# 732A95/TDDE01 Introduction to Machine Learning Lecture 3b Block 1: Support Vector Machines

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#### Contents

- Support Vector Machines for Classification
- Support Vector Machines for Regression
- Summary

#### Literature

- Main source
  - Bishop, C. M. Pattern Recognition and Machine Learning. Springer, 2006.
     Section 7.1.

- Consider binary classification with input space  $\mathbb{R}^D$ .
- ▶ Consider a training set  $\{(\mathbf{x}_n, t_n)\}$  where  $t_n \in \{-1, +1\}$ .
- Consider using the linear model

$$y(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + b$$

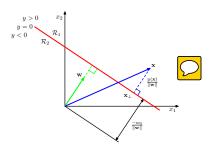
so that a new point x is classified according to the sign of y(x).

Assume that the training set is linearly separable in the feature space (but not necessarily in the input space), i.e.  $t_n y(\mathbf{x}_n) > 0$  for all n.



Aim for the separating hyperplane that maximizes the margin (i.e. the smallest perpendicular distance from any point to the hyperplane) so as to minimize the generalization error.





▶ The perpendicular distance from any point to the hyperplane is given by

$$\frac{t_n y(\mathbf{x}_n)}{\|\mathbf{w}\|} = \frac{t_n(\mathbf{w}^T \phi(\mathbf{x}_n) + b)}{\|\mathbf{w}\|}$$

▶ Then, the maximum margin separating hyperplane is given by

$$\underset{\boldsymbol{w},b}{\operatorname{arg\,max}} \Big( \min_{n} \frac{t_{n}(\boldsymbol{w}^{T} \phi(\boldsymbol{x}_{n}) + b)}{\|\boldsymbol{w}\|} \Big)$$

Multiply  $\mathbf{w}$  and b by  $\kappa$  so that  $t_n(\mathbf{w}^T\phi(\mathbf{x}_n)+b)=1$  for the point closest to the hyperplane. Note that  $t_n(\mathbf{w}^T\phi(\mathbf{x}_n)+b)/||\mathbf{w}||$  does not change.

▶ Then, the maximum margin separating hyperplane is given by

$$\underset{\boldsymbol{w},b}{\arg\min} \ \frac{1}{2} \|\boldsymbol{w}\|^2$$

subject to  $t_n(\mathbf{w}^T \phi(\mathbf{x}_n) + b) \ge 1$  for all n.

▶ To minimize the previous expression, we minimize

$$\frac{1}{2}||\boldsymbol{w}||^2 - \sum_{n} a_n (t_n(\boldsymbol{w}^T \phi(\boldsymbol{x}_n) + b) - 1)$$

where  $a_n \ge 0$  are called Lagrange multipliers.

- Note that any stationary point of the Lagrangian function is a stationary point of the original function subject to the constraints. Moreover, the Lagrangian function is a quadratic function subject to linear inequality constraints. Then, it is concave, actually concave up because of the +1/2 and, thus, "easy" to minimize.
- Note that we are now minimizing with respect to w and b, and maximizing with respect to a<sub>n</sub>.
- ▶ Setting its derivatives with respect to **w** and b to zero gives

$$\mathbf{w} = \sum_{n} a_{n} t_{n} \phi(\mathbf{x}_{n})$$
$$0 = \sum_{n} a_{n} t_{n}$$

 Replacing the previous expressions in the Lagrangian function gives the dual representation of the problem, in which we maximize

$$\sum_{n} a_{n} - \frac{1}{2} \sum_{n} \sum_{m} a_{n} a_{m} t_{n} t_{m} \phi(\boldsymbol{x}_{n})^{T} \phi(\boldsymbol{x}_{m}) = \sum_{n} a_{n} - \frac{1}{2} \sum_{n} \sum_{m} a_{n} a_{m} t_{n} t_{m} k(\boldsymbol{x}_{n}, \boldsymbol{x}_{m})$$

subject to  $a_n \ge 0$  for all n, and  $\sum_n a_n t_n = 0$ .

- Again, this "easy" to maximize.
- Note that the dual representation makes use of the kernel trick, i.e. it allows working in a more convenient feature space without constructing it.

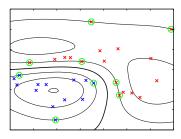
When the Lagrangian function is maximized, the Karush-Kuhn-Tucker condition holds for all n:

$$a_n(t_n y(\boldsymbol{x}_n) - 1) = 0$$

- ▶ Then,  $a_n > 0$  if and only if  $t_n y(x_n) = 1$ . The points with  $a_n > 0$  are called support vectors and they lie on the margin boundaries.
- A new point x is classified according to the sign of

$$y(\mathbf{x}) = \mathbf{w}^{T} \phi(\mathbf{x}) + b = \sum_{n} a_{n} t_{n} \phi(\mathbf{x}_{n})^{T} \phi(\mathbf{x}) + b = \sum_{n} a_{n} t_{n} k(\mathbf{x}, \mathbf{x}_{n}) + b$$
$$= \sum_{m \in S} a_{m} t_{m} k(\mathbf{x}, \mathbf{x}_{m}) + b$$

where S are the indexes of the support vectors.



▶ To find b, consider any support vector  $\mathbf{x}_n$ . Then,

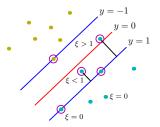
$$1 = t_n y(\mathbf{x}_n) = t_n \Big( \sum_{m \in \mathcal{S}} a_m t_m k(\mathbf{x}_n, \mathbf{x}_m) + b \Big)$$

and multiplying both sides by  $t_n$ , we have that

$$b = t_n - \sum_{m \in \mathcal{S}} a_m t_m k(\mathbf{x}_n, \mathbf{x}_m)$$

 We now drop the assumption of linear separability in the feature space, e.g. to avoid overfitting. We do so by introducing the slack variables ξ<sub>n</sub> ≥ 0 to penalize (almost-)misclassified points as

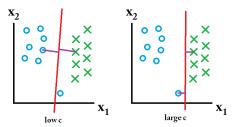
$$\xi_n = \begin{cases} 0 & \text{if } t_n y(\mathbf{x}_n) \ge 1 \\ |t_n - y(\mathbf{x}_n)| & \text{otherwise} \end{cases}$$



The optimal separating hyperplane is given by

$$\underset{\boldsymbol{w},b}{\operatorname{arg\,min}} \frac{1}{2} ||\boldsymbol{w}||^2 + C \sum_n \xi_n$$

subject to  $t_n y(\mathbf{x}_n) \geq 1 - \xi_n$  and  $\xi_n \geq 0$  for all n, and where C > 0 controls regularization. Its value can be decided by cross-validation. Note that the number of misclassified points is upper bounded by  $\sum_n \xi_n$ .



▶ To minimize the previous expression, we minimize

$$\frac{1}{2}||\boldsymbol{w}||^2 + C\sum_n \xi_n - \sum_n a_n (t_n(\boldsymbol{w}^T \phi(\boldsymbol{x}_n) + b) - 1 + \xi_n) - \sum_n \mu_n \xi_n$$

where  $a_n \ge 0$  and  $\mu_n \ge 0$  are Lagrange multipliers.

• Setting its derivatives with respect to  $\mathbf{w}$ , b and  $\xi_n$  to zero gives

$$\mathbf{w} = \sum_{n} a_{n} t_{n} \phi(\mathbf{x}_{n})$$
$$0 = \sum_{n} a_{n} t_{n}$$
$$a_{n} = C - \mu_{n}$$

 Replacing these in the Lagrangian function gives the dual representation of the problem, in which we maximize

$$\sum_{n} a_{n} - \frac{1}{2} \sum_{n} \sum_{m} a_{n} a_{m} t_{n} t_{m} k(\boldsymbol{x}_{n}, \boldsymbol{x}_{m})$$

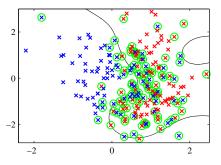
subject to  $a_n \ge 0$  and  $a_n \le C$  for all n, because  $\mu_n \ge 0$ .

When the Lagrangian function is maximized, the Karush-Kuhn-Tucker conditions hold for all n:

$$a_n(t_n y(\mathbf{x}_n) - 1 + \xi_n) = 0$$
$$\mu_n \xi_n = 0$$

- ► Then,  $a_n > 0$  if and only if  $t_n y(x_n) = 1 \xi_n$  for all n. The points with  $a_n > 0$  are called support vectors and they lie
  - on the margin if  $a_n < C$ , because then  $\mu_n > 0$  and thus  $\xi_n = 0$ , or
  - inside the margin (even on the wrong side of the decision boundary) if  $a_n = C$ , because then  $\mu_n = 0$  and thus  $\xi_n$  is unconstrained.

• Since the optimal w takes the same form as in the linearly separable case, classifying a new point is done the same as before. Finding b is done the same as before by considering any support vector  $\mathbf{x}_n$  with  $0 < a_n < C$ .



- Not covered topics:
  - Classifying into more than two classes.
  - Returning class posterior probabilities.

- Consider regressing an unidimensional continuous random variable on a D-dimensional continuous random variable.
- Consider a training set  $\{(\boldsymbol{x}_n, t_n)\}$ . Consider using the linear model

$$y(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + b$$

Instead of minimizing the classical regularized error function

$$\frac{1}{2}\sum_{n}(y(\boldsymbol{x}_{n})-t_{n})^{2}+\frac{\lambda}{2}||\boldsymbol{w}||^{2}$$

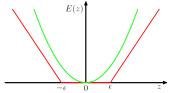
consider minimizing the  $\epsilon$ -insensitive regularized error function

$$C\sum_{n}E_{\epsilon}(y(\boldsymbol{x}_{n})-t_{n})+\frac{1}{2}||\boldsymbol{w}||^{2}$$

where C > 0 controls regularization and

$$E_{\epsilon}(y(\mathbf{x}) - t) = \begin{cases} 0 & \text{if } |y(\mathbf{x}) - t| < \epsilon \\ |y(\mathbf{x}) - t| - \epsilon & \text{otherwise} \end{cases}$$

Figure 7.6 Plot of an ε-insensitive error function (in red) in which the error increases linearly with distance beyond the insensitive region. Also shown for comparison is the quadratic error function (in green).

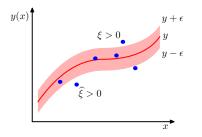


- ▶ The values of C and  $\epsilon$  can be decided by cross-validation.
- Consider the slack variables  $\xi \ge 0$  and  $\widehat{\xi}_n \ge 0$  such that

$$\xi_n = \begin{cases} t_n - y(\mathbf{x}_n) - \epsilon & \text{if } t_n > y(\mathbf{x}_n) + \epsilon \\ 0 & \text{otherwise} \end{cases}$$

and

$$\widehat{\xi}_n = \begin{cases} y(\mathbf{x}_n) + \epsilon - t_n & \text{if } t_n < y(\mathbf{x}_n) + \epsilon \\ 0 & \text{otherwise} \end{cases}$$



▶ The optimal regression curve is given by

$$\underset{\boldsymbol{w}}{\operatorname{arg\,min}} C \sum_{n} (\xi_{n} + \widehat{\xi}_{n}) + \frac{1}{2} ||\boldsymbol{w}||^{2}$$

subject to  $\xi \ge 0$ ,  $\widehat{\xi}_n \ge 0$ ,  $t_n \le y(\mathbf{x}_n) + \epsilon + \xi_n$  and  $t_n \ge y(\mathbf{x}_n) - \epsilon - \widehat{\xi}_n$ .

To minimize the previous expression, we minimize

$$C \sum_{n} (\xi_{n} + \widehat{\xi}_{n}) + \frac{1}{2} ||\mathbf{w}||^{2} - \sum_{n} (\mu_{n} \xi_{n} + \widehat{\mu}_{n} \widehat{\xi}_{n})$$
$$- \sum_{n} a_{n} (y(\mathbf{x}_{n}) + \epsilon + \xi_{n} - t_{n}) - \sum_{n} \widehat{a}_{n} (t_{n} - y(\mathbf{x}_{n}) + \epsilon + \widehat{\xi}_{n})$$

where  $\mu_n \ge 0$ ,  $\widehat{\mu}_n \ge 0$ ,  $a_n \ge 0$  and  $\widehat{a}_n \ge 0$  are Lagrange multipliers.

• Setting its derivatives with respect to  $\boldsymbol{w}$ , b,  $\xi_n$  and  $\widehat{\xi}_n$  to zero gives

$$\mathbf{w} = \sum_{n} (a_{n} - \widehat{a}_{n}) \phi(\mathbf{x}_{n})$$

$$0 = \sum_{n} (a_{n} - \widehat{a}_{n})$$

$$C = a_{n} + \mu_{n}$$

$$C = \widehat{a}_{n} + \widehat{\mu}_{n}$$

 Replacing these in the Lagrangian function gives the dual representation of the problem, in which we maximize

$$\frac{1}{2}\sum_{n}\sum_{m}(a_{n}-\widehat{a}_{n})(a_{m}-\widehat{a}_{m})k(\boldsymbol{x}_{n},\boldsymbol{x}_{m})-\epsilon\sum_{n}(a_{n}+\widehat{a}_{n})+\sum_{n}(a_{n}-\widehat{a}_{n})t_{n}$$

subject to  $a_n \ge 0$  and  $a_n \le C$  for all n, because  $\mu_n \ge 0$ . Similarly for  $\widehat{a}_n$ .

When the Lagrangian function is maximized, the Karush-Kuhn-Tucker conditions hold for all n:

$$a_n(y(\mathbf{x}_n) + \epsilon + \xi_n - t_n) = 0$$

$$\widehat{a}_n(t_n - y(\mathbf{x}_n) + \epsilon + \widehat{\xi}_n) = 0$$

$$\mu_n \xi_n = 0$$

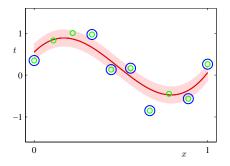
$$\widehat{\mu}_n \widehat{\xi}_n = 0$$

▶ Then,  $a_n > 0$  if and only if  $y(\mathbf{x}_n) + \epsilon + \xi_n - t_n = 0$ , which implies that  $\mathbf{x}_n$  lies on or above the upper margin of the  $\epsilon$ -tube. Similarly for  $\widehat{a}_n > 0$ .

▶ The prediction for a new point **x** is made according to

$$y(\boldsymbol{x}) = \sum_{m \in \mathcal{S}} (a_m - \widehat{a}_m) k(\boldsymbol{x}, \boldsymbol{x}_m) + b$$

where S are the indexes of the support vectors.



► To find b, consider any support vector  $\mathbf{x}_n$  with  $0 < a_n < C$ . Then,  $\mu_n > 0$  and thus  $\xi_n = 0$  and thus  $0 = t_n - \epsilon - y(\mathbf{x}_n)$ . Then,

$$b = t_n - \epsilon - \sum_{m \in \mathcal{S}} (a_m - \widehat{a}_m) k(\boldsymbol{x}_n, \boldsymbol{x}_m)$$

#### Summary

- Kernel trick: It allows to work in the feature space without constructing it.
- Properties Quadratic objective function: It allows to obtain the global optimum for a given kernel and  $C/\epsilon$  (which are obtained by cross-validation).
- Sparse model: Only the support vectors are needed for classification/regression (compare with kernel models).