

## ▼ When was used MSE measurement and when cross\_entropy(log loss)?

While cross entropy measures the classification performances whose outputs are probability between 0 and 1, MSE (mean square error) measures the regression performance.

## ▼ When is softmax activation function used?

Softmax activation function is used for multiclass classification predicting class membership probabilities of output layer which classes are mutually exclusive.

## ▼ What is difference between incremental learning and batch learning?

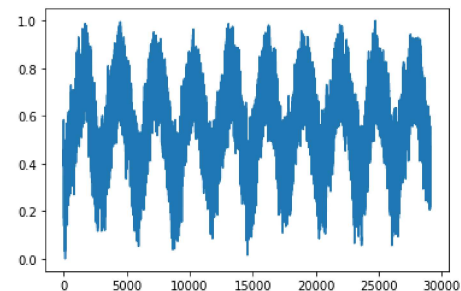
While in incremental learning the learning algorithm and its weights are updated by one training data, in batch learning they are updated by average of multiple training data feedback, providing faster speed on algorithm. Each learning method is appropriate for various problems. For example, batch learning is applied for systems only have new data every week, but in case of every minute data changing, incremental learning is more suitable. In addition, incremental learning will be efficient if machine learning's memory is not enough for huge data.

```
1 import pandas as pd
2 import numpy as np
3 import matplotlib.pyplot as plt
4 from tensorflow.keras.layers.experimental import preprocessing
5 import tensorflow as tf
6 from tensorflow.keras.utils import timeseries_dataset_from_array
7 from sklearn.model_selection import train_test_split
8 from keras.models import Sequential
9 from keras.layers import Dense
10
11
12 tmps_df = pd.read_excel('/content/drive/MyDrive/Temperature.xlsx')
13 dataset = np.array(tmps_df['تسا'])
14 print("total number = {}".format(len(dataset)))
```

```
total number = 29095
```

```
1 from sklearn.preprocessing import MinMaxScaler
2 scaler = MinMaxScaler()
3 print(scaler.fit(dataset.reshape(-1,1)))
4
5 print(scaler.data_max_)
6
7 normed_dataset = scaler.transform(dataset.reshape(-1,1))
8 plt.plot(normed_dataset)
9 print(normed_dataset.shape)
```

```
MinMaxScaler(copy=True, feature_range=(0, 1))
[41.7]
(29095, 1)
```



Data before normalization

```
1
2 plt.plot(dataset)
```

[<matplotlib.lines.Line2D at 0x7f4fbc886950>]

```
1
2 normalizer = preprocessing.Normalization(axis=None)
3 normalizer.adapt(dataset)
4 normed_dataset = normalizer(dataset)
```

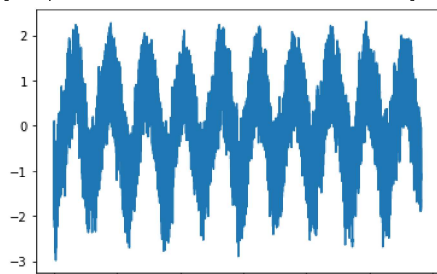
| 

Data after normalization

0 | 

```
1 plt.plot(normed_dataset)
```

[<matplotlib.lines.Line2D at 0x7f4fbc55e90>]



```
1
2 def prepare_timeseries(dataset, window_size, sequence_stride, sampling_rate=1):
3     time_series = timeseries_dataset_from_array(
4         dataset[:-sequence_stride], dataset[window_size:], window_size, sequence_stride=1, sampling_rate=1, batch_size=len(dataset), shuffle=True
5     )
6     return time_series.get_single_element()
7
8 window_sizes = [3, 5, 10]
9
10 time_series = prepare_timeseries(normed_dataset.flatten(), window_size=window_sizes[0], sequence_stride=1, sampling_rate=1)
11 x1, y1 = time_series
12 x1train, x1test = tf.split(x1, [ int(0.7*len(x1)), len(x1) - int(0.7*len(x1))] )
13 y1train, y1test = tf.split(y1, [ int(0.7*len(y1)), len(y1) - int(0.7*len(y1))] )
14
15 print("with winodw size={} train data{}={}".format(3, 1,x1train.shape))
16 print("with winodw size={} test data{}={}\n\n".format(3, 1,x1test.shape))
17
18 time_series = prepare_timeseries(normed_dataset.flatten(), window_size=window_sizes[1], sequence_stride=1, sampling_rate=1)
19 x2, y2 = time_series
20 x2train, x2test = tf.split(x2, [ int(0.7*len(x2)), len(x2) - int(0.7*len(x2))] )
21 y2train, y2test = tf.split(y2, [ int(0.7*len(y2)), len(y2) - int(0.7*len(y2))] )
22 print("with winodw size={} train data{}={}".format(3, 2,x2train.shape))
23 print("with winodw size={} test data{}={}\n\n".format(3, 2,x2test.shape))
24
25 time_series = prepare_timeseries(normed_dataset.flatten(), window_size=window_sizes[2], sequence_stride=1, sampling_rate=1)
26 x3, y3 = time_series
27 x3train, x3test = tf.split(x3, [ int(0.7*len(x3)), len(x3) - int(0.7*len(x3))] )
28 y3train, y3test = tf.split(y3, [ int(0.7*len(y3)), len(y3) - int(0.7*len(y3))] )
29 print("with winodw size={} train data{}={}".format(3, 3,x3train.shape))
30 print("with winodw size={} test data{}={}\n\n".format(3, 3, x3test.shape))
31
32
```

```
with winodw size=3 train data1=(20364, 3)
with winodw size=3 test data1=(8728, 3)
```

```
with winodw size=3 train data2=(20363, 5)
with winodw size=3 test data2=(8727, 5)
```

```
with winodw size=3 train data3=(20359, 10)
with winodw size=3 test data3=(8726, 10)
```

Window size = 3

```
1
2 model1 = Sequential()
3 model1.add(Dense(8, activation='relu'))
4
5 optimizer = tf.keras.optimizers.Adam(learning_rate=0.01)
6 model1.add(Dense(1,))
7
8 model1.compile(loss='mean_squared_error',optimizer=optimizer)
9 model1.build(input_shape=(1,window_sizes[0]))
10 model1.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
dense (Dense)	(1, 8)	32

```

dense_1 (Dense)          (1, 1)          9
=====
Total params: 41
Trainable params: 41
Non-trainable params: 0

```

```
1 history = model1.fit(x1train, y1train, validation_split=0.3, epochs=20, shuffle=True, verbose=1)
```

```

Epoch 1/20
446/446 [=====] - 2s 2ms/step - loss: 0.0140 - val_loss: 0.0050
Epoch 2/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0047
Epoch 3/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0056
Epoch 4/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0049
Epoch 5/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0046
Epoch 6/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0048
Epoch 7/20
446/446 [=====] - 1s 2ms/step - loss: 0.0049 - val_loss: 0.0045
Epoch 8/20
446/446 [=====] - 1s 2ms/step - loss: 0.0049 - val_loss: 0.0044
Epoch 9/20
446/446 [=====] - 1s 2ms/step - loss: 0.0048 - val_loss: 0.0045
Epoch 10/20
446/446 [=====] - 1s 2ms/step - loss: 0.0049 - val_loss: 0.0045
Epoch 11/20
446/446 [=====] - 1s 2ms/step - loss: 0.0049 - val_loss: 0.0044
Epoch 12/20
446/446 [=====] - 1s 2ms/step - loss: 0.0047 - val_loss: 0.0046
Epoch 13/20
446/446 [=====] - 1s 2ms/step - loss: 0.0047 - val_loss: 0.0044
Epoch 14/20
446/446 [=====] - 1s 2ms/step - loss: 0.0046 - val_loss: 0.0044
Epoch 15/20
446/446 [=====] - 1s 2ms/step - loss: 0.0046 - val_loss: 0.0043
Epoch 16/20
446/446 [=====] - 1s 2ms/step - loss: 0.0048 - val_loss: 0.0044
Epoch 17/20
446/446 [=====] - 1s 2ms/step - loss: 0.0047 - val_loss: 0.0044
Epoch 18/20
446/446 [=====] - 1s 2ms/step - loss: 0.0047 - val_loss: 0.0044
Epoch 19/20
446/446 [=====] - 1s 2ms/step - loss: 0.0046 - val_loss: 0.0046
Epoch 20/20
446/446 [=====] - 1s 2ms/step - loss: 0.0047 - val_loss: 0.0044

```

```
1 model1.evaluate(x1test,y1test)
```

```

273/273 [=====] - 0s 998us/step - loss: 0.0045
0.004452623426914215

```

```

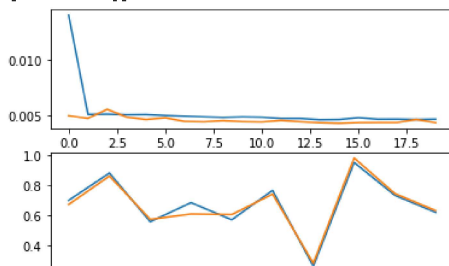
1 plt.subplot(2, 1, 1)
2 plt.plot(history.history['loss'])
3 plt.plot(history.history['val_loss'])
4
5 plt.subplot(2, 1, 2)
6 predicts = model1.predict(x1test)
7 plt.plot(predicts[:10])
8 plt.plot(y1test[:10])
9 print(predicts)

```

```

[[0.6981483 ]
 [0.8803155 ]
 [0.5555564 ]
 ...
 [0.28835797]
 [0.8523818 ]
 [0.657255  ]]

```



Window\_size 5 In this part i wil illustrate how plaining the netwrok structure results in bad result although the window size increased

```

1 model2 = Sequential()
2 # model2.add(Dense(8, activation='relu'))
3
4 optimizer = tf.keras.optimizers.Adam(learning_rate=0.01)
5 model2.add(Dense(1,))
6

```

```
7 model2.compile(loss='mean_squared_error',optimizer=optimizer)
8 model2.build(input_shape=(1,window_sizes[1]))
9 model2.summary()
10 history = model2.fit(x2train, y2train, validation_split=0.3, epochs=20, shuffle=True, verbose=1)
11 model2.evaluate(x2test,y2test)
```

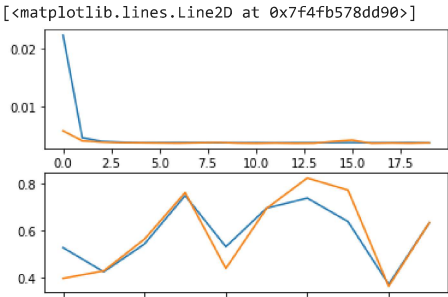
Model: "sequential\_1"

Layer (type)	Output Shape	Param #
dense_2 (Dense)	(1, 1)	6
Total params: 6		
Trainable params: 6		
Non-trainable params: 0		

Epoch 1/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0224 - val\_loss: 0.0057  
Epoch 2/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0045 - val\_loss: 0.0039  
Epoch 3/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0038 - val\_loss: 0.0037  
Epoch 4/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0037 - val\_loss: 0.0036  
Epoch 5/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0036  
Epoch 6/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 7/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 8/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0036  
Epoch 9/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0037  
Epoch 10/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 11/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 12/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 13/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 14/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 15/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0038  
Epoch 16/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0036 - val\_loss: 0.0041  
Epoch 17/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 18/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 19/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0036 - val\_loss: 0.0035  
Epoch 20/20  
446/446 [=====] - 1s 1ms/step - loss: 0.0036 - val\_loss: 0.0036  
273/273 [=====] - 0s 1ms/step - loss: 0.0035  
0.003546466352418065

Predicts

```
1 plt.subplot(2, 1, 1)
2 plt.plot(history.history['loss'])
3 plt.plot(history.history['val_loss'])
4
5 plt.subplot(2, 1, 2)
6 predicts = model2.predict(x2test)
7 plt.plot(predicts[:10])
8 plt.plot(y2test[:10])
```



Window size 10

```
1 model3 = Sequential()
2 # model3.add(Dense(8, activation='relu'))
3
4 optimizer = tf.keras.optimizers.Adam(learning_rate=0.01)
5 model3.add(Dense(1,))
6
7 model3.compile(loss='mean_squared_error',optimizer=optimizer)
8 model3.build(input_shape=(1,window_sizes[2]))
```

```

model3.summary()
10 history = model3.fit(x3train, y3train, validation_split=0.3, epochs=20, shuffle=True, verbose=1)
11 model3.evaluate(x3test, y3test)

```

Model: "sequential\_2"

Layer (type)	Output Shape	Param #
dense_3 (Dense)	(1, 1)	11
Total params: 11		
Trainable params: 11		
Non-trainable params: 0		

```

Epoch 1/20
446/446 [=====] - 1s 2ms/step - loss: 0.1127 - val_loss: 0.0148
Epoch 2/20
446/446 [=====] - 1s 2ms/step - loss: 0.0071 - val_loss: 0.0032
Epoch 3/20
446/446 [=====] - 1s 2ms/step - loss: 0.0027 - val_loss: 0.0024
Epoch 4/20
446/446 [=====] - 1s 2ms/step - loss: 0.0023 - val_loss: 0.0022
Epoch 5/20
446/446 [=====] - 1s 2ms/step - loss: 0.0021 - val_loss: 0.0020
Epoch 6/20
446/446 [=====] - 1s 2ms/step - loss: 0.0019 - val_loss: 0.0018
Epoch 7/20
446/446 [=====] - 1s 2ms/step - loss: 0.0018 - val_loss: 0.0018
Epoch 8/20
446/446 [=====] - 1s 2ms/step - loss: 0.0017 - val_loss: 0.0016
Epoch 9/20
446/446 [=====] - 1s 1ms/step - loss: 0.0016 - val_loss: 0.0014
Epoch 10/20
446/446 [=====] - 1s 2ms/step - loss: 0.0015 - val_loss: 0.0013
Epoch 11/20
446/446 [=====] - 1s 2ms/step - loss: 0.0014 - val_loss: 0.0012
Epoch 12/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0012
Epoch 13/20
446/446 [=====] - 1s 1ms/step - loss: 0.0013 - val_loss: 0.0012
Epoch 14/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0012
Epoch 15/20
446/446 [=====] - 1s 2ms/step - loss: 0.0014 - val_loss: 0.0014
Epoch 16/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0012
Epoch 17/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0011
Epoch 18/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0012
Epoch 19/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0012
Epoch 20/20
446/446 [=====] - 1s 2ms/step - loss: 0.0013 - val_loss: 0.0012
273/273 [=====] - 0s 1ms/step - loss: 0.0013
0.0012868698686361313

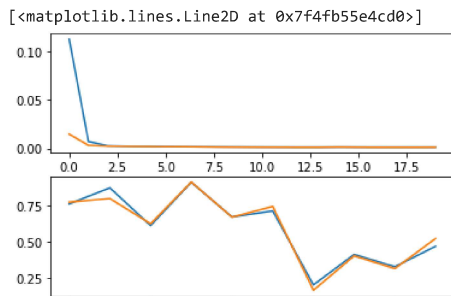
```

The line graph provided shows that as window become bigger model can learn more.

```

1 plt.subplot(2, 1, 1)
2 plt.plot(history.history['loss'])
3 plt.plot(history.history['val_loss'])
4
5 plt.subplot(2, 1, 2)
6 predicts = model3.predict(x3test)
7 plt.plot(predicts[:10])
8 plt.plot(y3test[:10])

```



lets change the activation function for window size 5

```

1 model4 = Sequential()
2 model4.add(Dense(2, activation='sigmoid'))
3
4 optimizer = tf.keras.optimizers.Adam(learning_rate=0.01)
5 model4.add(Dense(1,))
6
7 model4.compile(loss='mean_squared_error', optimizer=optimizer)
8 model4.build(input_shape=(1, window_sizes[0]))
9 model4.summary()
10 history = model4.fit(x1train, y1train, validation_split=0.3, epochs=20, shuffle=True, verbose=1)

```

```
11 model4.evaluate(x1test,y1test)
```

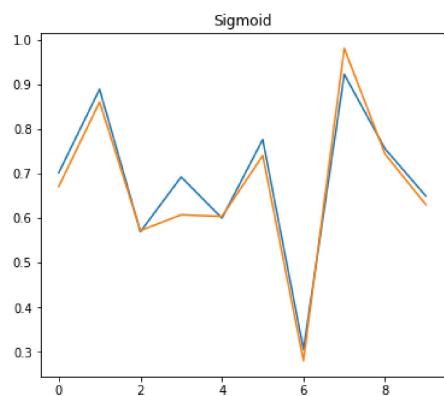
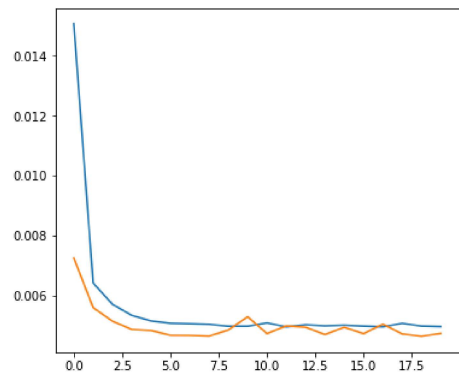
```
Model: "sequential_3"
```

Layer (type)	Output Shape	Param #
dense_4 (Dense)	(1, 2)	8
dense_5 (Dense)	(1, 1)	3
Total params: 11		
Trainable params: 11		
Non-trainable params: 0		

```
Epoch 1/20
446/446 [=====] - 1s 2ms/step - loss: 0.0151 - val_loss: 0.0073
Epoch 2/20
446/446 [=====] - 1s 2ms/step - loss: 0.0064 - val_loss: 0.0056
Epoch 3/20
446/446 [=====] - 1s 2ms/step - loss: 0.0057 - val_loss: 0.0052
Epoch 4/20
446/446 [=====] - 1s 2ms/step - loss: 0.0053 - val_loss: 0.0049
Epoch 5/20
446/446 [=====] - 1s 2ms/step - loss: 0.0052 - val_loss: 0.0048
Epoch 6/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0047
Epoch 7/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0047
Epoch 8/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0047
Epoch 9/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0049
Epoch 10/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0053
Epoch 11/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0047
Epoch 12/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0050
Epoch 13/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0049
Epoch 14/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0047
Epoch 15/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0049
Epoch 16/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0047
Epoch 17/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0051
Epoch 18/20
446/446 [=====] - 1s 2ms/step - loss: 0.0051 - val_loss: 0.0047
Epoch 19/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0046
Epoch 20/20
446/446 [=====] - 1s 2ms/step - loss: 0.0050 - val_loss: 0.0047
273/273 [=====] - 0s 1ms/step - loss: 0.0049
0.004926361609250307
```

The line graph illustrates with sigmoid function model did not work as well as relu function model which is a linear function.As a result the linear regression does not work effectively with non-linear functions.

```
1 plt.subplot(3, 1, 1)
2 plt.plot(history.history['loss'])
3 plt.plot(history.history['val_loss'])
4
5 plt.subplot(3, 1, 2)
6 predicts = model4.predict(x1test)
7 plt.title('Sigmoid')
8 plt.plot(predicts[:10])
9 plt.plot(y1test[:10])
10
11 plt.subplot(3, 1, 3)
12 predicts = model1.predict(x1test)
13 plt.title('Relu')
14 plt.plot(predicts[:10])
15 plt.plot(y1test[:10])
16
17 plt.subplots_adjust( top=3.5)
18
```



lets change the learning rate

```
1 model5 = Sequential()  
2 model5.add(Dense(2, activation='relu'))  
3  
4 optimizer = tf.keras.optimizers.Adam(learning_rate=0.1)  
5 model5.add(Dense(1,))  
6  
7 model5.compile(loss='mean_squared_error',optimizer=optimizer)  
8 model5.build(input_shape=(1,window_sizes[0]))  
9 model5.summary()  
10 history = model5.fit(x1train, y1train, validation_split=0.3, epochs=20, shuffle=True, verbose=1)  
11 model5.evaluate(x1test,y1test)
```

Model: "sequential\_4"

Layer (type)	Output Shape	Param #
dense_6 (Dense)	(1, 2)	8
dense_7 (Dense)	(1, 1)	3

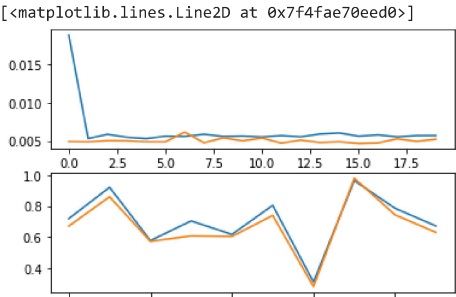
Total params: 11  
Trainable params: 11  
Non-trainable params: 0

```
Epoch 1/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0188 - val_loss: 0.0049  
Epoch 2/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0053 - val_loss: 0.0049  
Epoch 3/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0059 - val_loss: 0.0050  
Epoch 4/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0055 - val_loss: 0.0050  
Epoch 5/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0053 - val_loss: 0.0049  
Epoch 6/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0056 - val_loss: 0.0049  
Epoch 7/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0056 - val_loss: 0.0062  
Epoch 8/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0059 - val_loss: 0.0048  
Epoch 9/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0056 - val_loss: 0.0054  
Epoch 10/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0056 - val_loss: 0.0050  
Epoch 11/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0055 - val_loss: 0.0054  
Epoch 12/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0057 - val_loss: 0.0047  
Epoch 13/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0055 - val_loss: 0.0051  
Epoch 14/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0059 - val_loss: 0.0048  
Epoch 15/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0061 - val_loss: 0.0049  
Epoch 16/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0056 - val_loss: 0.0047  
Epoch 17/20  
446/446 [=====] - 1s 2ms/step - loss: 0.0058 - val_loss: 0.0047
```

```
Epoch 18/20
446/446 [=====] - 1s 2ms/step - loss: 0.0055 - val_loss: 0.0053
Epoch 19/20
446/446 [=====] - 1s 2ms/step - loss: 0.0057 - val_loss: 0.0049
Epoch 20/20
446/446 [=====] - 1s 2ms/step - loss: 0.0057 - val_loss: 0.0052
273/273 [=====] - 0s 1ms/step - loss: 0.0054
0.005379165057092905
```

it is evident that with bigger learning rate model works worse.

```
1 plt.subplot(2, 1, 1)
2 plt.plot(history.history['loss'])
3 plt.plot(history.history['val_loss'])
4
5 plt.subplot(2, 1, 2)
6 predicts = model5.predict(x1test)
7 plt.plot(predicts[:10])
8 plt.plot(y1test[:10])
```



lets change the loss function

```
1 model6 = Sequential()
2 model6.add(Dense(2, activation='relu'))
3
4 optimizer = tf.keras.optimizers.Adam(learning_rate=0.01)
5 model6.add(Dense(1,))
6
7 model6.compile(loss='binary_crossentropy',optimizer=optimizer)
8 model6.build(input_shape=(1,window_sizes[0]))
9 model6.summary()
10 history = model6.fit(x1train, y1train, validation_split=0.3, epochs=20, shuffle=True, verbose=1)
11 model6.evaluate(x1test,y1test)
```

Model: "sequential\_5"

Layer (type)	Output Shape	Param #
dense_8 (Dense)	(1, 2)	8
dense_9 (Dense)	(1, 1)	3

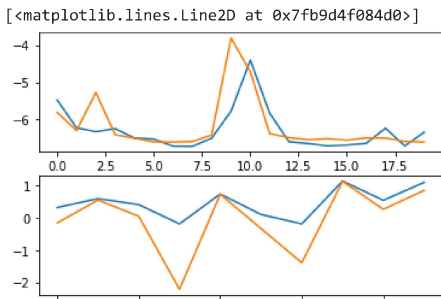
Total params: 11  
Trainable params: 11  
Non-trainable params: 0

```
Epoch 1/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 2/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 3/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 4/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 5/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 6/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 7/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 8/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 9/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 10/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 11/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 12/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 13/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 14/20
446/446 [=====] - 1s 2ms/step - loss: 8.7085 - val_loss: 8.6599
Epoch 15/20
272/446 [=====>.....] - ETA: 0s - loss: 8.7270
```

```
1 plt.subplot(2, 1, 1)
2 plt.plot(history.history['loss'])
```



```
3 plt.plot(history.history['val_loss'])
4
5 plt.subplot(2, 1, 2)
6 predicts = model6.predict(x1test)
7 plt.plot(predicts[:10])
8 plt.plot(y1test[:10])
```



## ▼ conclusion

- 1.linear activation functions are more appropriate for linear regression problems
- 2.As learning rate are become excessively big optimization algorithm could not find the best solution.
- 3.probability loss functions are not suitable for regression problems.
- 4.As layers in model increase overfitting occurred.
- 5.The most important point if window size increase, training model can learn better.