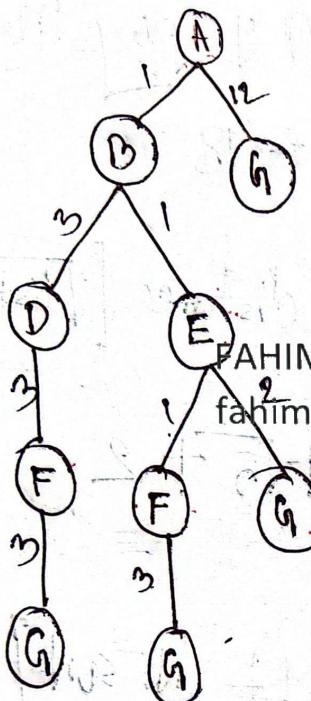


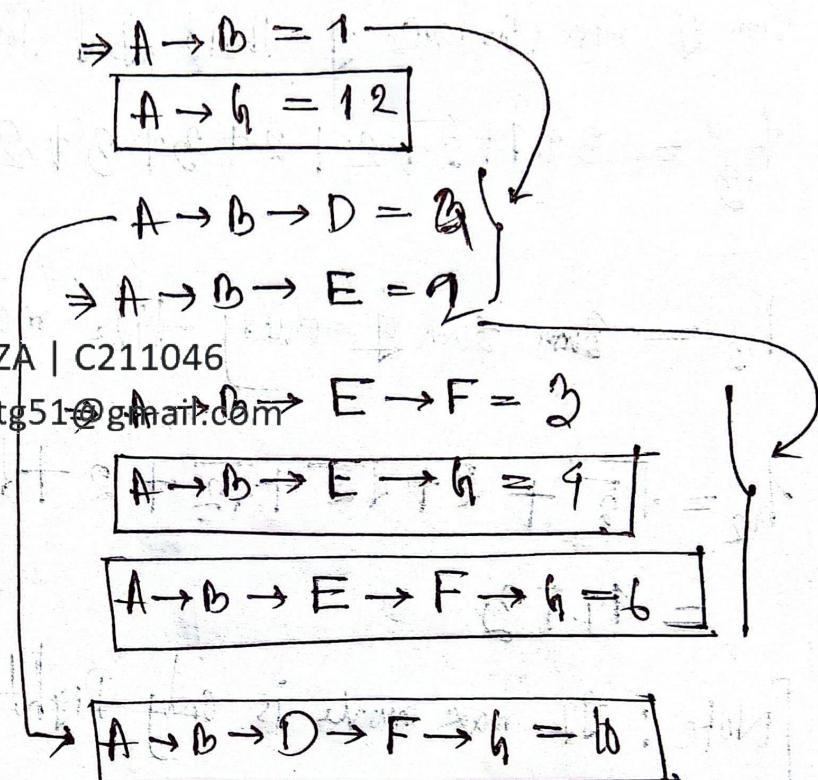
## "Mid Topic - AI"

### # Uniform Cost Search (UCS):



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An:  $A \rightarrow B \rightarrow E \rightarrow G \Rightarrow (4)$  Lowest

### # Heuristics 8-Puzzle Problem

7	2	9
5	*	6
8	3	1

Initial State

*	1	2
3	4	5
6	7	8

Final State

- ⇒ Number of misplaced state,  $h_1 = 8$
- ⇒ Sum of min distance of their goal position of every tile,  

$$h_2 = 3+1+2+2+3+3+2 = 18$$
- ⇒  $h_2 = \text{sum of every tile max distance}$  distance
- ⇒ 
$$h_2 = \sqrt{5} + 2 + \sqrt{2} + \sqrt{2} + 2 + \sqrt{5} + \sqrt{5} + 2$$
  

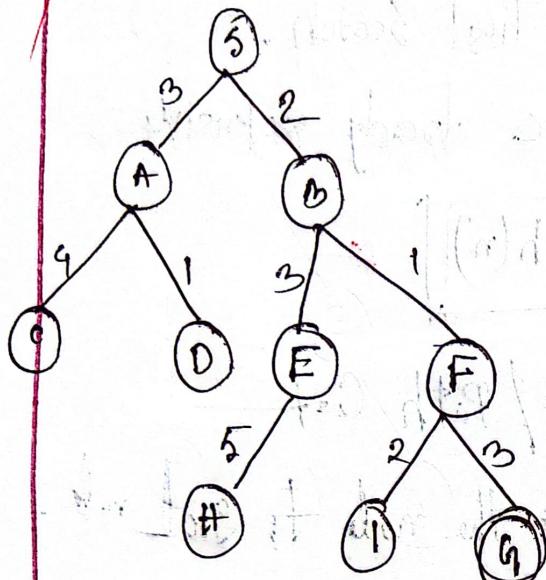
$$= 19.53$$
- ⇒ Note: If max move is only Right/Left, [No swap]

Max move  $\otimes$ ,  $h(m) = h_1 + h_2$

$$= 8 + 18 \rightarrow 26$$



## ~~#~~ Greedy Best first Search (GBFS):



node  $\rightarrow H(n)$

A  $\rightarrow 12$

B  $\rightarrow 4$

C  $\rightarrow 7$

D  $\rightarrow 3$

E  $\rightarrow 8$

F  $\rightarrow 2$

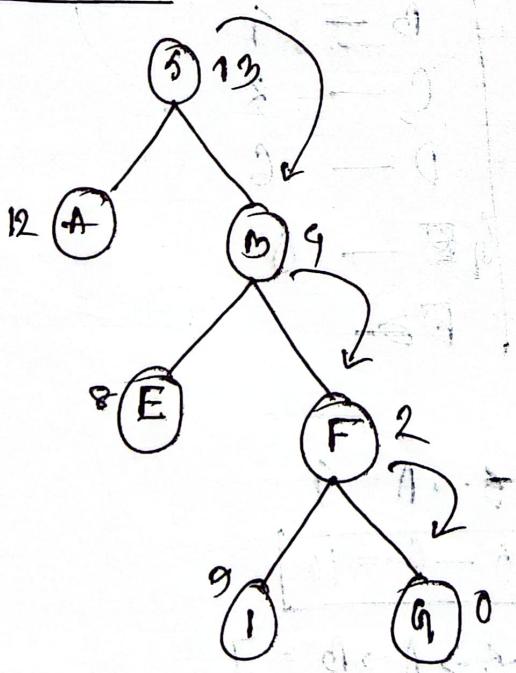
G  $\rightarrow 4$

I  $\rightarrow 9$

S  $\rightarrow 13$

G  $\rightarrow 0$

**Follow low heuristic first**  
**Don't Count Path Cost.**



$S \rightarrow B \rightarrow F \rightarrow I$

$$f = g + h = 0 + 13 = 13 \leftarrow S \leftarrow 5$$

$$f = g + h = 2 + 1 + 1 = 4 \leftarrow B \leftarrow 2$$

$$f = g + h = 1 + 2 + 1 = 4 \leftarrow F \leftarrow 1$$

## ~~#~~ A\* Search:

→ Best known from g best-first search.

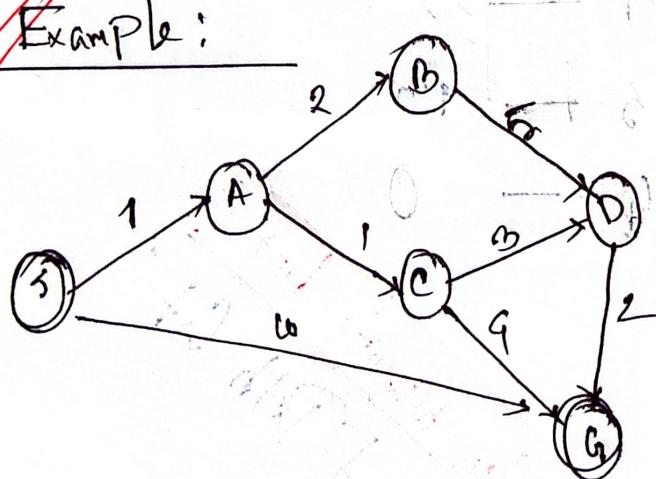
→ Avoid expanding paths that are already expensive

Evaluation Function  $f(n) = g(n) + h(n)$

$g(n)$  = Cost to reach the node / Path Cost

$h(n)$  = Cost to get from ~~to~~ the node to goal node.  
[heuristic value]

~~Example:~~



S	→	5
A	→	3
B	→	9
C	→	2
D	→	6
G	→	0
∅	→	∞

~~Ans:~~

$$S \rightarrow A = 1 + 3 = 4$$

$$S \rightarrow G = 10 + 0 = 10$$

$$S \rightarrow A \rightarrow B = 1 + 2 + 9 = 7$$

$$S \rightarrow A \rightarrow C = 1 + 1 + 2 = 4$$

$$S \rightarrow A \rightarrow C \rightarrow D = 1 + 1 + 3 + 6 = 11$$

$$\cancel{S \rightarrow A = 4}$$

$$\boxed{S \rightarrow G = 10}$$

$$\cancel{S \rightarrow A \rightarrow B = 7}$$

$$\cancel{S \rightarrow A \rightarrow C = 4}$$

$$S \rightarrow A \rightarrow C \rightarrow G = 1 + 1 + 9 + 0 = 6$$

$$S \rightarrow A \rightarrow B \rightarrow D = 1 + 2 + 5 + 6 = 14$$

$$S \rightarrow A \rightarrow C \rightarrow D \rightarrow G = 1 + 1 + 3 + 2 = 7$$

$$S \rightarrow A \rightarrow B \rightarrow D \rightarrow G = 1 + 2 + 5 + 2 + 0 = 10$$

$$S \rightarrow A \rightarrow C \rightarrow G$$

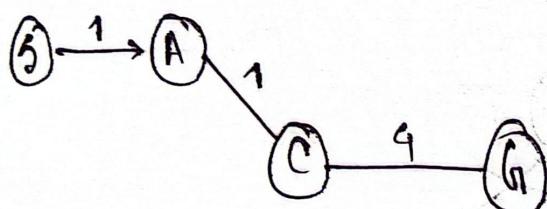
$$S \rightarrow A \rightarrow C \rightarrow D = 11$$

$$S \rightarrow A \rightarrow C \rightarrow G = 6$$

$$S \rightarrow A \rightarrow B \rightarrow D = 14$$

$$S \rightarrow A \rightarrow C \rightarrow D \rightarrow G = 7$$

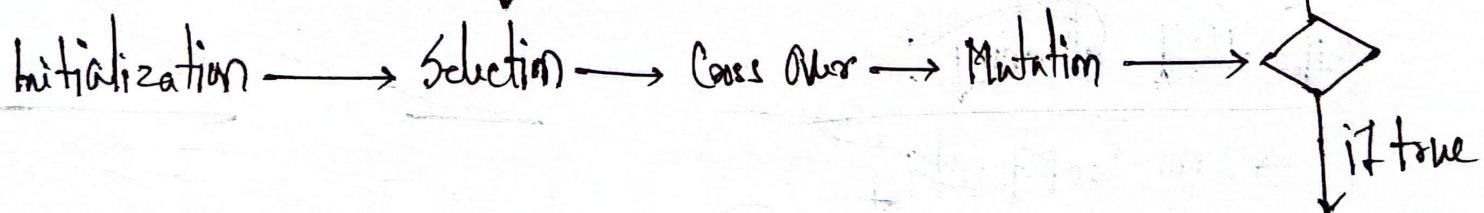
$$S \rightarrow A \rightarrow B \rightarrow D \rightarrow G = 10$$



# 8-Puzzle Problem Using A\* Search : 55

# Genetic Algo/8 queen Problem:

If false



Fitness function: Fitness funct'n evaluates how close a given solution is to the optimal solution of the desired Problem.

Close a given solution is to the optimal solution of the desired Problem.

CSP:

# 8-Queen Problem. Soln : SS

Vertex = {All Nodes}

Domain = {Colours}

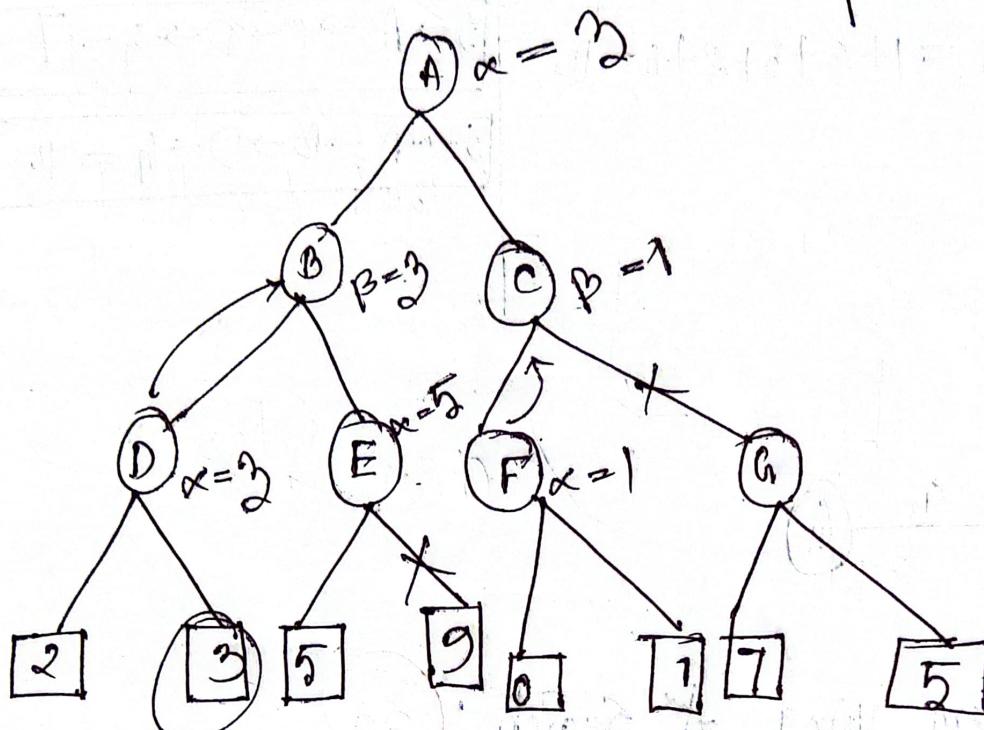
Constraint = {Conditions}

# Alpha-Beta Pruning :

max

min

max



Ans:

# Hill climbing :

→ NO backtracking

→ If goal found quit

Problem:

(i) Local Maximum → ↗

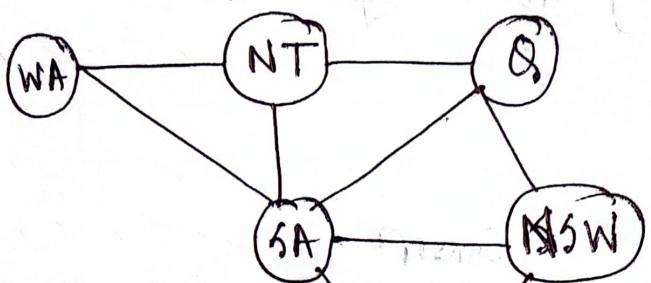
(ii) Flat ↗ ↗ ↗ ↗

(iii) Ridge ↗ ↗ ↗ ↗

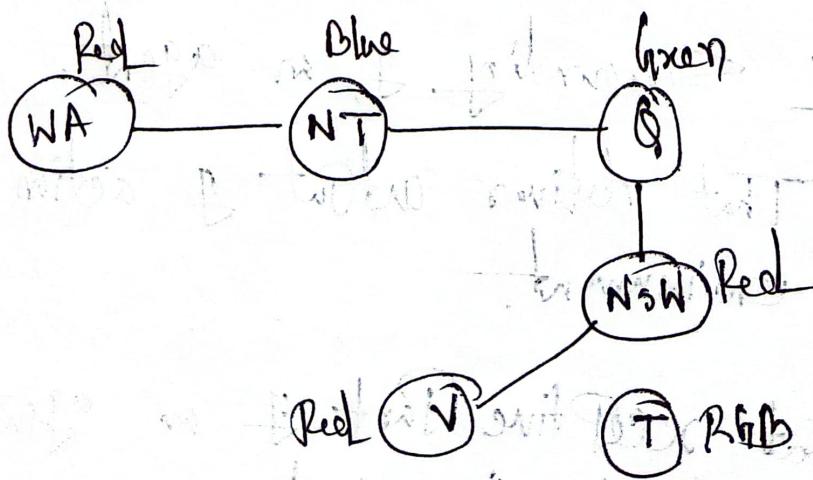
## # Constraint Satisfaction Problem (CSP)

→ Backtracking Algo. follow

DFS



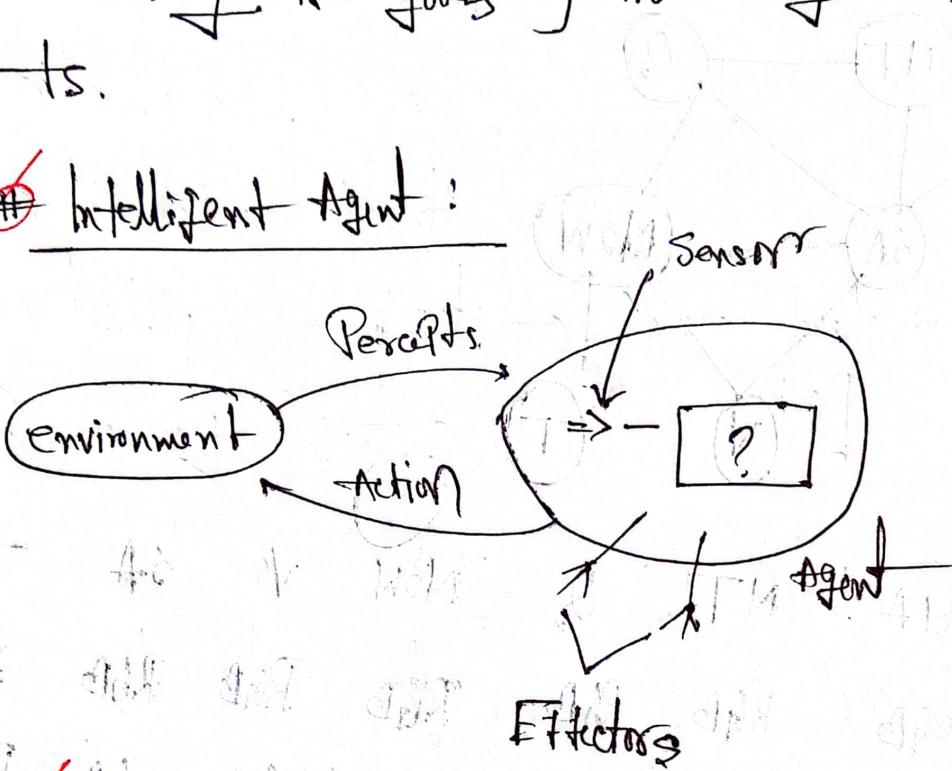
Initial Domain	WA	NT	Q	NSW	V	SA	T
Initial Domain	RGB	RGB	RB	RGB	RB	RB	RB
WA = R	R	GB	RB	RB	RB	GB	RB
Q = G	R	B	G	RB	RB	B	RB
V = B	R	B	G	R	B		RB



## ~~#~~ Artificial Intelligence:

→ Measurement of the success of an entity in achieving its goals by interacting with its environment.

## ~~#~~ Intelligent Agent:



## ~~#~~ Rational Agent:

## ~~PEAS~~:

Performance Measure / Goals: Define the success of an agent.

Environment: Surroundings of an agent.

Actuators: That deliver output of action to the environment.

Sensor: That receive input from the environment for the agent.

## Page

→ Agent = the

→ Percepts → the inputs to our system.

→ Actions → The output of our system.

→ Goals → Agent ex-expected to achieve

→ Env → Surrounding of agent.

## # Properties of Environments :

- i Accessible / Inaccessible
- ii Deterministic | Non-deterministic
- iii Episodic | Non-Episodic
- iv Static | Dynamic
- v Discrete | Continuous
- vi With/without rational adversaries .

## ~~#~~ Type of Agents :

- (i) Table lookup Driven Agent
- (ii) Simple Reflex Agent
- (iii) Model base reflex agent
- (iv) goal base Agent
- (v) Utility base Agent → [Choose best one from multiple option]
- (vi) Learning Agent.

## ~~#~~ Formulation Problem:

- (i) Single state Problem
- (ii) Multiple n n
- (iii) Contingency n
- (iv) Exploration n

7	2	9
1	-	3
5	6	8

State? → adjacent  
Action? → permissible  
Goal test? → satisfied  
Path Cost? → cost

State? → The board  
Action → Move left, Right --  
Goal → Tile in Order

Path Cost → 1 per move.

## ~~#~~ 8 Queen Problem (Heuristic Algo) :

Finding non attacking pair

1							
2	Q						Q
3							
4		Q		Q			
5				Q	Q		
6							
7		Q					
8					Q		

2 9 7 4 8 5 5 2

$$Q_1 = 6$$

$$Q_2 = 6$$

$$Q_3 = 6$$

$$Q_4 = 6$$

$$Q_5 = 7$$

$$Q_6 = 5$$

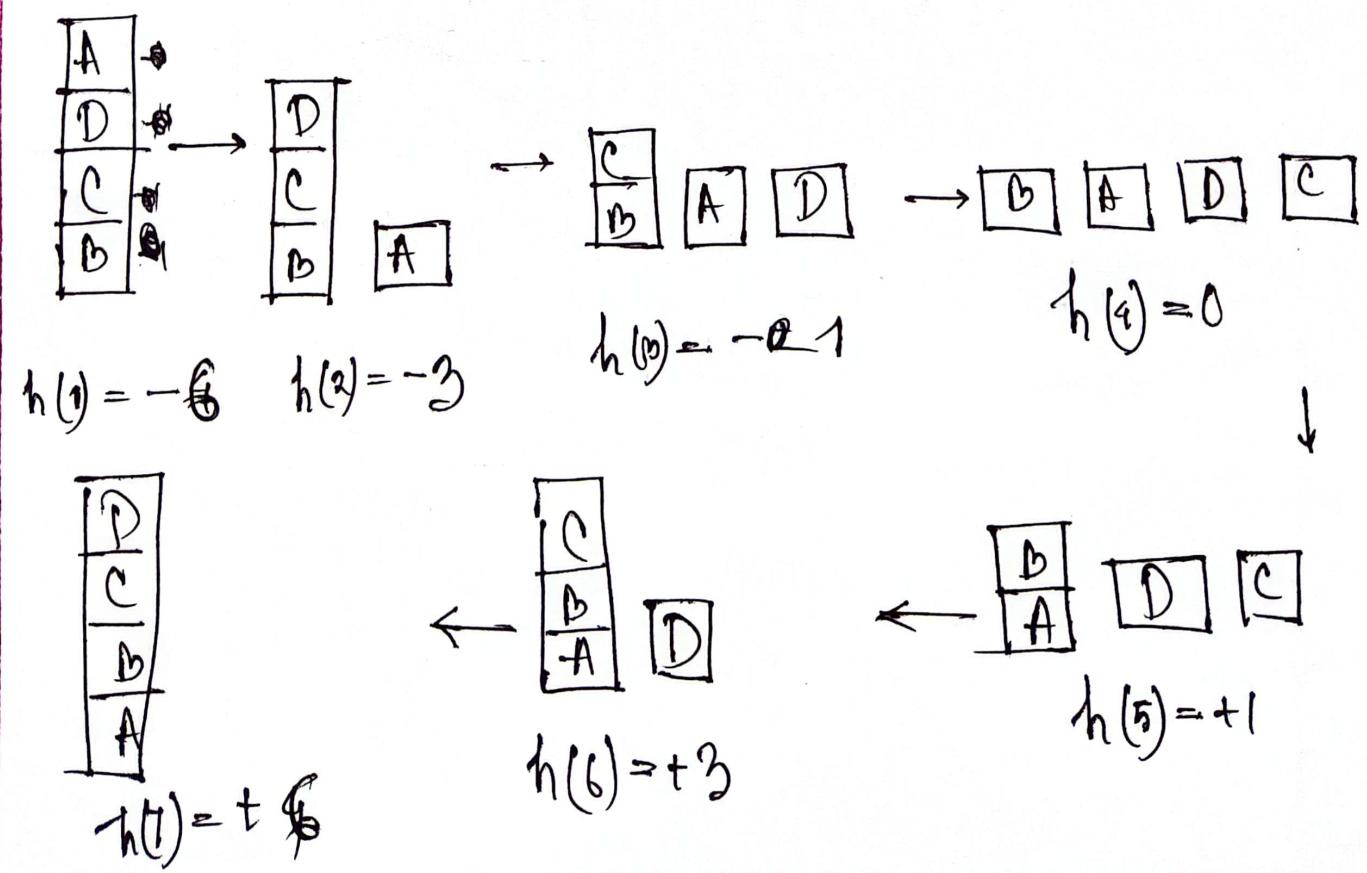
$$Q_7 = 6$$

$$Q_8 = 5$$

$$\frac{48}{2}$$

$$= (24) \text{ Pairs}$$

## ~~#~~ Hill Climbing :



$$\text{Ans} \quad S \rightarrow A = 1 + 4 = 5$$

$$S \rightarrow A = 5$$

$$S \rightarrow B = 1 + 1 = 2$$

$$S \rightarrow B = 2$$

$$S \rightarrow B \rightarrow C = 4$$

$$S \rightarrow B - C = 1 + 2 + 1 = 4$$

$$\boxed{S \rightarrow B \rightarrow C \rightarrow G = 1 + 2 + 3 + 0 = 6}$$

$$\text{Ans} \quad \boxed{S \rightarrow A \rightarrow C \rightarrow G = 1 + 1 + 3 = 5}$$



$$A = (1)_n$$

$$B = (0)_n$$

$$A =$$



$$C = (2)_n$$

$$D = (1)_n$$



$$E = (2)_n$$



$$F = (1)_n$$

