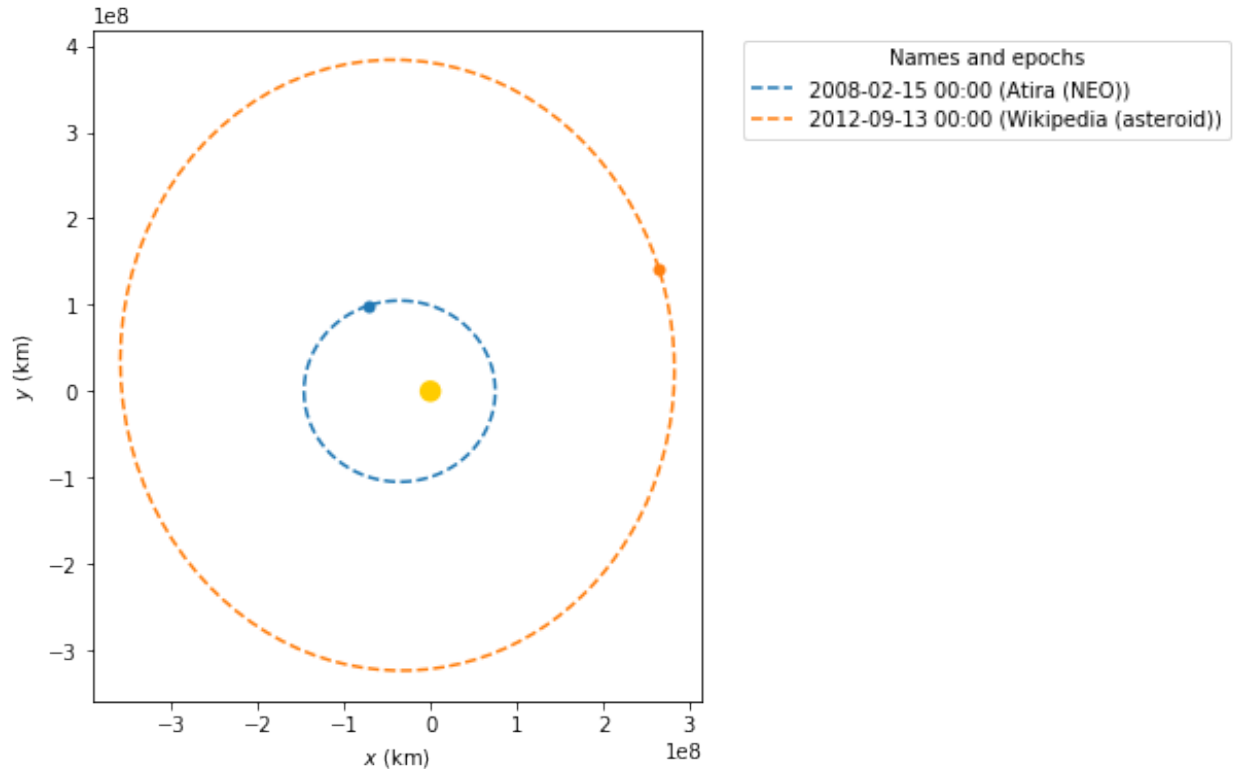
It relies on DASTCOM5 database, a NASA/JPL maintained asteroid and comet database. This database has to be downloaded at least once in order to use this module. According to its README, it is updated typically a couple times per day, but potentially as frequently as once per hour, so you can download it whenever you want the more recently discovered bodies. This also means that, after downloading the file, you can use the database offline.

The file is a ~230 MB zip that you can manually [download](#) and unzip in `~/.poliastro` or, more easily, you can use

```
dastcom5.download_dastcom5()
```

The main DASTCOM5 advantage over NeoWs is that you can use it to search not only NEOs, but any asteroid or comet. The easiest function is `orbit_from_name()`:

```
In [9]: from poliastro.neos import dastcom5  
  
In [10]: atira = dastcom5.orbit_from_name('atira')[0] # NEO  
        wikipedia = dastcom5.orbit_from_name('wikipedia')[0] # Asteroid, but not NEO.  
        frame = OrbitPlotter()  
        frame.plot(atira, label='Atira (NEO)')  
        frame.plot(wikipedia, label='Wikipedia (asteroid)')  
  
Out[10]: [<matplotlib.lines.Line2D at 0x22c8cdf2828>,  
        <matplotlib.lines.Line2D at 0x22c8cdf2a58>]
```

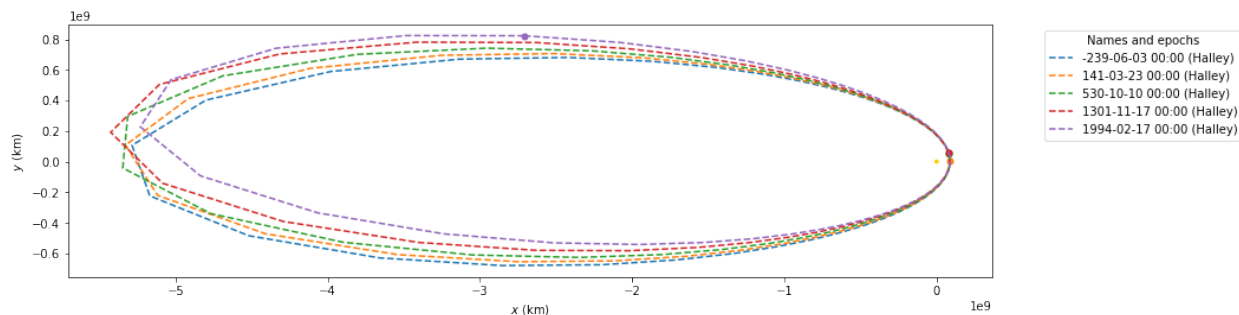



Keep in mind that this function returns a list of orbits matching your string. This is made on purpose given that there are comets which have several records in the database (one for each orbit determination in history) what allow plots like this one:

```
In [11]: halleys = dastcom5.orbit_from_name('1P')

frame = OrbitPlotter()
frame.plot(halleys[0], label='Halley')
frame.plot(halleys[5], label='Halley')
frame.plot(halleys[10], label='Halley')
frame.plot(halleys[20], label='Halley')
frame.plot(halleys[-1], label='Halley')

Out[11]: [<matplotlib.lines.Line2D at 0x22c8cb79668>,
<matplotlib.lines.Line2D at 0x22c8cb34e80>]
```



While neows can only be used to get Orbit objects, dastcom5 can also provide asteroid and comet complete database. Once you have this, you can get specific data about one or more bodies. The complete databases are ndarrays, so if you want to know the entire list of available parameters, you can look at the dtype, and they are also explained in [documentation API Reference](#):

```
In [12]: ast_db = dastcom5.asteroid_db()
        comet_db = dastcom5.comet_db()
        ast_db.dtype.names[:20] # They are more than 100, but that would be too much lines in this I

Out[12]: ('NO',
          'NOBS',
          'OBSFRST',
          'OBSLAST',
          'EPOCH',
          'CALEPO',
          'MA',
          'W',
          'OM',
          'IN',
          'EC',
          'A',
          'QR',
          'TP',
          'TPCAL',
          'TPFRAC',
          'SOLDAT',
          'SRC1',
          'SRC2',
          'SRC3')
```

Asteroid and comet parameters are not exactly the same (although they are very close):

With these `ndarrays` you can classify asteroids and comets, sort them, get all their parameters, and whatever comes to your mind.

For example, NEOs can be grouped in several ways. One of the NEOs group is called *Atiras*, and is formed by NEOs whose orbits are contained entirely with the orbit of the Earth. They are a really little group, and we can try to plot all of these NEOs using `asteroid_db()`:

Talking in orbital terms, *Atiras* have an aphelion distance, $Q < 0.983$ au and a semi-major axis, $a < 1.0$ au. Visiting [documentation API Reference](#), you can see that DASTCOM5 provides semi-major axis, but doesn't provide aphelion distance. You can get aphelion distance easily knowing perihelion distance (q , `QR` in DASTCOM5) and semi-major axis $Q = 2*a - q$, but there are probably many other ways.

```
In [13]: aphelion_condition = 2 * ast_db['A'] - ast_db['QR'] < 0.983
        axis_condition = ast_db['A'] < 1.3
        atiras = ast_db[aphelion_condition & axis_condition]
```

The number of *Atira* NEOs we use using this method is:

```
In [14]: len(atiras)

Out[14]: 16
```

Which is consistent with the [stats published by CNEOS](#)

Now we're gonna plot all of their orbits, with corresponding labels, just because we love plots :)

```
In [15]: from poliastro.twobody.orbit import Orbit
        from poliastro.bodies import Earth

        earth = Orbit.from_body_ephem(Earth)
```

We only need to get the 16 orbits from these 16 `ndarrays`.

There are two ways:

- Gather all their orbital elements manually and use the `Orbit.from_classical()` function.
- Use the `NO` property (logical record number in DASTCOM5 database) and the `dastcom5.orbit_from_record()` function.

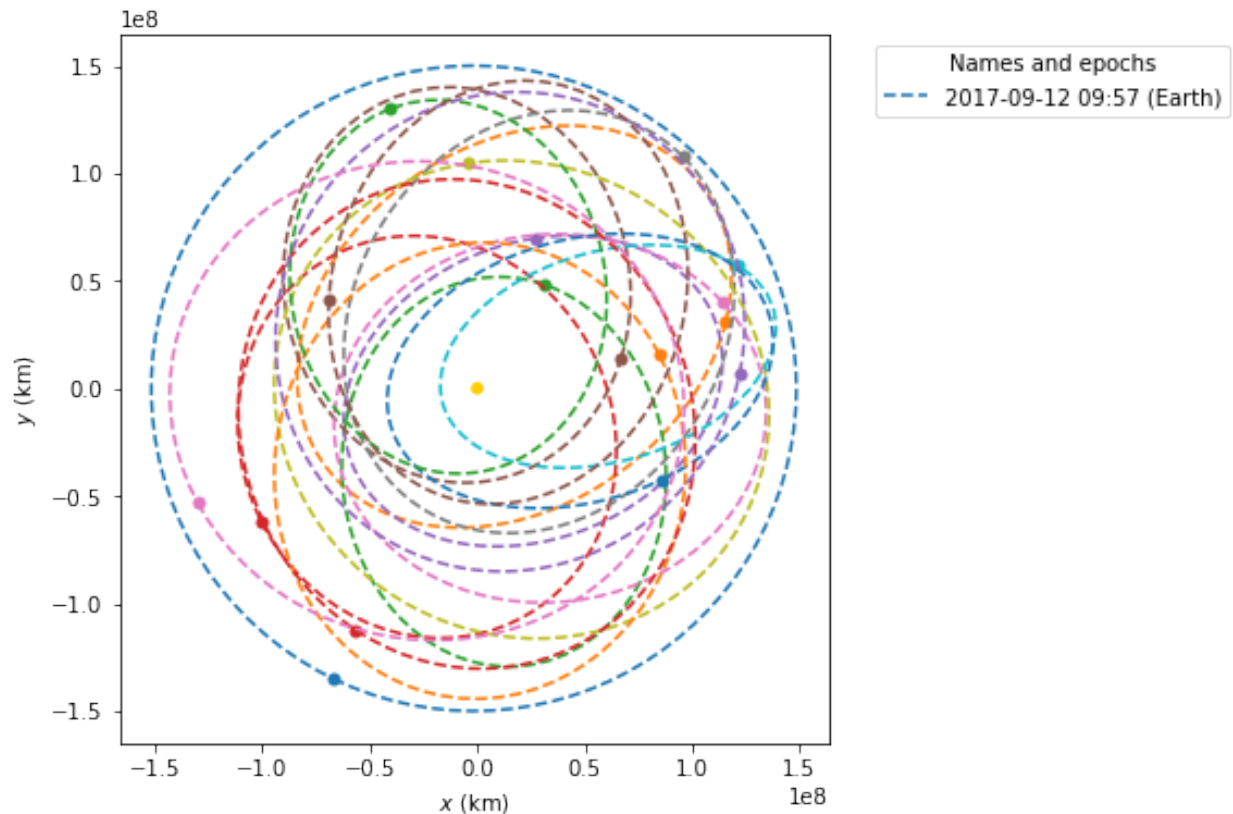
The second one seems easier and it is related to the current notebook, so we are going to use that one:

We are going to use `ASTNAM` property of DASTCOM5 database:

```
In [16]: frame = OrbitPlotter()

         frame.plot(earth, label='Earth')

         for record in atiras['NO']:
             ss = dastcom5.orbit_from_record(record)
             frame.plot(ss)
```



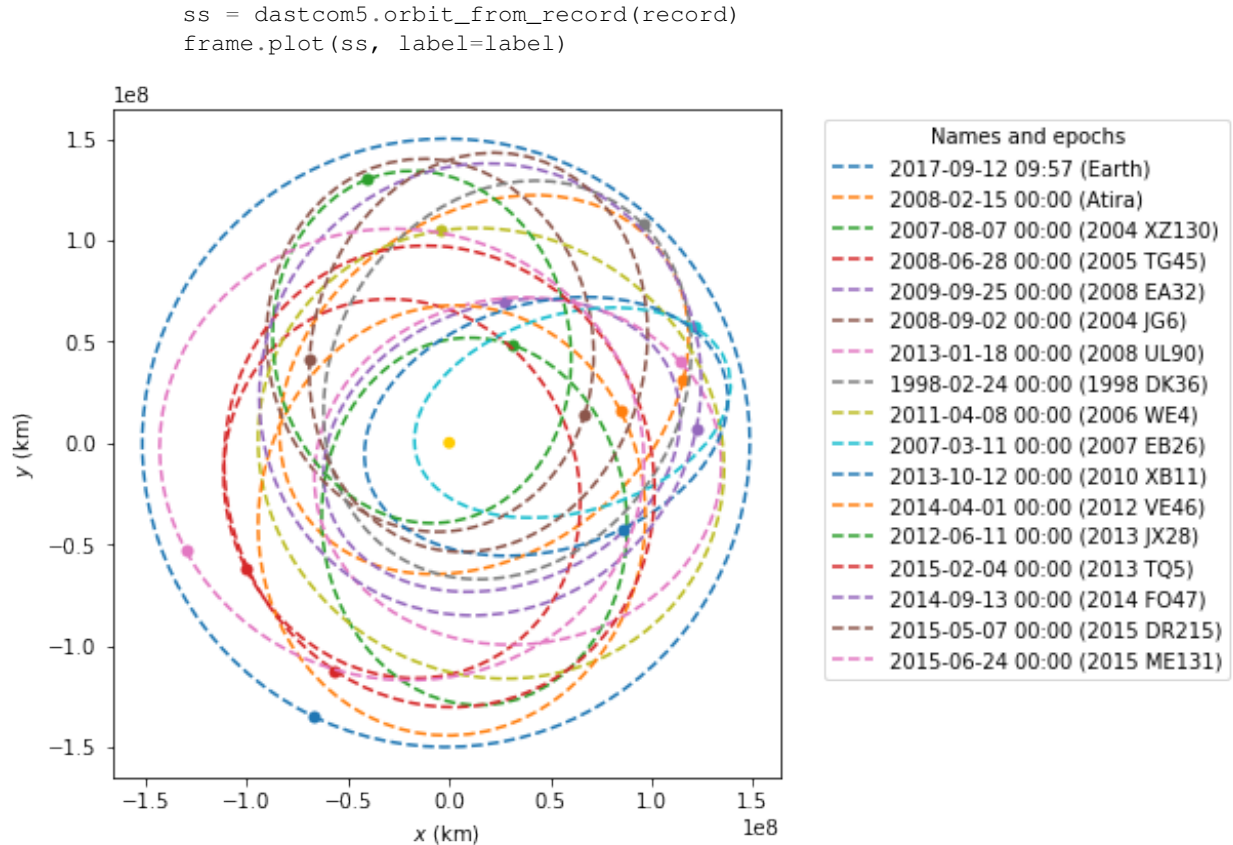
This is slightly incorrect, given that Earth coordinates are in a different frame from asteroids. However, for the purpose of this notebook, the effect is barely noticeable.

If we needed also the names of each asteroid, we could do:

```
In [17]: frame = OrbitPlotter()

         frame.plot(earth, label='Earth')

         for i in range(len(atiras)):
             record = atiras['NO'][i]
             label = atiras['ASTNAM'][i].decode().strip() # DASTCOM5 strings are binary
```



We knew beforehand that there are no Atira comets, only asteroids (comet orbits are usually more eccentric), but we could use the same method with `com_db` if we wanted.

Finally, another interesting function in `dastcom5` is `entire_db()`, which is really similar to `ast_db` and `com_db`, but it returns a Pandas dataframe instead of a numpy ndarray. The dataframe has asteroids and comets in it, but in order to achieve that (and a more manageable dataframe), a lot of parameters were removed, and others were renamed:

```
In [18]: db = dastcom5.entire_db()
db.columns
```

```
Out[18]: Index(['NUMBER', 'NOBS', 'OBSFRST', 'OBSLAST', 'EPOCH', 'CALEPOCH', 'MA', 'W',
               'OM', 'IN', 'EC', 'A', 'QR', 'TP', 'TPCAL', 'TPFRAC', 'SOLDAT', 'DESIG',
               'IREF', 'NAME'],
              dtype='object')
```

Also, in this function, DASTCOM5 data (specially strings) is ready to use (decoded and improved strings, etc):

```
In [19]: db[db.NAME == 'Halley'] # As you can see, Halley is the name of an asteroid too, did you know?
```

```
Out[19]:
```

NUMBER	NOBS	OBSFRST	OBSLAST	EPOCH	CALEPOCH	MA	\
2687	2688	1732	19500814	20160827	2455701.5	20110520.0	22.786977
737341	900001	161	0	0	1633920.5	-2390607.0	0.165294
737342	900002	161	0	0	1661840.5	-1631115.0	0.031113
737343	900003	161	0	0	1689880.5	-860823.0	0.211345
737344	900004	161	0	0	1717320.5	-111008.0	359.963217
737345	900005	161	0	0	1745200.5	660206.0	0.142118
737346	900006	161	0	0	1772640.5	1410324.0	0.019990

737347	900007	161	0	0	1800800.5	2180429.0	359.761537
737348	900008	161	0	0	1828920.5	2950425.0	0.057332
737349	900009	161	0	0	1857720.5	3740301.0	0.158377
737350	900010	161	0	0	1885960.5	4510625.0	359.959606
737351	900011	161	0	0	1914920.5	5301008.0	0.135791
737352	900012	161	0	0	1942840.5	6070318.0	0.032109
737353	900013	161	0	0	1971160.5	6840929.0	359.952171
737354	900014	161	0	0	1998800.5	7600602.0	0.157833
737355	900015	161	0	0	2026840.5	8370310.0	0.124640
737356	900016	161	0	0	2054360.5	9120714.0	359.940520
737357	900017	161	0	0	2082520.5	9890819.0	359.774025
737358	900018	161	0	0	2110480.5	10660308.0	359.839206
737359	900019	161	0	0	2139360.5	11450402.0	359.793477
737360	900020	161	0	0	2167680.5	12221015.0	0.201554
737361	900021	161	0	0	2196560.5	13011109.0	0.179564
737362	900022	161	0	0	2224680.5	13781105.0	359.927910
737363	900023	161	0	0	2253040.5	14560628.0	0.234781
737364	900024	161	0	0	2280480.5	15310814.0	359.842327
737365	900025	161	0	0	2308300.5	16071024.0	359.954121
737366	900026	161	0	0	2308300.5	16071024.0	359.954121
737367	900027	278	0	0	2335640.5	16820831.0	359.805545
737368	900028	278	0	0	2335640.5	16820831.0	359.805545
737369	900029	718	0	0	2363600.5	17590321.0	0.101706
737370	900030	718	0	0	2363600.5	17590321.0	0.101706
737371	900031	653	0	0	2391600.5	18351118.0	0.020156
737372	900032	653	0	0	2418800.5	19100509.0	0.243754
737373	900033	7428	18350821	19940111	2449400.5	19940217.0	38.384264

	W	OM	IN	EC	A	QR \
2687	183.484408	95.422520	3.454589	0.143215	3.165183	2.711882
737341	88.110000	30.810000	163.470000	0.967600	18.067901	0.585400
737342	89.110000	32.060000	163.700000	0.967700	18.095975	0.584500
737343	90.778000	34.018000	163.340000	0.967680	18.118812	0.585600
737344	92.559000	35.904000	163.589000	0.967370	17.995709	0.587200
737345	92.652000	36.129000	163.577000	0.967550	18.030817	0.585100
737346	93.694000	37.219000	163.437000	0.967840	18.132463	0.583140
737347	94.147000	37.908000	163.574000	0.967980	18.159588	0.581470
737348	95.241000	39.111000	163.367000	0.968750	18.429120	0.575910
737349	96.510000	40.579000	163.542000	0.968590	18.375995	0.577190
737350	97.028000	41.210000	163.479000	0.968910	18.454165	0.573740
737351	97.582000	41.974000	163.394000	0.968710	18.395334	0.575590
737352	98.799000	43.261000	163.476000	0.968040	18.173655	0.580830
737353	99.149000	43.800000	163.418000	0.968150	18.197174	0.579580
737354	99.997000	44.687000	163.443000	0.967850	18.097667	0.581840
737355	100.101000	44.930000	163.447000	0.967810	18.090090	0.582320
737356	100.777000	45.646000	163.311000	0.968070	18.169746	0.580160
737357	101.484000	46.561000	163.399000	0.967890	18.122392	0.581910
737358	102.473000	47.624000	163.112000	0.968870	18.454867	0.574500
737359	103.704000	49.054000	163.224000	0.968790	18.416854	0.574790
737360	103.849000	49.304000	163.192000	0.968840	18.427792	0.574210
737361	104.500000	50.152000	163.076000	0.968930	18.432893	0.572710
737362	105.295000	51.020000	163.113000	0.968370	18.216883	0.576200
737363	105.835000	51.866000	162.890000	0.968000	18.115625	0.579700
737364	106.976000	53.057000	162.917000	0.967750	18.021705	0.581200
737365	107.550300	53.770100	162.905500	0.967490	17.951861	0.583615
737366	107.550300	53.770100	162.905500	0.967490	17.951861	0.583615
737367	109.221400	55.566900	162.264900	0.967933	18.168865	0.582621
737368	109.221400	55.566900	162.264900	0.967933	18.168865	0.582621
737369	110.709300	57.245800	162.372500	0.967686	18.087083	0.584466

737370	110.709300	57.245800	162.372500	0.967686	18.087083	0.584466
737371	110.704300	57.518500	162.258800	0.967394	17.989419	0.586563
737372	111.737100	58.562900	162.218600	0.967302	17.958530	0.587208
737373	111.332485	58.420081	162.262691	0.967143	17.834144	0.585978

	TP	TPCAL	TPFRAC	SOLDAT	DESIG \
2687	2.455571e+06	2.011011e+07	0.309024	2.457850e+06	1982 HG1
737341	1.633908e+06	-2.390525e+06	0.620000	0.000000e+00	1P
737342	1.661838e+06	-1.631113e+06	0.070000	0.000000e+00	1P
737343	1.689864e+06	-8.608065e+05	0.962000	0.000000e+00	1P
737344	1.717323e+06	-1.110108e+05	0.349000	0.000000e+00	1P
737345	1.745189e+06	6.601260e+05	0.460000	0.000000e+00	1P
737346	1.772639e+06	1.410322e+06	0.934000	0.000000e+00	1P
737347	1.800819e+06	2.180518e+06	0.223000	0.000000e+00	1P
737348	1.828916e+06	2.950420e+06	0.898000	0.000000e+00	1P
737349	1.857708e+06	3.740216e+06	0.842000	0.000000e+00	1P
737350	1.885964e+06	4.510628e+06	0.749000	0.000000e+00	1P
737351	1.914910e+06	5.300927e+06	0.630000	0.000000e+00	1P
737352	1.942838e+06	6.070315e+06	0.976000	0.000000e+00	1P
737353	1.971164e+06	6.841003e+06	0.267000	0.000000e+00	1P
737354	1.998788e+06	7.600521e+06	0.171000	0.000000e+00	1P
737355	2.026831e+06	8.370228e+06	0.770000	0.000000e+00	1P
737356	2.054365e+06	9.120719e+06	0.174000	0.000000e+00	1P
737357	2.082538e+06	9.890906e+06	0.188000	0.000000e+00	1P
737358	2.110493e+06	1.066032e+07	0.434000	0.000000e+00	1P
737359	2.139377e+06	1.145042e+07	0.061000	0.000000e+00	1P
737360	2.167664e+06	1.222093e+07	0.323000	0.000000e+00	1P
737361	2.196546e+06	1.301103e+07	0.082000	0.000000e+00	1P
737362	2.224686e+06	1.378111e+07	0.187000	0.000000e+00	1P
737363	2.253022e+06	1.456061e+07	0.133000	0.000000e+00	1P
737364	2.280493e+06	1.531083e+07	0.739000	0.000000e+00	1P
737365	2.308304e+06	1.607103e+07	0.040600	0.000000e+00	1P
737366	2.308304e+06	1.607103e+07	0.040600	0.000000e+00	1P
737367	2.335656e+06	1.682092e+07	0.779400	0.000000e+00	1P
737368	2.335656e+06	1.682092e+07	0.779400	0.000000e+00	1P
737369	2.363593e+06	1.759031e+07	0.562300	0.000000e+00	1P
737370	2.363593e+06	1.759031e+07	0.562300	0.000000e+00	1P
737371	2.391599e+06	1.835112e+07	0.939600	0.000000e+00	1P
737372	2.418782e+06	1.910042e+07	0.678500	0.000000e+00	1P
737373	2.446467e+06	1.986021e+07	0.395317	2.452124e+06	1P

	IREF	NAME
2687	23	Halley
737341	SAO/-239	Halley
737342	SAO/-163	Halley
737343	SAO/-86	Halley
737344	SAO/-11	Halley
737345	SAO/66	Halley
737346	SAO/141	Halley
737347	SAO/218	Halley
737348	SAO/295	Halley
737349	SAO/374	Halley
737350	SAO/451	Halley
737351	SAO/530	Halley
737352	SAO/607	Halley
737353	SAO/684	Halley
737354	SAO/760	Halley
737355	SAO/837	Halley
737356	SAO/912	Halley

```

737357    SAO/989    Halley
737358    SAO/1066   Halley
737359    SAO/1145   Halley
737360    SAO/1222   Halley
737361    SAO/1301   Halley
737362    SAO/1378   Halley
737363    SAO/1456   Halley
737364    SAO/1531   Halley
737365      H593/0   Halley
737366    SAO/1607   Halley
737367      I353/0   Halley
737368    SAO/1682   Halley
737369      J103/0   Halley
737370    SAO/1759   Halley
737371    SAO/1835   Halley
737372    SAO/1910   Halley
737373      J863/77   Halley

```

Panda offers many functionalities, and can also be used in the same way as the `ast_db` and `comet_db` functions:

```

In [20]: aphelion_condition = (2 * db['A'] - db['QR']) < 0.983
        axis_condition = db['A'] < 1.3
        atiras = db[aphelion_condition & axis_condition]

In [21]: len(atiras)

Out[21]: 347

```

What? I said they can be used in the same way!

Dont worry :) If you want to know what's happening here, the only difference is that we are now working with comets too, and some comets have a negative semi-major axis!

```

In [22]: len(atiras[atiras.A < 0])

Out[22]: 331

```

So, rewriting our condition:

```

In [23]: axis_condition = (db['A'] < 1.3) & (db['A'] > 0)
        atiras = db[aphelion_condition & axis_condition]
        len(atiras)

Out[23]: 16

```

2.5 References

Nanos gigantum humeris insidentes.

2.5.1 Books and papers

Several books and articles are mentioned across the documentation and the source code itself. Here is the complete list in no particular order:

- Vallado, David A., and Wayne D. McClain. *Fundamentals of astrodynamics and applications*. Vol. 12. Springer Science & Business Media, 2001.
- Curtis, Howard. *Orbital mechanics for engineering students*. Butterworth-Heinemann, 2013.
- Bate, Roger R., Donald D. Mueller, William W. Saylor, and Jerry E. White. *Fundamentals of astrodynamics: (dover books on physics)*. Dover publications, 2013.

- Battin, Richard H. *An introduction to the mathematics and methods of astrodynamics*. Aiaa, 1999.
- Edelbaum, Theodore N. “Propulsion requirements for controllable satellites.” *ARS Journal* 31, no. 8 (1961): 1079-1089.
- Walker, M. J. H., B. Ireland, and Joyce Owens. “A set modified equinoctial orbit elements.” *Celestial Mechanics* 36.4 (1985): 409-419.

2.5.2 Software

poliastro wouldn’t be possible without the tremendous, often unpaid and unrecognised effort of thousands of volunteers who devote a significant part of their lives to provide the best software money can buy, for free. This is a list of direct poliastro dependencies with a citeable resource, which doesn’t account for the fact that I have used and enjoyed free (as in freedom) operative systems, compilers, text editors, IDEs and browsers for my whole academic life.

- Van Der Walt, Stefan, S. Chris Colbert, and Gael Varoquaux. “The NumPy array: a structure for efficient numerical computation.” *Computing in Science & Engineering* 13, no. 2 (2011): 22-30. DOI:10.1109/MCSE.2011.37
- Jones, Eric, Travis Oliphant, and Pearu Peterson. “SciPy: Open Source Scientific Tools for Python”, 2001-, <http://www.scipy.org/> [Online; accessed 2015-12-12].
- Hunter, John D. “Matplotlib: A 2D graphics environment.” *Computing in science and engineering* 9, no. 3 (2007): 90-95. DOI:10.1109/MCSE.2007.55
- Pérez, Fernando, and Brian E. Granger. “IPython: a system for interactive scientific computing.” *Computing in Science & Engineering* 9, no. 3 (2007): 21-29. DOI:10.1109/MCSE.2007.53
- Robitaille, Thomas P., Erik J. Tollerud, Perry Greenfield, Michael Droettboom, Erik Bray, Tom Aldcroft, Matt Davis et al. “Astropy: A community Python package for astronomy.” *Astronomy & Astrophysics* 558 (2013): A33. DOI:10.1051/0004-6361/201322068

2.6 API Reference

2.6.1 poliastro.twobody package

poliastro.twobody.angles module

Angles and anomalies.

`poliastro.twobody.angles.nu_to_E(nu, ecc)`
Eccentric anomaly from true anomaly.

New in version 0.4.0.

Parameters

- **nu** (*float*) – True anomaly (rad).
- **ecc** (*float*) – Eccentricity.

Returns **E** – Eccentric anomaly.

Return type *float*

`poliastro.twobody.angles.nu_to_F(nu, ecc)`
Hyperbolic eccentric anomaly from true anomaly.

Parameters

- **nu** (*float*) – True anomaly (rad).
- **ecc** (*float*) – Eccentricity (>1).

Returns **F** – Hyperbolic eccentric anomaly.

Return type *float*

Note: Taken from Curtis, H. (2013). *Orbital mechanics for engineering students*. 167

`poliastro.twobody.angles.E_to_nu(E, ecc)`

True anomaly from eccentric anomaly.

New in version 0.4.0.

Parameters

- **E** (*float*) – Eccentric anomaly (rad).
- **ecc** (*float*) – Eccentricity.

Returns **nu** – True anomaly (rad).

Return type *float*

`poliastro.twobody.angles.F_to_nu(F, ecc)`

True anomaly from hyperbolic eccentric anomaly.

Parameters

- **F** (*float*) – Hyperbolic eccentric anomaly (rad).
- **ecc** (*float*) – Eccentricity (>1).

Returns **nu** – True anomaly (rad).

Return type *float*

`poliastro.twobody.angles.M_to_E(M, ecc)`

Eccentric anomaly from mean anomaly.

New in version 0.4.0.

Parameters

- **M** (*float*) – Mean anomaly (rad).
- **ecc** (*float*) – Eccentricity.

Returns **E** – Eccentric anomaly.

Return type *float*

`poliastro.twobody.angles.M_to_F(M, ecc)`

Hyperbolic eccentric anomaly from mean anomaly.

Parameters

- **M** (*float*) – Mean anomaly (rad).
- **ecc** (*float*) – Eccentricity (>1).

Returns **F** – Hyperbolic eccentric anomaly.

Return type *float*

`poliastro.twobody.angles.E_to_M(E, ecc)`

Mean anomaly from eccentric anomaly.

New in version 0.4.0.

Parameters

- `E (float)` – Eccentric anomaly (rad).
- `ecc (float)` – Eccentricity.

Returns `M` – Mean anomaly (rad).

Return type `float`

`poliastro.twobody.angles.F_to_M(F, ecc)`

Mean anomaly from eccentric anomaly.

Parameters

- `F (float)` – Hyperbolic eccentric anomaly (rad).
- `ecc (float)` – Eccentricity (>1).

Returns `M` – Mean anomaly (rad).

Return type `float`

`poliastro.twobody.angles.M_to_nu(M, ecc)`

True anomaly from mean anomaly.

New in version 0.4.0.

Parameters

- `M (float)` – Mean anomaly (rad).
- `ecc (float)` – Eccentricity.

Returns `nu` – True anomaly (rad).

Return type `float`

Examples

```
>>> nu = M_to_nu(np.radians(30.0), 0.06)
>>> np.rad2deg(nu)
33.673284930211658
```

`poliastro.twobody.angles.nu_to_M(nu, ecc)`

Mean anomaly from true anomaly.

New in version 0.4.0.

Parameters

- `nu (float)` – True anomaly (rad).
- `ecc (float)` – Eccentricity.

Returns `M` – Mean anomaly (rad).

Return type `float`

`poliastro.twobody.angles.fp_angle(nu, ecc)`

Flight path angle.

New in version 0.4.0.

Parameters

- **nu** (*float*) – True anomaly (rad).
- **ecc** (*float*) – Eccentricity.

Note: Algorithm taken from Vallado 2007, pp. 113.

poliastro.twobody.classical module

Functions to define orbits from classical orbital elements.

`poliastro.twobody.classical.rv_pqw(k, p, ecc, nu)`

Returns r and v vectors in perifocal frame.

`poliastro.twobody.classical.coe2rv(k, p, ecc, inc, raan, argp, nu)`

Converts from classical orbital elements to vectors.

Parameters

- **k** (*float*) – Standard gravitational parameter (km^3 / s^2).
- **p** (*float*) – Semi-latus rectum or parameter (km).
- **ecc** (*float*) – Eccentricity.
- **inc** (*float*) – Inclination (rad).
- **omega** (*float*) – Longitude of ascending node (rad).
- **argp** (*float*) – Argument of perigee (rad).
- **nu** (*float*) – True anomaly (rad).

`poliastro.twobody.classical.coe2mee(p, ecc, inc, raan, argp, nu)`

Converts from classical orbital elements to modified equinoctial orbital elements.

The definition of the modified equinoctial orbital elements is taken from [Walker, 1985].

Parameters

- **k** (*float*) – Standard gravitational parameter (km^3 / s^2).
- **p** (*float*) – Semi-latus rectum or parameter (km).
- **ecc** (*float*) – Eccentricity.
- **inc** (*float*) – Inclination (rad).
- **omega** (*float*) – Longitude of ascending node (rad).
- **argp** (*float*) – Argument of perigee (rad).
- **nu** (*float*) – True anomaly (rad).

Note: The conversion equations are taken directly from the original paper.

class poliastro.twobody.classical.**ClassicalState** (*attractor, a, ecc, inc, raan, argp, nu*)
State defined by its classical orbital elements.

a
Semimajor axis.

ecc
Eccentricity.

inc
Inclination.

raan
Right ascension of the ascending node.

argp
Argument of the perigee.

nu
True anomaly.

to_vectors ()
Converts to position and velocity vector representation.

to_classical ()
Converts to classical orbital elements representation.

to_equinoctial ()
Converts to modified equinoctial elements representation.

poliastro.twobody.decorators module

Decorators.

poliastro.twobody.equinoctial module

Functions to define orbits from modified equinoctial orbital elements.

poliastro.twobody.equinoctial.**mee2coe** (*p, f, g, h, k, L*)
Converts from modified equinoctial orbital elements to classical orbital elements.

The definition of the modified equinoctial orbital elements is taken from [Walker, 1985].

Note: The conversion is always safe because arctan2 works also for 0, 0 arguments.

poliastro.twobody.orbit module

class poliastro.twobody.orbit.**Orbit** (*state, epoch*)
Position and velocity of a body with respect to an attractor at a given time (epoch).

state
Position and velocity or orbital elements.

epoch
Epoch of the orbit.

classmethod from_vectors (*attractor, r, v, epoch=<Time object: scale='tdb' format='jyear_str' value=J2000.000>*)

Return *Orbit* from position and velocity vectors.

Parameters

- **attractor** (*Body*) – Main attractor.
- **r** (*Quantity*) – Position vector wrt attractor center.
- **v** (*Quantity*) – Velocity vector.
- **epoch** (*Time, optional*) – Epoch, default to J2000.

classmethod from_classical (*attractor, a, ecc, inc, raan, argp, nu, epoch=<Time object: scale='tdb' format='jyear_str' value=J2000.000>*)

Return *Orbit* from classical orbital elements.

Parameters

- **attractor** (*Body*) – Main attractor.
- **a** (*Quantity*) – Semi-major axis.
- **ecc** (*Quantity*) – Eccentricity.
- **inc** (*Quantity*) – Inclination
- **raan** (*Quantity*) – Right ascension of the ascending node.
- **argp** (*Quantity*) – Argument of the pericenter.
- **nu** (*Quantity*) – True anomaly.
- **epoch** (*Time, optional*) – Epoch, default to J2000.

classmethod from_equinoctial (*attractor, p, f, g, h, k, L, epoch=<Time object: scale='tdb' format='jyear_str' value=J2000.000>*)

Return *Orbit* from modified equinoctial elements.

Parameters

- **attractor** (*Body*) – Main attractor.
- **p** (*Quantity*) – Semilatus rectum.
- **f** (*Quantity*) – Second modified equinoctial element.
- **g** (*Quantity*) – Third modified equinoctial element.
- **h** (*Quantity*) – Fourth modified equinoctial element.
- **k** (*Quantity*) – Fifth modified equinoctial element.
- **L** (*Quantity*) – True longitude.
- **epoch** (*Time, optional*) – Epoch, default to J2000.

classmethod from_body_ephem (*body, epoch=None*)

Return osculating *Orbit* of a body at a given time.

classmethod circular (*attractor, alt, inc=<Quantity 0.0 deg>, raan=<Quantity 0.0 deg>, arglat=<Quantity 0.0 deg>, epoch=<Time object: scale='tdb' format='jyear_str' value=J2000.000>*)

Return circular *Orbit*.

Parameters

- **attractor** (*Body*) – Main attractor.

- **alt** (*Quantity*) – Altitude over surface.
- **inc** (*Quantity*, *optional*) – Inclination, default to 0 deg (equatorial orbit).
- **raan** (*Quantity*, *optional*) – Right ascension of the ascending node, default to 0 deg.
- **arglat** (*Quantity*, *optional*) – Argument of latitude, default to 0 deg.
- **epoch** (*Time*, *optional*) – Epoch, default to J2000.

classmethod parabolic (*attractor*, *p*, *inc*, *raan*, *argp*, *nu*, *epoch*=<*Time* object: *scale*='tdb' format='jyear_str' value=J2000.000>)

Return parabolic *Orbit*.

Parameters

- **attractor** (*Body*) – Main attractor.
- **p** (*Quantity*) – Semilatus rectum or parameter.
- **inc** (*Quantity*, *optional*) – Inclination.
- **raan** (*Quantity*) – Right ascension of the ascending node.
- **argp** (*Quantity*) – Argument of the pericenter.
- **nu** (*Quantity*) – True anomaly.
- **epoch** (*Time*, *optional*) – Epoch, default to J2000.

propagate (*epoch_or_duration*, *rtol*=1e-10)

Propagate this *Orbit* some *time* and return the result.

Parameters

- **epoch_or_duration** (*Time*, *TimeDelta* or *equivalent*) – Final epoch or time of flight.
- **rtol** (*float*, *optional*) – Relative tolerance for the propagation algorithm, default to 1e-10.

sample (*values*=100)

Samples an orbit to some specified time values.

New in version 0.8.0.

Parameters values (*Multiple options*) – Number of interval points (default to 100), True anomaly values, Time values.

Returns Position vector in each given value.

Return type CartesianRepresentation

Notes

When specifying a number of points, the initial and final position is present twice inside the result (first and last row). This is more useful for plotting.

Examples

```
>>> from astropy import units as u
>>> from poliastro.examples import iss
>>> iss.sample()
>>> iss.sample(10)
>>> iss.sample([0, 180] * u.deg)
>>> iss.sample([0, 10, 20] * u.minute)
>>> iss.sample([iss.epoch + iss.period / 2])
```

apply_maneuver (*maneuver*, *intermediate=False*)

Returns resulting *Orbit* after applying maneuver to self.

Optionally return intermediate states (default to False).

Parameters

- **maneuver** (*Maneuver*) – Maneuver to apply.
- **intermediate** (*bool*, *optional*) – Return intermediate states, default to False.

poliastro.twobody.propagation module

Propagation algorithms.

poliastro.twobody.propagation.func_twobody (*t0*, *u*, *k*, *ad*)

Differential equation for the initial value two body problem.

This function follows Cowell’s formulation.

Parameters

- **t0** (*float*) – Time.
- **u** (*ndarray*) – Six component state vector [x, y, z, vx, vy, vz] (km, km/s).
- **k** (*float*) – Standard gravitational parameter.
- **ad** (*function*(*t0*, *u*, *k*)) – Non Keplerian acceleration (km/s²).

poliastro.twobody.propagation.cowell (*k*, *r0*, *v0*, *tof*, *rtol=1e-10*, *, *ad=None*, *callback=None*, *nsteps=1000*)

Propagates orbit using Cowell’s formulation.

Parameters

- **k** (*float*) – Gravitational constant of main attractor (km³ / s²).
- **r0** (*array*) – Initial position (km).
- **v0** (*array*) – Initial velocity (km).
- **ad** (*function*(*t0*, *u*, *k*), *optional*) – Non Keplerian acceleration (km/s²), default to None.
- **tof** (*float*) – Time of flight (s).
- **rtol** (*float*, *optional*) – Maximum relative error permitted, default to 1e-10.
- **nsteps** (*int*, *optional*) – Maximum number of internal steps, default to 1000.
- **callback** (*callable*, *optional*) – Function called at each internal integrator step.

Raises `RuntimeError` – If the algorithm didn’t converge.

Note: This method uses a Dormand & Prince method of order 8(5,3) available in the `scipy.integrate.ode` module.

`poliastro.twobody.propagation.kepler(k, r0, v0, tof, rtol=1e-10, *, numiter=35)`

Propagates Keplerian orbit.

Parameters

- **k** (*float*) – Gravitational constant of main attractor (km^3 / s^2).
- **r0** (*array*) – Initial position (km).
- **v0** (*array*) – Initial velocity (km).
- **tof** (*float*) – Time of flight (s).
- **rtol** (*float, optional*) – Maximum relative error permitted, default to 1e-10.
- **numiter** (*int, optional*) – Maximum number of iterations, default to 35.

Raises `RuntimeError` – If the algorithm didn't converge.

Note: This algorithm is based on Vallado implementation, and does basic Newton iteration on the Kepler equation written using universal variables. Battin claims his algorithm uses the same amount of memory but is between 40 % and 85 % faster.

`poliastro.twobody.propagation.propagate(orbit, time_of_flight, *, method=<function kepler>, rtol=1e-10, **kwargs)`

Propagate an orbit some time and return the result.

poliastro.twobody.rv module

Functions to define orbits from position and velocity vectors.

`poliastro.twobody.rv.rv2coe(k, r, v, tol=1e-08)`

Converts from vectors to classical orbital elements.

Parameters

- **k** (*float*) – Standard gravitational parameter (km^3 / s^2).
- **r** (*array*) – Position vector (km).
- **v** (*array*) – Velocity vector (km / s).
- **tol** (*float, optional*) – Tolerance for eccentricity and inclination checks, default to 1e-8.

`class poliastro.twobody.rv.RVState(tractor, r, v)`

State defined by its position and velocity vectors.

r
Position vector.

v
Velocity vector.

to_vectors()
Converts to position and velocity vector representation.

`to_classical()`
 Converts to classical orbital elements representation.

2.6.2 poliastro.iod package

poliastro.iod.izzo module

Izzo's algorithm for Lambert's problem

`poliastro.iod.izzo.lambert(k, r0, r, tof, M=0, numiter=35, rtol=1e-08)`
 Solves the Lambert problem using the Izzo algorithm.

New in version 0.5.0.

Parameters

- **k** (*Quantity*) – Gravitational constant of main attractor (km^3 / s^2).
- **r0** (*Quantity*) – Initial position (km).
- **r** (*Quantity*) – Final position (km).
- **tof** (*Quantity*) – Time of flight (s).
- **M** (*int, optional*) – Number of full revolutions, default to 0.
- **numiter** (*int, optional*) – Maximum number of iterations, default to 35.
- **rtol** (*float, optional*) – Relative tolerance of the algorithm, default to 1e-8.

Yields **v0, v** (*tuple*) – Pair of velocity solutions.

poliastro.iod.vallado module

Initial orbit determination.

`poliastro.iod.vallado.lambert(k, r0, r, tof, short=True, numiter=35, rtol=1e-08)`
 Solves the Lambert problem.

New in version 0.3.0.

Parameters

- **k** (*Quantity*) – Gravitational constant of main attractor (km^3 / s^2).
- **r0** (*Quantity*) – Initial position (km).
- **r** (*Quantity*) – Final position (km).
- **tof** (*Quantity*) – Time of flight (s).
- **short** (*boolean, optional*) – Find out the short path, default to True. If False, find long path.
- **numiter** (*int, optional*) – Maximum number of iterations, default to 35.
- **rtol** (*float, optional*) – Relative tolerance of the algorithm, default to 1e-8.

Raises `RuntimeError` – If it was not possible to compute the orbit.

Note: This uses the universal variable approach found in Battin, Mueller & White with the bisection iteration suggested by Vallado. Multiple revolutions not supported.

2.6.3 poliastro.neos package

Code related to NEOs.

Functions related to NEOs and different NASA APIs. All of them are coded as part of SOCIS 2017 proposal.

Notes

The orbits returned by the functions in this package are in the *HeliocentricEclipticJ2000* frame.

poliastro.neos.dastcom5 module

NEOs orbit from DASTCOM5 database.

`poliastro.neos.dastcom5.asteroid_db()`

Return complete DASTCOM5 asteroid database.

Returns `database` – Database with custom dtype.

Return type `numpy.ndarray`

`poliastro.neos.dastcom5.comet_db()`

Return complete DASTCOM5 comet database.

Returns `database` – Database with custom dtype.

Return type `numpy.ndarray`

`poliastro.neos.dastcom5.orbit_from_name(name)`

Return *Orbit* given a name.

Retrieve info from JPL DASTCOM5 database.

Parameters `name` (*str*) – NEO name.

Returns `orbit` – NEO orbits.

Return type `list` (*Orbit*)

`poliastro.neos.dastcom5.orbit_from_record(record)`

Return *Orbit* given a record.

Retrieve info from JPL DASTCOM5 database.

Parameters `record` (*int*) – Object record.

Returns `orbit` – NEO orbit.

Return type *Orbit*

`poliastro.neos.dastcom5.record_from_name(name)`

Search *dastcom.idx* and return logical records that match a given string.

Body name, SPK-ID, or alternative designations can be used.

Parameters `name` (*str*) – Body name.

Returns `records` – DASTCOM5 database logical records matching str.

Return type `list` (*int*)

`poliastro.neos.dastcom5.string_record_from_name(name)`

Search *dastcom.idx* and return body full record.

Search DASTCOM5 index and return body records that match string, containing logical record, name, alternative designations, SPK-ID, etc.

Parameters `name` (*str*) – Body name.

Returns `lines` – Body records

Return type `list(str)`

`poliastro.neos.dastcom5.read_headers()`

Read *DASTCOM5* headers and return asteroid and comet headers.

Headers are two numpy arrays with custom dtype.

Returns `ast_header, com_header` – DASTCOM5 headers.

Return type `tuple(numpy.ndarray)`

`poliastro.neos.dastcom5.read_record(record)`

Read *DASTCOM5* record and return body data.

Body data consists of numpy array with custom dtype.

Parameters `record` (*int*) – Body record.

Returns `body_data` – Body information.

Return type `numpy.ndarray`

`poliastro.neos.dastcom5.download_dastcom5()`

Downloads DASTCOM5 database.

Downloads and unzip DASTCOM5 file in default poliastro path (`~/poliastro`).

`poliastro.neos.dastcom5.entire_db()`

Return complete DASTCOM5 database.

Merge asteroid and comet databases, only with fields related to orbital data, discarding the rest.

Returns `database` – Database with custom dtype.

Return type `numpy.ndarray`

dastcom5 parameters

Dastcom5 parameters

avail:

- *a* if it is available for asteroids.
- *c* if it is available for comets.
- *[number]+* since which version of DASTCOM5 is available.

avail	Label	Definition
ac/3+	EPOCH	Time of osc. orbital elements solution, JD (CT,TDB)
ac/3+	CALEPO	Time of osc. orbital elements solution, YYYYDDMM.ffff
ac/3+	MA	Mean anomaly at EPOCH, deg (elliptical & hyperbolic cases “9.999999E99” if not available)

avail	Label	Definition
ac/3+	W	Argument of periapsis at EPOCH, J2000 ecliptic, deg.
ac/3+	OM	Longitude of ascending node at EPOCH, J2000 ecliptic, deg.
ac/3+	IN	Inclination angle at EPOCH wrt J2000 ecliptic, deg.
ac/3+	EC	Eccentricity at EPOCH
ac/3+	A	Semi-major axis at EPOCH, au
ac/3+	QR	Perihelion distance at EPOCH, au
ac/3+	TP	Perihelion date for QR at EPOCH, JD (CT,TDB)
ac/3+	TPCAL	Perihelion date for QR at EPOCH, format YYYYMMDD.fff
ac/5+	TPFRAC	Decimal (fractional) part of TP for extended precision
ac/4+	SOLDAT	Date orbit solution was performed, JD (CT,TDB)
ac/4+	SRC(01)	Square root covariance vector. Vector-stored upper- triangular matrix with order {EC,QR,TP,OM,W,IN,{ ESTI
ac/3+	H	Absolute visual magnitude (IAU H-G system) (99=unknown)
ac/3+	G	Mag. slope parm. (IAU H-G)(99=unknown & 0.15 not assumed)
c/3+	M1	Total absolute magnitude, mag.
c/3+	M2	Nuclear absolute magnitue, mag.
c/4+	K1	Total absolute magnitude scaling factor
c/4+	K2	Nuclear absolute magnitude scaling factor
c/4+	PHCOF	Phase coefficient for K2= 5
ac/3+	A1	Non-grav. accel., radial component, [s:10 ⁻⁸ au/day ²]
ac/3+	A2	Non-grav. accel., transverse component, [s:10 ⁻⁸ au/day ²]
ac/4+	A3	Non-grav. accel., normal component, [s:10 ⁻⁸ au/day ²]
c/4+	DT	Non-grav. lag/delay parameter, days
ac/5+	R0	Non-grav. model constant, normalizing distance, au
ac/5+	ALN	Non-grav. model constant, normalizing factor
ac/5+	NM	Non-grav. model constant, exponent m
ac/5+	NN	Non-grav. model constant, exponent n
ac/5+	NK	Non-grav. model constant, exponent k
c/4+	S0	Center-of-light estimated offset at 1 au, km
c/5+	TCL	Center-of-light start-time offset, d since “ref.time”
a /5+	LGK	Surface thermal conductivity log ₁₀ (k), (W/m/K)
ac/5+	RHO	Bulk density, kg/m ³
ac/5+	AMRAT	Solar pressure model, area/mass ratio, m ² /kg
c/5+	AJ1	Jet 1 acceleration, au/d ²
c/5+	AJ2	Jet 2 acceleration, au/d ²
c/5+	ET1	Thrust angle, colatitude of jet 1, deg.
c/5+	ET2	Thrust angle, colatitude of jet 2, deg.
c/5+	DTH	Jet model diurnal lag angle, deg. (delta_theta)
ac/5+	ALF	Spin pole orientation, RA, deg.
ac/5+	DEL	Spin pole orientation, DEC, deg.
ac/5+	SPHLM3	Earth gravity sph. harm. model limit, Earth radii
ac/5+	SPHLM5	Jupiter grav. sph. harm. model limit, Jupiter radii
ac/3+	RP	Object rotational period, hrs
ac/3+	GM	Object mass parameter, km ³ /s ²
ac/3+	RAD	Object mean radius, km
ac/5+	EXTNT1	Triaxial ellipsoid, axis 1/largest equat. extent, km
ac/5+	EXTNT2	Triaxial ellipsoid, axis 2/smallest equat. extent, km
ac/5+	EXTNT3	Triaxial ellipsoid, axis 3/polar extent, km
ac/4+	MOID	Earth MOID at EPOCH time, au; ‘99’ if not computed
ac/3+	ALBEDO	Geometric visual albedo, 99 if unknown

avail	Label	Definition
a /3+	BVCI	B-V color index, mag., 99 if unknown
a /5+	UBCI	U-B color index, mag., 99 if unknown
a /5+	IRCI	I-R color index, mag., 99 if unknown
ac/4+	RMSW	RMS of weighted optical residuals, arcsec
ac/5+	RMSU	RMS of unweighted optical residuals, arcsec
ac/5+	RMSN	RMS of normalized optical residuals
ac/5+	RMSNT	RMS of all normalized residuals
a /5+	RMSH	RMS of abs. visual magnitude (H) residuals, mag.
c/5+	RMSMT	RMS of MT estimate residuals, mag.
c/5+	RMSMN	RMS of MN estimate residuals, mag.
ac/3+	NO	Logical record-number of this object in DASTCOM
ac/4+	NOBS	Number of observations of all types used in orbit soln.
ac/4+	OBSFRST	Start-date of observations used in fit, YYYYMMDD
ac/4+	OBSLAST	Stop-date of observations used in fit, YYYYMMDD
ac/5+	PRELTV	Planet relativity “bit-switch” byte: bits 0-7 are set to 1 if relativity for corresponding planet was computed, 0 if not
ac/5+	SPHMX3	Earth grav. model max. degree; 0=point-mass, 2= J2 only, 3= up to J3 zonal, 22= 2x2 field, 33=3x3 field, etc.
ac/5+	SPHMX5	Jupiter grav. max. deg.; 0=point-mass, 2= J2 only, 3= up to J3 zonal, 22= 2x2 field, 33=3x3 field, etc.
ac/5+	JGSEP	Galilean satellites used as sep. perturbers; 0=no 1=yes
ac/5+	TWOBOD	Two-body orbit model flag; 0=no 1=yes
ac/5+	NSATS	Number of satellites; 99 if unknown.
ac/4+	UPARM	Orbit condition code; 99 if not computed
ac/4+	LSRC	Length of square-root cov. vector SRC (# elements used)
c/3+	IPYR	Perihelion year (i.e., 1976, 2012, 2018, etc.)
ac/3+	NDEL	Number of radar delay measurements used in orbit soln.
ac/3+	NDOP	Number of radar Doppler measurements used in orbit soln.
c/5+	NOBSMT	Number of magnitude measurements used in total mag. soln.
c/5+	NOBSMN	Number of magnitude measurements used in nuc. mag. soln.
c/3+	COMNUM	IAU comet number (parsed from DESIG)
ac/3+	EQUINOX	Equinox of orbital elements (‘1950’ or ‘2000’)
ac/4+	PENAM	Planetary ephemeris ID/name
ac/3+	SBNAM	Small-body perturber ephemeris ID/name
a /3	SPTYPT	Tholen spectral type
a /4+	SPTYPS	SMASS-II spectral type
ac/3+	DARC	Data arc span (year-year, OR integer # of days)
a /3+	COMNT1	Asteroid comment line #1
a /3+	COMNT2	Asteroid comment line #2
c/3+	COMNT3	Comet comment line #1
c/3+	COMNT4	Comet comment line #2
ac/3+	DESIG	Object designation
ac/4+	ESTL	Dynamic parameter estimation list. Last symbol set to ‘+’ if list is too long for field; check object record comment
ac/3+	IREF	Solution reference/ID/name
ac/3+	NAME	Object name

poliastro.neos.neows module

NEOs orbit from NEOWS and JPL SBDB

`poliastro.neos.neows.orbit_from_spk_id(spk_id, api_key='DEMO_KEY')`

Return *Orbit* given a SPK-ID.

Retrieve info from NASA NeoWS API, and therefore it only works with NEAs (Near Earth Asteroids).

Parameters

- **spk_id** (*str*) – SPK-ID number, which is given to each body by JPL.
- **api_key** (*str*) – NASA OPEN APIs key (default: *DEMO_KEY*)

Returns *orbit* – NEA orbit.

Return type *Orbit*

`poliastro.neos.neows.spk_id_from_name(name)`

Return SPK-ID number given a small-body name.

Retrieve and parse HTML from JPL Small Body Database to get SPK-ID.

Parameters **name** (*str*) – Small-body object name. Wildcards “*” and/or “?” can be used.

Returns **spk_id** – SPK-ID number.

Return type *str*

`poliastro.neos.neows.orbit_from_name(name, api_key='DEMO_KEY')`

Return *Orbit* given a name.

Retrieve info from NASA NeoWS API, and therefore it only works with NEAs (Near Earth Asteroids).

Parameters

- **name** (*str*) – NEA name.
- **api_key** (*str*) – NASA OPEN APIs key (default: *DEMO_KEY*)

Returns *orbit* – NEA orbit.

Return type *Orbit*

2.6.4 poliastro.bodies module

Bodies of the Solar System.

Contains some predefined bodies of the Solar System:

- `Sun()`
- `Earth()`
- `Moon()`
- `Mercury()`
- `Venus()`
- `Mars()`
- `Jupiter()`
- `Saturn()`
- `Uranus()`
- `Neptune()`
- `Pluto()`

and a way to define new bodies (*Body* class).

Data references can be found in *constants*

class poliastro.bodies.**Body** (*parent, k, name, symbol=None, R=<Quantity 0.0 km>, **kwargs*)
 Class to represent a generic body.

__init__ (*parent, k, name, symbol=None, R=<Quantity 0.0 km>, **kwargs*)
 Constructor.

Parameters

- **parent** (*Body*) – Central body.
- **k** (*Quantity*) – Standard gravitational parameter.
- **name** (*str*) – Name of the body.
- **symbol** (*str, optional*) – Symbol for the body.
- **R** (*Quantity, optional*) – Radius of the body.

2.6.5 poliastro.constants module

Astronomical and physics constants.

This module complements constants defined in *astropy.constants*, with gravitational parameters and radii.

Note that *GM_jupiter* and *GM_neptune* are both referred to the whole planetary system gravitational parameter.

Unless otherwise specified, gravitational and mass parameters were obtained from:

- Luzum, Brian et al. “The IAU 2009 System of Astronomical Constants: The Report of the IAU Working Group on Numerical Standards for Fundamental Astronomy.” *Celestial Mechanics and Dynamical Astronomy* 110.4 (2011): 293–304. Crossref. Web. DOI: [10.1007/s10569-011-9352-4](https://doi.org/10.1007/s10569-011-9352-4)

and radii were obtained from:

- Archinal, B. A. et al. “Report of the IAU Working Group on Cartographic Coordinates and Rotational Elements: 2009.” *Celestial Mechanics and Dynamical Astronomy* 109.2 (2010): 101–135. Crossref. Web. DOI: [10.1007/s10569-010-9320-4](https://doi.org/10.1007/s10569-010-9320-4)

2.6.6 poliastro.coordinates module

Functions related to coordinate systems and transformations.

This module complements *astropy.coordinates*.

poliastro.coordinates.body_centered_to_icrs (*r, v, source_body, epoch=<Time object: scale='tdb' format='yday_str' value=J2000.000>, rotate_meridian=False*)

Converts position and velocity body-centered frame to ICRS.

Parameters

- **r** (*Quantity*) – Position vector in a body-centered reference frame.
- **v** (*Quantity*) – Velocity vector in a body-centered reference frame.
- **source_body** (*Body*) – Source body.
- **epoch** (*Time, optional*) – Epoch, default to J2000.
- **rotate_meridian** (*bool, optional*) – Whether to apply the rotation of the meridian too, default to False.

Returns **r, v** – Position and velocity vectors in ICRS.

Return type `tuple (Quantity)`

`poliastro.coordinates.icrs_to_body_centered(r, v, target_body, epoch=<Time object: scale='tdb' format='yday_str' value=J2000.000>, rotate_meridian=False)`

Converts position and velocity in ICRS to body-centered frame.

Parameters

- **r** (*Quantity*) – Position vector in ICRS.
- **v** (*Quantity*) – Velocity vector in ICRS.
- **target_body** (*Body*) – Target body.
- **epoch** (*Time, optional*) – Epoch, default to J2000.
- **rotate_meridian** (*bool, optional*) – Whether to apply the rotation of the meridian too, default to False.

Returns **r, v** – Position and velocity vectors in a body-centered reference frame.

Return type `tuple (Quantity)`

`poliastro.coordinates.inertial_body_centered_to_pqw(r, v, source_body)`

Converts position and velocity from inertial body-centered frame to perifocal frame.

Parameters

- **r** (*Quantity*) – Position vector in a inertial body-centered reference frame.
- **v** (*Quantity*) – Velocity vector in a inertial body-centered reference frame.
- **source_body** (*Body*) – Source body.

Returns **r_pqw, v_pqw** – Position and velocity vectors in ICRS.

Return type `tuple (Quantity)`

2.6.7 poliastro.cli module

Command line functions.

2.6.8 poliastro.ephem module

Planetary ephemerides.

`poliastro.ephem.get_body_ephem(body, epoch)`

Position and velocity vectors of a given body at a certain time.

The vectors are computed with respect to the Solar System barycenter.

New in version 0.3.0.

Parameters

- **body** (*str*) – Name of the body.
- **epoch** (*Time*) – Computation time. Can be scalar or vector.

Returns **r, v** – Position and velocity vectors.

Return type `Quantity`

2.6.9 poliastro.examples module

Example data.

```
poliastro.examples.iss = 6772 x 6790 km x 51.6 deg orbit around Earth ()
```

ISS orbit example

Taken from Plyades (c) 2012 Helge Eichhorn (MIT License)

```
poliastro.examples.molniya = 6650 x 46550 km x 63.4 deg orbit around Earth ()
```

Molniya orbit example

```
poliastro.examples.soyuz_gto = 6628 x 42328 km x 6.0 deg orbit around Earth ()
```

Soyuz geostationary transfer orbit (GTO) example

Taken from Soyuz User's Manual, issue 2 revision 0

```
poliastro.examples.churi = 1 x 6 AU x 7.0 deg orbit around Sun ()
```

Comet 67P/Churyumov–Gerasimenko orbit example

2.6.10 poliastro.frames module

Coordinate frames definitions.

```
class poliastro.frames.HeliocentricEclipticJ2000 (*args, **kwargs)
```

Heliocentric ecliptic coordinates. These origin of the coordinates are the center of the sun, with the x axis pointing in the direction of the mean equinox of J2000 and the xy-plane in the plane of the ecliptic of J2000 (according to the IAU 1976/1980 obliquity model).

2.6.11 poliastro.hyper module

Utility hypergeometric functions.

```
poliastro.hyper.hyp2f1b
```

Hypergeometric function $2F1(3, 1, 5/2, x)$, see [Battin].

2.6.12 poliastro.maneuver module

Orbital maneuvers.

```
class poliastro.maneuver.Maneuver (*impulses)
```

Class to represent a Maneuver.

Each `Maneuver` consists on a list of impulses Δv_i (changes in velocity) each one applied at a certain instant t_i . You can access them directly indexing the `Maneuver` object itself.

```
>>> man = Maneuver((0 * u.s, [1, 0, 0] * u.km / u.s),
... (10 * u.s, [1, 0, 0] * u.km / u.s))
>>> man[0]
(<Quantity 0 s>, <Quantity [1,0,0] km / s>)
>>> man.impulses[1]
(<Quantity 10 s>, <Quantity [1,0,0] km / s>)
```

```
__init__ (*impulses)
```

Constructor.

Parameters **impulses** (*list*) – List of pairs (delta_time, delta_velocity)

Notes

TODO: Fix docstring, *args convention

classmethod `impulse` (*dv*)

Single impulse at current time.

classmethod `hohmann` (*orbit_i*, *r_f*)

Compute a Hohmann transfer between two circular orbits.

classmethod `bielliptic` (*orbit_i*, *r_b*, *r_f*)

Compute a bielliptic transfer between two circular orbits.

get_total_time ()

Returns total time of the maneuver.

get_total_cost ()

Returns total cost of the maneuver.

2.6.13 poliastro.patched_conics module

Patched Conics Computations

Contains methods to compute interplanetary trajectories approximating the three body problem with Patched Conics.

`poliastro.patched_conics.compute_soi` (*body*, *a=None*)

Approximated radius of the Laplace Sphere of Influence (SOI) for a body.

Parameters

- **body** (~*poliastro.bodies.Body*) – Astronomical body which the SOI's radius is computed for
- **a** (*float* or *None*, optional) – Semimajor Axis of the body's orbit

Returns Approximated radius of the Sphere of Influence (SOI) [m]

Return type `astropy.units.quantity.Quantity`

2.6.14 poliastro.plotting module

Plotting utilities.

`poliastro.plotting.plot` (*state*, *label=None*, *color=None*)

Plots a State.

For more advanced tuning, use the `OrbitPlotter` class.

class `poliastro.plotting.OrbitPlotter` (*ax=None*, *num_points=100*)

OrbitPlotter class.

This class holds the perifocal plane of the first `State` plotted in it using `plot()`, so all following plots will be projected on that plane. Alternatively, you can call `set_frame()` to set the frame before plotting.

__init__ (*ax=None*, *num_points=100*)

Constructor.

Parameters

- **ax** (*Axes*) – Axes in which to plot. If not given, new ones will be created.
- **num_points** (*int*, optional) – Number of points to use in plots, default to 100.

set_frame (*p_vec, q_vec, w_vec*)
Sets perifocal frame if not existing.

Raises

- `ValueError` – If the vectors are not a set of mutually orthogonal unit vectors.
- `NotImplementedError` – If the frame was already set up.

set_attractor (*orbit*)
Sets plotting attractor.

Parameters *orbit* (`Orbit`) – orbit with attractor to plot.

plot (*orbit, label=None, color=None*)
Plots state and osculating orbit in their plane.

2.6.15 poliastro.stumpff module

Stumpff functions.

`poliastro.stumpff.c2`
Second Stumpff function.

For positive arguments:

$$c_2(\psi) = \frac{1 - \cos \sqrt{\psi}}{\psi}$$

`poliastro.stumpff.c3`
Third Stumpff function.

For positive arguments:

$$c_3(\psi) = \frac{\sqrt{\psi} - \sin \sqrt{\psi}}{\sqrt{\psi^3}}$$

2.6.16 poliastro.util module

Function helpers.

`poliastro.util.circular_velocity` (*k, a*)
Compute circular velocity for a given body (*k*) and semimajor axis (*a*).

`poliastro.util.rotate` (*vector, angle, axis='z', unit=None*)
Rotates a vector around axis a right-handed positive angle.

This is just a convenience function around `astropy.coordinates.matrix_utilities.rotation_matrix()`.

Parameters

- **vector** (*array_like*) – Dimension 3 vector.
- **angle** (*convertible to Angle*) – Angle of rotation.
- **axis** (*str or 3-sequence*) – Either 'x', 'y', 'z', or a (x,y,z) specifying an axis to rotate about. If 'x', 'y', or 'z', the rotation sense is counterclockwise looking down the + axis (e.g. positive rotations obey left-hand-rule).

- **unit** (*UnitBase*, *optional*) – If *angle* does not have associated units, they are in this unit. If neither are provided, it is assumed to be degrees.

Note: This is just a convenience function around `astropy.coordinates.matrix_utilities.rotation_matrix()`. This performs a so-called *active* or *alibi* transformation: rotates the vector while the coordinate system remains unchanged. To do the opposite operation (*passive* or *alias* transformation) call the function as `rotate(vec, ax, -angle, unit)` or use the convenience function `transform()`, see¹.

References

`poliastro.util.transform(vector, angle, axis='z', unit=None)`
 Rotates a coordinate system around axis a positive right-handed angle.

Note: This is a convenience function, equivalent to `rotate(vec, -angle, axis, unit)`. Refer to the documentation of `rotate()` for further information.

`poliastro.util.norm(vec)`
 Norm of a Quantity vector that respects units.

`poliastro.util.time_range(start, *, periods=50, spacing=None, end=None)`
 Generates range of astronomical times.

New in version 0.8.0.

Parameters

- **periods** (*int*, *optional*) – Number of periods, default to 50.
- **spacing** (*Time or Quantity*, *optional*) – Spacing between periods, optional.
- **end** (*Time or equivalent*, *optional*) – End date.

Returns Array of time values.

Return type Time

2.7 What's new

2.7.1 poliastro 0.8 (Unreleased)

New features:

- **Sampling method** for `Orbit` objects that returns an array of positions. This was already done in the plotting functions and will help providing other applications, such as exporting an `Orbit` to other formats.

2.7.2 poliastro 0.7.0 - 2017-09-15

This is a new major release, which adds new packages and modules, besides fixing several issues.

¹ http://en.wikipedia.org/wiki/Rotation_matrix#Ambiguities

New features:

- **NEOS package:** a new package has been added to poliastro, *neos* package. It provides several ways of getting NEOs (Near Earth Objects) data from NASA databases, online and offline.
- **New patched conics module.** New module containing a function to compute the radius of the Sphere of Influence (SOI).
- **Use Astropy for body ephemerides.** Instead of downloading the SPK files ourselves, now we use Astropy builtin capabilities. This also allows the user to select a builtin ephemerides that does not require external downloads. See [#131](#) for details.
- **Coordinates and frames modules:** new modules containing transformations between ICRS and body-centered frame, and perifocal to body_centered, *coordinates* as well as Heliocentric coordinate frame in *frames* based on Astropy for NEOs.
- **Pip packaging:** troublesome dependencies have been released in wheel format, so poliastro can now be installed using pip from all platforms.
- **Legend plotting:** now label and epoch are in a figure legend, which ends with the ambiguity of the epochs when having several plots in the same figure.

Other highlights:

- **Joined Open Astronomy:** we are now part of [Open Astronomy](#), a collaboration between open source astronomy and astrophysics projects to share resources, ideas, and to improve code.
- **New constants module:** poliastro has now a *constants* module, with GMs and radii of solar system bodies.
- **Added Jupyter examples:** poliastro examples are now available in the documentation as Jupyter notebooks, thanks to [nbsphinx](#).
- **New Code of Conduct:** poliastro community now has a Code of conduct.
- **Documentation update:** documentation has been updated with new installation ways, propagation and NEOs examples, “refactored” code and images, improved contribution guidelines and intersphinx extension.
- **New success stories:** two new success stories have been added to documentation.
- **Bodies now have a parent.** It is now possible to specify the attractor of a body.
- **Relative definition of Bodies.** Now it is possible to define Body parameters with respect to another body, and also add any number of properties in a simple way.

New contributors

Thanks to the generous SOCIS grant from the European Space Agency, Antonio Hidalgo has devoted three months developing poliastro full time and gained write acces to the repository.

This is the complete list of the people that contributed to this release, with a + sign indicating first contribution.

- Juan Luis Cano
- MiguelHB+
- Antonio Hidalgo+
- Zac Miller+
- Fran Navarro+
- Pablo Rodríguez Robles+

Bugs fixed:

- [Issue #205](#): Bug when plotting orbits with different epochs.
- [Issue #128](#): Missing ephemerides if no files on import time.
- [Issue #131](#): Slightly incorrect ephemerides results due to improper time scale.
- [Issue #130](#): Wrong attractor size when plotting different orbits.

Backward incompatible changes:

- **Non-osculating orbits**: removed support for non-osculating orbits. `plotting.plot()` calls containing `osculating` parameter should be replaced.

2.7.3 poliastro 0.6.0 - 2017-02-12

This major release was focused on refactoring some internal core parts and improving the propagation functionality.

Highlights:

- **Support Python 3.6**. See [#144](#).
- **Introduced “Orbit” objects** to replace `State` ones. The latter has been simplified, reducing some functionality, now their API has been moved to the former. See the User Guide and the examples for updated explanations. See [#135](#).
- **Allow propagation functions to receive a callback**. This paves the way for better plotting and storage of results. See [#140](#).

2.7.4 poliastro 0.5.0 - 2016-03-06

This is a new major release, focused on expanding the initial orbit determination capabilities and solving some infrastructure challenges.

New features:

- **Izzo’s algorithm for the Lambert problem**: Thanks to this algorithm multirevolution solutions are also returned. The old algorithm is kept on a separate module.

Other highlights:

- **Documentation on Read the Docs**: You can now browse previous releases of the package and easily switch between released and development versions.
- **Mailing list**: poliastro now has a mailing list hosted on groups.io. Come and join!
- **Clarified scope**: poliastro will now be focused on interplanetary applications, leaving other features to the new [python-astrodynamics](#) project.

Bugs fixed:

- [Issue #110](#): Bug when plotting State with non canonical units

Backward incompatible changes:

- **Drop Legacy Python:** poliastro 0.5.x and later will support only Python 3.x. We recommend our potential users to create dedicated virtual environments using conda or virtualenv or to contact the developers to fund Python 2 support.
- **Change “lambert” function API:** The functions for solving Lambert’s problem are now `_generators_`, even in the single revolution case. Check out the User Guide for specific examples.
- **Creation of orbits from classical elements:** poliastro has reverted the switch to the *semilatus rectum* $\backslash(p\backslash)$ instead of the semimajor axis $\backslash(a\backslash)$ made in 0.4.0, so $\backslash(a\backslash)$ must be used again. This change is definitive.

2.7.5 poliastro 0.4.2 - 2015-12-24

Fixed packaging problems.

2.7.6 poliastro 0.4.0 - 2015-12-13

This is a new major release, focused on improving stability and code quality. New angle conversion and modified equinoctial elements functions were added and an important backwards incompatible change was introduced related to classical orbital elements.

New features:

- **Angle conversion functions:** Finally brought back from poliastro 0.1, new functions were added to convert between true $\backslash(\nu\backslash)$, eccentric $\backslash(E\backslash)$ and mean $\backslash(M\backslash)$ anomaly, see [#45](#).
- **Equinoctial elements:** Now it’s possible to convert between classical and equinoctial elements, as well as from/to position and velocity vectors, see [#61](#).
- **Numerical propagation:** A new propagator using SciPy Dormand & Prince 8(5,3) integrator was added, see [#64](#).

Other highlights:

- **MIT license:** The project has been relicensed to a more popular license. poliastro remains commercial-friendly through a permissive, OSI-approved license.
- **Python 3.5 and NumPy 1.10 compatibility.** poliastro retains compatibility with legacy Python (Python 2) and NumPy 1.9. *Next version will be Python 3 only.*

Bugs fixed:

- [Issue #62](#): Conversion between coe and rv is not transitive
- [Issue #69](#): Incorrect plotting of certain closed orbits

Backward incompatible changes:

- **Creation of orbits from classical elements:** poliastro has switched to the *semilatus rectum* $\backslash(p\backslash)$ instead of the semimajor axis $\backslash(a\backslash)$ to define `State` objects, and the function has been renamed to `from_classical()`. Please update your programs accordingly.
- Removed specific angular momentum $\backslash(h\backslash)$ property to avoid a name clash with the fourth modified equinoctial element, use `norm(ss.h_vec)` instead.

2.7.7 poliastro 0.3.1 - 2015-06-30

This is a new minor release, with some bug fixes backported from the main development branch.

Bugs fixed:

- Fixed installation problem in Python 2.
- [Issue #49](#): Fix velocity units in `ephem`.
- [Issue #50](#): Fixed `ZeroDivisionError` when propagating with time zero.

2.7.8 poliastro 0.3.0 - 2015-05-09

This is a new major release, focused on switching to a pure Python codebase. Lambert problem solving and ephemerides computation came back, and a couple of bugs were fixed.

New features:

- **Pure Python codebase:** Forget about Fortran linking problems and nightmares on Windows, because now poliastro is a pure Python package. A new dependency, `numba`, was introduced to accelerate the algorithms, but poliastro will use it only if it is installed.
- **Lambert problem solving:** New module `iod` to determine an orbit given two position vectors and the time of flight.
- **[PR #42](#): Planetary ephemerides computation:** New module `ephem` with functions to deal with SPK files and compute position and velocity vectors of the planets.
- **[PR #38](#):** New method `parabolic()` to create parabolic orbits.
- New conda package: visit [poliastro binstar channel](#)!
- New organization and logo.

Bugs fixed:

- [Issue #19](#): Fixed plotting region for parabolic orbits.
- [Issue #37](#): Fixed creation of parabolic orbits.

2.7.9 poliastro 0.2.1 - 2015-04-26

This is a bugfix release, no new features were introduced since 0.2.0.

- Fixed [#35](#) (failing tests with recent astropy versions), thanks to Sam Dupree for the bug report.
- Updated for recent Sphinx versions.

2.7.10 poliastro 0.2 - 2014-08-16

- **Totally refactored code** to provide a more pythonic API (see [PR #14](#) and [wiki](#) for further information) heavily inspired by [Plyades](#) by Helge Eichhorn.
 - Mandatory use of **physical units** through `astropy.units`.
 - Object-oriented approach: `State` and `Maneuver` classes.
 - Vector quantities: results not only have magnitude now, but also direction (see for example maneuvers).
- Easy plotting of orbits in two dimensions using matplotlib.
- Module `example` with sample data to start testing the library.

These features were removed temporarily not to block the release and will see the light again in poliastro 0.3:

- Conversion between anomalies.
- Ephemerides calculations, will look into Skyfield and the JPL ephemerides prepared by Brandon Rhodes (see [issue #4](#)).
- Lambert problem solving.
- Perturbation analysis.

Note: Older versions of poliastro relied on some Fortran subroutines written by David A. Vallado for his book “Fundamentals of Astrodynamics and Applications” and available on the Internet as the [companion software of the book](#). The author explicitly gave permission to redistribute these subroutines in this project under a permissive license.

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