

A review on Generative Learning in Computer Vision

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Abstract—Artificial intelligence has made it possible for computers to learn from experiences and perform simple tasks which a human can easily do. Visual perception by human-like object recognizing abilities is once such task which scientists have been able to teach computers. In the past few years due to advancement and innovation in computing power especially unlocking GPU based distributed computing, computer scientists have achieved good success in able to teach computers to do complex tasks beyond classification like object detection, image segmentation, object tracking, and event detection. Computer Vision (CV) has since been used in numerous ways ranging from automated cars to quality check at factories which usually required an expert to manually check the production line. Artificial intelligence has made it possible for computers to learn from experiences and perform simple tasks which a human can easily do. Visual perception by human-like object recognizing abilities is once such task which scientists have been able to teach computers. In the past few years due to advancement and innovation in computing power especially unlocking GPU based distributed computing, computer scientists have achieved good success in able to teach computers to do complex tasks beyond classification like object detection, image segmentation, object tracking, and event detection.

Index Terms—component, formatting, style, styling, insert

I. INTRODUCTION

Artificial intelligence has made it possible for computers to learn from experiences and perform simple tasks which a human can easily do. Visual perception by human-like object recognizing abilities is once such task which scientists have been able to teach computers. In the past few years due to advancement and innovation in computing power especially unlocking GPU based distributed computing, computer scientists have achieved good success in able to teach computers to do complex tasks beyond classification like object detection, image segmentation, object tracking, and event detection. Computer Vision (CV) has since been used in numerous ways ranging from automated cars to quality check at factories which usually required an expert to manually check the production line.

With such advancements, the need for data is never ending. CV models running on neural networks require huge amount labeled training data to train them. But the problem lies in finding suitable high-quality data. Manual scavenging and labelling of data is not an ideal approach as it is costly to do so. The only option left for computer scientists is to produce high

quality artificial data either from scratch or by manipulating existing data. Generative learning is one such popular way to generate artificial data. This paper will look at different generative methods introduced lately.

The rest of the paper is organized as follows— Section II will provide an overview of generative learning. Section III will cover recent techniques used for generative learning. Section IV will provide a comparison of different techniques discussed in section III. Finally, section V will provide some remarks to conclude the paper.

II. GENERATIVE LEARNING

A. Background

Computer scientists has contributed a lot of research towards generating synthetic visual data. With such techniques, computer scientists has been able to generate data which is almost indistinguishable by a human eye. This fast availability of generated data has made it possible to solve a lot of modern problems in deep learning.

There has been some generative techniques around in this field of deep learning. In 2014, Goodfellow et al. published a paper on Generative Adversarial Networks (GANs) [1]. This state-of-the-art technique proved to be a major breakthrough in deep learning especially in CV. GANs has since then been applied in numerous fields including Natural Language Processing (NLP) and computer vision. This family of deep learning methods has become quite popular due to its good results. This review paper provides a survey on recent adaptations of GAN alongwith the first-original version often called as vanilla GAN. Autoencoders is a class of unsupervised neural networks which is also a popular method to generate data with some applications dating back to the 80s [2], [3]. Variational Autoencoders (VAEs) in specific is a generative technique.

B. Taxonomy

The following Table I presents taxonomy of different generative learning techniques—

III. TECHNIQUES

A. Generative Adversarial Networks (GANs)

Goodfellow et al. developed this state-of-the-art class of neural networks with two key components; a generator and

TABLE I
TAXONOMY AND CITATIONS OF GENERATIVE LEARNING TECHNIQUES

Technique		Citations
Generative Adversarial Networks	Vanilla GAN	[1]
	Conditional GAN	[4]
	Progressive GAN	[12]
	Deep Convolutional GANs (DCGAN)	[5]
	Auxiliary Classifier GAN	[7]
	3D-GAN	[8]
	Info GANs	[6]
	PacGAN	[9]
	Pix2PixGAN	[10]
	Cycle-GAN	[11]
	Text-to-Image Synthesis (StackGAN)	[13]
Super-Resolution GAN	[14]	
Autoencoders	Variational Autoencoders (VAEs)	[15]

a discriminator. The generator is a neural network which takes a random vector input usually a noise and generates a new plausible output out of it in the domain. This vector input is taken from a Gaussian distribution. A Gaussian or normal distribution is a probability distribution around a mean, which signifies the data around the mean is more frequent as compared to data points away from the mean. A Gaussian distribution shows a bell curve when plotted. The vector is referred as a latent space which means significant variables but not explicitly visible. Due to the fact that it uses random vector sample every time, the model becomes stochastic, the output will be non-deterministic every time. The generator makes unlimited samples out of it. The discriminator, a classification model, then takes input from the training dataset as well as output from the generator model and attempts to identify source of the input, whether it is from the training dataset or from the generator generated output. Both models are meant to compete with each other, the generator has to fool the discriminator into incorrectly classifying its sample as a real sample from the training set and the discriminator has to make itself perfect in correctly classifying input samples. The generator and the discriminator are both trained alongwith. When the discriminator predicts the class of the input sample, it is tweaked to perform better for the next sample, likewise the generator is updated to create samples which will fool the discriminator. Even though GAN is an unsupervised learning technique but this architecture of it is designed as a supervised learning technique.

The following sections cover some variants of GAN:

- 1) *Vanilla GAN*:
- 2) *Conditional GAN*:
- 3) *Progressive GAN*:
- 4) *Deep Convolutional GAN (DCGAN)*:
- 5) *Auxiliary Classifier GAN*:
- 6) *3D-GAN*:
- 7) *Info GAN*:
- 8) *PacGAN*:
- 9) *Pix2PixGAN*:
- 10) *Cycle-GAN*:
- 11) *Text-to-Image Synthesis (StackGAN)*:

12) *Super-Resolution GAN*:

B. Autoencoders

1) *Variational Autoencoders (VAEs)*:

IV. COMPARISON

V. CONCLUSION

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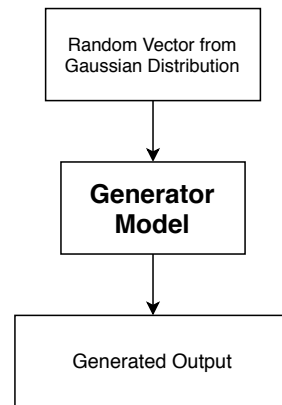


Fig. 1. The numbers depict the order of traversal of nodes in a BFS implementation