Spatial Data and Analysis Discussion 5: Review Session

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Outline

1. Distances

2. Geographic coordinates

3. Point processes

4. Polylines

5. Networks

6. Fields

7. High dimensional data

8. Matlab

Distances

- ► Things you need to know:
 - 1. How to calculate distances
 - 2. Use triangulation and trilateration
 - 3. Time, speed, and velocity

Matlab

Calculate distances

▶ Let $\vec{x_1}$ and $\vec{x_2}$ be two locations in \mathbb{R}^2

Calculate the Euclidean distance between them:

$$D(\vec{x_1}, \vec{x_2}) = \sqrt{(x_1(1) - x_2(1))^2 + (x_1(2) - x_2(2))^2}$$

▶ You should be able to generalize this concept to \mathbb{R}^n

Triangulation and trilateration

- ► <u>Triangulation</u> allow us to guess a distance of interest from angles and other distances
- Example on whiteboard

Triangulation and trilateration

- ► <u>Triangulation</u> allow us to guess a distance of interest from angles and other distances
- Example on whiteboard
- ► <u>Trilateration</u> allow us to uniquely guess a location using distances as information
- Example on whiteboard

Time, speed and velocity

▶ You need to remember the following relationship:

$$\mathsf{speed} \ = \ \frac{\mathsf{distance}}{\mathsf{time}}$$

▶ And be able to perform simple calculations with it

Midterm question

➤ Suppose we know the exact location of two landmarks within a city: City Hall and a statue that is 2 km away from City Hall. I tell you to meet me at a location that is 2 km from City Hall and 1.5 km from the statue. Do you have enough information to know where to meet me?

- 1. Yes
- 2. No

Geographic coordinates

► Things you need to know:

1. Latitude:

- specifies north-south position
- ▶ ranges from 0° at the equator to 90° (north or south)
- ▶ 1 degree = 111 km

2. Longitude

- specifies west-east position
- ▶ ranges from 0° at the Greenwich Meridian to 180° (west or east)
- ▶ 1 degree = 111 km $\times \cos(\theta)$

- ► A plane travels from 0°N Latitude and 0°E Longitude to 0°N Latitude and 20°E Longitude in 6 hours. What is the average speed of the plane?
 - 1. 270 km/hr
 - 2. 330 km/hr
 - 3. 185 km/hr
 - 4. 33 km/hr
 - 5. none of the above

Midterm question

▶ If we approximate a field covering the surface of the Earth using a 1° latitude by 1° longitude raster, how many grid cells will our field have?

- 1. 8,100
- 2. 16,200
- 3. 32,400
- 4. 64,800
- 5. 129,600
- J. 129,000
- 6. none of the above

Point processes

- ► Things you need to know:
 - 1. Intensity of point processes
 - 2. k-function
 - 3. Calculate centroids
 - 4. Interpolate using nearest neighbor and other weights

Point processes

▶ Intensity is simply the number of events over area:

$$\hat{\lambda} = \frac{Z}{A}$$

▶ k-function measures the number of events in a certain area from a certain point:

$$\hat{k}(h) = \frac{1}{\hat{\lambda}} \sum_{i} \sum_{j} \frac{1[d(\vec{s}_{i}, \vec{s}_{j}) < h]}{Z}$$

Matlab

Inverse distance weighting

Estimates using inverse distance weighting:

$$\hat{Z}(x) = \frac{1}{\sum_{i} d(x, x_{i})^{-k}} \left(Z_{1} d(x, x_{i})^{-k} + \cdots + Z_{N} d(x, x_{N})^{-k} \right)$$

- Think about it as an average of values close by
- Note that the right hand side is simply a weighted average, a generalization of an average

- ▶ Last year there were 6,743 crimes in Berkeley (area 46 sq. km), 28,085 crimes in Oakland (202 sq. km) and 39,244 crimes in San Francisco (600 sq. km). Which city has the highest average spatial density of crime events?
 - 1. Berkeley
 - 2. Oakland
 - 3. San Francisco
 - 4. not enough information

Midterm question

► What can we say about two point processes *A* and *B* that have the following *k*-functions:

$$k_B(h) = k_A(h) = \pi \times h^2$$

- 1. *A* is homogenous
- 2. *B* is homogenous
- 3. A and B are probably Poisson Point Processes
- 4. A and B are probably not Poisson Point Processes
- 5. $\lambda_A(\vec{c}) = \lambda_B(\vec{c})$
- 6. none of the above

Matlab

- ▶ Given the set of points $S = \{[2,3]; [4,9]; [-3,0]\}$, the centroid of S is:
 - 1. [1, 4]
 - 2. [1.5, 6]
 - **3**. [3, 6]
 - 4. [2, 3]
 - 5. none of the above

Matlab

Midterm question

▶ You're given the following data with locations and income:

$$\tilde{H} = \begin{cases} \vec{\varsigma}_1 = [6, 4], & Y_1 = \$24,000 \\ \vec{\varsigma}_2 = [2, 7], & Y_2 = \$32,000 \\ \vec{\varsigma}_3 = [1, 3], & Y_3 = \$30,000 \end{cases}$$

Use (1) nearest-neighbor, and (2) inverse distance weighting interpolation, to estimate the income of a household located in $\vec{c} = [3,4]$. Which one do you prefer?

Polylines

► Things you need to know:

- 1. Definitions:
 - lines
 - polygon
 - polylines
 - multiple polygons
- 2. Concepts:
 - concavity
 - convexity

▶ Line: $\ell = \{\vec{x}, \vec{y}\}$, where $\vec{x} = [x_1, x_2]'$ and $\vec{y} = [y_1, y_2]'$

- Polyline: $L = \{\vec{x}, \vec{y}\}$, where $\vec{x} = [x_1, \dots, x_N]'$ and $\vec{y} = [y_1, \dots, y_N]'$
- ▶ A polygon P is a polyline where $x_1 = x_N$ and $y_1 = y_N$
- ▶ A multiple polygon is a set of polygons $H = \{P_1, P_2, P_3\}$
- ▶ A polygon is convex if a linear combination of any two points remains inside the polygon. Concave = ¬ (Convex)

- ▶ A 5-pointed star is a convex shape
 - 1. true
 - 2. false

Midterm question

► Suppose you are given this structure in Matlab:

```
A.x = [0 \ 2 \ 1 \ 0 \ NaN \ 0 \ -1 \ 0 \ 1 \ 0 \ NaN \ 3 \ 4 \ 4 \ 3 \ 3]
A.y = [0 \ -1 \ 1 \ 0 \ NaN \ 4 \ 3 \ 2 \ 3 \ 4 \ NaN \ 2 \ 2 \ 3 \ 3 \ 2]
```

Are each of the polygons individually convex?

- 1. Yes
- 2. No
- 3. not enough information

Networks

- ► Things you need to know:
 - 1. Definitions
 - network
 - connectivity matrix
 - 2. How to interpret a connectivity matrix
 - 3. What is a stimulus

Definitions

► A network is a set of vertices and edges with a structure composed by attributes and a connectivity matrix:

$$\Gamma = \left\{ \vec{x}, \vec{y}, \vec{A}, L \right\}$$

- Let N be the number of vertices. Then, the connectivity matrix L has dimension $N \times N$, with L(i,j) = 1 if i and j connected and L(i,j) = 0 otherwise
- A stimulus is a signal transmitted through the network. $L \times \vec{S}$ receives the signal

Midterm question

► Individuals with connectivity matrix:
$$L = \begin{bmatrix} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$$

Which statement are true?

- 1. there are 10 individuals in the network
- 2. individual 3 and 4 are connected
- 3. individual 1 and 4 are not connected
- 4. individual 5 is considered 'connected' to herself
- 5. none of the above

► Connectivity matrix for ports:
$$L = \begin{bmatrix} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

- ▶ If a crate of coffee begins at location 1, is it possible to go to 5 using existing routes?
 - 1. Yes
 - 2. No

Fields

- ► Things you need to know:
 - 1. Definitions:
 - ► field
 - raster
 - contour
- ► What is map algebra

Fields

location

▶ A field is a function over space, i.e., an attribute at every

- ▶ A <u>raster</u> is the approximation of a field using a grid where points have a uniform value in each grid of area $\delta_x \cdot \delta_y$
- ► A <u>contour</u> is a polyline where the field value at points on the line is <u>constant</u>

Map algebra

- ► <u>Map algebra</u> is simply the computation of functions of fields on a point-wise basis, i.e., computed at each point separately
- Masking is one type of map algebra in which one of the fields, the mask, is binary

- ► What are examples of a <u>field</u>?
 - 1. temperature
 - 2. the risk of a car accident occurring
 - 3. all the rivers in the world
 - 4. your address
 - 5. travel time to Times Square, NYC
 - 6. the highest elevation in the country
 - 7. none of the above

Midterm question

- ▶ Which are examples of a static field?
 - . .
 - 2. the length of each river segment in Brazil
 - 3. the 3-dimensional centroid of each room in GSPP
 - 4. travel time to Ghirardelli Square, SF

1. the quality of soil across Wyoming

- 5. the population of all counties in China
- 6. the average crime rate
- 7. none of the above

High dimensional data

- A vector field is a vector of data \vec{f} at each location \vec{c}
- ► A <u>dynamic field</u> is a vector of fields in which elements in the vector represent sequential observations
- ► A <u>dynamic vector field</u> as multiple variables that vary over time at every point

- ▶ We collect temperature and rainfall data for all of Africa every day for a year. This data set represents a:
 - 1. dynamic vector field
 - static field
 - 3. gradient
 - 4. point process
 - 5. delimited shapefile
 - 6. kernel estimate
 - 7. none of the above

Matlab

- ► Things you need to know:
 - 1. Concepts we used in Labs
 - 2. Be ready to think in code terms
 - 3. Be ready to explain rough steps on how to code something

- ► A mask is useful for:
 - 1. measuring the bandwidth of a kernel
 - 2. computing the k-function for a Poison point process
 - 3. isolating raster data in a region of interest
 - 4. none of the above

- ► In Matlab, a buffer is:
 - 1. field
 - 2. raster
 - 3. polygon
 - 4. topology
 - 5. point process
 - 6. moving window

The End